

LECTURE NOTES

An introductory guide to fluid models with anisotropic temperatures. Part 2. Kinetic theory, Padé approximants and Landau fluid closures

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In Part 2 of our guide to collisionless fluid models, we concentrate on Landau fluid closures. These closures were pioneered by Hammett and Perkins and allow for the rigorous incorporation of collisionless Landau damping into a fluid framework. It is Landau damping that sharply separates traditional fluid models and collisionless kinetic theory, and is the main reason why the usual fluid models do not converge to the kinetic description, even in the long-wavelength low-frequency limit. We start with a brief introduction to kinetic theory, where we discuss in detail the plasma dispersion function $Z(\zeta)$, and the associated plasma response function $R(\zeta) = 1 + \zeta Z(\zeta) = -Z'(\zeta)/2$. We then consider a one-dimensional (1-D) (electrostatic) geometry and make a significant effort to map all possible Landau fluid closures that can be constructed at the fourth-order moment level. These closures for parallel moments have general validity from the largest astrophysical scales down to the Debye length, and we verify their validity by considering examples of the (proton and electron) Landau damping of the ion-acoustic mode, and the electron Landau damping of the Langmuir mode. We proceed by considering 1-D closures at higher-order moments than the fourth order, and as was concluded in Part 1, this is not possible without Landau fluid closures. We show that it is possible to reproduce linear Landau damping in the fluid framework to any desired precision, thus showing the

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convergence of the fluid and collisionless kinetic descriptions. We then consider a 3-D (electromagnetic) geometry in the gyrotropic (long-wavelength low-frequency) limit and map all closures that are available at the fourth-order moment level. In appendix A, we provide comprehensive tables with Padé approximants of $R(\zeta)$ up to the eighth-pole order, with many given in an analytic form.

Key words: astrophysical plasmas, space plasma physics, plasma waves

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1. Introduction

The incorporation of kinetic effects, such as Landau damping, into a fluid description naturally requires some knowledge of kinetic theory. There are many excellent plasma physics books available, for example Akhiezer *et al.* (1975), Swanson (1989), Stix (1992), Gary (1993), Gurnett & Bhattacharjee (2005), Fitzpatrick (2015) and many others. These books cover numerous topics in kinetic theory that need to be addressed, if a plasma physics book wants to be considered complete. However, the topics that are required for the construction of advanced fluid models are often covered only briefly, or not covered at all. For example, the Padé approximation of the Maxwellian plasma dispersion function $Z(\zeta)$ or the plasma response function $R(\zeta) = 1 + \zeta Z(\zeta)$, which is a crucial technique for the construction of collisionless fluid closures valid for all ζ , is not addressed by any of the cited plasma books.

A researcher interested in collisionless fluid models that incorporate kinetic effects has to follow for example Hammett & Perkins (1990), Hammett, Dorland & Perkins (1992), Snyder, Hammett & Dorland (1997), Passot & Sulem (2003), Goswami, Passot & Sulem (2005), Passot & Sulem (2006, 2007), Passot, Sulem & Hunana (2012), Sulem & Passot (2015) and references therein. The first three cited references are written in the guiding-centre reference frame (gyrofluid), which is a very powerful approach that enables the derivation of many results in an elegant way. However, the calculations in guiding-centre coordinates can be very difficult to follow. The other cited references are written in the usual laboratory reference frame (Landau fluid), but, the kinetic effects considered are of an even higher degree of complexity and

the papers can be very difficult to follow as well. There are other subtle differences between gyrofluids and Landau fluids and the vocabulary is not strictly enforced.

Additionally, the cited papers assume that the reader is already fully familiar with the nuances of the kinetic description, such as the definition of the plasma dispersion function $Z(\zeta)$ and the very confusing sign of the parallel wavenumber $\text{sign}(k_{\parallel})$, that almost every plasma book appears to treat slightly differently. This guide, which is a companion paper to ‘An introductory guide to fluid models with anisotropic temperatures. Part 1. CGL description and collisionless fluid hierarchy’, attempts to be a simple introductory paper to the collisionless fluid models, and we focus on the Landau fluid approach. The text is designed to be read as ‘lecture notes’, and may be regarded as a detailed exposition of Hunana *et al.* (2018). We focus on collisionless closures and use a technique pioneered by Hammett & Perkins (1990). Alternative approaches, including incorporation of collisional effects, were presented for example by Joseph & Dimits (2016), Ji & Joseph (2018), Jorge *et al.* (2019), Chen, Xu & Lei (2019), Wang *et al.* (2019) and references therein.

In §2, we introduce kinetic theory briefly, and we consider only aspects that are necessary for the construction of advanced fluid models that contain Landau damping. We focus on the integral $\int e^{-x^2}/(x-x_0) dx$ that we call the Landau integral, see figure 1. We discuss how this integral is expressed through the plasma dispersion function $Z(\zeta)$ and we discuss in detail the perhaps only technical (but very important) difference between defining $\zeta = \omega/(k_{\parallel}v_{\text{th}})$ and $\zeta = \omega/(|k_{\parallel}|v_{\text{th}})$. Only the latter choice allows one to use the original plasma dispersion function of Fried & Conte (1961), and the former choice requires that the $Z(\zeta)$ is redefined.

In §3, we consider a one-dimensional (1-D) electrostatic geometry. We discuss the concept of the Padé approximation to the plasma dispersion function $Z(\zeta)$ and the plasma response function $R(\zeta)$. We introduce a new classification scheme for approximants $R_{n,n'}(\zeta)$ that we believe is slightly more natural than the classification scheme introduced by Martín, Donoso & Zamudio-Cristi (1980) or the scheme of Hedrick & Leboeuf (1992). Nevertheless, we provide conversion relations that allow to convert one notation into the other. We verify the numerical values in table 1 of Hedrick & Leboeuf (1992) analytically and find a typo in one coefficient of the quite important $Z_{3,1}(\zeta)$ approximant previously used to construct closures. In figures 2 and 3 we compare precision of various approximants $R_{n,n'}(\zeta)$ with the exact $R(\zeta)$. We proceed by mapping all plausible Landau fluid closures that can be constructed at the level of fourth-order moment. For a brief summary of possible closures, see (3.241)–(3.242). For the sake of clarity, all closures are provided in Fourier space as well as in real space. Writing the closures in real space emphasizes the non-locality of collisionless closures, since all closures contain the Hilbert transform, which in real space should be calculated correctly by integration along the magnetic field lines. As discussed in detail by Passot *et al.* (2014), neglecting the distortion of magnetic field lines and calculating the Hilbert transform with respect to mean magnetic field B_0 can lead to spurious instabilities. We compare the precision of the obtained closures by calculating the dispersion relation of the ion-acoustic mode at wavelengths that are much longer than the Debye length. For some closures, an interesting property is observed in that the resulting fluid dispersion relation is analytically equivalent to the kinetic dispersion relation, once $R(\zeta)$ is replaced by the $R_{n,n'}(\zeta)$ approximant, and such closures are viewed as ‘reliable’, or physically meaningful. Subsequently, all unreliable closures were eliminated; see the discussion below (3.242). The closure with the highest power series precision is the $R_{5,3}(\zeta)$ closure.

