# POSITIVE SOLUTIONS FOR A CLASS OF SEMILINEAR TWO-POINT BOUNDARY VALUE PROBLEMS 

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We study the existence of positive solutions of the periodic, Neumann or Dirichlet problem for the semilinear equation

$$
u^{\prime \prime}+f(t, u)=0, \quad 0 \leqslant t \leqslant T
$$

where $f$ is a Carathéodory function. Our assumptions in each case are such that the problem possesses a lower solution or an upper solution.

## 1. Introduction

Let $f:[0, T] \times[0,+\infty) \rightarrow \mathbb{R}$ be a Carathéodory function (that is, measurable in the first variable and continuous in the second one) and consider the differential equation

$$
\begin{equation*}
u^{\prime \prime}+f(t, u)=0 . \tag{0}
\end{equation*}
$$

We are concerned with the problem of finding solutions of equation (0) subject to boundary conditions of periodic, Neumann, or Dirichlet type. By definition of $f$, these are nonnegative solutions, that is $u(t) \geqslant 0$ for all $t \in[0, T]$. In some cases we study the special form of (0) in which $f(t, u)=g(u)-h(t)$, where $g:[0,+\infty) \rightarrow \mathbb{R}$ is continuous and $h \in L^{1}(0, T)$. In the general case we assume, without further mention, that $f(t, u)$ has the following property: for each $k>0$ there exists a function $\varphi \in L^{1}(0, T)$ such that, for almost every $t \in[0, T]$ and every $u \in[0, k]$ we have

$$
|f(t, u)| \leqslant \varphi(t)
$$

Many authors have studied this problem, not only for equation (0) but also for semilinear elliptic equations in $\mathbb{R}^{\boldsymbol{N}}$. Recent work on the solvability of ( 0 ) may be found in the papers of Castro and Shivaj [4], Nkashama and Santanilla [11], Schaaf and Schmitt [16] and references of those papers. As long as the PDE case is concerned we

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confine ourselves to draw the attention of the reader to articles by Amann [1], Smoller and Wasserman [17], De Figueiredo [6], Brézis-Oswald [3] and Costa and Goncalves [5].

As is well known, the method of lower and upper solutions yields not only existence of a solution but it also locates the solution between given bounds. To use this method, one must be able to construct a lower solution $\underline{u}$ and an upper solution $\bar{u}$ of ( 0 ) (with the appropriate boundary condition) so that $0 \leqslant \underline{u} \leqslant \bar{u}$. The results presented in this paper aim at obtaining existence when a lower solution is given but no upper solution is known, or vice versa, or if a lower solution and an upper solution are given in the wrong order: thus our assumptions will involve the existence of one such lower or upper solution. We shall see that, adding some assumption on the local or asymptotic behaviour of $f(t, u)$, we are still in a position to guarantee, in some instances, the existence of a solution.

## 2. Periodic solutions

We start by analysing a special form of equation (0), namely

$$
\begin{equation*}
u^{\prime \prime}+g(u)=h(t) \tag{1}
\end{equation*}
$$

with periodic boundary conditions

$$
\begin{equation*}
u(0)=u(T), \quad u^{\prime}(0)=u^{\prime}(T) \tag{2}
\end{equation*}
$$

Here, $T>0, h \in L^{1}(0, T)$ and $g:[0, \infty) \rightarrow \mathbb{R}$ is a continuous function.
Let us introduce some notation. The symbol $\left\|\|_{p}\right.$ will denote the usual norm of $L^{p}(0, T), 1 \leqslant p \leqslant \infty$. For each function $h \in L^{1}(0, T)$, we write $h=\bar{h}+\widetilde{h}$, where

$$
\bar{h}=\frac{1}{T} \int_{0}^{T} h(t) d t
$$

so that $\widetilde{h}$ has mean value zero on ( $0, T$ ).
We shall make use of the fixed point index of a compact map in the positive cone of a Banach space (see [1] for instance). Let

$$
C_{+}=\{u \in C[0, T]: u(0)=u(T) \text { and } u(t) \geqslant 0, \quad \forall t \in[0, T]\}
$$

be the positive cone in the space of continuous, $T$-periodic functions. If $\Omega$ is a bounded open set in $C_{+}$, and $F: \bar{\Omega} \rightarrow C_{+}$is a compact mapping such that $F$ has no fixed points on the boundary $\partial_{+} \Omega$ of $\Omega$ relative to $C_{+}$, we denote by $i_{+}(F, \Omega)$ the fixed point index of $F$ in $\Omega$.

