



RESEARCH ARTICLE

A proof of the Elliott–Rödl conjecture on hypertrees in Steiner triple systems

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Abstract

Hypertrees are linear hypergraphs where every two vertices are connected by a unique path. Elliott and Rödl conjectured that for any given $\mu > 0$, there exists n_0 such that the following holds. Every n -vertex Steiner triple system contains all hypertrees with at most $(1 - \mu)n$ vertices whenever $n \geq n_0$. We prove this conjecture.

1. Introduction

A key question in extremal graph theory is to find (almost-)spanning subgraphs H in a host graph G chosen from a certain class of graphs. Perhaps the simplest case along these lines may be to find (almost-)perfect matchings or (almost-)spanning trees, but even these cases have led us to a profound and intricate theory.

When the host graph G is dense, there have been extensive studies relating the existence of such (almost-)spanning subgraphs and the minimum degree of G . One of the earliest examples may be Dirac's theorem, which states that the minimum degree condition $\delta(G) \geq n/2$ implies the existence of Hamiltonian cycles and paths. Another well-known example is that every n -vertex graph with the minimum degree $\delta(G)$ contains a matching with at least $\min\{\delta(G), \lfloor n/2 \rfloor\}$ edges. In particular, $\delta(G) \geq n/2$ implies that there exists a perfect matching in a graph, provided that n is even. This fact was subsequently generalized by Brandt [9], who proved that a graph G contains every forest F with at most $\delta(G)$ edges and at most n vertices. Note that this also includes another well-known fact that every graph G contains all trees with at most $\delta(G)$ edges. There have been more results along these lines (e.g., a theorem by Komlós, Sárközy and Szemerédi [20] which shows the existence of spanning trees under certain degree conditions or the bandwidth theorem by Böttcher, Schacht and Taraz [8]).

In contrast, finding (almost-)spanning structures in a sparse host graph G often turns out to be impossible in general, which forces one to consider more restricted classes of graphs. For example, a classical theorem of Pósa [29], also obtained by Komlós and Szemerédi [21], states that 'typical' graphs with at least $(1 + o(1))n \log n$ edges contain a Hamilton cycle. Recently, Montgomery [25] proved that typical graphs with $\Omega(n \log n)$ edges contain all spanning trees with bounded maximum degree. Other classes of graphs have also been considered (e.g., a 'resilience' version of these results [5, 24] or variants for randomly perturbed graphs [6, 7, 17, 22]).

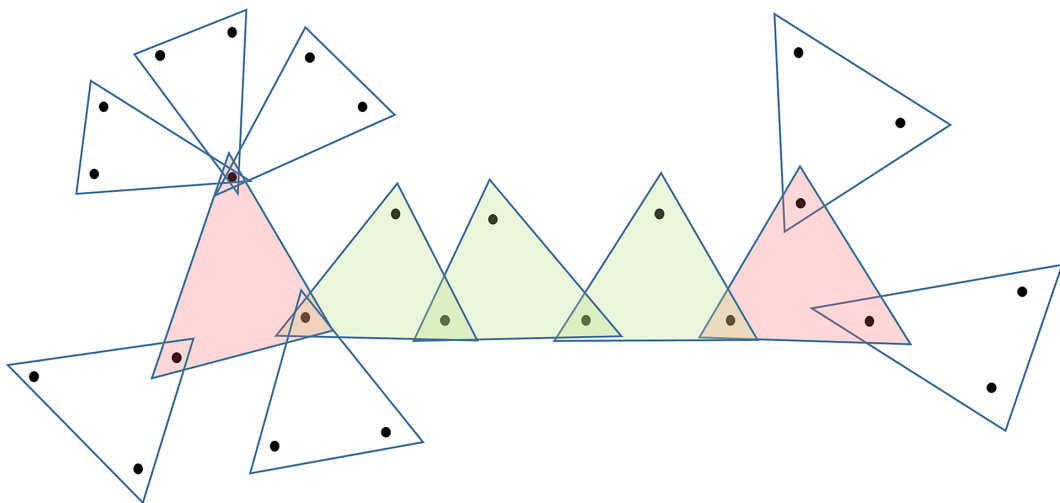


Figure 1. An example of a hypertree.

Although it is known that some large minimum codegree conditions on hypergraphs ensure existence of perfect matchings, spanning trees or cycles [23, 27, 30, 31, 32], the problem of finding spanning (or almost spanning) subhypergraphs in hypergraphs is fundamentally different from graphs. Our main goal is to explore this relatively less discovered area by proving the existence of an almost-spanning ‘hypertree’ in a well-known class of ‘sparse’ 3-uniform hypergraphs, the so-called *Steiner triple systems*. To further discuss our result, we first clarify what hypertrees are.

In what follows, we restrict our attention only to 3-uniform hypergraphs (or 3-graphs briefly). A 3-graph is *linear* if every pair of distinct edges has at most one vertex in common. A *hypertree* is a connected, linear 3-graph in which any two vertices are connected by a unique path (see Figure 1). Equivalently, a hypertree can be obtained by recursively adding edges such that each new edge intersects the current set of vertices in exactly one vertex. A *matching* in a 3-graph H is a collection of pairwise disjoint edges of H , and a *perfect matching* is a matching that covers all the vertices in H .

As mentioned before, (spanning) hypertrees in hypergraphs behave in a fundamentally different way from the graph case. For example, any connected graph contains at least one spanning tree; however, for 3-graphs, this may not be the case. First, a 3-graph with an even number of vertices has no spanning tree at all, as a hypertree always has an odd number of vertices. Even if we assume that the number of vertices is odd to set aside the parity issue, connectivity alone is still not sufficient to find a large hypertree. For example, a hypergraph with $2k + 1$ edges sharing the same two vertices forms a simplest 3-graph with no hypertree having more than one edge. For another example illustrating the difference, a simple greedy algorithm finds all trees with $\delta(G)$ edges in a graph G with the minimum degree $\delta(G)$, but the same algorithm for 3-graphs only yields all hypertrees with at most $\frac{1}{2}(\delta(G) + 1)$ edges.

However, Goodall and de Mier [15] proved that every 3-graph with an odd number of vertices where every pair belongs to at least one edge contains at least one spanning hypertree. The extremal cases in their theorem are the 3-graphs where every pair of vertices belongs to exactly one hyperedge (i.e., Steiner triple systems).

Steiner triple systems can be seen as an analogue of complete graphs (where all possible types of spanning trees exist) for linear 3-graphs. However, even though the Goodall–de Mier theorem proves that every Steiner triple system contains a spanning hypertree (in fact, they proved that an n -vertex Steiner triple system contains at least $\Omega((n/6)^{n/12})$ spanning hypertrees), it is far from the truth that every Steiner triple system contains all types of spanning hypertrees. For example, it is known [12] that for infinitely many odd n , there exist n -vertex Steiner triple systems with no perfect matching. Thus, any hypertree containing a perfect matching (there are super-exponentially many such hypertrees) cannot be

found in those Steiner triple systems. This motivates the following natural question: what is the largest number t such that any n -vertex Steiner triple system contains all hypertrees on t vertices?

This extremal question is hard even for matchings, which have a lot simpler structure than arbitrary hypertrees. A famous forty-year-old conjecture of Brouwer [10] states that every n -vertex Steiner triple system contains a matching covering $n - 4$ vertices. This conjecture remains open, and the best bound known so far is the recent progress by Keevash, Pokrovskiy, Sudakov and Yepremyan [19], proving that any n -vertex Steiner triple system contains a matching covering at least $n - O\left(\frac{\log n}{\log \log n}\right)$ vertices. These results on matchings already allude to the fact that determining the exact value of t may be out of reach at the moment.

In 2019, Elliott and Rödl asked an ‘asymptotic’ question, which appears to be the very first step toward determining the exact value of t .

Conjecture 1.1 (Elliott and Rödl [13]). *Given $\mu \geq 0$, there exists $n_0 = n_0(\mu)$ such that if $n \geq n_0$, T is any hypertree on n vertices, and S is any Steiner triple system on $m \geq n(1 + \mu)$ vertices, then T is a subhypergraph of S .*

The conjecture implies that, although there are super-exponentially many spanning hypertrees which cannot be found in some Steiner triple systems, a completely different behavior should exist for slightly smaller hypertrees. Elliott and Rödl gave a positive evidence for the conjecture by proving it for special types of hypertrees called *subdivision trees*. Later, Arman, Rödl and Sales [4, 3] proved Conjecture 1.1 for two different classes of hypertrees called *d-ary hypertrees* and *turkeys*. Our main result is to prove Conjecture 1.1 completely (i.e., for all hypertrees).

Theorem 1.2. *For every $\varepsilon > 0$, there exists $n_0 = n_0(\varepsilon)$ such that every n -vertex Steiner triple system G with $n \geq n_0$ contains every hypertree with at most $(1 - \varepsilon)n$ vertices.*

2. An outline of the proof

Our proof of Theorem 1.2 is partly motivated by the rainbow tree embedding theorem of Montgomery, Pokrovskiy and Sudakov [26], which states that there exists a ‘rainbow’ copy of every tree T with at most $(1 - o(1))n$ vertices in a properly edge-colored copy of K_n . As we consider 3-uniform linear hypergraphs instead of graphs, there are technical challenges to overcome, which will be discussed in due course.