We note that electron Landau damping of the ion-acoustic mode can be correctly captured, even if the electron inertia in the electron momentum equation is neglected (the ratio m_e/m_p still enters the electron heat flux and the fourth-order moment \tilde{r}). The dispersion relation of such a fluid model is of course not analytically equivalent to the kinetic dispersion relation (after $R(\zeta)$ is replaced by the $R_{n,n'}(\zeta)$), however, such a fluid model provides great benefit for direct numerical simulations, since the electron motion does not have to be resolved. In figure 5 we plot solutions for selected fluid models without the electron inertia. In figure 6, the electron inertia is retained, and we replot the fluid model with the $R_{5,3}(\zeta)$ closure to show that the differences are negligible. We also plot additional closures and discuss a regime where the electron temperature is much larger than the proton temperature, and where closures with higher asymptotic precision yield better accuracy. We then investigate the precision of the obtained closures by using the example of the Langmuir mode, see figures 7 and 8. These calculations were only noted but not presented in Hunana *et al.* (2018).

The case of 1-D geometry is then pursued further, and selected closures with fifth-order and sixth-order moments are constructed. For an impatient reader, the entire text can be perhaps summarized with figure 9, where the Landau damping of the ion-acoustic mode is plotted for dynamic closures with the highest power-series precision that can be constructed at a given fluid moment level. For the third-order moment (the heat flux) it is $R_{4,2}(\zeta)$, for the fourth-order moment it is $R_{5,3}(\zeta)$, for the fifth-order moment it is $R_{6,4}(\zeta)$ and for the sixth-order moment it is $R_{7,5}(\zeta)$ (we also briefly checked that for the seventh-order moment it will be $R_{8,6}(\zeta)$). In figure 10, we also plot solutions for the Langmuir mode with the $R_{7,5}(\zeta)$ closure. Additionally, it was verified that all these closures are ‘reliable’.

The remarkable result that the reliable 1-D closures reproduce the exact kinetic dispersion relation once $R(\zeta)$ is replaced by $R_{n,n'}(\zeta)$ leads us to the conjecture that there exist reliable fluid closures that can be constructed for even higher-order moments, i.e. satisfying the kinetic dispersion relation exactly, once $R(\zeta)$ is replaced by the $R_{n,n'}(\zeta)$ approximant. Furthermore, for a given n th-order fluid moment, the reliable closure with the highest power-series precision is the dynamic closure constructed with $R_{n+1,n-1}(\zeta)$. Indeed, for higher-order fluid moments one should be able to construct closures with higher-order $R_{n+1,n-1}(\zeta)$ approximants that will converge to $R(\zeta)$ with increasing precision. Thus, one can reproduce the linear Landau damping in the fluid framework to any desired precision, which establishes the convergence of fluid and kinetic descriptions.

In §4, we consider a 3-D electromagnetic geometry in the gyrotropic limit, and map all plausible Landau fluid closures at the fourth-order moment level. In a 3-D electromagnetic geometry, the most difficult part of the calculations actually consists in obtaining the perturbed distribution function $f^{(1)}$, since in the laboratory reference frame that we use here, one needs to first calculate the fully kinetic integration around the unperturbed orbit. Only then can the correct gyrotropic limit (where the gyroradius and the frequency ω are small) be obtained. The integration around the unperturbed orbit can be found in many plasma books, and can be found in appendix C. An alternative and very illuminating derivation of $f^{(1)}$ is obtained by using the guiding-centre reference frame. By writing the collisionless Vlasov equation in the guiding-centre limit and by prescribing from the beginning that the magnetic moment has to be conserved at the leading order, the same $f^{(1)}$ is obtained in a perhaps more intuitive way. The various terms in $f^{(1)}$ can be identified with the conservation of the magnetic moment, the electrostatic Coulomb force (which yields Landau damping) and the magnetic mirror force (which yields transit-time damping). Usually Landau

damping and its magnetic analogue, transit-time damping, are summarily described as Landau damping, and we note that 3-D Landau fluid models contain both of these collisionless damping mechanisms.

We show that the closures for the q_{\parallel} and $\tilde{r}_{\parallel\parallel}$ moments are the same as for the q and \tilde{r} moments in a 1-D geometry. The closure for $\tilde{r}_{\perp\perp}$ in the gyrotopropic limit is simply $\tilde{r}_{\perp\perp} = 0$. One therefore needs to consider only closures for the q_{\perp} and $\tilde{r}_{\parallel\perp}$ moments. For a summary of the q_{\perp} and $\tilde{r}_{\parallel\perp}$ closures, see (4.145)–(4.146). We did not compare the dispersion relation of the resulting fluid models with the fully kinetic dispersion relation in the gyrotopropic limit and therefore we cannot conclude which closures are ‘reliable’. Nevertheless, by briefly considering parallel propagation along B_0 , one closure was eliminated since it produced a growing higher-order mode. There is only one static closure available for the perpendicular heat flux q_{\perp} , which is constructed with the $R_1(\zeta)$ approximant. As discussed later in the appendix A, the simple $R_1(\zeta) = 1/(1 - i\sqrt{\pi}\zeta)$ is a quite imprecise approximant of $R(\zeta)$. This has the important implication that 3-D Landau fluid simulations should not be performed with static heat fluxes, and time-dependent heat flux equations have to be considered. The closure with the highest power-series precision for $\tilde{r}_{\parallel\perp}$ in the gyrotopropic limit is constructed with $R_{3,0}(\zeta)$. In appendix A, we provide tables of Padé approximants of $R(\zeta)$ up to the eight-pole approximation, and many solutions are provided in an analytic form.

2. A brief introduction to kinetic theory

In this section we introduce some building blocks of kinetic theory starting from the simple case of wave propagation along a mean magnetic field B_0 in a homogeneous plasma. Such an approach allows us to introduce the plasma dispersion function and the hierarchy of linearized kinetic moments, preparing the ground for the next section where various hierarchy closures will be described in detail. The collisionless Vlasov equation in CGS units reads

$$\frac{\partial f_r}{\partial t} + \mathbf{v} \cdot \nabla f_r + \frac{q_r}{m_r} \left(\mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{B} \right) \cdot \nabla_v f_r = 0. \quad (2.1)$$

