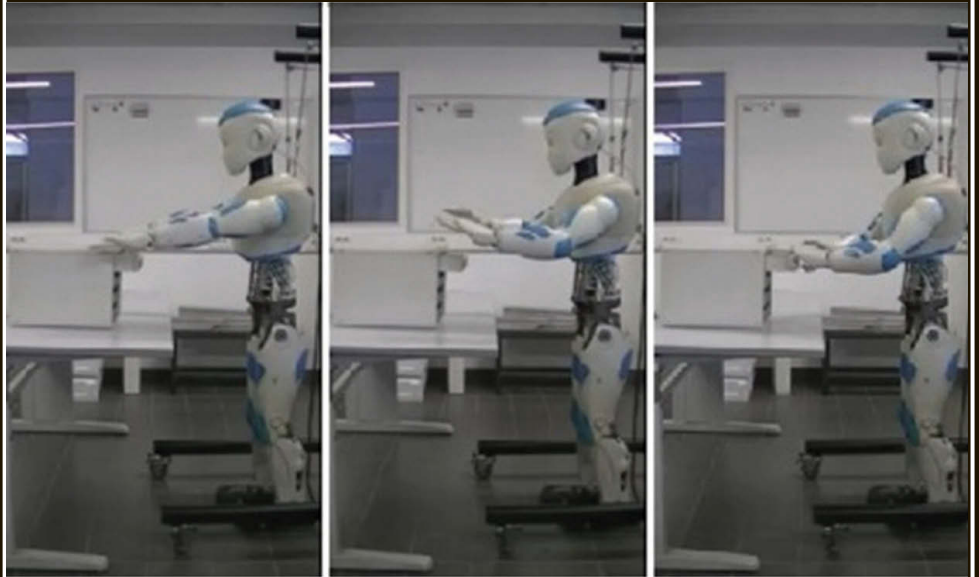


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Cover Image: Human to humanoid motion conversion for dual-arm manipulation tasks by Marija Tomić, Christine Chevallereau, Kosta Jovanović, Veljko Potkonjak, Aleksandar Rodić. Figure 10 'Snapshot of the "open/close drawer" motion performed by: (a) The actor; (b) And, the robot ROMEO. The robot was able to perform the same task under the same conditions as the actor'