

QUADRUPLE INTEGRAL EQUATIONS AND OPERATORS OF FRACTIONAL INTEGRATION

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Cooke [1] modified a technique used by Erdélyi and Sneddon [2] to solve triple integral equations of a certain type. In this paper, we extend this method to solve the quadruple integral equations

$$L_1(\alpha, \rho) \equiv \int_0^\infty \xi^{-2\alpha} \psi(\xi) J_\nu(\rho\xi) d\xi = F_1(\rho) \quad (0 < \rho < a), \quad (1a)$$

$$L_2(\beta, \rho) \equiv \int_0^\infty \xi^{-2\beta} \psi(\xi) J_\nu(\rho\xi) d\xi = G_2(\rho) \quad (a < \rho < b), \quad (1b)$$

$$L_3(\alpha, \rho) \equiv \int_0^\infty \xi^{-2\alpha} \psi(\xi) J_\nu(\rho\xi) d\xi = F_3(\rho) \quad (b < \rho < c), \quad (1c)$$

$$L_4(\beta, \rho) \equiv \int_0^\infty \xi^{-2\beta} \psi(\xi) J_\nu(\rho\xi) d\xi = G_4(\rho) \quad (\rho > c), \quad (1d)$$

where F_1, G_2, F_3 and G_4 are prescribed functions of ρ and $\psi(\xi)$ is to be determined. With no loss of generality we shall assume that $G_2(\rho) \equiv 0, G_4(\rho) \equiv 0$.

1. Operators. We recall here a few definitions and properties of the operators used in solving the integral equations (1). Cooke [1] has defined† the operators ${}_a^b I_{\eta, \alpha}$ and ${}_c^d K_{\eta, \alpha}$ by the formulae

$${}_a^b I_{\eta, \alpha} f(x) = \frac{2x^{-2\alpha-2\eta}}{\Gamma(\alpha)} \int_a^b (x^2 - u^2)^{\alpha-1} u^{2\eta+1} f(u) du \quad (\alpha > 0), \quad (2)$$

$${}_a^b I_{\eta, \alpha} f(x) = \frac{x^{-2\eta-2\alpha-1}}{\Gamma(1+\alpha)} \frac{d}{dx} \int_a^b (x^2 - u^2)^\alpha u^{2\eta+1} f(u) du \quad (-1 < \alpha < 0), \quad (3)$$

$${}_c^d K_{\eta, \alpha} f(x) = \frac{2x^{2\eta}}{\Gamma(\alpha)} \int_c^d (u^2 - x^2)^{\alpha-1} u^{-2\alpha-2\eta+1} f(u) du \quad (\alpha > 0), \quad (4)$$

$${}_c^d K_{\eta, \alpha} f(x) = -\frac{x^{2\eta-1}}{\Gamma(1+\alpha)} \frac{d}{dx} \int_c^d (u^2 - x^2)^\alpha u^{-2\alpha-2\eta+1} f(u) du \quad (-1 < \alpha < 0). \quad (5)$$

For $\alpha = 0$, these are just the identity operators. Note that with these definitions ${}_0^x I_{\eta, \alpha}$ and ${}_x^x K_{\eta, \alpha}$ are simply the Erdélyi-Kober operators [5]. In these cases we will drop the indices on the left and write them as $I_{\eta, \alpha}$ and $K_{\eta, \alpha}$. We also observe that (2), (3) make sense if $b < x$ and similarly (4), (5) are defined only if $c > x$.

† Cooke uses $({}_b^a)I_{\eta, \alpha}$, $({}_d^c)K_{\eta, \alpha}$, but our notation seems convenient.

The modified operator $S_{\eta,\alpha}$ of the Hankel transforms is defined by

$$S_{\eta,\alpha} f(x) = 2^\alpha x^{-\alpha} \int_0^\infty \xi^{1-\alpha} J_{2\eta+\alpha}(x\xi) f(\xi) d\xi. \tag{6}$$

Sneddon [4] has shown the following relations between the Erdélyi–Kober and Hankel operators.