It is often illuminating to work in the cylindrical coordinate system, where the particle velocity $\mathbf{v} = (v_x, v_y, v_z)$ is expressed as

$$\mathbf{v} = \begin{pmatrix} v_{\perp} \cos \phi \\ v_{\perp} \sin \phi \\ v_{\parallel} \end{pmatrix}, \quad (2.2)$$

and the gyrating (azimuthal) angle $\phi = \arctan(v_y/v_x)$. The reason is that it very nicely clarifies the meaning of gyrotopropy, where the distribution function and the expressions that follow are independent of the angle ϕ . The velocity gradient in the cylindrical coordinate system reads

$$\nabla_v = \hat{\mathbf{v}}_{\perp} \frac{\partial}{\partial v_{\perp}} + \hat{\boldsymbol{\phi}} \frac{1}{v_{\perp}} \frac{\partial}{\partial \phi} + \hat{\mathbf{v}}_{\parallel} \frac{\partial}{\partial v_{\parallel}}, \quad (2.3)$$

where the unit vectors

$$\hat{\mathbf{v}}_{\perp} = \begin{pmatrix} \cos \phi \\ \sin \phi \\ 0 \end{pmatrix}; \quad \hat{\boldsymbol{\phi}} = \begin{pmatrix} -\sin \phi \\ \cos \phi \\ 0 \end{pmatrix}; \quad \hat{\mathbf{v}}_{\parallel} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \quad (2.4)$$

so the velocity gradient is

$$\nabla_v = \begin{pmatrix} \cos \phi \frac{\partial}{\partial v_\perp} - \frac{\sin \phi}{v_\perp} \frac{\partial}{\partial \phi} \\ \sin \phi \frac{\partial}{\partial v_\perp} + \frac{\cos \phi}{v_\perp} \frac{\partial}{\partial \phi} \\ \frac{\partial}{\partial v_\parallel} \end{pmatrix}. \quad (2.5)$$

A straightforward calculation with $\mathbf{B}_0 = (0, 0, B_0)$ yields

$$\mathbf{v} \times \mathbf{B}_0 = B_0 \begin{pmatrix} v_\perp \sin \phi \\ -v_\perp \cos \phi \\ 0 \end{pmatrix}, \quad (2.6)$$

which further implies

$$\begin{aligned} (\mathbf{v} \times \mathbf{B}_0) \cdot \nabla_v &= v_\perp \sin \phi B_0 \left(\cos \phi \frac{\partial}{\partial v_\perp} - \frac{\sin \phi}{v_\perp} \frac{\partial}{\partial \phi} \right) \\ &\quad - v_\perp \cos \phi B_0 \left(\sin \phi \frac{\partial}{\partial v_\perp} + \frac{\cos \phi}{v_\perp} \frac{\partial}{\partial \phi} \right) \\ &= -B_0 \sin^2 \phi \frac{\partial}{\partial \phi} - B_0 \cos^2 \phi \frac{\partial}{\partial \phi} = -B_0 \frac{\partial}{\partial \phi}. \end{aligned} \quad (2.7)$$

Now we need to expand the Vlasov equation (2.1) around some equilibrium distribution function f_0 , i.e. the entire distribution function is separated to two parts as $f = f_0 + f^{(1)}$. For the distribution function, we drop the species index r . The magnetic field is separated as $\mathbf{B} = \mathbf{B}_0 + \mathbf{B}^{(1)}$, where $\mathbf{B}_0 = B_0 \hat{\mathbf{z}}$, and the electric field as $\mathbf{E} = \mathbf{E}_0 + \mathbf{E}^{(1)}$, but since there is no large-scale electric field in the system, $\mathbf{E}_0 = 0$.

The most important principle that is usually not emphasized enough, is that the kinetic velocity \mathbf{v} is an independent quantity, and is not linearized. The entire Vlasov equation reads

$$\frac{\partial(f_0 + f^{(1)})}{\partial t} + \mathbf{v} \cdot \nabla(f_0 + f^{(1)}) + \frac{q_r}{m_r} \left[\mathbf{E}^{(1)} + \frac{1}{c} \mathbf{v} \times (\mathbf{B}_0 + \mathbf{B}^{(1)}) \right] \cdot \nabla_v(f_0 + f^{(1)}) = 0, \quad (2.8)$$

or equivalently by using the r -species cyclotron frequency $\Omega_r = q_r B_0 / (m_r c)$

$$\begin{aligned} \frac{\partial(f_0 + f^{(1)})}{\partial t} + \mathbf{v} \cdot \nabla(f_0 + f^{(1)}) + \frac{q_r}{m_r} \mathbf{E}^{(1)} \cdot \nabla_v(f_0 + f^{(1)}) \\ + \Omega_r \left[\mathbf{v} \times \left(\hat{\mathbf{z}} + \frac{\mathbf{B}^{(1)}}{B_0} \right) \right] \cdot \nabla_v(f_0 + f^{(1)}) = 0. \end{aligned} \quad (2.9)$$

The Vlasov equation is now expanded (i.e. linearized) by assuming that the '(1)' components are small, and that terms containing 2 small '(1)' quantities can be neglected. At the leading order, the situation is similar as many times before, i.e. at very low frequencies ($\omega \ll \Omega_r$) and very long spatial scales, the term proportional to Ω_r dominates and must be by itself equal to zero

$$\frac{q_r}{m_r c} (\mathbf{v} \times \mathbf{B}_0) \cdot \nabla_v f_0 = 0; \quad \Rightarrow \quad \Omega_r \frac{\partial}{\partial \phi} f_0 = 0, \quad (2.10)$$

where in the last step we used already calculated identity (2.7). The obtained result implies that at the longest spatial scales, the distribution function cannot depend on the azimuthal angle ϕ , or in another words, the distribution function must be isotropic in the perpendicular velocity components and can depend only on $v_x^2 + v_y^2 = v_\perp^2$, i.e. the distribution function must be gyrotropic. The second most important principle for doing the linear kinetic hierarchy is to realize that the hierarchy is linear, and all the quantities will have to be linearized. Additionally, we are interested only in a simplified case where the plasma is perturbed around a homogeneous equilibrium state, and we can assume that the equilibrium f_0 does not depend on time and position, so that $\partial f_0/\partial t = 0$ and $\nabla f_0 = 0$. Therefore, the distribution f_0 contains only density n_0 that is not (t, \mathbf{x}) dependent, or in another words $f(\mathbf{x}, \mathbf{v}, t) = f_0(\mathbf{v}) + f^{(1)}(\mathbf{x}, \mathbf{v}, t)$. Perhaps a different way of looking at it is that the f_0 must satisfy the leading-order Vlasov equation

$$\frac{\partial f_0}{\partial t} + \mathbf{v} \cdot \nabla f_0 + \frac{q_r}{m_r} \left[\mathbf{E}_0 + \frac{1}{c} \mathbf{v} \times \mathbf{B}_0 \right] \cdot \nabla_v f_0 = 0, \quad (2.11)$$

which at long spatial scales and low frequencies further implies gyrotropy (2.10) and $\mathbf{E}_0 = 0$, together with $\partial f_0/\partial t + \mathbf{v} \cdot \nabla f_0 = 0$.