In our first results (Theorems 2.1 and 2.2) $u(t) \equiv 0$ is a subsolution of (1)-(2). We first prove two lemmas where a slightly stronger hypothesis, which we call (A.1), is used; this kind of hypothesis appears also in [11].

Lemma 2.1. Suppose that there exist $0<a<b$ such that

$$
\begin{gather*}
b-a>\frac{T\|\tilde{h}\|_{1}}{4},  \tag{3}\\
g(u)<\bar{h} \text { if } u \in(a, b), \tag{4}
\end{gather*}
$$

and
(A1) There exists $R>0$ such that for all $0 \leqslant u \leqslant b$ and almost everywhere $t \in[0, t]$, we have

$$
g(u)+R u \geqslant h(t) .
$$

Then the problem (1) - (2) has at least one solution $u(t) \geqslant 0$.
Remark 2.1. Our hypotheses demand, roughly speaking, that either $T$ be small or the interval $(a, b)$ where (4) holds be large. This result is of a kind similar to one of Zanolin [18, Corollary 2].

Proof: Let $g_{0}:[0, \infty) \rightarrow[0,+\infty)$ be defined as $g_{0}(u)=\bar{h}+a-u$ and consider the homotopic equations

$$
\begin{gather*}
u^{\prime \prime}+\lambda g(u)+(1-\lambda) g_{0}(u)=\lambda h+(1-\lambda) \bar{h}  \tag{5}\\
u(0)=u(T), u^{\prime}(0)=u^{\prime}(T)
\end{gather*}
$$

and the bounded, open subset of $C_{+}$

$$
\Omega=\left\{u \in C_{+}:\|u\|_{\infty}<b\right\} .
$$

We claim that there exist no solutions of (5) on the boundary (relative to $C_{+}$) of $\Omega$, $\partial_{+} \Omega$. To see this we first show that, given a solution $u \in \bar{\Omega}$ of (5) the following estimate holds:

$$
\begin{equation*}
\left|u^{\prime}(t)\right| \leqslant\|\widetilde{h}\|_{1} / 2 \text { if } a \leqslant u(t) \leqslant b \tag{6}
\end{equation*}
$$

In order to prove (6) we remark that integrating (5) in $[0, T]$ and using (4) we conclude that for some $s \in[0, T]$ we have $u(s)<a$. Now let $t_{0} \in \mathbb{R}$ be such that $a \leqslant u\left(t_{0}\right) \leqslant b$ and $u^{\prime}\left(t_{0}\right)>0$, for a given solution $u \in \bar{\Omega}$. Extending $u$ to $\mathbb{R}$ as a $T$-periodic function and using the above remark we may choose $t_{1}>t_{0}$ such that $a \leqslant u(t) \leqslant b$ if $t_{0} \leqslant t \leqslant t_{1}$ and $u^{\prime}\left(t_{1}\right)=0$. Then (5) yields

$$
-u^{\prime}\left(t_{0}\right)+\int_{t_{0}}^{t_{1}}\left(g_{\lambda}(u)-\bar{h}\right) d t=\lambda \int_{t_{0}}^{t_{1}} \widetilde{h} d t
$$

where we have set $g_{\lambda}(u)=\lambda g(u)+(1-\lambda) g_{0}(u)$. The integrand in the left-hand side is negative because of (4), so that

$$
-u^{\prime}\left(t_{0}\right) \geqslant-\lambda \int_{t_{0}}^{t_{1}} \tilde{h}^{-} d t \geqslant-\|\tilde{h}\|_{1} / 2
$$

and (6) holds. A similar argument applies if $u^{\prime}\left(t_{0}\right)<0$.
Now let $u \in \partial_{+} \Omega$ be a solution of (5). Then $\|u\|_{\infty}=b$ and we may choose $t_{1}<t_{2}<t_{3}$ such that $u\left(t_{1}\right)=u\left(t_{3}\right)=a, u\left(t_{2}\right)=b$ and $a \leqslant u(t) \leqslant b$ if $t_{1} \leqslant t \leqslant t_{3}$. Using (6) we deduce that

