FINITE PRANDTL NUMBER CONVECTION
WITH NEARLY INSULATING BOUNDARIES

N. RIAHI

Arbitrary Prandtl number convection in a layer with nearly
insulating boundaries is investigated. For $B^{1/3} > 3.95P$ (P is
the Prandtl number and B being the ratio between the thermal
conductivities of the boundary and of the fluid) two-dimensional
rolls are stable. The heat transported by the stable rolls
reaches its peak at a critical $P = B^{1/3}/5.77$ beyond which the
heat flux decreases with increasing P. For $B^{1/3} = 3.95P$
rolls become unstable to disturbances in the form of rolls
oriented at a right angle to the original rolls. For
$B^{1/3} < 3.95P$ square pattern convection represents the preferred
stable convection. The stable square pattern transports the
maximum amount of heat at a critical $P = B^{1/3}/3.7$.

I. Introduction

In two recent studies of finite amplitude convection in a layer with
nearly insulating boundaries Busse and Riahi [3] and Riahi [4], it was
found that for the Prandtl number P vanishingly small two-dimensional
rolls are the preferred stable convection pattern, while square pattern
convection represents the preferred stable convection for infinitely large
P . The present study is concerned with the arbitrary Prandtl number
convection case and includes a detailed analysis of the transition range

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from rolls to square cells and *vice versa*. An important result of the
present study and in sharp contrast to the corresponding problem with
isothermal boundaries (Schlüter *et al* [5]) is that the heat transported by
the preferred stable flow pattern exhibits a non-monotonicity behavior with
respect to P at a given Rayleigh number R in a low Prandtl number
fluid. The background, motivation and derivation of the governing
equations for the problem can be found in [3] and [4]. Consequently the
governing equations are derived briefly in Section II and only the
essential details of the finite amplitude convection are given and discuss
discussed in Section III.

II. Governing equations

We consider an infinite horizontal layer of fluid of depth d bounded
by two infinite half spaces with the thermal conductivity λ^e which is
assumed to be small compared to the thermal conductivity λ of the fluid.
In the steady static state, a constant heat flux traverses the system such
that the temperatures T_1 and T_2 are attained at the upper and lower
boundaries of the fluid. Under the usual Boussinesqr approximation, the
non-dimensional forms of the equations for momentum, heat and conservation
of mass can be simplified by using the general representation for the
velocity vector as the sum of the poloidal $\nabla x \nabla x \lambda v$ and toroidal $\nabla x \lambda \psi$
vectors where λ represents a unit vector in vertical direction. The
detailed analysis, though omitted here, indicates that the terms containing
ψ in the basic equations are essentially insignificant, since the toroidal
component of the velocity vector is of the order of the mth power of the
amplitude ε $(m \geq 3)$ and thus cannot enter the small amplitude analysis
discussed in this paper. Therefore, we simply set $\psi = 0$ in the basic
equations for the subsequent analysis to be discussed in the next section.
Vertical component of the double curl of the momentum equation together
with the heat equation then yield the following governing equations

(1a)
$$\nabla^4 \Delta_2 v - \Delta_2 \theta - \frac{\partial}{\partial t} \nabla^2 \Delta_2 v = \boldsymbol{\delta} \cdot (\boldsymbol{\delta} v \cdot \nabla \boldsymbol{\delta} v) \ ,$$

(1b)
$$\nabla^2 \theta - R \Delta_2 v - P \frac{\partial \theta}{\partial t} = P \boldsymbol{\delta} v \cdot \nabla \theta \ ,$$

where $\boldsymbol{\delta} = \nabla x \nabla x \lambda$, θ is the deviation of the temperature from its static

value, $R = \alpha\left(T_2 - T_1\right)gd^3\rho_0 c/\nu\lambda$ is the Rayleigh number, $p = \nu\rho_0 c\lambda^{-1}$ is the Prandtl number, ρ_0 is the reference density, c is the specific heat at constant pressure, α is the coefficient of thermal expansion, ν is the kinematic viscosity, g is acceleration due to gravity and Δ_2 is the horizontal Laplacian.