Let T be a hypertree with $(1 - o(1))n$ vertices, and let G be an n -vertex Steiner triple system. We first decompose T into $T_0 \subseteq T_1 \subseteq \dots \subseteq T_\ell = T$ such that

- (1) $|T_0| = o(n)$,
- (2) $\ell = O(\text{polylog}(n))$,
- (3) T_1 is obtained by adding ‘large’ stars to T_0 , and
- (4) each T_i , $i > 1$, is obtained by adding either $o(n)$ many paths of length 3 whose endpoints are in T_{i-1} or a matching where each edge contains exactly one vertex in T_{i-1} .

We will embed T into G by first embedding T_0 (in Step 0) and then extend T_{i-1} to T_i (in Step i) for each $i \geq 1$. We will treat the initial steps, embedding T_0 and extending T_0 to T_1 , with extra care and execute the remaining steps inductively. More precisely, we first embed T_0 by a deterministic greedy algorithm and collect a set \mathcal{S} of ‘large’ vertex-disjoint stars centered at vertices in the copy of T_0 (where a star centered at a vertex v is a set of edges whose pairwise intersection is $\{v\}$). Here, the stars we find are in fact almost spanning (i.e., ‘larger’ than the large stars described in (3) due to a technical reason). We then partition all the $(1 - o(1))n$ vertices of G that are not in the copy of T_0 into $R \cup X_1 \cup \dots \cup X_\ell$ in a randomized way while also making sure that the two leaves in every edge of every star in \mathcal{S} lie in the same part of the partition. Given the partition, ‘most’ vertices in $T_i \setminus T_{i-1}$ are embedded into X_i , and the remaining vertices are embedded into the ‘reservoir’ R at each step.

Let us take a closer look at each of the steps. First, let us consider Steps 0, 1. The decomposition $T_0 \subseteq T_1 \subseteq \dots \subseteq T_\ell$ of T closely follows the ideas of [26]. Finding \mathcal{S} is not hard either; it follows from

adapting the switching technique in Section 8 of [26], originally introduced by Woolbright [33] and Brouwer, de Vries and Wieringa [11]. A technical problem occurs when we build the vertex set X_1 . In [26], X_1 was simply taken by choosing each vertex independently at random, but in our 3-graph setting, a straightforward application of this approach no longer captures the structures of stars that we need, as the ‘leaves’ of a star in a 3-graph are pairs of vertices rather than singletons; for instance, too few edges of a star will be selected if X_1 is taken by choosing vertices uniformly at random. To resolve this issue, we pair the leaf vertices of each star, and we either select both vertices in each pair or we select neither of them while choosing the random subset X_1 .

Now let us consider Step i for $i > 1$. Let $\{X_{i,1}, X_{i,2}\}$ be a random partition of X_i . For each $i > 1$, Step i uses the following properties of the partition $R \cup (X_{1,1} \cup X_{1,2}) \cup (X_{2,1} \cup X_{2,2}) \cup \dots \cup (X_{\ell,1} \cup X_{\ell,2})$, which can be obtained by using standard concentration inequalities. For each $i > 1$ and $j \in [2]$,

- (i) every vertex has ‘many’ neighbors in $X_{i,j}$ as well as in R , and
- (ii) for every pair of large enough disjoint sets $A, B \subseteq V(G) \setminus X_{i,j}$, the number of edges of the form $\{a, b, c\}$ with $a \in A$, $b \in B$ and $c \in X_{i,j}$ is close to their expectation.

To perform (4), one should find $o(n)$ paths of length three or a matching to extend T_{i-1} to T_i . In the former case, it is not hard to find $o(n)$ paths of length three by using (i) and (ii) above, and this follows the ideas of [26] closely. However, we use a completely different approach for finding a matching to extend T_{i-1} to T_i . Using (ii) and Pippenger’s hypergraph matching theorem, we embed most of the edges of the matching using vertices in $X_i = X_{i,1} \cup X_{i,2}$. Then we embed the remaining edges of the matching using vertices in R by making use of (i).

Organization. We introduce preliminary results in Section 3. We show (i) and (ii) are true for our random process and use it to embed matchings and bare paths in Section 4. In Section 5, we show that we can embed large vertex-disjoint stars into a Steiner triple system with prescribed centers. Finally, we put everything together to iteratively find an embedding of T in Section 6. The proof of hypertree splitting lemma is illustrated in Appendix A.

3. Preliminaries and notation

As outlined in the previous section, we need to decompose a hypertree T into $T_0 \subseteq T_1 \subseteq \dots \subseteq T_\ell = T$, following the approach taken in [26]. To this end, we introduce some auxiliary definitions.

First of all, let us clarify our definition of paths. A (*Berge*-)path of length ℓ in a hypergraph is a sequence $v_1, e_1, v_2, \dots, e_\ell, v_{\ell+1}$ of distinct vertices and edges such that $v_i, v_{i+1} \in e_i$ for all $i \in [\ell]$. In particular, a path in a linear 3-graph G is a subgraph of G on $2\ell+1$ vertices $\{v_0, v_1, \dots, v_\ell\} \cup \{u_1, \dots, u_\ell\}$ such that each $\{v_i, u_{i+1}, v_{i+1}\}$ is an edge for $i = 0, 1, \dots, \ell-1$. Each of the two pairs $\{v_0, u_1\}$ and $\{u_\ell, v_\ell\}$ in the first and the last edges of P is called an *end pair* of P .

A hypergraph T is a hypertree if and only if there is a unique path between any pair of distinct vertices. It is straightforward to see that a hypertree is a linear hypergraph. A u - v path P (or a path P between u and v) means a path P paired with the specified end vertices u and v , each of which is chosen from each end pair, respectively. The vertices other than u and v in a u - v path P are called the *internal* vertices of P .

In a hypertree T , a *bare path* P is a subhypergraph of T such that it is a u - v path of length $\ell \geq 2$ where no edges in $T \setminus E(P)$ are incident to the internal vertices of P . For example, the green edges in Figure 1 form a bare path, but green edges plus one of the red edges does not.

A *leaf* of a hypertree T is a vertex $v \in V(T)$ of degree one such that the edge e containing v has another vertex u of degree one. That is, removing u and v from T produces a subhypertree of T . The edges that contain a leaf are called *leaf edges* of T . In particular, the number of leaves of T is always even unless T is a single edge.

A *star* of size D is a 3-graph S on $2D+1$ vertices $\{v\} \cup \{u_1, \dots, u_D\} \cup \{w_1, \dots, w_D\}$ such that each triple $\{v, u_i, w_i\}$ is an edge for $i \in [D]$. The vertex v of degree D is called the *center* of S . A *matching* M is a collection of pairwise disjoint edges. If a matching M consists of leaf edges of a hypertree T , the

set of leaves of T in M is called the *leaf set* of M . We simply say that a vertex subset X of T is a *matching leaf set* of T if X is the leaf set of a matching M in T .

Using these terminologies, the following lemma formalizes (1)–(4) in the previous section by adapting the tree splitting lemma in Section 4 of [26] to our linear 3-graph setting.

Lemma 3.1. *Let $D, n \geq 2$ be integers, and let $0 < \mu < 1$. For any hypertree T with at most n edges and $2n + 1$ vertices, there exist integers $\ell \leq 10^5 D\mu^{-2}$ and $s \in [\ell]$ and a sequence of subgraphs $T_0 \subseteq T_1 \subseteq \dots \subseteq T_\ell = T$ such that the following holds:*

- (i) T_0 has at most μn edges and at most $3\mu n$ vertices.
- (ii) T_1 is obtained by adding stars of size at least D to T_0 ; that is, take pairwise vertex-disjoint stars of size at least D and identify their centers with vertices in T_0 .
- (iii) For $i \notin \{0, s\}$, T_{i+1} is obtained by adding a matching to T_i such that $V(T_{i+1}) \setminus V(T_i)$ is a matching leaf set of T_{i+1} .
- (iv) T_{s+1} is obtained by adding at most μn vertex-disjoint bare paths of length 3 to T_s such that every bare path we add is a u - v path P where $u, v \in V(T_s)$, and $V(P) \setminus \{u, v\}$ is disjoint from $V(T_s)$.

Although this lemma does not seem to follow directly from [26], the proof closely resembles theirs. Thus, we will give a brief proof in Appendix A.

We will frequently use standard concentration inequalities, which can be found, for example, in [2].

Lemma 3.2 (One-sided Chernoff Bound). *Let X_1, \dots, X_n be mutually independent Bernoulli random variables, and let $X = \sum_{i=1}^n X_i$. Then,*

$$\mathbb{P}(X \geq (1 + \varepsilon)\mathbb{E}[X]) \leq \exp\left(-\frac{\varepsilon^2}{\varepsilon + 2}\mathbb{E}[X]\right) \text{ for every } \varepsilon > 0, \text{ and}$$

$$\mathbb{P}(X \leq (1 - \varepsilon)\mathbb{E}[X]) \leq \exp\left(-\frac{\varepsilon^2}{2}\mathbb{E}[X]\right) \text{ for every } \varepsilon \in (0, 1).$$

The following corollary will be enough in most of the applications.