$$I_{\eta+\alpha,\beta} S_{\eta,\alpha} = S_{\eta,\alpha+\beta}, \tag{7}$$

$$K_{\eta,\alpha} S_{\eta+\alpha,\beta} = S_{\eta,\alpha+\beta}, \tag{8}$$

$$S_{\eta+\alpha,\beta} S_{\eta,\alpha} = I_{\eta,\alpha+\beta}, \tag{9}$$

$$S_{\eta,\alpha} S_{\eta+\alpha,\beta} = K_{\eta,\alpha+\beta}, \tag{10}$$

provided that the conditions for the existence of the various operations are satisfied. The inverse operators are

$${}_a^b I_{\eta,\alpha}^{-1} = {}_a^b I_{\eta+\alpha,-\alpha}, \tag{11}$$

$${}_c^d K_{\eta,\alpha}^{-1} = {}_c^d K_{\eta+\alpha,-\alpha}, \tag{12}$$

$$S_{\eta,\alpha}^{-1} = S_{\eta+\alpha,-\alpha}. \tag{13}$$

We require two lemmas also given by Cooke [1], which define the product of pairs of operators.

LEMMA A. Let ${}_a^b I_{\eta,\alpha}$, ${}_x^d I_{\eta,\alpha}^{-1}$ be operators as defined in (2), (3) and (11). Then

$${}_x^d I_{\eta,\alpha}^{-1} {}_a^b I_{\eta,\alpha} f(x) = \frac{2 \sin \pi\alpha}{\pi} x^{-2\eta} (x^2 - d^2)^{-\alpha} \int_a^b \frac{(d^2 - t^2)^\alpha t^{2\eta+1} f(t)}{x^2 - t^2} dt \tag{14}$$

provided that $x > d \geq b > a$.

LEMMA B. Let ${}_a^b K_{\eta,\alpha}$, ${}_x^d K_{\eta,\alpha}^{-1}$ be operators as defined in (4), (5), and (12). Then

$${}_x^d K_{\eta,\alpha}^{-1} {}_a^b K_{\eta,\alpha} f(x) = \frac{2 \sin \pi\alpha}{\pi} x^{2\eta+2\alpha} (d^2 - x^2)^{-\alpha} \int_a^b \frac{(t^2 - d^2)^\alpha t^{-2\alpha-2\eta+1} f(t)}{t^2 - x^2} dt, \tag{15}$$

provided that $x < d \leq a < b$.

2. Solution of the equations (1). We transform the equations (1) into a form to which the operational theory is applicable by substituting

$$\psi(\xi) = \xi A(\xi), \quad f(\rho) = (2/\rho)^2 F(\rho); \tag{16}$$

by means of this we get

$$L_1(\alpha, \rho) \equiv 2^{2\alpha} \rho^{-2\alpha} \int_0^\infty \xi^{1-2\alpha} A(\xi) J_\nu(\rho\xi) d\xi = f_1(\rho) \quad (0 < \rho < a), \tag{17a}$$

$$L_2(\beta, \rho) \equiv 2^{2\beta} \rho^{-2\beta} \int_0^\infty \xi^{1-2\beta} A(\xi) J_\nu(\rho\xi) d\xi = 0 \quad (a < \rho < b), \tag{17b}$$

$$L_3(\alpha, \rho) \equiv 2^{2\alpha} \rho^{-2\alpha} \int_0^\infty \xi^{1-2\alpha} A(\xi) J_\nu(\rho\xi) d\xi = f_3(\rho) \quad (b < \rho < c), \tag{17c}$$

$$L_4(\beta, \rho) \equiv 2^{2\beta} \rho^{-2\beta} \int_0^\infty \xi^{1-2\beta} A(\xi) J_\nu(\rho\xi) d\xi = 0 \quad (\rho > c). \tag{17d}$$

Let I_1 denote the interval $(0, a)$, I_2 the interval (a, b) , I_3 the interval (b, c) and I_4 the interval (c, ∞) . For a function f in $L_2(0, \infty)$ we shall write $f_1 + f_2 + f_3 + f_4$, where

$$f_i = f \text{ on } I_i \text{ and } = 0 \text{ on } I_j \quad (i, j = 1, 2, 3, 4; i \neq j)$$

and similarly for g . Using the S -operator defined in (6), we see that the integral equations (17) reduce to the form

$$S_{\frac{1}{2}\nu-\alpha, 2\alpha} A(\rho) = f(\rho), \tag{18}$$

$$S_{\frac{1}{2}\nu-\beta, 2\beta} A(\rho) = g(\rho). \tag{19}$$

Here f_1 and f_3 are prescribed, $g_2 = 0 = g_4$ but g_1, f_2, g_3 and f_4 are to be determined. Let us take as trial solution