Following [3], the boundary conditions for v and θ are

(2) $$v = \frac{\partial v}{\partial z} = \frac{\partial \theta}{\partial z} \pm aB\theta = 0 \quad \text{at} \quad z = \pm\tfrac{1}{2} \ ,$$

where a is the horizontal mere number of the linear planform function

$$w(x, y) = \sum_{n=-N}^{N} c_n \exp\left(i\mathbf{k}_n\cdot\mathbf{r}\right) \ , \quad B = \lambda^e/\lambda \ , \quad \mathbf{r} \text{ is the position vector and}$$

the horizontal wave number vectors $\mathbf{k}_n$ satisfy the properties

(3) $$\mathbf{k}_n\cdot\boldsymbol{\lambda} = 0 \ , \quad \left|\mathbf{k}_n\right| = a \ , \quad \mathbf{k}_{-n} = -\mathbf{k}_n \ .$$

The coefficients c_n satisfy the conditions

(4) $$\sum_{n=-N}^{N} c_n c_n^* = 1 \ , \quad c_n^* = c_{-n} \ ,$$

where c_n^* denotes the complex conjugate of c_n. The linear planform function w and (3), (4) are now standard in thermal convection theory. The reader is referred to the recent review of the problem of thermal convection, Busse [2], for details on the subject.

III. Finite amplitude convective motion

Since the linear problem of the present study is identical to that discussed in [3], it is found again that the value a_c which minimizes R is proportional to $B^{1/3}$. Thus it is assumed that $a^2 = \eta^2\gamma$, where $\gamma \equiv B^{2/3}$ and η is of the order unity for the convection modes of physical interest. We then seek solutions in terms of a double series in powers of γ and ε :

(5) $\begin{pmatrix} v \\ \theta \end{pmatrix} = \sum_{n=0, m=1} \epsilon^m \gamma^n \begin{pmatrix} v_m^{(n)} \\ \theta_m^{(n)} \end{pmatrix}$, $R = \sum_{m,n=0} \epsilon^m \gamma^n R_m^{(n)}$.

As we mentioned above, the linear analysis has already been discussed in [3]. It was found in [3] that

(6) $\theta_1^{(0)} = w(x,\ y)$, $v_1^{(0)} = w(x,\ y) \left(z^2 - \tfrac{1}{4} \right)^2 / 4!$,

$$R_0^{(0)} = 720\ ,\quad \eta_c = (462/17)^{1/3}\ .$$

The detailed analysis of the nonlinear problem in [3] and [4] indicates that only the solutions in the orders $\epsilon^2 \gamma$ and $\epsilon^3 \gamma^2$ are needed to form the necessary solvability conditions. It was found in [3] that $\theta_2^{(1)}$ was the significant solution which was needed in the nonlinear analysis, while $v_2^{(1)}$ and $v_3^{(2)}$ were found in [4] to be significant. Keeping the necessary leading order terms in P , it is found that $\theta_2^{(1)}$ has essentially the same expression as in the case discussed in [4], except a factor of P which is resulted from the present non-dimensionalization procedure. $\theta_3^{(2)}$ is found to be insignificant, and the expressions for $v_2^{(1)}$ and $v_3^{(2)}$ are essentially the same as in the case discussed in [4]. Their expressions are lengthy and are not given here. Since we are interested in discussing the solutions for arbitrary P it is found that the expression

(7) $F = \epsilon^2 \gamma R_2^{(1)} + \epsilon^2 \gamma^2 R_2^{(2)}$

is turned out to be the largest non-zero term, in the nonlinear domain $(m > 1)$, in the expansion (5) for R . The expression for $R_2^{(1)}$ is found after forming the solvability condition for the heat equation in the order $\epsilon^3 \gamma^2$. Similarly, $R_2^{(2)}$ is found after forming the solvability condition for the heat equation in the order $\epsilon^3 \gamma^3$. After some considerable algebra, these conditions yield the following system of equations

(8) $\quad Fc_n = \dfrac{\eta\epsilon^2\gamma^2}{2^{15}.63.221} \displaystyle\sum_{m,l,p} \left(1+\phi_{lp}\right)\left[13884\phi_{lp}^2 - 24813\phi_{lp} + 76288\right]c_m c_l c_p$

$\qquad\qquad \cdot \langle w_n^* w_m w_l w_p \rangle - \dfrac{P^2\eta^2\epsilon^2\gamma}{504} \displaystyle\sum_{\substack{m,l,p \\ l\neq p}} \phi_{lp}\phi_{mn} c_m c_l c_p \langle w_n^* w_m w_l w_p \rangle + \dfrac{P^2\eta^2\epsilon^2\gamma}{16.105} c_n \; ,$

$$n = -N, \; \ldots, \; -1, \; 1, \; \ldots, \; N \; ,$$

where $\quad \phi_{mn} = \left(k_m \cdot k_n\right)a^{-2}$ and an angle bracket denotes total horizontal average. The integral expression in (8) differs from zero only if