Corollary 3.3 (The Chernoff Bound). *Let X_1, X_2, \dots, X_n be i.i.d. Bernoulli random variables, and let $X = \sum_{i=1}^n X_i$. Then for $\varepsilon \in (0, 1)$,*

$$\mathbb{P}(|X - \mathbb{E}[X]| \geq \varepsilon\mathbb{E}[X]) \leq 2 \exp\left(-\frac{\varepsilon^2\mathbb{E}[X]}{3}\right).$$

Given a probability space $\Omega = \prod_{i=1}^n \Omega_i$ and a random variable $X : \Omega \rightarrow \mathbb{R}$, X is k -Lipschitz if $|X(\omega) - X(\omega')| \leq k$ whenever ω and ω' differ in at most one coordinate.

Lemma 3.4 (Azuma’s inequality). *If $X : \prod_{i=1}^n \Omega_i \rightarrow \mathbb{R}$ is k -Lipschitz, then*

$$\mathbb{P}(|X - \mathbb{E}[X]| > t) \leq 2 \exp\left(-\frac{t^2}{k^2 n}\right).$$

We use the notation \ll for the hierarchy between constants. For instance, if we claim that a statement holds under the condition $0 < a \ll b, c \ll d$, then it means that there exist non-decreasing functions $f_1, f_2 : (0, 1] \rightarrow (0, 1]$ and $g : (0, 1]^2 \rightarrow (0, 1]$ such that the statement holds if $0 < b \leq f_1(d)$, $0 < c \leq f_2(d)$, and $0 < a \leq g(b, c)$. We do not attempt to describe all these functions explicitly. We also write $a = (b \pm c)d$ if $(b - c)d \leq a \leq (b + c)d$.

For a given 3-graph G and $v \in V(G)$, $\deg(v)$ denotes the number of edges containing v , and a vertex $u \in V(G)$ is a *neighbor* of another vertex $v \in V(G)$ if there exists an edge of G containing both u and v . Let $\delta(G) = \min_{v \in V(G)} \deg(v)$ be the minimum degree of G . In particular, the number of neighbors of v in a linear 3-graph G is exactly $2 \deg(v)$. Let $G[A_1, A_2, A_3]$ denote the subhypergraph of G with the vertex set $A_1 \cup A_2 \cup A_3$ and the edge set $\{\{x, y, z\} \in E(G) : x \in A_1, y \in A_2, z \in A_3\}$. We allow nonempty

intersection of A_1, A_2, A_3 so an edge in $G[A_1, A_2, A_3]$ may have more than one vertex contained in A_i for some $i \in [3]$. Let $e_G(A_1, A_2, A_3)$ (or simply $e(A_1, A_2, A_3)$) be the number of edges of $G[A_1, A_2, A_3]$.

With these terminologies, Pippenger’s theorem [28], which strengthens a theorem in [14] (which also appears in [2] as a standard application of Rödl’s nibble), can be stated as follows.

Lemma 3.5 (Pippenger’s theorem). *Let $\varepsilon, \delta > 0$, and let D, k be integers such that $0 < \frac{1}{D}, \delta \ll \frac{1}{k}, \varepsilon$. If an n -vertex k -uniform hypergraph H satisfies that*

- (i) *the degree of v , $\deg(v) = (1 \pm \delta)D$ for all $v \in V(H)$ and*
 - (ii) *for any two distinct vertices $u, v \in V(H)$, the number of edges in H containing $\{u, v\}$ is less than δD ,*
- then H contains a matching of size at least $(1 - \varepsilon)\frac{n}{k}$.*

4. Matchings and bare paths

Our goal in this section is to collect lemmas for extending a given hypertree T_i to T_{i+1} when T_{i+1} is obtained by adding a matching or bare paths to T_i . The key tool to handle the former case is Pippenger’s theorem, and the latter case follows from standard concentration results for random edge subsets.

Let G be an n -vertex Steiner triple system. A *singleton-pair partition* \mathcal{U} of $V(G)$ is a partition $\{U_1, U_2, \dots, U_m\}$ of $V(G)$ such that $|U_i| \leq 2$ for each $i \in [m]$. Throughout this section, G always denotes an n -vertex Steiner triple system with a given singleton-pair partition \mathcal{U} . For such a fixed singleton-pair partition \mathcal{U} , the random subset \mathcal{U}_p of \mathcal{U} is then obtained by choosing each U_i independently at random with probability p . Let $X = \bigcup_{U \in \mathcal{U}_p} U$, which we denote by $X \sim \mathcal{U}_p$.

To find a large matching using Pippenger’s theorem (Lemma 3.5), we need to prove that a randomly chosen vertex set $X \sim \mathcal{U}_p$ together with certain sets A, B of already-embedded vertices induces an almost-regular hypergraph (see Lemma 4.2). As we cannot specify these sets of already-embedded vertices at the beginning, we want to show that $X \sim \mathcal{U}_p$ together with any pair of disjoint vertex sets A, B of size at least $\Omega(n)$ induces an almost-regular hypergraph. However, as there are too many choices of such vertex sets A and B , naive applications of concentration results do not yield a strong enough result to use the union bound. Hence, we first prove Lemma 4.1 which shows that $X \sim \mathcal{U}_p$ together with any pair of much smaller sets induces an almost-regular hypergraph, and we use these much smaller sets as building blocks for A and B to prove Lemma 4.2.

Lemma 4.1. *Let $X \sim \mathcal{U}_p$ for $p \geq 1/(\log n)^{100}$, and let $\varepsilon \geq 1/(\log n)^{100}$. Then the following holds with probability at least $1 - o(1/n)$: For every pair of disjoint sets $A, B \subseteq V(G)$ satisfying*

- (a) $n^{2/5} \leq |A|, |B| \leq n^{1/2}$,
- (b) $e(A, B, \{v\}) \leq (\log n)^{10}$ for every $v \in V(G)$, and
- (c) X is disjoint from $A \cup B$,

we have $e(A, B, X) = (1 \pm \varepsilon)p|A||B|$.

Proof. Let $G_X[A, B]$ be the auxiliary bipartite graph on the bipartition $A \cup B$, where $(a, b) \in A \times B$ is an edge if there exists $x \in X$ such that $abx \in E(G)$. As G is a Steiner triple system, every pair $(a, b) \in A \times B$ extends to a unique edge together with a vertex x , which belongs to X with probability p . Thus, the expected size of $E(G_X[A, B])$ is $p|A||B|$.

One may then apply Azuma’s inequality to prove concentration results for $|E(G_X[A, B])|$. Indeed, for a fixed pair of disjoint $A, B \subseteq V(G)$ such that $e(A, B, \{v\}) \leq k$ for every $v \in V(G)$, each event $U \in \mathcal{U}_p$ changes $|E(G_X[A, B])|$ by at most $2k$. Therefore, by Azuma’s inequality (Lemma 3.4), the probability that $|E(G_X[A, B])|$ deviates from its expectation by more than $\varepsilon p|A||B|$ is at most $2 \exp(-\varepsilon^2 p^2 |A|^2 |B|^2 / 4nk^2)$.

The number of pairs (A, B) such that $n^{2/5} \leq |A|, |B| \leq n^{1/2}$ is at most

$$\left(n^{1/2} \binom{n}{n^{1/2}} \right)^2 \leq n \left(\frac{en}{n^{1/2}} \right)^{2n^{1/2}} \leq (en^{1/2})^{2n^{1/2}+2}.$$

Among these choices, we call a pair (A, B) *bad* if $||E(G_X[A, B])| - p|A||B|| \geq \varepsilon p|A||B|$. Then the probability that there exists a bad pair (A, B) is at most

$$\begin{aligned} 2 \exp(-\varepsilon^2 p^2 |A|^2 |B|^2 / 4nk^2) (en^{1/2})^{2n^{1/2}+2} &\leq 2 \exp(-\varepsilon^2 p^2 |A|^2 |B|^2 / 4nk^2 + 10n^{1/2} \log n) \\ &\leq 2 \exp(-\varepsilon^2 p^2 n^{3/5} / 4k^2 + 10n^{1/2} \log n) \\ &= o\left(\frac{1}{n}\right), \end{aligned}$$

provided $k = (\log n)^{10}$ and $\varepsilon, p \geq (\log n)^{-100}$. If X, A, B are pairwise disjoint, then $e(X, A, B) = |E(G_X[A, B])|$, which completes the proof. □

By using the above lemma, we prove a concentration result for larger sets A and B of size $o(n)$.

