

# ON THE GENERAL THEORY OF DIFFERENTIABLE MANIFOLDS WITH ALMOST TANGENT STRUCTURE

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Some of the most important G-Structures of the first kind [1] are those defined by linear operators satisfying algebraic relations. If the linear operator  $J$  acting on the complexified space of a differentiable manifold  $V$  satisfies a relation of the form

$$J^2 = -I,$$

where  $I$  is the identity operator, the manifold has an almost complex structure ([2] [3]). The structures defined by

$$J^2 = I$$

are the almost product structures ([3] [4]). In the present paper we investigate the structures defined by nilpotent operators of degree 2, that is by relations of the form

$$J^2 = 0.$$

Some of the results of this investigation are stated in [5]. Recently, an attempt has been made to study the more general case

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$$J^r = 0$$

where  $r \geq 2$ . So far, only the integrability of such structures has been studied [6].

1. General definitions. We consider a differentiable manifold  $V_{2n}$  of class  $C^\infty$ . Let  $T_x$  be the tangent space at any point  $x \in V_{2n}$ , and  $T_x^C$  the complexified space of  $T_x$ . We assume that a field of class  $C^\infty$  of linear operators  $J_x$  is defined on  $V_{2n}$ , such that, at each point  $x \in V_{2n}$ ,  $J_x$  maps  $T_x^C$  into itself; moreover  $J_x$  is of rank  $n$  everywhere in  $V_{2n}$ , and it satisfies the relation

$$J_x^2 = 0$$

for any  $x \in V_{2n}$ , where  $0$  is the null operator. In this case we say that  $J$  defines an almost tangent structure on the manifold  $V_{2n}$ .

PROPOSITION 1. The image  $J(T_x^C)$  and the  $\text{Ker} J$  coincide with the space of the eigenvectors of  $J$ .

Proof. Let  $a \in T_x^C$ .  $Ja$  is an eigenvector of  $J$ , since

$$J(Ja) = J^2 a = 0.$$

Hence, the image  $J(T_x^C)$  is composed of the eigenvectors of  $J$ . On the other hand, every vector of  $J(T_x^C)$  is mapped unto the zero vector; therefore

$$J(T_x^C) = \text{Ker} J.$$

If  $S_x$  is the complementary space of  $\text{Ker} J$  with respect

to  $T_x^c$ , we have

$$T_x^c = \text{Ker}J \oplus S_x,$$

and  $J$  induces an isomorphism between  $S_x$  and  $\text{Ker}J$ .

Let  $(e_1, e_2, \dots, e_n; e_{n+1}, \dots, e_{2n})$  be a basis of  $T_x^c$ , where  $(e_1, \dots, e_n)$  is a basis of  $\text{Ker}J$  and  $(e_{n+1}, \dots, e_{2n})$  is a basis of  $S_x$ . We shall write briefly  $(e_\alpha, e_{\alpha^*})$  where  $\alpha = 1, 2, \dots, n$ ,  $\alpha^* = \alpha + n$  (Greek indices take the values  $1 \dots n$  and Latin indices the values  $1 \dots 2n$ ). We can always arrange that

$$e_\alpha = J e_{\alpha^*}.$$

We call the basis  $(J e_{\alpha^*}, e_{\alpha^*})$  a basis adapted to the almost tangent structure or briefly an adapted basis. Let  $(e_{\alpha'}, e_{\alpha'^*})$  be another adapted basis; we have

$$e_{\alpha'} = A_{\alpha'}^\beta e_\beta$$

$$e_{\alpha'^*} = B_{\alpha'^*}^\beta e_\beta + A_{\alpha'^*}^{\beta^*} e_{\beta^*}.$$

From the latter we have

$$J e_{\alpha'^*} = A_{\alpha'^*}^{\beta^*} J e_{\beta^*},$$

and hence

$$A_{\alpha'^*}^{\beta^*} = A_{\alpha'}^\beta.$$

Therefore

$$(1.1) \quad e_{\alpha'} = A_{\alpha'}^\beta e_\beta, \quad e_{\alpha'^*} = B_{\alpha'^*}^\beta e_\beta + A_{\alpha'^*}^{\beta^*} e_{\beta^*},$$

with  $A_{\alpha'^*}^{\beta*} = A_{\alpha'}^{\beta}$ . The transformation matrix for the adapted bases is of the form

$$\alpha = \begin{pmatrix} A & 0 \\ B & A \end{pmatrix},$$

where  $A \in GL(n, C)$ ,  $B$  is an  $(n, n)$  matrix and  $0$  the null  $(n, n)$  matrix.

LEMMA 1. The set of all the matrices  $\alpha$  is a group under multiplication, which will be denoted by  $G_{nn}^{(n)}$ .

Proof. For any two matrices  $\alpha, \alpha_1 \in G_{nn}^{(n)}$ , we have, as we use multiplication by blocks,

$$\alpha \alpha_1 = \begin{pmatrix} AA_1 & 0 \\ BA_1 + AB_1 & AA_1 \end{pmatrix} \in G_{nn}^{(n)}$$

and also

$$\alpha^{-1} = \begin{pmatrix} A^{-1} & 0 \\ -A^{-1}BA^{-1} & A^{-1} \end{pmatrix} \in G_{nn}^{(n)}.$$

Hence  $G_{nn}^{(n)}$  is a subgroup of the group  $GL(2n, C)$ . It is moreover a Lie group.

Consider the operator  $J_x$  or  $J$ ; to this operator there corresponds a tensor  $F_j^i$  defined by

$$(1.2) \quad (Jv)^i = F_j^i v^j,$$

and if we use the relation  $J^2 = 0$ , we obtain

$$(1.3) \quad F_i^j F_j^k = 0.$$

If the vector space  $T_x^C$  is referred to an adapted basis, the components of the tensor  $F_i^j$  are given by

$$(1.4) \quad F_\alpha^\beta = F_\alpha^{\beta*} = F_{\alpha*}^{\beta*} = 0, \quad F_{\alpha*}^\beta = \delta_\alpha^\beta = \delta_{\alpha*}^{\beta*}.$$

Hence  $F_i^j$  is represented by a matrix of the form

$$(1.5) \quad \begin{pmatrix} 0 & 0 \\ E_n & 0 \end{pmatrix},$$

where  $E_n$  denotes the unit matrix of order  $n$ . Since the matrix (1.5) commutes with all the elements of  $G_{nn}^n$ ,  $J$  will have the form (1.5) with respect to any adapted basis.

Note. The group  $G_{nn}^n$  is composed of all the elements of  $GL(2n, C)$  which commute with the matrix (1.5).