$$-k_n + k_m + k_l + k_p = 0 \; .$$

This condition yields a much simplified set of equations

(9) $\qquad Fc_n = \dfrac{\eta\epsilon^2\gamma}{504} \displaystyle\sum_{m=-N}^{N} T_{nm}|c_m|^2 c_n \; , \quad n = -N, \; \ldots, \; -1, \; 1, \; \ldots, \; N \; ,$

where

(10) $\quad T_{nm} = \begin{cases} \dfrac{65359\gamma}{2^{12}.221} + \dfrac{4P^2\eta}{5} \quad \text{for} \quad m = \pm n \; , \\[4mm] \dfrac{\gamma}{2^{11}.221}\left(1+\phi_{mn}\right)\left[13884\phi_{mn}^2 - 24813\phi_{mn} + 76288\right] + 2P^2\eta\left(\phi_{mn}^2 + \dfrac{3}{20}\right) \\[4mm] \hspace{9cm} \text{otherwise.} \end{cases}$

Equations (9) and (4) represent an inhomogeneous system of $2N + 1$ non-linear algebraic equations for the $2N$ coefficients c_n and the expression F. The general solution of this system is not known, but a simple set of solutions can be easily derived in the regular case, in which all angles between two neighboring k-vectors are equal. The solution is simply

(11) $\quad |c_1|^2 = \ldots = |c_N|^2 = \dfrac{1}{2N} \; , \quad F = \dfrac{\eta\gamma\epsilon^2}{2^4.63N}\displaystyle\sum_{m=1}^{N} \tilde{T}_{nm} \; ,$

$$\tilde{T}_{nm} = T_{nm} + T_{n,-m} \; , \quad 1 \leq n \leq N \; .$$

This result allows us to express the heat transport H_c by convection in terms of $\left(R-R_c\right)$ for small values of the latter parameter. Using the approximate relationship

(12) $\qquad H_c \approx -\epsilon^2 \gamma \left.\dfrac{\partial \theta_2^{(1)}}{\partial z}\right|_{z=\frac{1}{2}}$, $R - R_c = F$,

we find in the case of two-dimensional rolls

(13a) $\qquad N = 1$: $\dfrac{H_c^{\text{rolls}}}{R-R_c} = 7\eta P / \left[\dfrac{326795}{2^{11}.221}\gamma + 8P^2\eta\right]$

in the case of square pattern

(13b) $\qquad N = 2$: $\dfrac{H_c^{\text{squares}}}{R-R_c} = 14\eta P / \left[\dfrac{75.14529}{2^{11}.221}\gamma + 11P^2\eta\right]$

and in the case of hexagonal pattern

(13c) $\qquad N = 3$: $\dfrac{H_c^{\text{hexagons}}}{R-R_c} = 7\eta P / \left[\dfrac{898955}{2^{10}.663}\gamma + 8P^2\eta\right]$.

It is clearly seen from (13) that, in contrast to the case discussed in
[3], rolls exhibit a higher heat transport than hexagons. For $p^2 \gg \gamma$,
square cells transport more heat than rolls. The situation is reversed for
$p^2 \ll \gamma$. For $p^2 = O(\gamma)$, we must compare (13a) and (13b). We find that
square cells transport more heat than rolls, provided

(14) $\qquad\qquad\qquad\qquad \gamma < 15.62 P^2$;

otherwise, rolls transport more heat than squares. Another interesting
result which can be derived from (13) is that the heat transport exhibits a
a non-monotonicity behavior with respect to p at a given R . For
$P \leq \gamma^{\frac{1}{2}}/5.77$, H_c^{rolls} increases with P and decreases with increasing P
in the range $P > \gamma^{\frac{1}{2}}/5.77$. Similar behavior is exhibited by H_c^{squares} .
For $P \leq \gamma^{\frac{1}{2}}/3.95$, H_c^{squares} increases with P and decreases with
increasing P in the range $P > \gamma^{\frac{1}{2}}/3.95$. As the stability analysis to be
discussed next indicate H_c^{rolls} and H_c^{squares} reach their peaks in the
ranges where rolls and squares are the stable flow patterns, respectively.
Hence the stable flow pattern, as expected, transports heat more

efficiently than the unstable ones.