Lemma 4.2. *Let $X \sim \mathcal{U}_p$ for $p \geq 1/(\log n)^{100}$, and let $\eta \geq 1/(\log n)^{100}$. Then with probability $1 - o(1/n)$, every pair of disjoint subsets $A, B \subseteq V(G) \setminus X$ of size at least ηn satisfies $e(A, B, X) = (1 \pm \eta)p|A||B|$.*

Proof. Let us fix disjoint subsets $A, B \subseteq V(G) \setminus X$ of size at least ηn . We will partition A and B into ‘manageable’ subsets to which Lemma 4.1 can apply. To that end, let $s := \lceil \frac{|A|}{3n^{2/5}} \rceil$ and $t := \lceil \frac{|B|}{3n^{2/5}} \rceil$. Partition A into s subsets A_1, A_2, \dots, A_s by choosing $i_a \in [s]$ uniformly and independently at random for each $a \in A$ and putting a in A_{i_a} . We also partition B in the same way but using t subsets B_1, B_2, \dots, B_t . For each $i \in [s]$ and $j \in [t]$, the expected sizes of each A_i and B_j are $|A|/s$ and $|B|/t$, respectively, each of which are of size $(3 + o(1))n^{2/5}$. The Chernoff bound (Lemma 3.3) then implies that all A_i and B_j are of size between $n^{2/5}$ and $n^{1/2}$ with probability at least $1 - 2(s + t) \exp(-n^{2/5}/12) = 1 - o(1/n)$.

For fixed $v \in V(G)$, $i \in [s]$, and $j \in [t]$, let \mathcal{E}_e be the event that an edge $e \in E(G)$ containing v is in $G[\{v\}, A_i, B_j]$. Then \mathcal{E}_e occurs with probability at most $1/(st) = o(1/n)$ for any $e \in E(G)$ containing v . Furthermore, linearity of G ensures that the events $\{\mathcal{E}_e\}_{e \in E(G), e \ni v}$ are mutually independent. Thus, by the one-sided Chernoff bound (Lemma 3.2), $e(A_i, B_j, \{v\}) \leq (\log n)^{10}$ with probability at least $1 - \exp(-(\log n)^8)$. Together with the union bound, this is enough to conclude that $e(A_i, B_j, \{v\}) \leq (\log n)^{10}$ holds for all vertices $v \in V(G)$ and indices $i \in [s]$, $j \in [t]$ with positive probability. Therefore, there exist partitions A_1, A_2, \dots, A_s of A and B_1, B_2, \dots, B_t of B such that A_i and B_j satisfy the conditions (a) and (b) of Lemma 4.1 for every i and j .

Thus, Lemma 4.1 implies that, with probability at least $1 - o(1/n)$, we have $e(A_i, B_j, X) = (1 \pm \eta)p|A_i||B_j|$ for every $i \in [s]$, $j \in [t]$ (for all choices of $A, B \subseteq V(G) \setminus X$). Now, taking the sum over all $i \in [s]$ and $j \in [t]$ completes the proof of the lemma. □

Finally, using Lemma 4.2, we find a matching M that covers almost all the vertices of any prescribed set A which is small enough and disjoint from the random set X .

Lemma 4.3. *Let $\varepsilon > 0$ be a constant and suppose $0 < 1/n \ll \varepsilon$. Let $X \sim \mathcal{U}_p$ for $p \geq 1/(\log n)^{20}$. Then the following holds with probability $1 - o(1/n)$. For all vertex sets $A \subseteq V(G) \setminus X$ of size at most $pn/2$, there exists a matching M of size at least $|A| - \varepsilon pn$ such that each edge $e \in M$ satisfies $|e \cap X| = 2$ and $|e \cap A| = 1$.*

Proof. Choose $\tau > 0$ such that $0 < 1/n \ll \tau \ll \varepsilon$, and let $\eta = \tau p^2$. In particular, we choose τ so that $\eta = \tau p^2 \geq 1/(\log n)^{100}$.

Let $\{X_1, X_2\}$ be a random partition of X obtained by assigning each $U_i \in \mathcal{U}_p$ to exactly one of X_1, X_2 independently at random. Then each X_i is a (possibly dependent) copy of $\mathcal{U}_{p/2}$ (i.e., $X_i \sim \mathcal{U}_{p/2}$).

By Lemma 4.2, with probability $1 - o(1/n)$, every pair of disjoint subsets $A', B' \subseteq V(G) \setminus X_2$ of size at least ηn satisfies $e(A', B', X_2) = (1 \pm \eta)p|A'||B'|/2$. Similarly, with probability $1 - o(1/n)$, every pair of disjoint subsets $A', B' \subseteq V(G) \setminus X_1$ of size at least ηn satisfies $e(A', X_1, B') = (1 \pm \eta)p|A'||B'|/2$.

Conditioning on these two events, say \mathcal{E}_1 and \mathcal{E}_2 , the following holds for any $A^* \subseteq V(G) \setminus X$ with $|A^*| = pn/2$:

- (i) For every $A' \subseteq A^*$ and $X' \subseteq X_1$ of size at least ηn , we have $e(A', X', X_2) = (1 \pm \eta)p|A'| |X'|/2$;
- (ii) For every $A' \subseteq A^*$ and $X' \subseteq X_2$ of size at least ηn , we have $e(A', X_1, X') = (1 \pm \eta)p|A'| |X'|/2$.

This implies that $e(A^*, \{v\}, X_2) = (1 \pm \eta)p|A^*|/2$ for all but at most $2\eta n$ vertices v in X_1 . Indeed, if not, we can collect ηn vertices to obtain a subset $X' \subseteq X_1$ with $|X'| \geq \eta n$ and either $e(A^*, X', X_2) > (1 + \eta)p|A^*| |X'|/2$ or $e(A^*, X', X_2) < (1 - \eta)p|A^*| |X'|/2$, which contradicts the conditioned events \mathcal{E}_1 and \mathcal{E}_2 . Moreover, by swapping the roles of X_1 and X_2 , one can prove that, for all but at most $2\eta n$ vertices $v \in X_2$, $e(A^*, X_1, \{v\}) = (1 \pm \eta)p|A^*|/2$ holds. Analogously, for all but at most $2\eta n$ vertices $v \in A^*$, $e(\{v\}, X_1, X_2) = (1 \pm \eta)p|X_1|/2$ holds.

One can also control the sizes of X_1 and X_2 . Namely, since X_1 and X_2 are 2-Lipschitz, Azuma’s inequality (Lemma 3.4) gives that $|X_1|, |X_2| = (1 \pm \eta)pn/2$ with probability at least

$$1 - 2 \exp\left(-\frac{\eta^2 p^2 n^2}{16n}\right) \geq 1 - 2 \exp\left(-\frac{\tau^2 p^6 n}{16}\right) = 1 - o\left(\frac{1}{n}\right).$$

In particular, for each $i \in [2]$, we have $(1 \pm \eta)p|X_i|/2 = (1 \pm 3\eta)p^2 n/4$.

Assuming all these four high probability events occur, namely $\mathcal{E}_1, \mathcal{E}_2$, and that $|X_1|, |X_2| = (1 \pm \eta)pn/2$, let $A \subseteq V(G) \setminus X$ be a vertex set of size at most $pn/2$. By adding arbitrary vertices to A , we obtain a set A^* with $|A^*| = pn/2$. Let H be the 3-graph obtained by removing all the exceptional vertices from $G[A^*, X_1, X_2]$ (i.e., those vertices whose degrees in $G[A^*, X_1, X_2]$ are not in the range $(1 \pm 3\eta)p^2 n/4$). By the discussion above concerning the number of such exceptional vertices, we remove at most $2\eta n$ vertices from each part. Thus, as G is linear, each remaining vertex has degree

$$\frac{1}{4}(1 \pm 3\eta)p^2 n \pm 4\eta n = \frac{1}{4}(1 \pm (3\eta + 16\eta/p^2))p^2 n.$$

As H is linear, each pair of vertices has codegree at most 1. Therefore, by Pippenger’s theorem (Lemma 3.5), as $(3\eta + 16\eta/p^2) \ll \varepsilon/2$, H contains a matching M^* of size at least

$$(1 - \varepsilon/2)(|A^*| + |X_1| + |X_2| - 6\eta n)/3 \geq (1 - \varepsilon/2)(|A^*| - 3\eta n) \geq |A^*| - \varepsilon pn.$$

By removing the edges containing a vertex of $A^* \setminus A$ from M^* , we obtain the desired matching M of size at least $|A| - \varepsilon pn$. □

Lemma 4.3 allows us to extend T_{i-1} to T_i whenever T_i is obtained by adding a matching, each of whose edges contains exactly one vertex in T_{i-1} . We now proceed to the other case where we add $o(n)$ bare paths of length 3. A pair of u - v paths P_1 and P_2 are said to be *internally vertex-disjoint* if their vertex sets are disjoint except the two vertices u and v (i.e., $(V(P_1) \setminus \{u, v\}) \cap (V(P_2) \setminus \{u, v\}) = \emptyset$). The next lemma proves that there are ‘many’ internally vertex-disjoint paths of length 3 between pairs of vertices u and v .

Lemma 4.4. *Let $0 < 1/n \ll \mu \ll p$, and let $X \sim \mathcal{U}_p$. Then with probability $1 - o(1/n)$, the following holds: For every pair of distinct vertices $u, v \in V(G)$, there exist at least μn internally vertex-disjoint u - v paths of length 3 such that all of their internal vertices are contained in X .*

To prove this, we need the following consequence of concentration inequalities.