For any vector  $v \in T_x^C$  referred to an adapted basis we have

$$v = v^\alpha e_\alpha + v^{\alpha*} e_{\alpha*},$$

and hence

$$Jv = v^\alpha J e_\alpha + v^{\alpha*} J e_{\alpha*} = v^{\alpha*} e_\alpha$$

or

$$(Jv)^\alpha = v^{\alpha*}, \quad (Jv)^{\alpha*} = 0.$$

2. The dual space. Let us consider the dual space  $(T_x^C)^*$  of the complexified space  $T_x^C$  at a point  $x$  of the differentiable manifold  $V_{2n}$ . If  $(e_i)$ ,  $(e_{j'})$  are two adapted bases at  $x$ , to these there correspond two dual bases  $(\theta^i)$ ,  $(\theta^{j'})$ . From the relation

$$e_{j'} = A_{j'}^i e_i$$

for the adapted bases, we have the relation

$$\theta^\alpha = A_{\beta'}^\alpha \theta^{\beta'}$$

for the dual bases. Hence

$$\theta^\alpha = A_{\beta'}^\alpha \theta^{\beta'} + A_{\beta'^*}^\alpha \theta^{\beta'^*}$$

and

$$\theta^{\alpha^*} = A_{\beta'^*}^{\alpha^*} \theta^{\beta'^*}$$

We thus see that if the transformation matrix for the adapted bases is given by (1.1), the transformation matrix for the dual bases is of the form

$$(t_\alpha)^{-1} = \begin{pmatrix} tA & tB^{-1} \\ 0 & tA \end{pmatrix} = \begin{pmatrix} A_1 & B_1 \\ 0 & A_1 \end{pmatrix}.$$

On the other hand, if  $(\text{Ker } J)^*$  is the dual space of  $\text{Ker } J$ , to the basis  $(e_\alpha)$  of  $\text{Ker } J$  there corresponds the dual basis

$(\theta^{\alpha^*})$  of  $(\text{Ker } J)^*$ .

**PROPOSITION 2.** An almost tangent structure is defined in the dual space  $(T_x^C)^*$  by the space  $(\text{Ker } J)^*$ , that is, there

exists a linear operator  $J_1$  of rank  $n$  satisfying  $J_1^2 = 0$ , such that

$$J_1[(T_x^C)^*] = (\text{Ker}J)^*.$$

Proof. Let us define in  $(T_x^C)^*$  an operator  $J_1$ , which with respect to an adapted basis is represented by the matrix

$$J_1 = \begin{pmatrix} 0 & E_n \\ 0 & 0 \end{pmatrix}.$$

This operator has the same representation with respect to any other adapted dual basis. Indeed we have

$$\begin{aligned} \begin{pmatrix} B & B_1 \\ 0 & B \end{pmatrix} \begin{pmatrix} 0 & E_n \\ 0 & 0 \end{pmatrix} \begin{pmatrix} B & B_1 \\ 0 & B \end{pmatrix}^{-1} &= \begin{pmatrix} B & B_1 \\ 0 & B \end{pmatrix} \begin{pmatrix} 0 & E_n \\ 0 & 0 \end{pmatrix} \begin{pmatrix} B^{-1} & -B^{-1}B_1B^{-1} \\ 0 & B^{-1} \end{pmatrix} \\ &= \begin{pmatrix} B & B_1 \\ 0 & B \end{pmatrix} \begin{pmatrix} 0 & B^{-1} \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & E_n \\ 0 & 0 \end{pmatrix}. \end{aligned}$$

$J_1$  has therefore an intrinsic meaning. Since  $\det(E_n) = 1$  and all the other submatrices of  $J_1$  of order greater than  $n$  are singular,  $\text{rank } J_1 = n$ . In the other hand  $J_1^2 = 0$ . It is easy to see, by using the components of the vectors  $\theta^\alpha$  and  $\theta^{\alpha^*}$ , that

$$J_1 \theta^\alpha = \theta^{\alpha^*}, \quad J_1 \theta^{\alpha^*} = 0.$$

For any element  $v \in (T_x^C)^*$  with components  $v_i$  with respect to the basis  $(\theta^i)$  we have

$$v = v_\alpha \theta^\alpha + v_{\alpha^*} \theta^{\alpha^*},$$

and hence

$$J_1 \tilde{v} = v_\alpha J_1 \theta^\alpha + v_{\alpha^*} J_1 \theta^{\alpha^*} = v_\alpha \theta^{\alpha^*} \in (\text{Ker} J)^*.$$

We thus see that the elements of  $(\text{Ker} J)^*$  are the images under  $J_1$  of the elements of  $(T_x^c)^*$ .

3. Connections in  $V_{2n}$ . Let  $E_T(V_{2n})$  be the set of all the adapted bases at the different points of  $V_{2n}$ , and  $p$  the canonical mapping

$$p : E_T(V_{2n}) \rightarrow V_{2n},$$

which associates with an adapted basis at  $x$  the point  $x$  itself.  $E_T(V_{2n})$  has, with respect to  $p$ , a natural structure of a principal fibre bundle of base  $V_{2n}$  and structural group the sub-group  $G_{nn}^n$  of  $GL(2n, C)$ .

Definition. We will call an almost tangent connection (briefly A. T. connection) on  $V_{2n}$ , every infinitesimal connection defined on the fibre bundle of the adapted bases.

For the definition of an infinitesimal connection one may consult [7].

Given a covering of  $V_{2n}$  by neighbourhoods endowed with local cross sections of  $E_T(V_{2n})$ , an A. T. connection may be defined in each neighbourhood  $U$  by a form  $w_U$  with values in the Lie Algebra of the group  $G_{nn}^n$ ; such a form may be represented at  $x$  by means of a matrix of order  $2n$  whose elements are complex-valued linear forms at  $x$ ; it will be denoted by

$$\pi_U = (\pi_i^j).$$



Hence an A. T. connection is represented by the matrix

$$\begin{pmatrix} \pi_{\beta}^{\alpha} & 0 \\ \pi_{\beta^*}^{\alpha} & \pi_{\beta^*}^{\alpha^*} = \pi_{\beta}^{\alpha} \end{pmatrix}.$$

PROPOSITION 3. With respect to an A. T. connection we have

$$\nabla J = 0.$$

Proof. We refer the tensor  $J = (F_i^j)$  to an adapted basis.