Terms that contain 2 small (1) quantities in (2.8) can be neglected, and putting the $f^{(1)}$ contributions to the left-hand side and the f_0 contributions to the right-hand side yields

$$\frac{\partial f^{(1)}}{\partial t} + \mathbf{v} \cdot \nabla f^{(1)} + \frac{q_r}{m_r c} (\mathbf{v} \times \mathbf{B}_0) \cdot \nabla_v f^{(1)} = -\frac{q_r}{m_r} \left[\mathbf{E}^{(1)} + \frac{1}{c} \mathbf{v} \times \mathbf{B}^{(1)} \right] \cdot \nabla_v f_0. \quad (2.12)$$

This is the starting equation that expresses $f^{(1)}$ with respect to f_0 and that is used in plasma physics books to derive the kinetic dispersion relation for waves in hot magnetized plasmas. The second term on the left-hand side $\mathbf{v} \cdot \nabla f^{(1)}$, introduces the simplest forms of Landau damping. The most complicated term, by far, is the third term $\Omega_r (\mathbf{v} \times \mathbf{B}_0/B_0) \cdot \nabla_v f^{(1)}$, since it introduces non-gyrotropic $f^{(1)}$ effects. This term introduces the complicated integration around the unperturbed orbit with associated sums over expressions containing Bessel functions, that are found in the full kinetic dispersion relations. It is this third term that makes the collisionless damping (and the kinetic theory) a very complicated process, even at the linear level. Without this third term, life would much easier, and Landau fluid models would be an excellent match for a full kinetic description, at least at the linear level.

The third term is obviously equal to zero if the $f^{(1)}$ distribution function is assumed to be strictly gyrotropic (see (2.7)). Or, we can just neglect the term by hand, assuming that we are at low frequencies and that $\omega \ll \Omega$, meaning, if we apply an ‘overly strict’ and slightly *ad hoc* performed low-frequency limit. However, as we will see later in the 3-D geometry section, it turns out that even if a strictly gyrotropic $f^{(1)}$ is assumed, the third term cannot be just eliminated from the onset. To obtain the correct $f^{(1)}$ in the gyrotropic limit the third term has to be retained and the integration around the unperturbed orbit performed. Only then can the term be eliminated in a limit. It is emphasized that the sophisticated Landau fluid models of Passot & Sulem (2007), that we do not address here, do not neglect this third term and these models do not assume the $f^{(1)}$ to be gyrotropic. It is exactly the deviations from gyrotropy that introduce the Bessel functions found in kinetic theory and sophisticated Landau fluid models.

Now, for a moment we do not perform any calculations, and just reformulate the important equation (2.12). The first-order fields are typically transformed to Fourier space ($\sim e^{ik \cdot x - i\omega t}$), but we will postpone that for now. By defining the operator

$$\frac{D}{Dt} \equiv \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla + \frac{q_r}{m_r c} (\mathbf{v} \times \mathbf{B}_0) \cdot \nabla_v, \quad (2.13)$$

that represents a rate of change along an unperturbed orbit (zero-order trajectory), the equation is rewritten as

$$\frac{Df^{(1)}}{Dt} = -\frac{q_r}{m_r} \left[\mathbf{E}^{(1)} + \frac{1}{c} \mathbf{v} \times \mathbf{B}^{(1)} \right] \cdot \nabla_v f_0. \quad (2.14)$$

To obtain the $f^{(1)}$, one therefore has to calculate the integral of the above equation, where also the integration of the right-hand side must be naturally done along the zero-order trajectory (along the unperturbed orbit) in order to cancel the d/dt on the left-hand side. The integration is denoted with prime quantities, and the integral is performed along dt' . If the integral is performed from time $t' = t_0$ to $t' = t$, the integration of the left-hand side yields $f^{(1)}(\mathbf{x}, \mathbf{v}, t) - f^{(1)}(\mathbf{x}, \mathbf{v}, t_0)$, i.e. the result depends on the initial condition at time t_0 . To remove this dependence, the integral is performed from $t_0 = -\infty$ and it is typically stated that, in this case, the initial condition $f^{(1)}(\mathbf{x}, \mathbf{v}, -\infty)$ can be neglected. (This is however not that obvious and, for example, Stix have a rather long discussion in this regard on page 249). The distribution function $f^{(1)}(\mathbf{x}, \mathbf{v}, t)$ is therefore obtained by performing the integral

$$f^{(1)}(\mathbf{x}, \mathbf{v}, t) = -\frac{q_r}{m_r} \int_{-\infty}^t \left[\mathbf{E}^{(1)}(\mathbf{x}', t') + \frac{1}{c} \mathbf{v}' \times \mathbf{B}^{(1)}(\mathbf{x}', t') \right] \cdot \nabla_{v'} f_0(\mathbf{v}') dt'. \quad (2.15)$$

The calculation of this integral is cumbersome because of the required change of coordinates. We want to get the final $f^{(1)}$ expression and we will repeat the algebra concerning how to obtain it, but before doing that, let us consider the simplest possible case.

2.1. The simplest case: 1-D geometry, Maxwellian f_0

Let us consider a particular situation, when (for whatever reason) the third term on the left-hand side of equation (2.12) disappears, i.e. let us briefly consider

$$(\mathbf{v} \times \mathbf{B}_0) \cdot \nabla_v f^{(1)} = 0, \quad (2.16)$$

which according to (2.10) implies that $f^{(1)}$ is gyrotropic (it does not depend on the angle ϕ). Let us also consider the even more special case in which f_0 is isotropic. In such a case, that is a specific case of (2.16), the direction of $\mathbf{B}^{(1)}$ does not matter at all for f_0 and naturally

$$(\mathbf{v} \times \mathbf{B}^{(1)}) \cdot \nabla_v f_0 = 0. \quad (2.17)$$

To quickly double check the correctness of the above expression, for isotropic $f_0(v)$ the velocity gradient is given by $\partial f_0 / \partial v_i = (\partial f_0 / \partial v)(\partial v / \partial v_i) = f_0' v_i / v$ and the velocity gradient $\nabla_v f_0 = f_0' \hat{\mathbf{v}}$ is in the direction of velocity \mathbf{v} . The result (2.17) then immediately follows since $\epsilon_{ijk} v_j B_k^{(1)} v_i = 0$. The equation (2.12) therefore reduces to

$$\frac{\partial f^{(1)}}{\partial t} + \mathbf{v} \cdot \nabla f^{(1)} = -\frac{q_r}{m_r} \mathbf{E}^{(1)} \cdot \nabla_v f_0. \quad (2.18)$$

Fourier transforming the first-order quantities and $\partial/\partial t \rightarrow -i\omega$, $\nabla \rightarrow i\mathbf{k}$ yields

$$(-i\omega + i\mathbf{v} \cdot \mathbf{k})f^{(1)} = -\frac{q_r}{m_r} \mathbf{E}^{(1)} \cdot \nabla_v f_0, \tag{2.19}$$

which allows us to obtain an expression for $f^{(1)}$ in the form

$$f^{(1)} = -i \frac{q_r}{m_r} \frac{\mathbf{E}^{(1)} \cdot \nabla_v f_0}{\omega - \mathbf{v} \cdot \mathbf{k}}. \tag{2.20}$$

Even though it is not necessary, it is useful to express the (electrostatic) electric field through the scalar potential $\mathbf{E}^{(1)} = -\nabla\Phi$, which in Fourier space reads $\mathbf{E}^{(1)} = -i\mathbf{k}\Phi$, yielding

$$f^{(1)} = -\frac{q_r}{m_r} \Phi \frac{\mathbf{k} \cdot \nabla_v f_0}{\omega - \mathbf{v} \cdot \mathbf{k}}. \tag{2.21}$$

Now, we want to integrate $f^{(1)}$, and obtain the linear ‘kinetic’ moments for density, velocity (current), pressure (temperature), heat flux and the fourth-order moment r (or the correction \tilde{r}). To continue, we have to prescribe some distribution function f_0 .