Lemma 4.5. *Let $0 < 1/n \ll p$, and let $X \sim \mathcal{U}_p$. Then with probability $1 - o(1/n)$, every vertex $u \in V(G)$ satisfies $e(\{u\}, X, X) \geq p^2 n/3$.*

Proof. For a fixed vertex $u \in V(G)$, let $Y_u := e(\{u\}, X, X)$. An edge e containing u contributes to Y_u if and only if $e \setminus \{u\} \in \mathcal{U}_p$ or the two vertices in $e \setminus \{u\}$ are in two disjoint sets in \mathcal{U}_p . Thus, e is an edge in $G[\{u\}, X, X]$ with probability either p or p^2 , which implies that $p^2(n - 1)/2 \leq \mathbb{E}[Y_u] \leq p(n - 1)/2$.

As each event $U_i \in \mathcal{U}_p$ affects at most two edges containing u , Y_u is 2-Lipshitz. This enables us to apply Azuma's inequality (Lemma 3.4) to obtain

$$\mathbb{P}\left(Y_u < \frac{p^2n}{3}\right) \leq 2 \exp\left(-\frac{p^4n^2}{10^3n}\right) \leq \frac{1}{n^3}.$$

Thus, the probability that $Y_u \geq p^2n/3$ holds for every $u \in V(G)$ is at least $1 - 1/n^2 = 1 - o(1/n)$. \square

Proof of Lemma 4.4. Let $\{X_1, X_2, X_3\}$ be a random partition of X obtained by assigning each $U_i \in \mathcal{U}_p$ to exactly one of X_i independently at random. Then each X_i is a (possibly dependent) copy of $\mathcal{U}_{p/3}$.

By Lemma 4.5, with probability $1 - o(1/n)$, all vertices $u, v \in V(G)$ satisfy $e(\{u\}, X_1, X_1) \geq p^2n/27$ and $e(\{v\}, X_3, X_3) \geq p^2n/27$. By Lemma 4.2, with probability $1 - o(1/n)$, for every pair of disjoint subsets $A, B \subseteq V(G) \setminus X_2$ with $|A|, |B| \geq p^2n/100$, we have $e(A, X_2, B) \geq p|A||B|/6$. As both of these two events hold simultaneously with probability $1 - o(1/n)$, it suffices to show that these two events imply the existence of the desired paths for all pairs of distinct vertices $u, v \in V(G)$.

Suppose for a contradiction that there exists a pair u, v of distinct vertices such that there are less than μn internally vertex-disjoint $u-v$ paths of length three (with their internal vertices contained in X). Choose a maximal collection P_1, P_2, \dots, P_k of internally vertex-disjoint $u-v$ paths of length three such that their internal vertices are contained in X ; then $k < \mu n$. Let Y_i be the set of the internal vertices of P_i for $1 \leq i \leq k$ (so the sets Y_i are pairwise disjoint). Let $Y := \bigcup_{i=1}^k Y_i$, and let $E_1 := E(G[\{u\}, X_1, X_1]) - E(G[\{u\}, Y, X_1])$ and let $E_3 := E(G[\{v\}, X_3, X_3]) - E(G[\{v\}, Y, X_3])$. As $e(\{u\}, Y, X_1) \leq |Y|$ and $e(\{v\}, Y, X_3) \leq |Y|$ (since G is linear) and $|Y| \leq 5k \leq 5\mu n$, by the conditioned events, we have $|E_1|, |E_3| \geq p^2n/27 - 5\mu n \geq p^2n/30$.

Let Z_1 and Z_3 be the set of vertices in the edges of E_1 and E_3 except u and v , respectively. Then $|Z_1|, |Z_3| \geq p^2n/15$. By the conditioned events, we have $e(Z_1, X_2, Z_3) \geq p|Z_1||Z_3|/6 \geq p^5n^2/2000$. As there are at most $5\mu n^2$ edges incident to a vertex in Y , $e(Z_1, X_2 \setminus Y, Z_3) \geq p^5n^2/2000 - 5\mu n^2$. In particular, there is an edge e in $G[Z_1, X_2 \setminus Y, Z_3]$. Hence, there exists a $u-v$ path P' of length three containing e such that $V(P')$ is disjoint from Y (i.e., P' is internally vertex-disjoint from the collection P_1, \dots, P_k). Moreover, the internal vertices of P' are contained in X . This contradicts the maximality of the collection P_1, \dots, P_k . Hence, the conditioned events, which hold with probability $1 - o(1/n)$, imply the existence of the desired collection of paths for all pairs $u, v \in V(G)$ of distinct vertices. \square

5. Stars

In this section, we will prove that if the minimum degree of a linear hypergraph G is large enough, then we can find vertex-disjoint stars of desired size.

Lemma 5.1. *Let $0 < 1/n \ll \varepsilon < \frac{1}{100}$. Let G be an n -vertex linear 3-uniform hypergraph with $\delta(G) \geq (1 - \varepsilon)n/2$, and let $X = \{v_1, v_2, \dots, v_\ell\}$ be an independent set in G of size $\ell \leq \varepsilon^2n/10$. Then for any given positive integers n_1, n_2, \dots, n_ℓ such that $\sum_{i=1}^\ell n_i \leq (1 - 5\varepsilon)n/2$, G contains vertex-disjoint stars S_1, S_2, \dots, S_ℓ such that each S_i has size n_i and is centered at v_i .*

Proof. Let $m = \lceil \varepsilon^{-1} \rceil + 1$. As G is a linear 3-graph with $\delta(G) \geq (1 - \varepsilon)n/2$, there exists a vertex set W of size at most εn such that for all vertices $w \in V(G) \setminus (W \cup \{v_1\})$, there exists an edge v_1ww' in G for some $w' \in V(G) \setminus (W \cup \{v_1\})$.

We then choose vertex-disjoint stars S_1, \dots, S_ℓ in G which satisfy the following:

- (i) each S_i is centered at v_i and has size $t_i \leq n_i + m$. and
- (ii) among all S_1, S_2, \dots, S_ℓ that satisfy (i), choose one that maximizes $\sum_{i=1}^\ell t_i$.

By allowing empty S_i 's, such a choice is always possible. We claim that $t_i \geq n_i$ for all $i \in [\ell]$, which concludes the proof. Suppose to the contrary that $t_1 < n_1$, by reindexing if necessary.

For two vertex sets U, U' , denote by $N(U, U')$ the set of vertices v such that there is an edge uvv' of G with $u \in U$ and $u' \in U'$. Let M be the graph matching on $V(G)$ where $E(M) = \bigcup_{i \in [\ell]} \{xy : xyv_i \in$

$E(S_i)$. Let $N_M(U) = \bigcup_{u \in U} \{x : xu \in M\}$ for a vertex set U . These definitions are convenient for us to describe how one can replace the stars S_1, \dots, S_ℓ with other stars contradicting the maximality in (ii). Let $A_1 := V(G) \setminus \bigcup_{i=1}^\ell V(S_i)$. We then define $A_2, \dots, A_m, B_1, \dots, B_m \subseteq V(G)$ recursively as

$$B_i := N(A_i, \{v_1\}) \text{ and } A_{i+1} := N_M(B_i).$$

As $|A_1| \geq n - 2 \sum_{i=1}^\ell (n_i + m) \geq 2\epsilon n$ and v_1 has at least $(1 - \epsilon)n$ neighbors, v_1 has at least ϵn neighbors in A_1 . Thus, $|B_1| \geq \epsilon n$.

From the definition of B_i and the fact that G is linear, for each $y \in B_i$, we have unique $x \in A_i$ with $xyv_1 \in E(G)$. Again, for each $x \in A_i$ with $i > 1$, there exists unique $y' \in B_{i-1}$ such that $y'x \in M$. Hence, for each vertex $v \in \bigcup_{i \in [\ell]} B_i$, there exists a unique sequence $v = y_k, x_k, y_{k-1}, x_{k-1}, \dots, y_1, x_1$ such that $\{x_i\} = N(\{y_i\}, \{v_1\})$ and $\{y_{i-1}\} = N_M(\{x_i\})$ for all $i \in [\ell]$. As this sequence is unique, this determines the unique $k \in [\ell]$ that $v \in B_k$. From this, we conclude that

$$A_i \cap A_j = \emptyset \text{ and } B_i \cap B_j = \emptyset \text{ for } i \neq j \in [m].$$

Furthermore, for such a sequence for every vertex $v \in \bigcup_{i \in [\ell]} B_i$, the vertices $y_k, x_k, \dots, y_1, x_1$ are all distinct. As all A_i s are pairwise disjoint and all B_i s are pairwise disjoint, we only have to show that $x_i \neq y_j$ for all $i \neq j \in [k]$. If not, choose i and j with the minimum $|i - j| > 0$ such that $x_i = y_j$. Then the definition ensures that $\{x_j\} = \{y_i\} = N(\{x_i\}, \{v_1\})$, so $x_i = y_j$ and $x_j = y_i$. By symmetry, assuming $i > j$, we know that $i > j + 1$. If not, then $i = j + 1$, but $y_j = x_i = x_{j+1} = N_M(y_j)$, a contradiction that M forms a matching. Moreover, as we have $y_{i-1} = x_{j+1} = N_M(x_i)$ and $i > j + 1$, a contradiction to the minimality of $|i - j|$.