We have

$$\begin{aligned} \nabla F_{\beta}^{\alpha} &= dF_{\beta}^{\alpha} + \pi_{\rho}^{\alpha} F_{\beta}^{\rho} + \pi_{\rho^*}^{\alpha} F_{\beta}^{\rho^*} - \pi_{\beta}^{\rho} F_{\rho}^{\alpha} - \pi_{\beta}^{\rho^*} F_{\rho^*}^{\alpha} = -\pi_{\beta}^{\rho^*} \delta_{\rho^*}^{\alpha} \\ &= -\pi_{\beta}^{\alpha^*} = 0, \end{aligned}$$

$$\begin{aligned} \nabla F_{\beta^*}^{\alpha^*} &= dF_{\beta^*}^{\alpha^*} + \pi_{\rho}^{\alpha^*} F_{\beta^*}^{\rho} + \pi_{\rho^*}^{\alpha^*} F_{\beta^*}^{\rho^*} - \pi_{\beta^*}^{\rho} F_{\rho}^{\alpha^*} - \pi_{\beta^*}^{\rho^*} F_{\rho^*}^{\alpha^*} \\ &= \pi_{\rho}^{\alpha^*} \delta_{\beta}^{\rho} = \pi_{\beta}^{\alpha^*} = 0, \end{aligned}$$

(3.1)

$$\begin{aligned} \nabla F_{\beta^*}^{\alpha} &= dF_{\beta^*}^{\alpha} + \pi_{\rho}^{\alpha} F_{\beta^*}^{\rho} + \pi_{\rho^*}^{\alpha} F_{\beta^*}^{\rho^*} - \pi_{\beta^*}^{\rho} F_{\rho}^{\alpha} - \pi_{\beta^*}^{\rho^*} F_{\rho^*}^{\alpha} \\ &= \pi_{\rho}^{\alpha} \delta_{\beta}^{\rho} - \pi_{\beta^*}^{\rho^*} \delta_{\rho^*}^{\alpha} = \pi_{\beta}^{\alpha} - \pi_{\beta^*}^{\alpha^*} = 0, \end{aligned}$$

$$\nabla F_{\beta}^{\alpha^*} = dF_{\beta}^{\alpha^*} + \pi_{\rho}^{\alpha^*} F_{\beta}^{\rho} + \pi_{\rho^*}^{\alpha^*} F_{\beta}^{\rho^*} - \pi_{\beta}^{\rho} F_{\rho}^{\alpha^*} - \pi_{\beta}^{\rho^*} F_{\rho^*}^{\alpha^*} = 0.$$

$E_T(V_{2n})$  may be considered as a sub-bundle of the fibre bundle  $E_c(V_{2n})$  of the complex bases. An A. T. connection defines canonically a complex linear connection with which it

may be identified. Conversely, let us consider a complex linear connection and a covering of  $V_{2n}$  by neighbourhoods equipped with local cross sections of  $E_T(V_{2n})$ . This connection may be defined on each neighbourhood by a local form, with values in the Lie Algebra of  $GL(2n, C)$ , represented by a matrix  $(w_i^j)$  whose elements are complex-valued local Pfaffian forms. In order that the given connection may be identified with an A. T. connection it is necessary and sufficient that  $(w_i^j)$  belongs in the Lie Algebra of the structural group  $G_{nn}^n$  of  $E_T(V_{2n})$ . That is,

$$w_\alpha^\beta = w_{\alpha^*}^{\beta^*}, \quad w_\alpha^{\beta^*} = 0.$$

Comparing with (3.1), we obtain the following

**PROPOSITION 4.** In order that a complex linear connection may be identified with an A. T. connection it is necessary and sufficient that the tensor  $J = (F_i^j)$  have a zero absolute differential with respect to this connection.

We shall now consider any complex linear connection referred to an adapted basis. Let

$$w = (w_i^j)$$

be the matrix representing this connection. Under transformations of bases the forms  $w_i^j$  transform according to

$$w_{m'}^{\ell'} = A_a^{\ell'} w_b^a A_{m'}^b + A_s^{\ell'} dA_{m'}^s$$

or

$$(3.2) \quad A_{\ell'}^j w_{m'}^{\ell'} = A_{m'}^b w_b^j + dA_{m'}^j.$$

If we apply the above relation for  $j = \zeta^*$  and  $m = \mu$  we obtain

$$(3.3) \quad w_{\mu'}^{\lambda' *} = A_{\lambda' *}^{\lambda' *} A_{\mu' \zeta}^{\zeta} w_{\zeta}^{\lambda' *}$$

On the other hand, substituting in (3.2), first  $j = \zeta$ ,  $m = \mu$ , then  $j = \zeta^*$ ,  $m = \mu^*$ , and subtracting the second equation from the first we obtain

$$(3.4) \quad A_{\lambda'}^{\zeta} w_{\mu'}^{\lambda'} - A_{\lambda' *}^{\zeta} w_{\mu'}^{\lambda' *} - A_{\lambda' *}^{\zeta^*} w_{\mu' *}^{\lambda' *} = w_{\zeta}^{\lambda} A_{\mu'} - w_{\zeta}^{\lambda^*} A_{\mu' *}^{\zeta} - w_{\zeta^*}^{\lambda^*} A_{\mu' *}^{\zeta^*}$$

If we consider the transformation relations given in the Appendix, we see that the quantities

$$(3.5) \quad t_{\mu}^{\lambda} = 0, \quad t_{\mu}^{\lambda^*} = t_{\mu^*}^{\lambda} = w_{\mu}^{\lambda^*}, \quad t_{\mu^*}^{\lambda^*} = w_{\mu^*}^{\lambda^*} - w_{\mu}^{\lambda}$$

are the components of a tensor form of type (1, 1). We call it the tensor form associated to the linear connection. From the relation (3.5) we have

PROPOSITION 5. In order that a complex linear connection on  $V_{2n}$  be an A. T. connection it is necessary and sufficient that the associated tensor form be equal to zero.

#### 4. The operators C and M in an A. T. manifold.

As in the theory of almost complex manifolds and the almost product manifolds, we may introduce, in the theory of manifolds with A. T. structure, operators C and M.

Let  $V_{2n}$  be such manifold and let us denote by  $\Lambda_r^c(V_{2n})$  the vector space of all the complex-valued exterior r-forms defined on  $V_{2n}$ . We associate with the A. T. structure two operators C and M defined on  $(V_{2n})$  in the following way:

If  $(v_1, v_2, \dots, v_r)$  are r vectors of  $T_x^c$  and f an r-form, we denote by  $f(v_1, \dots, v_r)$  the value of f for

$v_1 \wedge v_2 \wedge \dots \wedge v_r$ .  $C$  is then defined by the relation

$$(4.1) \quad Cf(v_1, \dots, v_r) = f(Jv_1, Jv_2, \dots, Jv_r).$$

If the components of  $f$  are  $f_{j_1 j_2 \dots j_r}$  the components of  $Cf$  will be

$$(4.2) \quad (Cf)_{i_1 i_2 \dots i_r} = F_{i_1}^{j_1} F_{i_2}^{j_2} \dots F_{i_r}^{j_r} f_{j_1 j_2 \dots j_r}.$$

It is obvious from (1.1) that  $C$  satisfies the relation

$$(4.3) \quad C^2 = 0.$$

Definition. A pure form  $f$  of type  $r$ , can be written

$$f = \frac{1}{r!} f_{\alpha_1 \alpha_2 \dots \alpha_r} \theta^{\alpha_1} \wedge \theta^{\alpha_2} \wedge \dots \wedge \theta^{\alpha_r}.$$

It is obvious that this definition is independent of the adapted basis to which this form is referred.