The 3-D (isotropic) Maxwellian distribution is

$$f_{0r} = n_{0r} \left(\frac{\alpha_r}{\pi}\right)^{3/2} e^{-\alpha_r v^2}, \tag{2.22}$$

where the isotropic $v^2 = v_x^2 + v_y^2 + v_z^2$ and $\alpha_r = m_r/(2T_r^{(0)}) = 1/v_{\text{th}r}^2$. For simplicity, let us drop the species index r , except for the charge q_r . The velocity gradient

$$\begin{aligned} \frac{\partial f_0}{\partial v_i} &= n_0 \left(\frac{\alpha}{\pi}\right)^{3/2} (-\alpha) 2v_i e^{-\alpha v^2} = -2\alpha v_i f_0 = -\frac{m}{T^{(0)}} v_i f_0, \\ \nabla_v f_0 &= -\frac{m}{T^{(0)}} \mathbf{v} f_0. \end{aligned} \tag{2.23}$$

Therefore, for a Maxwellian

$$f^{(1)} = +\frac{q_r}{T^{(0)}} \Phi \frac{\mathbf{k} \cdot \mathbf{v}}{\omega - \mathbf{v} \cdot \mathbf{k}} f_0. \tag{2.24}$$

Before continuing, let us slightly rearrange the above expression for $f^{(1)}$ and add $0 = \omega - \omega$ to the numerator, otherwise we will have to do this each time, when calculating the higher-order moments. The rearrangement yields

$$f^{(1)} = +\frac{q_r}{T^{(0)}} \Phi \frac{\mathbf{k} \cdot \mathbf{v} - \omega + \omega}{\omega - \mathbf{v} \cdot \mathbf{k}} f_0 = -\frac{q_r}{T^{(0)}} \Phi \left(1 + \frac{\omega}{\mathbf{v} \cdot \mathbf{k} - \omega}\right) f_0. \tag{2.25}$$

For clarity, let us simplify even further and discuss the simplest possible 1-D case, for a 1-D Maxwellian distribution

$$f_0 = n_0 \sqrt{\frac{\alpha}{\pi}} e^{-\alpha v^2}; \quad \text{where } \alpha \equiv \frac{m}{2T^{(0)}} = \frac{1}{v_{\text{th}}^2}. \tag{2.26}$$

Here we consider fluctuations along the magnetic field B_0 and the wavenumber is therefore denoted as k_{\parallel} . Note that the case is strictly one-dimensional, and the velocity

fluctuations are along the B_0 as well. For example from the MHD perspective, we are therefore considering the parallel propagating ion-acoustic mode. The $f^{(1)}$ for a Maxwellian f_0 is expressed as (dropping all the species indices 'r' except for the charge q_r)

$$f^{(1)} = i \frac{q_r}{T^{(0)}} E^{(1)} \frac{v}{\omega - vk_{\parallel}} f_0, \quad (2.27)$$

$$f^{(1)} = -\frac{q_r}{T^{(0)}} \Phi \left(1 + \frac{\frac{\omega}{k_{\parallel}}}{v - \frac{\omega}{k_{\parallel}}} \right) f_0. \quad (2.28)$$

Now, we are ready to calculate the velocity integrals. Let us start with the density $n^{(1)}$, by integrating

$$n^{(1)} = \int_{-\infty}^{\infty} f^{(1)} dv = -\frac{q_r}{T^{(0)}} \Phi \left(\underbrace{\int_{-\infty}^{\infty} f_0 dv}_{=n_0} + \int_{-\infty}^{\infty} \frac{\frac{\omega}{k_{\parallel}} f_0}{v - \frac{\omega}{k_{\parallel}}} dv \right). \quad (2.29)$$

By using the prescribed Maxwellian f_0 , the second integral is rewritten as

$$\begin{aligned} \int_{-\infty}^{\infty} \frac{\frac{\omega}{k_{\parallel}} f_0}{v - \frac{\omega}{k_{\parallel}}} dv &= n_0 \sqrt{\frac{\alpha}{\pi}} \frac{\omega}{k_{\parallel}} \int_{-\infty}^{\infty} \frac{e^{-\alpha v^2}}{v - \frac{\omega}{k_{\parallel}}} dv \\ &= \left[\begin{array}{l} \sqrt{\alpha} v = x \\ \sqrt{\alpha} dv = dx \end{array} \right] = n_0 \sqrt{\frac{\alpha}{\pi}} \frac{\omega}{k_{\parallel}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel}} \sqrt{\alpha}} dx = \left[\frac{\omega}{k_{\parallel}} \sqrt{\alpha} \equiv x_0 \right] \\ &= \frac{n_0}{\sqrt{\pi}} x_0 \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx. \end{aligned} \quad (2.30)$$

The notation $[\dots]$ just indicates change of a variable. We purposely wrote the integral with

$$x_0 \equiv \frac{\omega}{k_{\parallel}} \sqrt{\alpha} = \frac{\omega}{k_{\parallel} v_{\text{th}}}, \quad (2.31)$$

instead of the usual ζ , since we want to define ζ slightly differently. The integral is related to the famous plasma dispersion function $Z(\zeta)$, that is responsible for the famous Landau damping. Each plasma physics book devotes many pages to the discussion of Landau damping, that was first correctly described by Landau (1946), by considering an initial value problem and using Laplace transforms. It was later shown by van Kampen (1955), that the Landau damping can be indeed obtained by using Fourier analysis. We refer the reader for example to books by Swanson, Stix, Akhiezer, Gary, Gurnett and Bhattacharjee, Fitzpatrick, etc. Let us call the integral (2.30) the 'Landau integral'. Nevertheless, the very-well-known secret is that, even if one is armed with all these excellent books, the Landau damping effect can still be very confusing (even at the linear level). We did not find any secret recipe that explains the Landau damping in a simplified and different way, and the reader is

referred to the thick plasma physics books. Here, we want to concentrate only how to express the integral (2.30) through the plasma dispersion function.

Since the Landau integral can be very confusing and boring to explain, to increase the ‘pedagogical’ value of this text, let us talk a bit more freely on the next few pages. The plasma dispersion function can be defined with a short definition

$$Z(\zeta) \equiv \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx, \quad \text{for } \text{Im}(\zeta) > 0. \tag{2.32}$$

In the definition of x_0 , the thermal speed v_{th} is always a positive real number, and we do not have to worry about it. Now, considering the specific case $k_{\parallel} > 0$ and $\text{Im}(\omega) > 0$, where we indeed have $\text{Im}(x_0) > 0$, we can directly use the plasma dispersion function and the result of the Landau integral (2.30) is $n_0 x_0 Z(x_0)$. For this case, we are done. Really? Yes, there is nothing else we can do for this case, we calculated the Landau integral. Reeeaaallyy?? Yes, because the Landau integral cannot be analytically ‘calculated’, the integral cannot be expressed through elementary functions, unless the $Z(\zeta)$ function is somehow simplified, for example by expansion for cases $|\zeta| \ll 1$ or $|\zeta| \gg 1$, or by considering the weak damping limit when $\text{Im}(x_0)$ is small (see plasma physics books). We are not interested in these limits and the $Z(\zeta)$ function has to be calculated numerically or looked up in the table. We are really done here!¹ So why is the Landau integral so confusing for the other cases? It is exactly because of that – basically nothing gets ‘really calculated’.