For each $i \in [\ell]$, let L_i be the set of all leaf vertices of S_i , and let $L = \bigcup_{i \in [\ell]} L_i$. We claim that, for $k \in [m]$, the vertex set B_k is contained in L .

Suppose that $B_k \not\subseteq L$ while $B_j \subseteq L$ for all $j < k$. Choose $y_k \in B_k \setminus L$, and consider the unique sequence $y_k, x_k, \dots, y_1, x_1$ as above. As all vertices in the sequence are distinct, we use this sequence to contradict the maximality assumption of $\sum_{j=1}^\ell t_j$ in (ii). Delete all the edges of the form of $y_i x_{i+1} v_{i'}$ from $S_{i'}$ for $1 \leq i \leq k - 1$ and add all edges of the form of $x_i y_i v_1$ for $1 \leq i \leq k$ to S_1 . Note that the choice of i' is uniquely determined for each i . As x_1, y_k are not contained in $\bigcup_{j=1}^\ell V(S_j)$ and all x_i, y_i are distinct, S_1, \dots, S_ℓ are still vertex disjoint stars. Moreover, S_1 has at most $n_1 + k \leq n_1 + m$ edges. Thus, our new S_1, \dots, S_ℓ satisfies the condition (i) and increases $\sum_{j=1}^\ell t_j$ by 1. Therefore, $B_k \subseteq \bigcup_{j=1}^\ell V(S_j)$.

As M is a perfect matching on L , we have $|A_{i+1}| = |B_i|$ for all $i \in [m]$. However, by the definition of B_i , we have $|B_i| = |A_i \setminus W|$ for all $i \in [m]$. As we have $|A_1| \geq n - 2 \sum_{i=1}^\ell (n_i + m) \geq 2\epsilon n$ and all A_i are pairwise disjoint, we conclude that for each k ,

$$\sum_{i \in [k]} |B_i| = \sum_{i \in [k]} |A_i \setminus W| \geq |A_1| + \sum_{2 \leq i \leq k} |A_i| - |W| \geq 2\epsilon n + \sum_{1 \leq i \leq k-1} |B_i| - \epsilon n \geq \epsilon n + \sum_{1 \leq i \leq k-1} |B_i|.$$

This yields that

$$\left| \bigcup_{i \in [m]} B_i \right| = \sum_{i \in [k]} |B_i| \geq m\epsilon n > n,$$

which concludes the proof by contradiction. □

6. Proof of Theorem 1.2

We begin by stating a variant of the well-known fact which easily follows from a simple greedy algorithm. We omit the proof.

Lemma 6.1. *Let G be a linear hypergraph with minimum degree δ . Then G contains every tree T with less than $\delta/2$ vertices.*

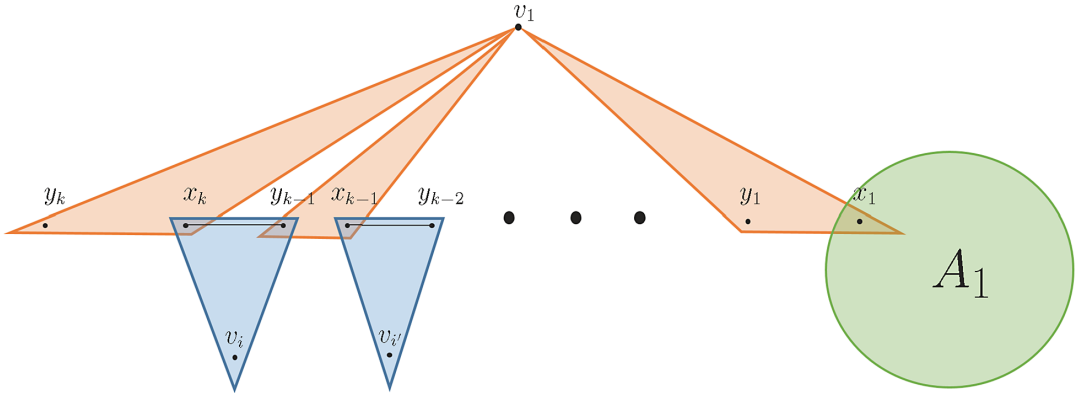


Figure 2. Choice of $x_1, y_1, \dots, x_k = v$.

We may assume that ε is small enough. Choose μ and n so that we have $0 < 1/n \ll \mu \ll \varepsilon \ll 1$. Let T be a hypertree with at most $(1 - \varepsilon)n$ vertices. Applying Lemma 3.1 with $D = \lceil \log^{10} n \rceil$ and the chosen μ , we obtain a chain of sub-hypergraphs $T_0 \subseteq T_1 \subseteq \dots \subseteq T_\ell = T$ with $\ell \leq 10^5 D \mu^{-2}$, $s \in [\ell]$ satisfying the assertions (i)–(iv) of Lemma 3.1.

By (i), $|V(T_0)| \leq 3\mu n$, so there exists an injective homomorphism $\varphi : V(T_0) \rightarrow V(G)$ that embeds T_0 into G by Lemma 6.1. In what follows, we shall identify T_0 as its image under φ (i.e., we assume that T_0 is embedded as a subgraph of G). Let $\{v_1, \dots, v_k\} \subseteq V(G)$ be the set of vertices of T_0 with $e_{T_1}(v_i, V(T_1 \setminus T_0), V(T_1 \setminus T_0)) \geq D$, and let $d_i := e_T(v_i, V(T_1 \setminus T_0), V(T_1 \setminus T_0))$ for each $i \in [k]$. Note that k is at most $O(n(\log n)^{-10}) \leq \mu n \leq \varepsilon^2 n/10$.

First, we remove all vertices in $V(T_0) \setminus \{v_1, \dots, v_k\}$ from G . This removes at most $3\mu n$ edges incident to a fixed remaining vertex $x \in (V(G) \setminus V(T_0)) \cup \{v_1, \dots, v_k\}$. Furthermore, we remove all the edges containing at least two of v_1, \dots, v_k from G . This removes at most $k/2$ edges incident to any vertex $x \in V(G)$. Thus, after removing all these edges from G , the minimum degree of the resulting hypergraph H is still at least $(1 - 10\mu)n/2 \geq (1 - 10\mu)|V(H)|/2$. Let $d := \sum_{i=1}^k d_i$, and let $n_i := \lceil \frac{d_i}{2d} n(1 - \varepsilon/8) \rceil$. Then $\sum_{i=1}^k n_i \leq k + \sum_{i=1}^k \frac{d_i}{2d} n(1 - \varepsilon/8) \leq (1 - \frac{\varepsilon}{10}) \frac{|V(H)|}{2} \leq |V(H)| \geq n - 3\mu n$. By applying Lemma 5.1 to H , we get vertex-disjoint stars S_1, \dots, S_k in G where each S_i is centered at v_i of size d_i and does not contain any vertices of T_0 other than v_i .

We then define a singleton-pair partition \mathcal{U} of $V(G)$ as follows. For every $1 \leq i \leq k$ and for every edge $xyv_i \in E(S_i)$, let $\{x, y\}$ be a part of \mathcal{U} . Moreover, let each of the remaining vertices of $V(G)$ be a part of \mathcal{U} of size one.

Let $p_0 := \varepsilon/200$. Let $m_i := |V(T_i) \setminus V(T_{i-1})|$, and let $p_i := (1 + \frac{\varepsilon}{4}) \frac{m_i}{n} + \frac{\varepsilon}{4\ell}$ for $i \in [\ell]$. Recall that $\ell \leq 10^5 D \mu^{-2} = O((\log n)^{10})$. As $\varepsilon > 0$ is a constant, $p_i \geq \frac{1}{(\log n)^{20}}$ for all $i \in [\ell]$.

Now sample $X_1 \subseteq V(G)$ by choosing each $U \in \mathcal{U}$ with probability p_1 independently at random and taking their union (i.e., $X_1 \sim \mathcal{U}_{p_1}$).

Provided that X_1, X_2, \dots, X_{i-1} are chosen, select each $U \in \mathcal{U}$ that is not included in $X_1 \cup \dots \cup X_{i-1}$ with probability $p_i/(1 - p_1 - p_2 - \dots - p_{i-1})$ independently at random and add it to X_i . After choosing X_ℓ , we choose the ‘reservoir’ R by selecting each $U \in \mathcal{U}$ that is not in $X_1 \cup \dots \cup X_\ell$ with probability $p_0/(1 - p_1 - p_2 - \dots - p_\ell)$ independently at random and adding it to R . Note that $\sum_{i=0}^\ell p_i \leq (1 + \varepsilon/4)|T|/n + \varepsilon/4 + \varepsilon/200 \leq 1$. Then $X_i \sim \mathcal{U}_{p_i}$ for each $i \in [\ell]$ and $R \sim \mathcal{U}_{p_0}$.

