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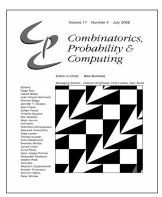


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# Ergodic theory and dynamical systems

### VOLUME 30 PART 2 APRIL 2010

### **CONTENTS**

Austin, 1. On the norm convergence of non-conventional ergodic	
averages	321
Bautista, S. and Morales, C. A sectional-Anosov connecting lemma	339
Begun, B. and del Junco, A. Partitions with independent iterates in random dynamical systems	361
Calta, K. and Wortman, K. On unipotent flows in $\mathcal{H}(1,1)$	379
Elekes, M., Keleti, T. and Máthé, A. Self-similar and self-affine sets: measure of the intersection of two copies	399
Gogolev, A. Diffeomorphisms Hölder conjugate to Anosov diffeomorphisms	441
Ji, L. and Weber, A. Dynamics of the heat semigroup on symmetric spaces	457
Jiang, Y. and Ye, YL. Ruelle operator theorem for non-expansive systems	469
Julien, A. Complexity and cohomology for cut-and-projection tilings	
Kittrell, J. and Tsankov, T. Topological properties of full groups	525
Liu, C. Strong bounded operators for ergodic averages and Lebesgue derivatives	547
Aliste-Prieto, J. Translation numbers for a class of maps on the dynamical systems arising from quasicrystals in the real line	565
Rempe, L. The escaping set of the exponential	595
Sumi, H. and Urbański, M. Real analyticity of Hausdorff dimension for expanding rational semigroups	601

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