2.2. The dreadful Landau integral $\int e^{-x^2}/(x - x_0) dx$

There are many reasons why the ‘Landau integral’ (2.30) can be so confusing. The first reason is, (i) that the integral (2.30) cannot be expressed by using only elementary functions. If we did not arrive at this integral in the middle of a thick plasma physics book, but instead encountered it during our undergraduate studies of complex analysis, we would perhaps not have such a respect to this integral, and immediately attempt to calculate it by using the residue theorem. The integral appears to be so simple. Instead of calculating $\int_{-\infty}^{\infty}$, we would calculate a different integral over a closed contour in the complex plane \oint_C . That integral can be calculated by using the residue theorem, that states that $\oint_C = 2\pi i \sum \text{Res}$, if the big path that encircles all the poles is counter-clockwise.² An equivalent statement is that the integral is equal to $\oint_C = -2\pi i \sum \text{Res}$, if the big path that encircles all the poles is clockwise. In our case, there is always just one pole, at $x = x_0$, and the residue of $e^{-x^2}/(x - x_0)$ evaluated at $x = x_0$ is actually very simple, it is always

$$\text{Res}_{x=x_0} \frac{e^{-x^2}}{x - x_0} = e^{-x_0^2}, \tag{2.33}$$

regardless of the value of x_0 , since for a general function $f(x)$, the residue $\text{Res}_{x=x_0} f(x)/(x - x_0) = f(x_0)$.

However, to make the result \oint_C useful for the calculation of our integral on the real axis $\int_{-\infty}^{\infty}$, we need to separate the closed contour integral to $\oint_C = \int_{-\infty}^{\infty} + \int_{arc}$, where the

¹In old times, a good barber would loudly shout: the next in line for shaving!

²As noted in the footnote of Appendix A of the book by Swanson, page 363, the rumour has it that the famous Cauchy’s residue theorem, is actually due to Cauchy’s dog, that usually went around leaving residues at every existing pole.

\int_{arc} represents the big half-circle at infinitely large radius. To preserve the direction of integration along the real axis $\int_{-\infty}^{\infty}$, if the pole is in the upper complex plane, i.e. if $\text{Im}(x_0) > 0$, we need to close the big arc contour in the upper half of the complex plane counter-clockwise. Similarly, if the pole is in the lower complex plane, i.e. if $\text{Im}(x_0) < 0$, we need to close the big arc contour clockwise. Importantly, in contrast to typical examples presented in basic complex analysis classes, the arc integral \int_{arc} does not disappear. The problem is, that the function $f(x) = e^{-z^2}$ is a very strongly decaying function on the real axis (for $z = x \rightarrow \pm\infty$), however, this is not true at all in the complex plane. Considering the purely Imaginary axis $z = \pm iy$, the function $e^{-z^2} = e^{+y^2}$ is a very strongly diverging function as y increases, and the arc integral \int_{arc} cannot be neglected! This is a very sad news, since now we clearly see, that with $\int_{\text{arc}} \neq 0$, we will not be able to use the complex analysis to actually ‘calculate’ the Landau integral (2.30).

We note that the well-known Gaussian integral $I = \int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$, is typically calculated in the real plane by means of a trick which consists in evaluating I^2 in polar coordinates, $I^2 = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-x^2-y^2} dx dy = 2\pi \int_0^{\infty} e^{-r^2} r dr$. The Gaussian integral can still be calculated in the complex plane by using the residue theorem, even though quite sophisticated tricks are required.³

The second reason why Landau damping is confusing is, (ii) the necessity of analytic continuation. The third reason is very closely related to the second and it is (iii) The analytic continuation has to be done differently for $k_{\parallel} > 0$ and for $k_{\parallel} < 0$. The big result of Landau (1946) can be summarized as follows: if $k_{\parallel} > 0$, the path of integration always has to pass below the pole $x = x_0$. Therefore, starting with the basic case in the upper complex plane $\text{Im}(x_0) > 0$, nothing has to be done and the integration is just along the real axis. Now, if the pole is moved to the real axis, so $\text{Im}(x_0) = 0$, one needs to go around that pole with a tiny half-circle from below. This creates a contribution of 1/2 times $2\pi i$ times the residue at that pole, so the contribution is $\pi i e^{-x_0^2}$. If the pole x_0 is moved further down to the lower complex plane, a full circle around the pole is required to enclose it from below, which yields a contribution of $2\pi i e^{-x_0^2}$. The situation is demonstrated in figure 1(a). The integral (2.30) for $k_{\parallel} > 0$ is therefore ‘calculated’ as

$$\int_C \frac{e^{-x^2}}{x - x_0} dx \stackrel{k_{\parallel} > 0}{=} \begin{cases} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx, & \text{Im}(\omega) > 0; \text{Im}(x_0) > 0; \\ V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx + \pi i e^{-x_0^2}, & \text{Im}(\omega) = 0; \text{Im}(x_0) = 0; \\ \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx + 2\pi i e^{-x_0^2}, & \text{Im}(\omega) < 0; \text{Im}(x_0) < 0. \end{cases} \quad (2.34)$$

For the Cauchy principal value, we prefer the original French pronunciation ‘*Valeur Principale*’, abbreviated as *V.P.*

The above result is completely consistent with the definition of the plasma dispersion function, since the plasma dispersion function was developed exactly to describe this integral. One starts with the definition in the upper complex plane

³For example, by considering $\oint e^{i\pi z^2} / \sin(\pi z) dz$, calculated along lines with a 45° angle with the real axis, that encircle the pole at $z = 0$ and where the residue $\text{Res}_{z=0} = 1/\pi$.

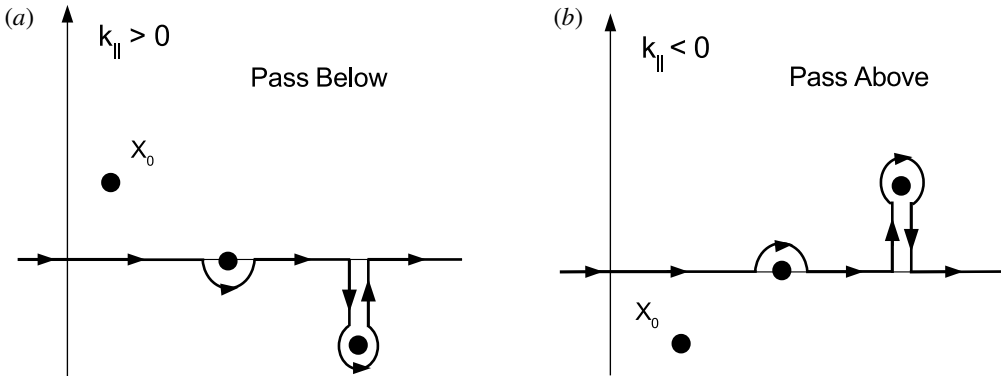


FIGURE 1. (a) Landau contours for $k_{\parallel} > 0$. (b) Landau contours for $k_{\parallel} < 0$.