$$
\begin{aligned}
& b-a=u\left(t_{2}\right)-u\left(t_{1}\right) \leqslant\left(t_{2}-t_{1}\right)\|\tilde{h}\|_{1} / 2 \\
& b-a=u\left(t_{2}\right)-u\left(t_{3}\right) \leqslant\left(t_{3}-t_{2}\right)\|\tilde{h}\|_{1} / 2
\end{aligned}
$$

and it follows that

$$
2(b-a) \leqslant T\|\tilde{h}\|_{1} / 2
$$

a contradiction with (3). Thus our claim is proved.
Denote by $K: L^{1}(0, T) \rightarrow W^{2,1}(0, T)$ the inverse of the linear differential operator $-u^{\prime \prime}+R u$ with periodic conditions (2). We take $R$ in (A1) so large that also $g_{0}(u)+$ $R u \geqslant \bar{h}$ whenever $u \geqslant 0$. Let

$$
N(\lambda, u)=g_{\lambda}(u)+R u-\lambda h-(1-\lambda) \bar{h} .
$$

Then $N$ is a continuous mapping of $[0,1] \times \bar{\Omega}$ into the positive cone of $L^{1}(0, T)$; it takes bounded sets into bounded sets. Since $K$ is a positive linear operator, the product $K N:[0,1] \times \bar{\Omega} \rightarrow C_{+}$is compact and we see that (5) may be written simply as

$$
\begin{equation*}
u=K N(\lambda, u), \quad u \in \bar{\Omega} \tag{7}
\end{equation*}
$$

From what we have proved above and the homotopy invariance of the fixed point index we get

$$
\begin{equation*}
i_{+}(K N(1, .), \Omega)=i_{+}(K N(0, .), \Omega) \tag{8}
\end{equation*}
$$

When $\lambda=0$, the only solution of (7) is $u \equiv a \in \Omega$ as (5) shows. By linearisation we easily obtain

$$
i_{+}(K N(0, .), \Omega)=1
$$

Therefore (8) and the existence property of the fixed point index implies that (7) is solvable in $\Omega$ for $\lambda=1$ as well.

Lemma 2.2. Suppose that there exist $0<a<b$ such that (A1), (4) are satisfied and

$$
\begin{equation*}
\int_{a}^{b}(g(u)-\bar{h}) d u<-\frac{\|\tilde{h}\|_{1}^{2}}{2} \tag{9}
\end{equation*}
$$

Then problem (1) - (2) has at least one solution $u \geqslant 0$.

REMARK 2.2. Unlike condition (3), (9) holds if $\|\tilde{h}\|_{1}$ is sufficiently small (regardless of the period).

Proof: Take a function $g_{0}$ of the form $g_{0}(u)=\bar{h}+k(a-u)$ where $k>\|\tilde{h}\|_{1}^{2}$. $(b-a)^{-2}$, so that, for any $\lambda \in[0,1]$, we have

$$
\begin{equation*}
\int_{a}^{b}\left(g_{\lambda}(u)-\bar{h}\right) d u<-\frac{\|\tilde{h}\|_{1}^{2}}{2} \tag{10}
\end{equation*}
$$

where $g_{\lambda}=\lambda g+(1-\lambda) g_{0}$. Consider $\Omega$ and the homotopy (5) as in the proof of Lemma 2.1. Let us show that (5) has no solution in $\partial_{+} \Omega$. For, if $u$ is such a solution, we may choose $t_{1}<t_{2}$ such that $u\left(t_{1}\right)=a, u\left(t_{2}\right)=b, a \leqslant u(t) \leqslant b$ if $t_{1} \leqslant t \leqslant t_{2}$, and then multiplying (5) by $u^{\prime}$ and integrating we have

$$
-\frac{u^{\prime}\left(t_{1}\right)^{2}}{2}+\int_{a}^{b}\left(g_{\lambda}(u)-\bar{h}\right) d u=\lambda \int_{t_{1}}^{t_{2}} \tilde{h} u^{\prime} d t
$$

Using the estimate (6) we obtain:

$$
\int_{a}^{b}\left(g_{\lambda}(u)-\bar{h}\right) d u \geqslant-\int_{t_{1}}^{t_{2}}\left|\widetilde{h} u^{\prime}\right| d t \geqslant-\frac{\|\widetilde{h}\|_{1}^{2}}{2}
$$

a contradiction with (10). Hence we compute, as in the preceeding lemma,

$$
i_{+}(K N(0, .), \Omega)=1
$$

and the proof is complete.
Theorem 2.1. Suppose that $g(0) \geqslant h(t)$ for almost every $t \in[0, T]$ and there exist $0<a<b$ satisfying (3) and (4). Then the problem (1)-(2) has at least one solution $u(t) \geqslant 0$.