PROPOSITION 6.  $C$  maps every  $r$ -form of  $\wedge_r^c(V_{2n})$  into a pure  $r$ -form.

Proof. The relation (4.2) written in an adapted basis provides

$$(Cf)_{\alpha_1 \alpha_2 \dots \alpha_r} = F_{\alpha_1}^{j_1} F_{\alpha_2}^{j_2} \dots F_{\alpha_r}^{j_r} f_{j_1 \dots j_r} = 0,$$

$$(Cf)_{\alpha_1 \dots \alpha_k^* \dots \alpha_r} = F_{\alpha_1}^{j_1} \dots F_{\alpha_k^*}^{j_k} \dots F_{\alpha_r}^{j_r} f_{j_1 \dots j_r} = 0,$$

$$(Cf)_{\alpha_1^* \alpha_2^* \dots \alpha_r^*} = F_{\alpha_1^*}^{j_1} F_{\alpha_2^*}^{j_2} \dots F_{\alpha_r^*}^{j_r} f_{j_1 \dots j_r} =$$

$$= \delta_{\alpha_1}^{\beta_1} \delta_{\alpha_2}^{\beta_2} \dots \delta_{\alpha_r}^{\beta_r} f_{\beta_1 \dots \beta_r} = f_{\alpha_1 \dots \alpha_r},$$

and hence

$$Cf = \frac{1}{r!} f_{\alpha_1 \dots \alpha_r} \theta^{\alpha_1} \wedge \theta^{\alpha_2} \wedge \dots \wedge \theta^{\alpha_r}.$$

The operator  $M$  will be defined in the following way:

For any  $v_1, v_2, \dots, v_r \in T_x^C$ ,  $M$  is defined by the relation

$$(4.4) \quad Mf(v_1, v_2, \dots, v_r) = \sum_{k=1}^r f(v_1, v_2, \dots, v_{k-1}, Jv_k, v_{k+1}, \dots, v_r),$$

where the right-hand side obviously defines an  $r$ -form.

PROPOSITION 7.

$$(4.5) \quad C = \frac{1}{r!} M^r \quad \text{and} \quad M^{r+1} = 0.$$

Proof. By repeated application of the operator  $M$  on the form  $f$  we obtain

$$(4.6) \quad M^r f(v_1, v_2, \dots, v_r) = r! f(Jv_1, Jv_2, \dots, Jv_r);$$

using (4.1), we find

$$M^r f(v_1, v_2, \dots, v_r) = r! Cf(v_1, v_2, \dots, v_r).$$

The above relation holds for any  $r$ -form  $f$ , hence

$$C = \frac{1}{r} M^r.$$

The same relation (4.6) provides

$$M^{r+1} f(v_1, v_2, \dots, v_r) = 0,$$

hence

$$M^{r+1} = 0.$$

From the relations (4.5) we obtain

$$(4.7) \quad MC = CM = 0.$$

If  $f$  admits the components  $f_{i_1 i_2 \dots i_r}$ , the form  $Mf$  has the components

$$(4.8) \quad (Mf)_{i_1 i_2 \dots i_r} = \sum_k f_{i_1 i_2 \dots i_{k-1} i_{k+1} \dots i_r} F_{ik}^s \\ = \frac{1}{(r-1)!} \epsilon_{i_1 i_2 \dots i_r}^{j_1 j_2 \dots j_r} F_{j_1}^s f_{s j_2 \dots j_r},$$

where  $\epsilon_{i_1 \dots i_r}^{j_1 \dots j_r}$  is the Kronecker tensor.

PROPOSITION 8. For any 1-form  $f$  we have

$$(4.9) \quad Cdf - MdCf = f \circ T$$

where  $T$  is the tensor of the structure of the manifold  $V_{2n}$ .

Proof. We consider a 1-form  $f$  defined in a neighbourhood  $U$  of  $V_{2n}$  by

$$f = f_i \theta^i.$$

Its exterior differential is

$$df = df_i \wedge \theta^i + f_i d\theta^i,$$

or

$$df = \frac{1}{2}(\partial_{ij} f - \partial_{ji} f)(\theta^i \wedge \theta^j) + \frac{1}{2}f c_{ijk}^i \theta^j \wedge \theta^k,$$

where  $c_{jk}^i$  are the coefficients of  $d\theta^i$  in the decomposition

$$d\theta^i = \frac{1}{2}c_{jk}^i \theta^j \wedge \theta^k, \quad (c_{jk}^i + c_{kj}^i = 0).$$

Operating by  $C$ , we find

$$Cdf = \frac{1}{2}(\partial_{\alpha\beta} f - \partial_{\beta\alpha} f)(\theta^{\alpha*} \wedge \theta^{\beta*}) + \frac{1}{2}f c_{\alpha\beta}^i \theta^{\alpha*} \wedge \theta^{\beta*}.$$

Similarly,

$$Cf = f \theta^{\alpha*}$$

and

$$\begin{aligned} dCf &= df \wedge \theta^{\alpha*} + f d\theta^{\alpha*} \\ &= \frac{1}{2}(\partial_{\lambda\alpha} f - \partial_{\alpha\lambda} f) \theta^\lambda \wedge \theta^{\alpha*} + \frac{1}{2}(\partial_{\lambda*\alpha} f - \partial_{\alpha*\lambda} f) \theta^{\lambda*} \wedge \theta^{\alpha*} \\ &\quad + \frac{1}{2} f c_{ij}^{\alpha*} \theta^i \wedge \theta^j. \end{aligned}$$

$$\begin{aligned} \text{Let us put } dCf = \alpha. \quad \text{Then } (M\alpha)_{ij} &= \varepsilon_{ij}^{kl} F_{k\ s l}^s \alpha = \varepsilon_{ij}^{u*\ l} F_{u*\ \sigma l}^\sigma \\ &= \varepsilon_{ij}^{\sigma*\ l} \alpha_{\sigma l}, \end{aligned}$$

$$(M\alpha)_{\iota\ \zeta} = 0$$

$$(M\alpha)_{\iota*\ \zeta} = \varepsilon_{\iota*\ \zeta}^{\sigma*\ l} \alpha_{\sigma l} = \varepsilon_{\iota*\ \zeta}^{\sigma*\ \lambda} \alpha_{\sigma \lambda} = \alpha_{\iota\ \zeta} = 0,$$

$$\begin{aligned} (M\alpha)_{\iota*\ \zeta*} &= \varepsilon_{\iota*\ \zeta*}^{\sigma*\ l} \alpha_{\sigma l} = \varepsilon_{\iota*\ \zeta*}^{\sigma*\ \lambda*} \alpha_{\sigma \lambda*} = \alpha_{\iota\ \zeta*} - \alpha_{\zeta\ \iota*} \\ &= \frac{1}{2}(\partial_{\iota\ \zeta} f - \partial_{\zeta\ \iota} f). \end{aligned}$$