(2.32), and analytically continues this function to a lower complex plane, according to

$$Z(\zeta) \equiv \frac{1}{\sqrt{\pi}} \int_C \frac{e^{-x^2}}{x - \zeta} dx = \frac{1}{\sqrt{\pi}} \begin{cases} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx, & \text{Im}(\zeta) > 0; \\ V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + \pi i e^{-\zeta^2}, & \text{Im}(\zeta) = 0; \\ \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + 2\pi i e^{-\zeta^2}, & \text{Im}(\zeta) < 0. \end{cases} \quad (2.35)$$

To save space in scientific papers and plasma physics books, the definition of $Z(\zeta)$ is often abbreviated as (2.32), i.e. only as a first line of (2.35), with a powerful statement that for $\text{Im}(\zeta) < 0$ the function is analytically continued. That statement indeed completely defines $Z(\zeta)$, since the powerful complex analysis tells us that an analytic continuation of a function, if it exists, is unique. Another abbreviated definition is by essentially writing down only the second (middle) line of (2.35). This is the most useful 1-line abbreviation because one can immediately recognize how the $\text{sign}(k_{\parallel})$ was treated (as we will see soon). However, such a definition of $Z(\zeta)$, only specifying it for $\text{Im}(\zeta) = 0$, would not be a complete definition of that function, and no powerful statement regarding how the function is extended above and below from the x -axis is available. So plasma physicists found a very smart workaround, how not to write the $\text{Im}(\zeta) = 0$ restriction in the second line of (2.35) and how to completely define the $Z(\zeta)$ with this 1-line statement. Let us still consider the case $k_{\parallel} > 0$, where our x_0 and ζ are equivalent. It is often stated (e.g. Stix, bottom of page 190), that ‘the principal value of an integral through an isolated singular point may be considered the average of the two integrals that pass just above and just below the point’. For example, for a specific situation when x_0 lies on the real x -axis, integrating along a horizontal line below the x -axis yields the first line of (2.35), and integration along a horizontal line above the x -axis yields the third line of (2.35) since when the pole is encountered we have to pass it from below. An average of the first line and third line of (2.35) yields the second line. The idea can now be generalized to an entire complex plane, for all values of $\text{Im}(x_0)$, where two integrals are done; one integral

along a horizontal line that passes below the x_0 point (where nothing has to be done) and one integral along a horizontal line that passes above the x_0 point (and where a deformation that passes below the point has to be performed, accounting for the full residuum). The average of these two integrals yields an abbreviated $Z(\zeta)$ definition for all values of ζ in the form

$$Z(\zeta) = \frac{1}{\sqrt{\pi}} V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + i\sqrt{\pi} e^{-\zeta^2}, \quad \text{for } \forall \text{Im}(\zeta), \quad (2.36)$$

where the integration is said to go through the pole. Of course, no integration can be really done ‘through’ a singular point, and what the wording means is that the integration is done along the horizontal axis that goes through x_0 , i.e. the integration is along horizontal axis $\text{Im}(x_0)$.

It is possible to look at it from another (perhaps more illuminating) perspective. Consider the situation in which x_0 is somewhere in the upper half of the complex plane. One can perform the integral along the real axis, so that the first line of (2.35) applies. Let us call this result c_1 . Alternatively, one can perform the integral along the horizontal line that passes through $\text{Im}(x_0)$ (with the required tiny half-circle passing below x_0), and (2.36) applies. Let us call this result c_2 . These two different integrals must be equal. Why? Because one can plot two vertical lines (passing through $\text{Re}(x_0) = \pm\infty$) that, together with the two horizontal integration lines, enclose an area that does not contain any pole, and integration around all four lines (in a circular direction, let us say counter-clockwise) must yield zero. The two integrals along the vertical lines cancel each other, yielding that $c_1 - c_2 = 0$, the minus sign in front of c_2 appears since the integration along c_2 was now done in the opposite direction. Even though it is perhaps a bit confusing when seen at first, the definition (2.36) is very useful, and when encountered, it should be just interpreted as an abbreviated definition of (2.35).

Unfortunately, the plasma dispersion function was obviously developed only with the case $k_{\parallel} > 0$ in mind. The Landau result requires that for $k_{\parallel} < 0$, the path of integration always encircles the pole from above, see figure 1(b). For $k_{\parallel} < 0$, the Landau integral is defined as

$$\int_C \frac{e^{-x^2}}{x - x_0} dx \stackrel{k_{\parallel} < 0}{=} \begin{cases} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx, & \text{Im}(\omega) > 0; \text{Im}(x_0) < 0; \\ V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx - \pi i e^{-x_0^2}, & \text{Im}(\omega) = 0; \text{Im}(x_0) = 0; \\ \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx - 2\pi i e^{-x_0^2}, & \text{Im}(\omega) < 0; \text{Im}(x_0) > 0. \end{cases} \quad (2.37)$$

The two different cases for $k_{\parallel} > 0$ and $k_{\parallel} < 0$ can be easily combined together by using the sign of the wavenumber k_{\parallel} function, that is equal to +1 for $k_{\parallel} > 0$, and equal to -1 for $k_{\parallel} < 0$. However, one needs to forget the sign of $\text{Im}(x_0)$, and arrange the results only with respect to the sign of $\text{Im}(\omega)$. The Landau integral with $x_0 = \omega / (k_{\parallel} v_{th})$ therefore reads

$$\int_C \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{th}}} dx \stackrel{\forall k_{\parallel}}{=} \begin{cases} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx, & \text{Im}(\omega) > 0; \\ V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx + \text{sign}(k_{\parallel}) \pi i e^{-x_0^2}, & \text{Im}(\omega) = 0; \\ \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx + \text{sign}(k_{\parallel}) 2\pi i e^{-x_0^2}, & \text{Im}(\omega) < 0. \end{cases} \quad (2.38)$$

Obviously, it is the sign of $\text{Im}(\omega)$, and not the sign of $\text{Im}(x_0)$, that is the ‘natural language’ of the Landau integral. However, the connection to the plasma dispersion function $Z(\zeta)$ is unnecessarily difficult. Sometimes, the definition of the plasma dispersion function is then altered so that the above expression is satisfied. Stix, for example, uses, in addition to the usual $Z(\zeta)$, also a different function $Z_0(\zeta)$ that can be defined with respect to the sign of $\text{Im}(\omega)$ instead of the sign of $\text{Im}(\zeta)$, where as noted on page 202, $Z_0(\zeta) = Z(\zeta)$ for $k_{\parallel} > 0$, and, $Z_0(\zeta) = -Z(-\zeta)$ for $k_{\parallel} < 0$. With $\zeta = \omega / (k_{\parallel} v_{th})$, the function $Z_0(\zeta)$ is defined according to

$$Z_0(\zeta) = \frac{1}{\sqrt{\pi}} \begin{cases} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx, & \text{Im}(\omega) > 0; \\ V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + \text{sign}(k_{\parallel}) \pi i e^{-\zeta^2}, & \text{Im}(\omega) = 0; \\ \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + \text{sign}(k_{\parallel}) 2\pi i e^{-\zeta^2}, & \text{Im}(\omega) < 0. \end{cases} \quad (2.39)$$