Proof: Let $\varepsilon>0$ and consider the perturbed equation

$$
\begin{equation*}
u^{\prime \prime}+g(u)=h(t)-\varepsilon . \tag{1}
\end{equation*}
$$

Choose $a<a^{\prime}<b^{\prime}<b$ so that $b^{\prime}-a^{\prime}>T\|\tilde{h}\|_{1} / 4$. Then if $\varepsilon$ is sufficiently small all the assumptions of Lemma 2.1 are satisfied with respect to (1) $e_{e}-(2)$. Lemma 2.1 implies that $(1)_{e}-(2)$ has a solution $u_{e}(t)$ such that $0 \leqslant u_{\varepsilon}(t) \leqslant b$. A standard argument shows that the family ( $u_{e}$ ) is (bounded and) equicontinuous in $C[0, T]$. Passing to the limit along a convenient subsequence as $\varepsilon \rightarrow 0$ yields the result.

Using Lemma 2.2 and a similar approximation argument, one proves:

Theorem 2.2. Suppose that $g(0) \geqslant h(t)$ for almost every $t \in[0, T]$ and there exist $0<a<b$ such that (4) and (9) are satisfied. Then problem (1)-(2) has at least one solution $u(t) \geqslant 0$.

In our next theorem the assumptions imply in particular that we have a lower solution $\bar{u}(t) \equiv a>0$ and an upper solution $\underline{u}(t) \equiv 0$ (thus in the wrong order) for problem (0)-(2). Precisely, let us state (see [11]):
(A2) There exists $R \in\left(0, \pi^{2} T^{-2}\right]$ such that $f(t, u) \leqslant R u$ for all $t \in[0, T]$ and $u \geqslant 0$.
The significance of the bound for $R$ in (A2) is the following. If $0<R \leqslant \pi^{2} / T^{2}$, then the (unique) solution of

$$
\begin{gather*}
u^{\prime \prime}+R u=h(t) \\
u(0)=u(T), u^{\prime}(0)=u^{\prime}(T) \tag{11}
\end{gather*}
$$

where $h \in L^{1}(0, T)$ and $h$ is nonnegative, is itself nonnegative. In fact, multiplying (11) by $\cos \sqrt{R}\left(t-t_{0}\right)$, then by $\sin \sqrt{R}\left(t-t_{0}\right)$ and integrating over $\left[t_{0}, t_{0}+T\right]$ (we assume that $h(t)$ is $T$-periodically extended) we are left with a linear system which yields

$$
u\left(t_{0}\right)=\frac{\int_{t_{0}}^{t_{0}+T} h(t)\left[\sin \sqrt{R}\left(t-t_{0}\right)+\sin \sqrt{R} T-\left(t-t_{0}\right)\right] d t}{2 \sqrt{R}(1-\cos \sqrt{R} T)}
$$

and the remark easily follows.
Theorem 2.3. Let $f(t, u)$ satisfy (A2). Assume also that there exist $a>0$ and $\varepsilon>0$ such that

$$
\begin{equation*}
f(t, u) \geqslant 0, \text { for all } u \in[a, a+\varepsilon] \text { and almost every } t \in[0, T] \tag{12}
\end{equation*}
$$

and either $R<2 T^{-2}$ or there exists $\alpha \in L^{1}(0, T)$ such that, for $t \in[0, T]$ and $u \geqslant 0$,

$$
\begin{equation*}
f(t, u) \geqslant \alpha(t) \tag{13}
\end{equation*}
$$

Then problem (0)-(2) has at least one solution $u \geqslant 0$.
Proof: Choose $a^{\prime}<a$, close to $a$. Consider the homotopic equations

$$
\begin{gather*}
u^{\prime \prime}+\lambda f(t, u)+(1-\lambda) \sigma\left(u-a^{\prime}\right)=0  \tag{14}\\
u(0)=u(T), u^{\prime}(0)=u^{\prime}(T)
\end{gather*}
$$

where $\sigma \in(0, R)$ and $0 \leqslant \lambda \leqslant 1$. We claim that there exists $A>0$ such that, if $u(t)$ is a solution of (14) for some $\lambda \in[0,1]$ and $\min u \leqslant a$, then

$$
\begin{equation*}
u(t)<A \text { for all } t \in[0, T] \tag{15}
\end{equation*}
$$