Let $\mathcal{F}, \mathcal{E}_0, \mathcal{E}_1, \mathcal{E}_M$ be the following events.

\mathcal{F} : $|V(T_0) \cap X_i| \leq 10p_i \mu n$ for each $i \in [\ell]$ and $|V(T_0) \cap R| \leq 10p_0 \mu n$.

\mathcal{E}_0 : Every vertex v is incident to at least $10^4 \mu n$ edges e such that $e \setminus \{v\} \subseteq R$, and between every pair $u, v \in V(G)$ of distinct vertices, there are at least $100 \mu n$ internally vertex-disjoint u - v paths of length 3 and all of their internal vertices are in R .

- \mathcal{E}_1 : For each $i \in [k]$, $e(\{v_i\}, X_1, X_1) \geq d_i$.
- \mathcal{E}_M : For each $2 \leq i \leq \ell$ and for all sets $A \subseteq V(G) \setminus X_i$ of size $|A| \leq p_i n/2$, there exists a matching M of G of size at least $|A| - \mu p_i n$ such that each edge $e \in M$ satisfies $|e \cap X_i| = 2$ and $|e \cap A| = 1$.

We first show that all of the events $\mathcal{F}, \mathcal{E}_0, \mathcal{E}_1, \mathcal{E}_M$ hold with high probability, and then conditioning on these events, we show that one can embed T into G .

Claim 6.2. $\mathbb{P}(\mathcal{E}_0), \mathbb{P}(\mathcal{E}_1), \mathbb{P}(\mathcal{F}) = 1 - o(1)$, and $\mathbb{P}(\mathcal{E}_M) = 1 - o(1)$.

Proof. First, Lemma 4.4 and 4.5 imply that $\mathbb{P}(\mathcal{E}_0) = 1 - o(1/n)$. Second, by Azuma’s inequality (Lemma 3.4), we have

$$\mathbb{P}(\mathcal{F}^c) \leq \sum_{i=0}^{\ell} 2 \exp\left(-\frac{p_i^2 \mu^2 n^2}{10n}\right) \leq o\left(\frac{1}{n}\right),$$

where the last inequality follows from the fact that $p_i \geq \frac{\varepsilon}{4\ell} \geq \frac{1}{(\log n)^{20}}$ for each i . Now we show $\mathbb{P}(\mathcal{E}_1) = 1 - o(1)$. As $T_1 \setminus T_0$ consists of the stars S_1, \dots, S_k that have $2d$ leaves in total, $m_1 = |V(T_1) \setminus V(T_0)| = 2d$. Hence, the expected value of $e(\{v_i\}, X_1, X_1)$ is

$$p_1 n_i \geq \left(1 + \frac{\varepsilon}{4}\right) \frac{m_1}{n} \cdot \left(1 - \frac{\varepsilon}{8}\right) \frac{d_i n}{2d} \geq \left(1 + \frac{\varepsilon}{4}\right) \frac{2d}{n} \cdot \left(1 - \frac{\varepsilon}{8}\right) \frac{d_i n}{2d} \geq \left(1 + \frac{\varepsilon}{10}\right) \cdot d_i.$$

Indeed, for any edge in S_i , the probability that its two leaves are included in $X_1 \sim \mathcal{U}_{p_1}$ is equal to p_1 , as they form a part (of size two) in the singleton-pair partition \mathcal{U} . Moreover, these events for all edges in S_i are mutually independent. This enables us to use the Chernoff bound (Lemma 3.3) to prove that $e(\{v_i\}, X_1, X_1)$ is less than $2d_i$ with probability at most

$$2 \exp\left(-\frac{\varepsilon^2 d_i}{10^3}\right) \leq \exp\left(-\frac{\varepsilon^2 \log^{10} n}{10^3}\right) = o\left(\frac{1}{n}\right),$$

where the inequality follows from $d_i \geq D \geq \log^{10} n$ which is guaranteed by (ii) of Lemma 3.1. Therefore, $\mathbb{P}(\mathcal{E}_1) = 1 - o(1)$. Finally, Lemma 4.3 together with a union bound ensures that $\mathbb{P}(\mathcal{E}_M) = 1 - o(\frac{\ell}{n}) = 1 - o(1)$. □

By Claim 6.2, the events $\mathcal{F}, \mathcal{E}_0, \mathcal{E}_1$ and \mathcal{E}_M occur with probability $1 - o(1)$. Now we show that there exists a sequence $T_0 \subseteq T_1 \subseteq \dots \subseteq T_\ell = T$ of subgraphs of G satisfying the following properties for all $i \in [\ell]$ (conditioning on the events $\mathcal{F}, \mathcal{E}_0, \mathcal{E}_1$ and \mathcal{E}_M).

- (a) If $i \neq s+1$, then T_i extends T_{i-1} and it satisfies $V(T_i) \setminus V(T_{i-1}) \subseteq X_i \cup R$ and $|(V(T_i) \setminus V(T_{i-1})) \cap R| \leq 30p_i \mu n$.
- (b) If $i = s+1$, then T_{s+1} extends T_s and it satisfies $V(T_{s+1}) \setminus V(T_s) \subseteq R$ and $|V(T_{s+1}) \setminus V(T_s)| \leq 7\mu n$.

As T_0 vacuously satisfies the above two properties, assume that we have $T_0 \subseteq \dots \subseteq T_{i-1}$ satisfying the above properties with the maximum i , and assume $i \leq \ell$. Since $T_0 \subseteq \dots \subseteq T_{i-1}$ satisfy (a) and (b), we have

$$|V(T_{i-1}) \cap R| \leq |V(T_0)| + \sum_{j < i, j \neq s} 30p_j \mu n + 7\mu n \leq 40\mu n. \tag{I}$$

If $i = 1$, by using vertices in $X_1 \cap S_j$ for each $j \in [k]$, one can extend T_0 to T_1 by \mathcal{E}_1 . It is straightforward to check $V(T_1) \setminus V(T_0) \subseteq X_1 \cup R$ and $|(V(T_1) \setminus V(T_0)) \cap R| = 0$, as we only used vertices in X_1 to extend T_0 to T_1 . Hence, (a) is satisfied, a contradiction to the maximality of i . Hence, we have $i > 1$.

Suppose $2 \leq i \leq \ell$ and $i \neq s+1$. By (iii) of Lemma 3.1, in this case, T_i can be obtained by adding a matching to T_{i-1} such that $V(T_i) \setminus V(T_{i-1})$ is a matching leaf set of T_i . Let A_i be the set of vertices of T_{i-1} that are contained in the edges of the matching $E(T_i) \setminus E(T_{i-1})$. Then $|A_i| = m_i/2$. By \mathcal{E}_M , there exists a

matching M in G of size at least $|A_i| - \mu p_i n$ such that each edge e satisfies $|e \cap A_i| = 1$ and $|e \cap X_i| = 2$. Now remove all the edges that are incident to a vertex in T_0 from M to produce a matching M' . By \mathcal{F} , $|M| - |M'| \leq 10p_i\mu n$. Adding the edges of M' to T_{i-1} then yields a partial embedding of T_i , where at most $11p_i\mu n$ edges of T_i are not embedded yet. We now show that one can use vertices of R to embed these edges (which would then show that the first part of (a) is satisfied).

As every vertex v in A_i is incident to at least $10^4\mu n$ edges e such that $e \setminus \{v\} \subseteq R$ by \mathcal{E}_0 , (I) ensures that one can greedily choose edges to complete the embedding of T_i by using at most $2(11p_i\mu n) \leq 30p_i\mu n$ vertices in R (i.e., $|(V(T_i) \setminus V(T_{i-1})) \cap R| \leq 30p_i\mu n$) so (a) is satisfied, a contradiction to the maximality of i .

Suppose $i = s + 1$. By (iv) of Lemma 3.1, in this case, T_{s+1} is obtained by adding at most μn vertex-disjoint bare paths of length 3 to T_s . Conditioning on \mathcal{E}_0 , for every pair of vertices $u, v \in V(G)$, there are at least $100\mu n$ internally vertex-disjoint $u-v$ paths (of length 3) such that all of their internal vertices are in R . By (I), the embedding of T_{i-1} already used at most $40\mu n$ vertices from R , so for any pair of vertices $u, v \in V(G)$, there are at least $60\mu n$ internally vertex-disjoint $u-v$ paths (of length 3) remaining. As each path of length 3 uses at most 7 vertices in R , one can greedily find at most μn vertex-disjoint paths (of length 3) that are required for embedding T_{s+1} in G . As we have used at most $7\mu n$ vertices of R , (b) is satisfied, a contradiction to the maximality of i .

Hence, we have $i - 1 = \ell$, and this completes the proof of Theorem 1.2.

Concluding remarks. As noted before, a complete graph on n vertices contains all possible trees on at most n vertices. This simple fact motivated the tree packing conjecture of Gyárfás and Lehel [16], which states that for $n \in \mathbb{N}$, any given set of trees T_1, T_2, \dots, T_n with $|V(T_i)| = i$ can be packed into the complete graph K_n . This notorious conjecture since 1976 has driven a lot of research and it still remains open (see, for example, [1, 18] for results toward this conjecture).