In a similar manner, if we put  $f_{\alpha} C_{ij}^{\alpha*} = \beta_{ij}$  and

$$\beta = \frac{1}{2}(f_{\alpha} C_{ij}^{\alpha*} \theta^i \wedge \theta^j) \text{ we obtain}$$

$$(M\beta)_{\iota \zeta} = 0,$$

$$(M\beta)_{\iota * \zeta} = \beta_{\iota \zeta} = f_{\alpha} c_{\iota \zeta}^{\alpha*},$$

$$(M\beta)_{\iota * \zeta *} = \beta_{\iota \zeta *} - \beta_{\zeta \iota *} = \beta_{\iota \zeta *} + \beta_{\iota * \zeta};$$

$$\begin{aligned} \text{hence } M\beta &= (f_{\alpha} c_{\iota \zeta}^{\alpha*}) \theta^{\iota *} \wedge \theta^{\zeta} + \beta_{\iota \zeta *} \theta^{\iota *} \wedge \theta^{\zeta *} \\ &= (f_{\alpha} c_{\iota \zeta}^{\alpha*}) \theta^{\iota *} \wedge \theta^{\zeta} + f_{\alpha} c_{\iota * \zeta}^{\alpha*} \theta^{\iota *} \wedge \theta^{\zeta *}, \end{aligned}$$

and

$$MdCf = \frac{1}{2}(\partial_{\iota} f_{\zeta} - \partial_{\zeta} f_{\iota}) \theta^{\iota *} \wedge \theta^{\zeta *} + f_{\alpha} [c_{\iota \zeta}^{\alpha*} \theta^{\iota *} \wedge \theta^{\zeta} + c_{\iota * \zeta}^{\alpha*} \theta^{\iota *} \wedge \theta^{\zeta *}].$$

Therefore

$$\begin{aligned} \text{Cdf} - MdCf &= f_{\alpha} \{c_{\iota \zeta}^{\alpha*} \theta^{\zeta} \wedge \theta^{\iota *} + \frac{1}{2}(c_{\iota \zeta}^{\alpha} - [c_{\iota * \zeta}^{\alpha*} + c_{\iota \zeta *}^{\alpha*}]) \theta^{\iota *} \wedge \theta^{\zeta *}\} \\ &\quad + \frac{1}{2} f_{\alpha} c_{\iota \zeta}^{\alpha*} \theta^{\iota *} \wedge \theta^{\zeta *}. \end{aligned}$$

In the other hand, if we apply the relations of p. 5328 of [6] for  $p=q=\frac{1}{2}n$ ,  $r=1$ , we obtain for the components of the tensor of structure

$$t_{\beta * \lambda *}^{\alpha} = c_{\beta \lambda}^{\alpha} - c_{\beta * \lambda}^{\alpha*} - c_{\beta \lambda *}^{\alpha*}, \quad t_{\beta * \lambda}^{\alpha} = c_{\beta \lambda}^{\alpha*}, \quad t_{\beta \lambda}^{\alpha} = 0,$$

$$t_{\beta * \lambda *}^{\alpha*} = c_{\beta \lambda}^{\alpha*}, \quad t_{\beta * \lambda}^{\alpha*} = 0, \quad t_{\beta \lambda}^{\alpha*} = 0;$$

the structure form is then given by



$$T^\alpha = c_{\iota\zeta}^{\alpha*} \theta^\zeta \wedge \theta^{\iota*} + \frac{1}{2}(c_{\iota\zeta}^\alpha - c_{\iota*\zeta}^{\alpha*} - c_{\iota\zeta*}^{\alpha*}) \theta^{\iota*} \wedge \theta^{\zeta*},$$

$$T^{\alpha*} = \frac{1}{2} c_{\beta}^{\alpha*} \theta^{\beta*} \wedge \theta^{\lambda*}.$$

and finally

$$\text{Cdf-MdCf} = f T^\alpha + f_{\alpha*} T^{\alpha*} = f \circ T.$$

The relation (4.9) can be used in order to obtain, in local coordinates, an expression of the tensor of the structure in terms of the tensor  $F_i^j$  of the almost tangent structure.

Indeed, (4.9) provides, in local coordinates,

$$(4.10) \quad (\text{Cdf-MdCf})_{jk} = \frac{1}{2} t_{jk}^i f_i.$$

The form  $df$  has, as components in local coordinates,

$$(df)_{jk} = \frac{1}{2} (\partial_{j^*} f_k - \partial_k f_{j^*}),$$

also

$$(\text{Cdf})_{jk} = \frac{1}{2} F_j^a F_k^b (\partial_a f_b - \partial_b f_a).$$

Hence for  $\text{MdCf}$  we have, according to the relation (4.8),

$$(\text{MdCf})_{jk} = \frac{1}{2} F_j^a [\partial_a (F_k^b f_b) - \partial_k (F_a^b f_b)] - \frac{1}{2} F_k^a [\partial_a (F_j^b f_b) - \partial_j (F_a^b f_b)].$$

Using the relation  $F_i^a F_a^j = 0$ , we obtain

$$\begin{aligned} (\text{MdCf})_{jk} &= \frac{1}{2} F_j^a \partial_a F_k^b f_b + \frac{1}{2} F_j^a F_k^b \partial_a f_b - \frac{1}{2} F_j^a \partial_a F_k^b f_b \\ &\quad - \frac{1}{2} F_k^a \partial_a F_j^b f_b - \frac{1}{2} F_k^a F_j^b \partial_a f_b - \frac{1}{2} F_k^a F_j^b \partial_a f_b + \frac{1}{2} F_k^a \partial_a F_j^b f_b, \end{aligned}$$

and

$$(\text{Cdf-MdCf})_{jk} = \frac{1}{2} \{ F_j^a (\partial_k F_a^b - \partial_a F_k^b) + F_k^a (\partial_a F_j^b - \partial_j F_a^b) \} f_b .$$

From (4.10) we see that

$$t_{jk}^i = F_j^a (\partial_k F_a^i - \partial_a F_k^i) + F_k^a (\partial_a F_j^i - \partial_j F_a^i) ,$$

or

$$t_{jk}^i = F_a^i (\partial_j F_k^a - \partial_k F_j^a) + F_k^a \partial_a F_j^i - F_j^a \partial_a F_k^i ,$$

since

$$F_j^a \partial_k F_a^i = - F_a^i \partial_k F_j^a .$$

PROPOSITION 9. For the almost tangent structures the Nijenhuis tensor, is the negative of the tensor of the structure.