To prove this, assume first that $R<2 T^{-2}$. Using Proposition 3.1 in [8] we obtain for solutions of (14) the inequality

$$
\left\|u^{\prime}\right\|_{\infty} \leqslant \int_{0}^{T}\left[\lambda f(t, u)+(1-\lambda) \sigma\left(u-a^{\prime}\right)\right]^{+} d t \leqslant R \int_{0}^{T} u d t
$$

If we choose $t_{m} \in[0, T]$ such that $u\left(t_{m}\right) \leqslant a$, we have

$$
\left\|u^{\prime}\right\|_{\infty} \leqslant R T a+R \int_{0}^{T} d t \int_{t_{m}}^{t} u^{\prime}(s) d s \leqslant R T a+\frac{R T^{2}}{2}\left\|u^{\prime}\right\|_{\infty}
$$

so that $\left\|u^{\prime}\right\|_{\infty} \leqslant 2 R T a\left(2-R T^{2}\right)^{-1}$. Therefore (15) is satisfied with $A=a+$ $2 R T^{2} a\left(2-R T^{2}\right)^{-1}+1$. Next assume (13). Then we obtain the estimate

$$
\left\|u^{\prime}\right\|_{\infty} \leqslant \int_{0}^{T}\left[\lambda f(t, u)+(1-\lambda) \sigma\left(u-a^{\prime}\right)\right]^{-} d t \leqslant\|\alpha\|_{1}+\sigma a^{\prime} T
$$

so that (15) holds with $A=a+T\left(\|\alpha\|_{1}+\sigma a T\right)+1$.
Now we take the bounded, open set

$$
\Omega=\left\{u \in C_{+}: \min u<a,\|u\|_{\infty}<A\right\} .
$$

From what has been proved above we can assert that, if $0 \leqslant \lambda<1$, (14) has no solution in $\partial_{+} \Omega$. In fact the possibility that $\min u=a$ for such a solution $u(t)$ is ruled out by (12). Otherwise we would be able to choose an interval $\left[t_{0}, t_{1}\right]$ such that $u\left(t_{0}\right)=a$, $u^{\prime}\left(t_{1}\right) \geqslant 0, u(t) \leqslant a+\varepsilon$ if $t \in\left[t_{0}, t_{1}\right]$ and (14) would imply

$$
0=u^{\prime}\left(t_{1}\right)+\int_{t_{0}}^{t_{1}}\left[\lambda f(t, u)+(1-\lambda) \sigma\left(u-a^{\prime}\right)\right] d t>0
$$

a contradiction. Rewriting (14) as

$$
u=S\left[R u-\lambda f(t, u)-(1-\lambda) \sigma\left(u-a^{\prime}\right)\right]
$$

where $S$ is the inverse of the linear operator $u^{\prime \prime}+R u$ with periodic conditions (which, as the remark preceeding the theorem shows, sends nonnegative functions into $C_{+}$), we conclude: either (0)-(2) has a solution $u \in \bar{\Omega}$ or $i_{+}(S N(1,),. \Omega)=1$, where

$$
N(\lambda, u)=R u-\lambda f(t, u)-(1-\lambda) \sigma\left(u-a^{\prime}\right)
$$

in which case (0)-(2) has a solution $u \in \Omega$. This ends the proof.

Remark 2.3. Assuming that $f$ is continuous in $[0, T] \times \mathbb{R}_{+}$, it is easily seen that the proof works (even in a simpler form) if (12) is stated simply as

$$
f(t, a) \geqslant 0, \quad t \in[0, T]
$$

In the next theorem we return to equation (1), and $u(t) \equiv 0$ is again a subsolution.
Theorem 2.4. Suppose that

$$
\begin{equation*}
g(0) \geqslant h(t) \text { for almost every } t \in[0, T] \tag{16}
\end{equation*}
$$

that $L:=\lim _{u \rightarrow+\infty}(\bar{h} u-G(u))$ exists, where $G(u)=\int_{0}^{u} g(s) d s,(u \geqslant 0)$, and for some $R>0$ we have

$$
\begin{equation*}
\bar{h} u-G(u) \leqslant L \quad \text { if } u \geqslant R . \tag{17}
\end{equation*}
$$