$$A(\rho) = S_{\frac{1}{2}\nu+\beta, -\alpha-\beta} l(\rho). \tag{20}$$

Substituting this value of $A(\rho)$ in (18), (19) and using formulas (9), (10) we have

$$f = I_{\frac{1}{2}\nu+\beta, \alpha-\beta} l, \tag{21}$$

$$g = K_{\frac{1}{2}\nu-\beta, \beta-\alpha} l. \tag{22}$$

Also, we have

$$l = I_{\frac{1}{2}\nu+\beta, \alpha-\beta}^{-1} f \tag{23}$$

$$= K_{\frac{1}{2}\nu-\beta, \beta-\alpha}^{-1} g. \tag{24}$$

We proceed to determine l . The subscripts on all the operators will be dropped for brevity sake. All I 's will be supposed to have subscripts $\frac{1}{2}\nu + \beta, \alpha - \beta$ understood and all K 's to have $\frac{1}{2}\nu - \beta, \beta - \alpha$.

Evaluating (23) on I_1 , we get

$$l_1 = {}_0^{\rho} I^{-1} f_1. \tag{25}$$

Taking (24) on I_4 , we have

$$l_4 = {}_\rho^\infty K^{-1} g_4 = 0. \tag{26}$$

Evaluate (22) on I_2 ; then

$${}_b^b K l_2 + {}_b^c K l_3 + {}_c^c K l_4 = 0,$$

which gives

$$l_2 = -{}_b^b K^{-1} {}_b^c K l_3. \tag{27}$$

Applying Lemma B, we have

$$l_2(\rho) = -\frac{2 \sin \pi(\beta - \alpha)}{\pi} \rho^{v-2\alpha} (b^2 - \rho^2)^{\alpha-\beta} \int_b^c \frac{(t^2 - b^2)^{\beta-\alpha} t^{-v+2\alpha+1} l_3(t)}{t^2 - \rho^2} dt. \tag{28}$$

Finally, evaluating (21) on I_3 , we have

$$l_3 = {}_b^b I^{-1} f_3 - {}_b^b I^{-1} {}_a^a I l_1 - {}_b^b I^{-1} {}_a^b I l_2. \tag{29}$$

Since f_3 and l_1 are known functions, the function

$$d(\rho) = {}_b^b I^{-1} f_3(\rho) - {}_b^b I^{-1} {}_a^a I l_1 \tag{30}$$

is known. Applying Lemma A to the last term on the right-hand side of (29) and substituting (28), (30) in that equation, we obtain

$$\begin{aligned} l_3(\rho) &= d(\rho) + \frac{2 \sin \pi(\alpha - \beta)}{\pi} \rho^{-v-2\beta} (\rho^2 - b^2)^{\beta-\alpha} \\ &\quad \times \int_a^b (b^2 - y^2)^{\alpha-\beta} y^{v+2\beta+1} \left\{ \frac{2 \sin \pi(\beta - \alpha)}{\pi} y^{v-2\alpha} (b^2 - y^2)^{\alpha-\beta} \right. \\ &\quad \left. \times \int_b^c \frac{(t^2 - b^2)^{\beta-\alpha} t^{-v+2\alpha+1} l_3(t)}{t^2 - y^2} dt \right\} \frac{1}{\rho^2 - y^2} dy. \end{aligned} \tag{31}$$

Inverting the order of integration, we get

$$\begin{aligned} l_3(\rho) &= d(\rho) - \frac{4 \sin^2 \pi(\alpha - \beta)}{\pi^2} \int_b^c \left\{ \rho^{-v-2\beta} (\rho^2 - b^2)^{\beta-\alpha} \right. \\ &\quad \times (t^2 - b^2)^{\beta-\alpha} t^{-v+2\alpha+1} \int_a^b (b^2 - y^2)^{2(\alpha-\beta)} y^{2v-2\alpha+2\beta+1} \\ &\quad \left. \times \frac{1}{(t^2 - y^2)(\rho^2 - y^2)} dy \right\} l_3(t) dt. \end{aligned} \tag{32}$$

Putting $4\pi^{-2} \sin^2 \pi(\alpha - \beta) = -\lambda$, and the expression within the curly brackets equal to $K(\rho, t)$, we obtain

$$l_3(\rho) = d(\rho) + \lambda \int_b^c K(\rho, t) l_3(t) dt, \quad (33)$$

which is a Fredholm's integral equation of the second kind and can be solved by known methods. The equations (25), (26), (28) and (33) completely determine l and our problem is formally solved.

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