Proof. The Nijenhuis tensor is defined [8] by

$$N(u, v) = [Ju, Jv] + J^2[u, v] - J[Ju, v] - J[u, Jv] ,$$

for any vector fields  $u, v$ . For A. T. structures we have  $J^2=0$ , hence

$$(4.11) \quad N(u, v) = [Ju, Jv] - J[Ju, v] - J[u, Jv] .$$

The relation (4.11) may be written explicitly

$$[N(u, v)]^k = [Ju, Jv]^k - F_\ell^k [Ju, v]^\ell - F_\ell^k [u, Jv]^\ell ,$$

where

$$[Ju, v]^\ell = F_a^m u^a \partial_m v^\ell - v^m \partial_m (F_a^\ell u^a) ,$$

$$[u, Jv]^\ell = u^m \partial_m (F_b^\ell v^b) - F_a^m v^a \partial_m u^\ell ,$$

$$\begin{aligned}
[J_u, J_v]^k &= F_{a \quad m}^m u^a \partial_m (F_b^k v^b) - F_{a \quad m}^m v^a \partial_m (F_b^k u^b) \\
&= F_{a \quad b}^m F_{u \quad m}^k a \partial_m v^b - F_{a \quad b}^m F_{v \quad m}^k a \partial_m u^b + F_{a \quad m}^m \partial_m F_b^k u^a v^b \\
&\quad - F_{a \quad m}^m \partial_m F_b^k v^a u^b.
\end{aligned}$$

Hence, after cancellations of opposite terms and rearrangement of indices, we obtain

$$N(u, v)^k = [F_{r \quad l}^k \partial_m F_m^r - F_{r \quad m}^k \partial_l F_m^r + F_{m \quad r}^r \partial_l F_m^k - F_{l \quad r}^r \partial_m F_m^k] v^l u^m.$$

Therefore

$$N_{ml}^k = F_{r \quad l}^k (\partial_m F_m^r - \partial_m F_l^r) + F_{m \quad r}^r \partial_l F_m^k - F_{l \quad r}^r \partial_m F_m^k,$$

and

$$N_{ml}^k = -t_{ml}^k.$$

**COROLLARY.** In order that an A. T. structure be completely integrable it is necessary and sufficient that the Nijenhuis tensor be equal to zero.

### 5. Curvature tensor of the almost tangent connection.

Given an A. T. connection, the curvature of this connection is defined by the relation

$$(5.1) \quad \Omega_i^j = d\pi_i^j + \pi_\ell^j \wedge \pi_i^\ell,$$

where the tensor 2-form (5.1) is the curvature form of the connection and it satisfies Bianchi's identity

$$(5.2) \quad d\Omega_i^j = \Omega_\ell^j \wedge \pi_i^\ell - \pi_\ell^j \wedge \Omega_i^\ell.$$

From the relation (5.1) we have

$$\Omega_{\alpha}^{\beta} = d\pi_{\alpha}^{\beta} + \pi_{\lambda}^{\beta} \wedge \pi_{\alpha}^{\lambda} + \pi_{\lambda^{*}}^{\beta} \wedge \pi_{\alpha}^{\lambda^{*}} = d\pi_{\alpha}^{\beta} + \pi_{\lambda}^{\beta} \wedge \pi_{\alpha}^{\lambda}$$

$$\Omega_{\alpha^{*}}^{\beta^{*}} = d\pi_{\alpha^{*}}^{\beta^{*}} + \pi_{\lambda}^{\beta^{*}} \wedge \pi_{\alpha^{*}}^{\lambda} + \pi_{\lambda^{*}}^{\beta^{*}} \wedge \pi_{\alpha^{*}}^{\lambda^{*}} = d\pi_{\alpha^{*}}^{\beta^{*}} + \pi_{\lambda^{*}}^{\beta^{*}} \wedge \pi_{\alpha^{*}}^{\lambda^{*}}$$

(Hence  $\Omega_{\alpha^{*}}^{\beta^{*}} = \Omega_{\alpha}^{\beta}$ .)

$$\Omega_{\alpha}^{\beta^{*}} = d\pi_{\alpha}^{\beta^{*}} + \pi_{\lambda}^{\beta^{*}} \wedge \pi_{\alpha}^{\lambda} + \pi_{\lambda^{*}}^{\beta^{*}} \wedge \pi_{\alpha}^{\lambda^{*}} = 0,$$

$$\Omega_{\alpha^{*}}^{\beta} = d\pi_{\alpha^{*}}^{\beta} + \pi_{\lambda}^{\beta} \wedge \pi_{\alpha^{*}}^{\lambda} + \pi_{\lambda^{*}}^{\beta} \wedge \pi_{\alpha^{*}}^{\lambda^{*}}.$$

By contraction on  $\alpha$  and  $\beta$  we obtain

$$(5.3) \quad \Omega_{\alpha}^{\alpha} = d\pi_{\alpha}^{\alpha} \quad \text{or} \quad \Omega_{\alpha^{*}}^{\alpha^{*}} = d\pi_{\alpha^{*}}^{\alpha^{*}},$$

$$\left( \pi_{\alpha}^{\alpha} = \pi_{\alpha^{*}}^{\alpha^{*}} = \frac{1}{2} \pi_{i}^{i} \quad \text{and} \quad \Omega_{\alpha}^{\alpha} = \Omega_{\alpha^{*}}^{\alpha^{*}} = \frac{1}{2} \Omega_{i}^{i} \right).$$

If we consider a covering of  $V_{2n}$  by neighbourhoods  $U, V, \dots$  equipped with local cross sections of  $E_{\mathbb{T}}(V_{2n})$ , we see that

$$\psi = \Omega_{\alpha}^{\alpha} = \Omega_{\alpha^{*}}^{\alpha^{*}}$$

is a complex 2-form. We call  $\psi$  the characteristic form of the A. T. connection. We deduce from (5.3) that  $\psi$  is a closed form.  $\pi_{\alpha}^{\alpha}$  defines on the fibre bundle  $E_{\mathbb{T}}(V_{2n})$  a complex-valued 1-form and if  $p^{*}\psi$  is the inverse image of  $\psi$  in  $E_{\mathbb{T}}(V_{2n})$  by the projection, we may write

$$p^{*}\psi = d\phi.$$

Thus,  $p^{*}\psi$  is homologous to 0 on  $E_{\mathbb{T}}(V_{2n})$ . The cohomology class on  $V_{2n}$  of the form  $\psi$  does not depend on the connection

under consideration. If  $(\hat{\pi}_\beta^\alpha)$  is another A. T. connection,

$$\hat{\psi} - \psi = d(\hat{\pi}_\alpha^\alpha - \pi_\alpha^\alpha),$$

where  $\hat{\pi}_\alpha^\alpha - \pi_\alpha^\alpha$  defines a complex-valued 1-form on  $V_{2n}$ . Then  $\hat{\psi} - \psi$  is homologous to 0 in  $V_{2n}$ . The form  $\psi$  defines an integral cohomology class of degree 2.