Then problem (1)-(2) has at least one solution $u \geqslant 0$.
Proof: Let us extend $g$ to $(-\infty, 0]$, defining $g(u)=g(0)$ if $u<0$ and let us still denote by $G(u)$ the primitive of the extended function. Consider the $C^{1}$ functional

$$
\begin{aligned}
J(u) & =\int_{0}^{T}\left[\frac{u^{\prime 2}}{2}+h(t) u-G(u)\right] d t \\
& =\int_{0}^{T}\left[\frac{u^{\prime 2}}{2}+(\bar{h} u-G(u))+\widetilde{h}(t) u\right] d t
\end{aligned}
$$

defined in the Sobolev space $H_{T}^{1}=\left\{u \in H^{1}(0, T): u(0)=u(T)\right\}$. It is easily seen that the method used in [14, Theorem 1] or [15, Theorem 1] may be adapted to show that $J$ attains a minimum in $H_{T}^{1}$ : it is enough to check that (i) the function $\bar{h} u-G(u)$ is bounded below, and (ii) $\lim _{u \rightarrow-\infty} \bar{h} u-G(u):=L^{\prime}$ exists and $\bar{h} u-G(u) \leqslant L^{\prime}$ if $u \leqslant 0$. Now (ii) follows from (16) and the fact that $\bar{h} u-G(u)=(\bar{h}-g(0)) u$ if $u \leqslant 0$. For the same reason we have $L^{\prime}=0$ or $L^{\prime}=+\infty$; also $L>-\infty$ on account of (17), and (i) holds. Hence $J$ has indeed a minimum attained at some function $u(t)$ which solves (1)-(2) with the extended function $g$. It remains to show that $u(t) \geqslant 0$ for all $t \in[0, T]$. This is a straightforward consequence of (16) and the definition of $g(u)$ for $u<0$.

Remark 2.4. Theorems 2.1, 2.2 and 2.4 extend naturally to the case where one considers the Neumann boundary condition $u^{\prime}(0)=0, u^{\prime}(T)=0$. As long as Theorem 2.3 is concerned, the only difference is that in the assumption A2 one should write

$$
0<R \leqslant \pi^{2} /\left(4 T^{2}\right)
$$

(see [7]).

## 3. Dirichlet boundary conditions

In this section we consider the boundary value problem

$$
\begin{gather*}
u^{\prime \prime}+f(t, u)=0  \tag{18}\\
u(0)=0, \quad u(\pi)=0 \tag{19}
\end{gather*}
$$

where the Carathéodory function $f$ is defined in $[0, \pi] \times \mathbb{R}_{+}$and is such that, for each $K>0$, there exists a function $\alpha \in L^{1}(0, \pi)$ such that $|f(t, u)| \leqslant \alpha(t)$ if $t \in[0, \pi]$ and $0 \leqslant u \leqslant K$. To motivate our setting of the problem some remarks are in order. Let $m \in L^{\infty}(0, \pi)$ be a function such that $m(t)>0$ in a set of positive measure and denote by $\mu(m)$ the first positive eigenvalue of the linear problem (see [10])

$$
\begin{align*}
& u^{\prime \prime}+\lambda m(t) u=0 \\
& u(0)=0, u(\pi)=0 \tag{20}
\end{align*}
$$

Then, if

$$
\liminf _{u \rightarrow 0^{+}} \frac{f(t, u)}{u}=a(t), \quad \limsup _{u \rightarrow+\infty} \frac{f(t, u)}{u}=b(t)
$$

and

$$
\mu(a)<1<\mu(b)
$$

we can construct a lower solution $\underline{u}>0$ and an upper solution $\bar{u}$ of (18)-(19), such that $\underline{u} \leqslant \bar{u}$ (see [5]) or else we can solve the problem through minimisation of the associated functional, see [3]. A quite different situation occurs if

$$
\limsup _{u \rightarrow 0^{+}} \frac{f(t, u)}{u}=a(t), \quad \liminf _{u \rightarrow+\infty} \frac{f(t, u)}{u}=b(t)
$$