To distinguish the physically realizable solution among all possible steady solutions, the stability of v, θ must be investigated. The equations for the time-dependent disturbances v, θ are given by

$$\text{(15a)} \qquad \nabla^4 \Delta_2 \tilde{v} - \Delta_2 \tilde{\theta} - \sigma \nabla^2 \Delta_2 \tilde{v} = \boldsymbol{\delta} \cdot (\boldsymbol{\delta}\tilde{v} \cdot \nabla \boldsymbol{\delta} v + \boldsymbol{\delta} v \cdot \nabla \boldsymbol{\delta}\tilde{v}) ,$$

$$\text{(15b)} \qquad \nabla^2 \tilde{\theta} - R\Delta_2 \tilde{v} - P\sigma\tilde{\theta} = P(\boldsymbol{\delta}\tilde{v} \cdot \nabla \theta + \boldsymbol{\delta} v \cdot \nabla\tilde{\theta}) ,$$

where we have introduced a growth rate σ by $\partial/\partial t = \sigma$. The equations (15) are soluved by the following expansion

$$\text{(16)} \qquad \binom{\tilde{v}}{\tilde{\theta}} = \sum_{n=1,m=0} \varepsilon^{n-1}\gamma^m \begin{pmatrix} \tilde{v}_n^{(m)} \\ \tilde{\theta}_n^{(m)} \end{pmatrix} , \quad \sigma = \sum_{n,m=0} \varepsilon^n \gamma^m \sigma_n^{(m)} .$$

As in [3], the investigation of the order $\varepsilon^0 \gamma^m$ of (15) yields $\sigma_0^{(m)} \leq 0$ if $\eta = \eta_c$. Restricting the attention to the most dangerous disturbances, we assume $\sigma_0^{(m)} = 0$. Using the representation

$$\text{(17)} \qquad \tilde{w}(x, y) = \sum_{n=-\infty}^{\infty} \tilde{c}_n \exp(\dot{\overline{\imath}} \mathbf{k}_n \cdot \mathbf{r})$$

for the horizontal dependence of the general three-dimensional disturbance, we consider (15) in higher orders of ε . The possibility of a non-vanishing positive coefficient(s) $\sigma_n^{(m)}$ appears first in the order $\varepsilon^2\gamma^2$, where the solvability condition yields the following systems of equations

$$\text{(18a)} \qquad PG\tilde{c}_n + \left[\frac{11\varepsilon^2\gamma^2}{2^6 . 3^3 . 85}\right] \sum_{m=-N}^{N} \tilde{T}_{nm} c_m^* \tilde{c}_m c_n = 0 ,$$

where

$$\text{(18b)} \qquad G = \varepsilon^2\gamma^2\sigma_2^{(2)} + \varepsilon^2\gamma^3\sigma_2^{(3)} .$$

Following Schlüter *et al* [5], it follows that N eigenvalues G of the characteristic equation for the system (18) are zero. Restricting our attention to regular solutions satisfying (11) and following [3], we find that all the solutions with $N \geq 3$ are unstable. Discarding the N

eigenvalues $G = 0$, the characteristic equation for (18) can be written in the form

(19) $\qquad \text{Det}\left|PG\delta_{nm}+\tilde{T}_{nm}c_m^*c_n\right| = 0$, $\quad n, m = 1, \ldots, N$.

For $N = 1$, the root G of the equation (19) is negative. For square pattern, the steady motion is stable only if

(20) $\qquad\qquad\qquad\qquad\qquad \tilde{T}_{11} \geq \tilde{T}_{12} > 0$.

Using (10), we find that (20) holds only when the condition (14) (with the sign < replaced by $\leq$) is satisfied.

So far the analysis was restricted to disturbances whose wave number vectors were coincided with those of the steady motion. We now examine the stability of the steady motion with respect to disturbances whose wave number vectors are not coincided with the basic vectors of steady motion. Defining a disturbance vector $\mathbf{k}_r$, the expression for the maximum growth rate G in the case $N = 1$ leads to the following equation

(21) $\qquad PG = \dfrac{11\epsilon^2\gamma^2}{2^7.3^3.85}\left[P^2\eta\left(1-4\phi_{1r}^2\right) + \dfrac{\gamma}{2^{11}.221}\left(21858\phi_{1r}^2-87217\right)\right]$.

It is readily seen from (21) that the maximum positive eigenvalue G is obtained when (14) holds and $\phi_{1r} = 0$ implying that rolls are unstable to disturbances in the form of rolls oriented at a right angle to the original rolls. Hence as $\gamma \to 15.62P^2$ there is a pattern transformation from rolls to squares or *vice versa*. The result that the preferred stable flow pattern is squares or rolls depending on whether (14) holds or not implies that the realized convection pattern transports maximum amount of heat at least in the weakly non-linear regime. This result has already been shown to hold in a layer with isothermal boundaries [1]. It is expected that in the strongly non-linear convection regime the flow field still has the tendency to maximize the heat transport.

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Department of Theoretical and Applied Mechanics,
College of Engineering,
University of Illinois at Urbana-Champaign,
Urbana,
Illinois 61801,
USA.