6. The Holonomy group of the A. T. connections. Let  $V_{2n}$  be a manifold endowed with an A. T. connection. The holonomy group of this connection is a sub-group of the structural group  $G_{nn}^n$  of the fibre bundle  $E_T(V_{2n})$  [(2), p. 62]. Conversely, let  $V_{2n}$  be a differentiable manifold endowed with a linear complex connection. Let us consider a point  $x \in V_{2n}$  and let us assume that there exists at  $x$ , a complex basis  $b$  such that the holonomy group of the connection  $\psi_b$  at  $b$ , is a subgroup of  $G_{nn}^n$ ; the elements of  $\psi_b$  are matrices of the form

$$\begin{pmatrix} A & 0 \\ B & A \end{pmatrix}.$$

Let us now consider, at the point  $x$ , the tensor whose components with respect to the basis  $b$  are

$$F_\alpha^\beta = F_\alpha^{\beta*} = F_{\alpha*}^{\beta*} = 0, \quad F_{\alpha*}^\beta = \delta_\alpha^\beta = \delta_{\alpha*}^{\beta*},$$

that is, the tensor represented by the matrix

$$\begin{pmatrix} 0 & 0 \\ E_n & 0 \end{pmatrix}.$$

It will be invariant under transformations by the elements of  $\psi_b$ , since

$$\begin{pmatrix} A & 0 \\ B & A \end{pmatrix} \begin{pmatrix} 0 & 0 \\ E & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ E_n & 0 \end{pmatrix} \begin{pmatrix} A & 0 \\ B & A \end{pmatrix},$$

and its components satisfy, at  $x$ , the relation

$$(6.1) \quad F_k^j F_i^k = 0.$$

From this tensor, we obtain by parallel transport in  $V_{2n}$ , a tensor  $F_i^j$  defined on the whole manifold  $V_{2n}$  with absolute differential equal to zero [(2), p. 113]. Moreover the relation (6.1) remains true at every point of  $V_{2n}$ . An A. T. structure is thus defined on  $V_{2n}$ . Since  $\nabla F_i^j = 0$ , by proposition 4, the given connection may be identified with an A. T. connection. We may thus state the following proposition:

PROPOSITION 10. A necessary and sufficient condition in order that a complex linear connection in a manifold  $V_{2n}$  be an A. T. connection of an A. T. structure is that the holonomy group of the linear connection be a sub-group of  $G\left(\begin{smallmatrix} n \\ nn \end{smallmatrix}\right)$ .

7. The restricted holonomy group. Before studying the restricted holonomy group we shall prove the following lemma.

LEMMA. The set  $SG\left(\begin{smallmatrix} n \\ nn \end{smallmatrix}\right)$  of all the matrices of the form

$$\alpha = \begin{pmatrix} A & 0 \\ B & A \end{pmatrix} \text{ with } \det A = 1 \text{ is an invariant subgroup of } G\left(\begin{smallmatrix} n \\ nn \end{smallmatrix}\right).$$

Proof. If

$$\alpha = \begin{pmatrix} A & 0 \\ B & A \end{pmatrix}, \quad \alpha_1 = \begin{pmatrix} A_1 & 0 \\ B_1 & A_1 \end{pmatrix},$$

with  $\det A = \det A_1^{-1} = 1$ , we have

$$\alpha \alpha_1^{-1} = \begin{pmatrix} AA_1^{-1} & 0 \\ * & AA_1^{-1} \end{pmatrix}$$

and  $\det(AA_1^{-1}) = \det A \det(A_1^{-1}) = 1$ . Hence  $\alpha \alpha_1^{-1} \in SG(\frac{n}{nn})$  and

and  $SG(\frac{n}{nn})$  is a subgroup of  $G(\frac{n}{nn})$ . It is an invariant subgroup, because for any  $A \in SG(\frac{n}{nn})$  and any  $A_1 \in G(\frac{n}{nn})$  we have

$$\det(A_1^{-1} AA_1) = \det(A_1^{-1})(\det A)(\det A_1) = 1. \text{ Hence } \alpha_1^{-1} \alpha \alpha_1 \in SG(\frac{n}{nn}).$$

The  $SG(\frac{n}{nn})$  is obviously a Lie subgroup of the Lie group  $G(\frac{n}{nn})$ .

Without changing notations we shall now pass to the universal covering of  $V_{2n}$ .

Let  $b$  be an adapted basis at the point  $x_o \in V_{2n}$ , and let us assume that the restricted holonomy group  $\sigma_b$  is a subgroup of  $SG(\frac{n}{nn})$ . Then this assumption will be true at every point of  $E_T(V_{2n})$ . We introduce at the point  $x_o$  the covariant tensor  $t_o$  of order  $n$ , whose components with respect to the base  $b$  are

$$t_{i_1 i_2 \dots i_n} = \epsilon_{i_1 i_2 \dots i_n}^{1*2*\dots n*}.$$

The tensor  $t_o$  is invariant under  $\sigma_b$ . Indeed,

$$t_{j'_1 j'_2 \dots j'_n} = A_{j'_1}^{i_1} A_{j'_2}^{i_2} \dots A_{j'_n}^{i_n} \epsilon_{i_1 i_2 \dots i_n}^{1*2*\dots n*}.$$

Hence

$$\begin{aligned}
t_{\zeta'_1 \zeta'_2 \dots \zeta'_n} &= t_{\zeta'_1 \zeta'_2 \dots \zeta'_n} = 0, \\
t_{\zeta'_1 \zeta'_2 \dots \zeta'_n} &= A_{\zeta'_1}^{\alpha_1^*} A_{\zeta'_2}^{\alpha_2^*} \dots A_{\zeta'_n}^{\alpha_n^*} \varepsilon_{\alpha_1^* \alpha_2^* \dots \alpha_n^*} \\
&= \varepsilon_{\zeta'_1 \zeta'_2 \dots \zeta'_n}^{1^* 2^* \dots n^*}.
\end{aligned}$$

Therefore

$$t_{j'_1 j'_2 \dots j'_n} = \varepsilon_{j'_1 j'_2 \dots j'_n}^{1^* 2^* \dots n^*}.$$

By parallel displacement,  $t_{\circ}$  generates a tensor  $t$  defined on the whole  $V_{2n}$  and  $\nabla t = 0$ . If  $U$  is an open neighbourhood of  $V_{2n}$  endowed with a local cross section of  $E_T(V_{2n})$ , there exists a differentiable function  $e^f$  with complex values  $\neq 0$ , defined on  $U$ , such that we have in  $U$

$$(7.1) \quad t_{i_1 i_2 \dots i_n} = \varepsilon_{i_1 i_2 \dots i_n}^{1^* 2^* \dots n^*} e^f.$$