and

$$
\mu(a)>1>\mu(b)
$$

this may be studied through the fixed-point index (see [1]) or the time map (see [12]). Here we are interested in starting from an hypothesis similar to this one but only where the behaviour near zero is concerned; we then add a one-sided Landsman-Lazer condition. Note that if $\mu(a)>1$ holds as above, it is easy to see that (18)-(19) has a (small) positive upper solution. Precisely, we state:
(A3) Let $F(t, u)=\int_{0}^{u} f(t, s) d s$. We assume that $f(t, 0)=0$ almost everywhere and that there exist $\varepsilon>0$ and a function $a \in L^{\infty}(0, \pi), a(t) \geqslant 0$ almost everywhere, such that for almost every $t \in[0, \pi]$ and $0 \leqslant u \leqslant \varepsilon$, we have

$$
F(t, u) \leqslant a(t) u^{2} / 2
$$

and $\mu(a)>1$.
For convenience we now write $f(t, u)=u+p(t, u)$ and accordingly (18) turns into

$$
\begin{equation*}
u^{\prime \prime}+u+p(t, u)=0 \tag{18'}
\end{equation*}
$$

It is easily seen that (A3) implies that $p(t, u)$ is negative somewhere to the right of zero, for small $u$.

Theorem 3.1. Let $f$ satisfy (A3) and, with the notation introduced in (18 ), assume that there exists a function $\beta \in L^{1}(0, \pi)$ such that, for almost every $t \in[0, T]$ and $u \geqslant 0$,

$$
\begin{equation*}
|p(t, u)| \leqslant \beta(t) \tag{20}
\end{equation*}
$$

moreover let $p$ satisfy the Landesman-Lazer condition

$$
\begin{equation*}
\int_{0}^{\pi} p_{+}(t) \sin t d t>0 \tag{21}
\end{equation*}
$$

where $p_{+}(t)=\liminf _{u \rightarrow+\infty} p(t, u)$. Then (18)-(19) has a (nontrivial) nonnegative solution.
Proof: Extend $f(t, u)$ to all values of $u \in \mathbb{R}$ by setting $f(t, u)=0$ if $u \leqslant 0$. For simplicity, we denote by the same symbol the corresponding extensions of $p(t, u)$, $F(t, u)$. Let $P(t, u)=\int_{0}^{u} p(t, s) d s$. We consider the functional

$$
J(u)=\int_{0}^{\pi}\left[\frac{u^{\prime 2}}{2}-\frac{u^{2}}{2}-P(t, u)\right] d t
$$

which is of class $C^{1}$ in $H_{0}^{1}(0, \pi)$, and we look for a critical point $u \neq 0$ of $J$. To prove that such a critical point exists we use the mountain-pass lemma [2].

Step 1. $J$ has a strict local minimum at the origin. This is an easy consequence of the injection $H_{0}^{1}(0, \pi) \subset C[0, \pi]$ which, combined with the fact that (A3) obviously holds for $|u| \leqslant \varepsilon$ with respect to the extended function $F(t, u)$, shows that, for some $\delta>0$, $\|u\|<\delta$ (where $\|u\|$ is a norm of $u$ in $H_{0}^{1}(0, \pi)$ ) implies

$$
J(u) \geqslant \int_{0}^{\pi}\left(\frac{u^{\prime 2}}{2}-a(t) \frac{u^{2}}{2}\right) d t
$$

Since $\mu(a)>1$, the quadratic form in the right-hand side is positive definite in $H_{0}^{1}(0, \pi)$. In particular we can fix $\delta>0$ and $c>0$ such that

$$
\begin{equation*}
J(u) \geqslant c \quad \text { if } \quad\|u\|=\delta \tag{22}
\end{equation*}
$$

Step 2. There exists $v \in H_{0}^{1}(0, \pi)$, with $\|v\|$ large, such that $J(v) \leqslant 0$. In fact, it can be shown as in [ 9, p.39] or [14, Theorem 4.1] that (21) implies

$$
\lim _{b \rightarrow+\infty} J(b \sin t)=-\infty
$$

Step 3. $J$ satisfies the Palais-Smale condition. Indeed let $u_{n} \in H_{0}^{1}(0, \pi)$ and $M \in \mathbb{R}$ be such that

$$
J\left(u_{n}\right) \leqslant M, \quad J^{\prime}\left(u_{n}\right) \rightarrow 0
$$