As our theorem guarantees that an n -vertex Steiner triple system contains all possible hypertrees with at most $(1 - o(1))n$ vertices, it is natural to ask if a corresponding ‘packing’ statement for Steiner triple systems also holds. This question was in fact already asked by Frankl, as recorded in [13], in the following form: what is the largest integer s such that any s hypertrees $T_3, T_5, T_7, \dots, T_{2s+1}$ with $|V(T_i)| = i$ can be packed into every n -vertex Steiner triple system? Indeed, this question is a natural analogue of the tree packing conjecture, since every hypertree contains an odd number of vertices. Frankl showed that any given set of hypertrees $T_3, T_5, T_7, \dots, T_{(n+3)/2}$ can be packed into every n -vertex Steiner triple system but it is not known if a larger set of hypertrees can be embedded.

By analyzing our proof more carefully with some modifications, one may prove a minimum-degree version of our theorem. That is, there exists some $\delta > 0$ such that the following holds: If $\varepsilon = \Omega(n^{-\delta})$ and n is sufficiently large, then every n -vertex linear 3-graph G with the minimum degree at least $n(\frac{1}{2} - (\frac{\varepsilon}{\log n})^{100})$ contains any hypertree T with at most $(1 - \varepsilon)n$ vertices. By repeatedly applying this to a Steiner triple system and deleting low degree vertices, one can also show that any given set of hypertrees $T_{n-j-t \log^{100} n}$, $j = 0, 2, 4, \dots, 2t$, with $|V(T_i)| = i$ pack into every n -vertex Steiner triple system for an appropriate choice of $t = \Theta(\frac{n}{\text{polylog}(n)})$.

Appendix A. Hypertree splitting

The very first step toward our proof of Theorem 1.2 is Lemma 3.1, which splits the given hypertree T into ‘manageable’ pieces. Our proofs in this section will closely follow that of [26], whose first step is the following lemma for 2-graphs. For a (graph) tree T , a path P in T is a *bare path* if all the internal vertices of P have degree two.

Lemma A.1 [26]. *Let $\ell, m \geq 2$ be integers, and let T be a tree with at most ℓ leaves. Then there exist vertex-disjoint bare paths P_1, P_2, \dots, P_s of length m such that*

$$|V(T - P_1 - P_2 - \dots - P_s)| \leq 6m\ell + \frac{2|V(T)|}{m + 1},$$

where $T - P$ denotes the graph obtained by removing all of internal vertices of P from T .

By considering the breadth-first search (BFS) tree of the line graph of a hypertree, this lemma can be adapted for hypertrees. To that end, we need to specify the corresponding definitions for 3-uniform hypergraphs. A *semi-bare path* P in a hypertree T is a path such that edges in $T \setminus E(P)$ are only incident to the vertices in its end pairs. This is a weaker notion than a bare path (in hypertrees); in Figure 1, green edges plus the right red edge form a semi-bare path but not a bare path. For a semi-bare path P , denote by $T - P$ the hypergraph obtained from T by removing all vertices of P except the vertices in the edges that contains one of the end pairs of P .

Lemma A.2. *Let $\ell, m \geq 2$ be integers. Let T be a hypertree with at most ℓ leaf edges. Then there exist edge-disjoint semi-bare paths P_1, P_2, \dots, P_s of length $m + 1$ such that*

$$e(T - P_1 - P_2 - \dots - P_s) \leq 6m\ell + \frac{2e(T)}{m + 1}.$$

Proof. If all the edges of T are leaf edges, then $e(T) = \ell$, so the conclusion trivially holds. We may thus assume that there is a non-leaf edge $e^* \in E(T)$. Let \mathcal{G} be the auxiliary (2-)graph on the edge set $E(T)$ where e_1 and e_2 are adjacent if they intersect.

Let $T_{\mathcal{G}}$ be the BFS tree of \mathcal{G} rooted at e^* . Then a leaf of $T_{\mathcal{G}}$ corresponds to a leaf edge of T . Indeed, an edge e of T is a leaf edge if and only if it has only one vertex incident to other edges. Thus, if there exists a parent e' of e in the rooted tree $T_{\mathcal{G}}$, then the other edges that intersect with e also intersect with e' and the BFS puts them in the same depth as e . This makes e a leaf vertex in $T_{\mathcal{G}}$. Conversely, if e is not a leaf edge in T , then deleting e disconnects the hypertree, which also disconnects the BFS tree $T_{\mathcal{G}}$. In particular, e is not a leaf vertex in $T_{\mathcal{G}}$. Since the root e^* of $T_{\mathcal{G}}$ is not a leaf edge in T , an edge $e \in E(T)$ is a leaf edge if and only if it is a leaf (vertex) in $T_{\mathcal{G}}$. Therefore, $T_{\mathcal{G}}$ has at most ℓ leaves.

Moreover, a bare path of length m in $T_{\mathcal{G}}$ corresponds to a semi-bare path of length $m + 1$ in T . Indeed, the $m - 1$ internal vertices of a bare path of length m in $T_{\mathcal{G}}$ form edges of a bare path of T because of the BFS, which uniquely extends to a semi-bare path of length $m + 1$. Conversely, the hyperedges of a semi-bare path in T becomes the vertex set of a bare path. Therefore, applying Lemma A.1 to $T_{\mathcal{G}}$ yields the desired result. \square

We are now ready to prove Lemma 3.1.

Proof of Lemma 3.1. We construct a decreasing sequence $T = T'_0 \supseteq T'_1 \supseteq \dots \supseteq T'_\ell$, which will yield the desired increasing sequence $T_k = T'_{\ell-k}$. Let $m := \lceil 10^3/\mu \rceil$. Starting from T , we iteratively remove a matching leaf set of size at least $\mu n/(50mD)$ as many times as possible. There are at most $50mD/\mu$ such iterations, so starting from $T'_0 = T$ gives the resulting tree T'_k , $k \leq 50mD/\mu$.

We say that a non-leaf vertex v in a leaf edge is the *parent* of the edge or simply a parent if it is a parent of a leaf edge. By the choice of T'_k , there are at most $\mu n/(50mD)$ parent vertices. For every vertex v which is a parent of at least D leaf edges, remove all the leaf edges incident to v to obtain a smaller hypertree S . Then S contains at most $\mu n/50m$ leaf edges, since each leaf edge in S is either a leaf edge in T'_k which shares its parent with at most D leaf edges or it contains a parent in T'_k .

Then by Lemma A.2, S contains edge-disjoint semi-bare paths P_1, \dots, P_r of length $m + 1$ such that $e(S - P_1 - \dots - P_r) \leq 3\mu n/25 + 2e(S)/(m + 1) \leq \mu n/2$ since S has at most $\mu n/50m$ leaf edges. As there are at most $\mu n/(50mD)$ vertices in S whose degrees differ from theirs in T'_k , at least $\max\{0, r - \mu n/(50mD)\}$ of the semi-bare paths P_1, P_2, \dots, P_r are still semi-bare paths of T'_k . Let $Q_1, \dots, Q_{r'}$ be such semi-bare paths with $r' \geq \max\{0, r - \mu n/(50mD)\}$. As each of the Q_i 's contains a bare path of length three in the middle, we can remove the vertices in these bare paths to obtain T'_{k+1} . Indeed, as Q_i 's are semi-bare paths that are edge-disjoint, they are vertex-disjoint except the vertices in their end pairs; thus, the removed bare paths are vertex-disjoint.

Starting from T'_{k+1} , at each step, we delete one leaf edge from the remaining edges in each Q_i except the edges at the end of Q_i . This yields $T'_{k+2}, T'_{k+3}, \dots, T'_{k+m-3}$, where each T'_{k+t+1} is obtained by deleting vertex-disjoint leaf edges from T'_{k+t} .

The final step from T'_{k+m-3} to T'_{k+m-2} essentially repeats what we did to obtain S . For every vertex that is a parent of at least D leaf edges in T'_{k+m-3} , remove all the leaf edges incident to v to obtain T'_{k+m-2} and take $\ell = k + m - 2$. Then $\ell \leq m + 50mD/\mu \leq 10^5 D\mu^{-2}$.

It remains to prove that $e(T'_{k+m-2}) \leq \mu n$. First, recall that $e(S - P_1 - \dots - P_r) \leq \mu n/2$. Also, if a vertex is a common parent of D leaf edges in T'_k , then it is so in T'_{k+m-3} as well. Thus, if an edge in T'_{k+m-3} is not removed when obtaining T'_{k+m-2} , then it must have remained when obtaining S from T'_k (i.e., $E(T'_{k+m-2}) \subseteq E(S)$). Thus, T'_{k+m-2} is contained in both S and $T'_{k+m-3} = T'_k - Q_1 - Q_2 - \dots - Q_{r'}$, which implies that

$$e(T'_{k+m-2}) \leq e(S - Q_1 - \dots - Q_{r'}) \leq e(S - P_1 - \dots - P_r) + m \cdot \mu n / (50mD) \leq \mu n.$$

This completes the proof of the lemma. \square

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