From (7.1) we obtain

$$\nabla t_{i_1 i_2 \dots i_n} = (de^f) \varepsilon_{i_1 \dots i_n}^{1^* \dots n^*} + e^f \nabla \varepsilon_{i_1 \dots i_n}^{1^* \dots n^*};$$

but

$$\begin{aligned}
\nabla \varepsilon_{i_1 i_2 \dots i_n}^{1^* \dots n^*} &= -\pi_{i_1}^{\rho} \varepsilon_{\rho i_2 \dots i_n}^{1^* 2^* \dots n^*} - \pi_{i_2}^{\rho} \varepsilon_{i_1 \rho i_3 \dots i_n}^{1^* \dots n^*} - \dots \\
&\quad - \pi_{i_n}^{\rho} \varepsilon_{i_1 \dots i_{n-1} \rho}^{1^* \dots n^*}
\end{aligned}$$

or



$$\begin{aligned} \nabla \varepsilon_{\alpha_1^* \dots \alpha_n^*}^{1^* \dots n^*} &= -\pi_{\alpha_1^*}^{\rho^*} \varepsilon_{p^* \alpha_2^* \dots \alpha_n^*}^{1^* \dots n^*} - \pi_{\alpha_2^*}^{\rho^*} \varepsilon_{\alpha_1^* p^* \dots \alpha_n^*}^{1^* \dots n^*} - \dots \\ &\quad - \pi_{\alpha_n^*}^{\rho^*} \varepsilon_{\alpha_1^* \dots \alpha_{n-1}^* p^*}^{1^* \dots n^*} \\ &= -\left(\pi_{\alpha_1^*}^{\alpha_1^*} + \pi_{\alpha_2^*}^{\alpha_2^*} + \dots + \pi_{\alpha_n^*}^{\alpha_n^*}\right) \varepsilon_{\alpha_1^* \alpha_2^* \dots \alpha_n^*}^{1^* 2^* \dots n^*} = -\pi_{\alpha^*}^{\alpha^*} \varepsilon_{\alpha_1^* \dots \alpha_n^*}^{1^* \dots n^*}. \end{aligned}$$

Finally

$$\nabla \varepsilon_{i_1 \dots i_n}^{i^* \dots n^*} = -\pi_{\alpha^*}^{\alpha^*} \varepsilon_{i_1 i_2 \dots i_n}^{i^* 2^* \dots n^*}.$$

We may thus write (7.2)

$$\nabla t_{i_1 i_2 \dots i_n} = e^f (df - \pi_{\alpha^*}^{\alpha^*} \varepsilon_{i_1 \dots i_n}^{1^* \dots n^*})$$

and obtain

$$\pi_{\alpha^*}^{\alpha^*} = \pi_{\alpha}^{\alpha} = df,$$

or

$$\psi = d\pi_{\alpha}^{\alpha} = d^2 f = 0.$$

The characteristic form is everywhere equal to zero.

Conversely, let us consider a differentiable manifold  $V_{2n}$ , equipped with an A. T. connection and let us assume that the characteristic form  $\psi$  is zero at every point of  $V_{2n}$ . With respect to any local cross section of  $E_T(V_{2n})$ , we have

$$d\pi_{\alpha}^{\alpha} = d\pi_{\alpha^*}^{\alpha^*} = 0.$$

To every point  $x$  of  $V_{2n}$  we may associate an open neighbourhood  $U(x)$  and a complex-valued function  $f$  defined in  $U$  such that, with respect to the cross section,

$$\pi_{\alpha}^{\alpha} = df.$$

We now consider the covariant tensor of order  $n$  defined in  $U$ , whose components with respect to the local cross section are

$$t_{i_1 i_2 \dots i_n} = \varepsilon_{i_1 \dots i_n}^{1* \dots n*} e^f;$$

its absolute differential is given by

$$\nabla t_{i_1 i_2 \dots i_n} = \varepsilon_{i_1 \dots i_n}^{1* \dots n*} e^f (df - \pi_{\alpha}^{\alpha}) = 0.$$

If  $b_x$  is an adapted basis at  $x$ , the holonomy group  $\sigma_{b_x}$  of the connection at  $b_x$  is, as we have seen previously, a subgroup of  $G_{nn}^n$ . Since  $\nabla t = 0$  in  $U$ , the elements of  $\sigma_{b_x}$  which we obtain by developing the loops at  $x$  situated in  $U$ , leave  $t$  invariant. Therefore they belong in  $SG_{nn}^n$ . Since we may associate to every point  $x$ , such a neighbourhood  $U$ , it follows from the factorization lemma [(2), p. 52], that for every  $b \in E_T(V_{2n})$ ,  $\sigma_b$  is a subgroup of  $SG_{nn}^n$ . We may thus state:

**PROPOSITION 11.** In order that a manifold with an A. T. connection has an holonomy group  $\sigma$  as sub-group of  $SG_{nn}^n$ , it is necessary and sufficient that the characteristic form of the connection be equal to zero.

Some interesting topics of the theory of manifolds with A. T. structures are: 1. The compatibility of Euclidean and

A. T. structures. 2. Compatibility of Hermitian and A. T. structures. 3. The automorphisms of such manifolds. The first topic is already studied in [9], the other two will be investigated in another paper.

#### APPENDIX

If  $t_i^j$  and  $t_{l'}^{m'}$  are the components of a tensor of type (1, 1) with respect to two different adapted bases, we have the following relations:

$$t_{\lambda'}^{\mu'} = A_{\lambda'}^{\alpha} A_{\zeta}^{\mu'} t_{\alpha}^{\zeta} + A_{\lambda'}^{\alpha} B_{\zeta*}^{\mu'} t_{\alpha}^{\zeta*},$$

$$t_{\lambda' *}^{\mu' *} = B_{\lambda' *}^{\alpha} A_{\zeta*}^{\mu' *} t_{\alpha}^{\zeta*} + A_{\lambda' *}^{\alpha*} A_{\zeta*}^{\mu' *} t_{\alpha*}^{\zeta*},$$

$$t_{\lambda'}^{\mu' *} = A_{\lambda'}^{\alpha} A_{\zeta*}^{\mu'} t_{\alpha}^{\zeta*},$$

$$t_{\lambda' *}^{\mu'} = B_{\lambda' *}^{\alpha} A_{\zeta}^{\mu'} t_{\alpha}^{\zeta} + B_{\lambda' *}^{\alpha} A_{\zeta*}^{\mu'} t_{\alpha}^{\zeta*} + A_{\lambda' *}^{\alpha*} A_{\zeta}^{\mu'} t_{\alpha*}^{\zeta} + A_{\lambda' *}^{\alpha*} B_{\zeta*}^{\mu'} t_{\alpha*}^{\zeta*}.$$

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