It suffices to show that $\left(u_{n}\right)$ is bounded since the remaining properties of ( $u_{n}$ ) follow in a standard way, see [13]. We have, because of (20),

$$
\begin{aligned}
\int_{0}^{\pi} \frac{u_{n}^{\prime 2}}{2} d t & \leqslant \int_{u_{n}>0} F\left(t, u_{n}\right) d t+M \\
& =\int_{u_{n}>0} \frac{u_{n}^{2}}{2} d t+\int_{u_{n}>0} P\left(t, u_{n}\right) d t+M \\
& \leqslant \int_{0}^{\pi} \frac{u_{n}^{2}}{2} d t+c_{1}\left\|u^{+}\right\|_{\infty}+M
\end{aligned}
$$

where $c_{1}=\|\beta\|_{1}$. Splitting $u_{n}$ as usual into $u_{n}=a_{n} \sin t+w_{n}$, $\left(a_{n} \in \mathbb{R}, \int_{0}^{\pi} w_{n}(t) \sin t d t=0\right)$, and letting $c_{2}, c_{3}, c_{4}$ denote positive constants independent of $n$,

$$
\begin{gather*}
\int_{0}^{\pi}\left(\frac{w_{n}^{\prime 2}}{2}-\frac{w_{n}^{2}}{2}\right) d t \leqslant c_{2}\left(\left|a_{n}\right|+\left\|w_{n}\right\|\right)+M  \tag{23}\\
\left\|w_{n}\right\|^{2} \leqslant c_{3}\left(\left|a_{n}\right|+\left\|w_{n}\right\|\right)+c_{4}
\end{gather*}
$$

Now we argue by contradiction: suppose that $\left|a_{n}\right| \rightarrow \infty$ (at least along some subsequence). Then from (23) easily follows, as in the proof of Theorem 4.1 in [14], that

$$
v_{n}=\frac{w_{n}}{a_{n}} \rightarrow 0 \text { in } H_{0}^{1}(0, \pi) \text { and uniformly in }[0, \pi]
$$

We must examine two possible cases: (i) $a_{n} \rightarrow+\infty$, and (ii) $a_{n} \rightarrow-\infty$. Since $u_{n}=a_{n}\left(\sin t+v_{n}\right)$, we have $u_{n}(t) \rightarrow+\infty$ if $t \in(0, \pi)$ in case (i). Since $p(t, u)=-u$ if $u<0$ and (20) holds, the sequence $p\left(t, u_{n}(t)\right)$ is bounded below by an integrable function, and Fatou's lemma implies

$$
\int_{0}^{\pi} \liminf _{n \rightarrow \infty} p\left(t, u_{n}(t)\right) \sin t d t \leqslant \lim \int_{0}^{\pi} p\left(t, u_{n}(t)\right) \sin t d t=0
$$

where the last equality comes from

$$
\left\langle J^{\prime}\left(u_{n}\right), \sin t\right\rangle \rightarrow 0
$$

Since $p_{+}(t) \leqslant \lim \inf p\left(t, u_{n}(t)\right)$, we have reached a contradiction with (21). In case (ii) we may choose $N \in \mathbb{N}$ such that if $n \geqslant N, u_{n}(t)<0$ in $[\pi / 3,2 \pi / 3]=I$. Using the decomposition, for $n \geqslant \mathbb{N}$,

$$
\int_{0}^{\pi} p\left(t, u_{n}(t)\right) \sin t d t=\int_{I}\left|u_{n}(t)\right| \sin t d t+\int_{[0, \pi] \backslash I} p\left(t, u_{n}(t)\right) \sin t d t
$$

and noting that the integrand in the last integral is bounded below, we conclude that

$$
\lim \int_{0}^{\pi} p\left(t, u_{n}(t)\right) \sin t d t=+\infty
$$

again a contradiction. This ends the proof of Step 3.
From Steps 1 to 3 we conclude that $J$ has a critical value $\geqslant c$. In particular the corresponding critical point is a nonzero function $u(t)$. This function is a solution of (18)-(19) with the extended function. But then an elementary version of the maximum principle implies that $u(t) \geqslant 0$ for all $t \in[0, T]$, and the proof of the theorem is complete.

REmARK 3.1. It is easy to see that the same proof works, as in [14], with (20) replaced for the less restrictive hypothesis:

$$
\limsup _{u \rightarrow+\infty} \frac{P(t, u)}{u^{2}}=0
$$

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