Again, the function $Z_0(\zeta)$ can be defined in an abbreviated form as the first line of (2.39), with analytic continuation for $\text{Im}(\omega) \leq 0$ (Stix, page 206, equation (91)). The second possible abbreviated definition of $Z_0(\zeta)$, valid for all values of $\text{Im}(\omega)$, is the trick with the principal value (Stix, page 206, equation (92))

$$Z_0(\zeta) = \frac{1}{\sqrt{\pi}} V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + \text{sign}(k_{\parallel}) i \sqrt{\pi} e^{-\zeta^2}, \quad \text{for } \forall \text{Im}(\omega), \quad (2.40)$$

where the integration path goes ‘through’ the pole, i.e. the integration is done along the horizontal line $\text{Im}(\zeta)$. With the use of this new function $Z_0(\zeta)$ of Stix, we can therefore express the dreadful Landau integral for all values of k_{\parallel} as

$$\frac{1}{\sqrt{\pi}} \int_C \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{th}}} dx \stackrel{\forall k_{\parallel}}{=} Z_0(\zeta); \quad \text{where } \zeta = \frac{\omega}{k_{\parallel} v_{th}}. \quad (2.41)$$

However, we do not like this formulation with Z_0 . Here, we insist on using the original plasma dispersion function Z . In our opinion, the most elegant solution is the one that is used for example in the book by Peter Gary and in some Landau fluid papers, and that is to use $|k_{\parallel}|$ in the definition of ζ , by defining

$$\zeta \equiv \frac{\omega}{|k_{\parallel}| v_{th}}. \quad (2.42)$$

This amazingly convenient definition simplifies the expressions and represents the ‘natural language’ of the plasma dispersion function. We note that $|k_{\parallel}| = \text{sign}(k_{\parallel}) k_{\parallel}$,

and also $k_{\parallel} = \text{sign}(k_{\parallel})|k_{\parallel}|$. With the new definition of ζ , for $k_{\parallel} > 0$ obviously nothing is changed since $|k_{\parallel}| = k_{\parallel}$. However, for $k_{\parallel} < 0$,

$$\begin{aligned} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{\text{th}}}} dx &\stackrel{k_{\parallel} < 0}{=} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x + \zeta} dx = \left[\begin{array}{l} x = -y \\ dx = -dy \end{array} \right] \\ &= \int_{\infty}^{-\infty} \frac{e^{-y^2}}{-y + \zeta} (-dy) = \left[\begin{array}{l} \text{rename} \\ y \rightarrow x \end{array} \right] = - \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx \\ &= \text{sign}(k_{\parallel}) \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx, \end{aligned} \tag{2.43}$$

where in the last step we used $-1 = \text{sign}(k_{\parallel})$. By examining the first and the last expressions, the result is also obviously valid for $k_{\parallel} > 0$, and therefore for all k_{\parallel} . Or alternatively, (perhaps more confusingly, but keeping an exact track of the $\text{sign}(k_{\parallel})$), for all values of k_{\parallel}

$$\begin{aligned} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{\text{th}}}} dx &\stackrel{\forall k_{\parallel}}{=} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \text{sign}(k_{\parallel})\zeta} dx \\ &= \text{sign}(k_{\parallel}) \int_{-\infty}^{\infty} \frac{e^{-x^2}}{\text{sign}(k_{\parallel})x - \zeta} dx = \left[\begin{array}{l} y = \text{sign}(k_{\parallel})x \\ dy = \text{sign}(k_{\parallel}) dx \end{array} \right] \\ &= \text{sign}(k_{\parallel}) \int_{-\infty \text{sign}(k_{\parallel})}^{+\infty \text{sign}(k_{\parallel})} \frac{e^{-y^2}}{y - \zeta} \left(\frac{dy}{\text{sign}(k_{\parallel})} \right) \\ &= \int_{-\infty \text{sign}(k_{\parallel})}^{+\infty \text{sign}(k_{\parallel})} \frac{e^{-y^2}}{y - \zeta} dy = \text{sign}(k_{\parallel}) \int_{-\infty}^{+\infty} \frac{e^{-y^2}}{y - \zeta} dy \\ &= \text{sign}(k_{\parallel}) \int_{-\infty}^{+\infty} \frac{e^{-x^2}}{x - \zeta} dx, \end{aligned} \tag{2.44}$$

which is the same result as the one obtained above. The definition of ζ (2.42) therefore yields

$$\int_C \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{\text{th}}}} dx \stackrel{\forall k_{\parallel}}{=} \text{sign}(k_{\parallel}) \begin{cases} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx, & \text{Im}(\zeta) > 0; \\ V.P. \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + \pi i e^{-\zeta^2}, & \text{Im}(\zeta) = 0; \\ \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \zeta} dx + 2\pi i e^{-\zeta^2}, & \text{Im}(\zeta) < 0. \end{cases} \tag{2.45}$$

This result allows us to use the original plasma dispersion function definition (2.35), and express the dreadful Landau integral for all k_{\parallel} simply as

$$\frac{1}{\sqrt{\pi}} \int_C \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{\text{th}}}} dx \stackrel{\forall k_{\parallel}}{=} \text{sign}(k_{\parallel}) Z(\zeta); \quad \text{where } \zeta \equiv \frac{\omega}{|k_{\parallel}| v_{\text{th}}}. \tag{2.46}$$

Now we have calculated the Landau integral to our satisfaction, and we can continue with the calculation of the linear kinetic hierarchy. Wait. We had basically the same result several pages back! For the case $k_{\parallel} > 0$ and $\text{Im}(\omega) > 0$. The Landau integral was just expressed through the plasma dispersion function, basically the same result as is done now, there is just one $\text{sign}(k_{\parallel})$ in front of the integral and one in the definition of ζ . Are we suggesting that all these calculations, contour drawings and discussions, were done just to get a sign right? Affirmative. The Landau integral is all about chasing minus signs, but to get the correct signs is very important. This is exactly the reason why the Landau damping is so confusing, and why it needed the genius of Landau to correctly figure it out. Nevertheless, that the Landau damping (Landau 1946) is indeed very confusing can be understood from the fact that the effect was questioned for almost 20 years before it was experimentally verified by Malmberg & Wharton (1966).

To conclude, and to summarize the differences between the plasma physics books of Stix and Peter Gary, we have two equivalent recipes to ‘calculate’ the Landau integral, that can be written as

$$\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{\text{th}}}} dx \stackrel{A.C.}{=} \frac{1}{\sqrt{\pi}} \int_C \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{\text{th}}}} dx = \begin{cases} Z_0(\zeta), & \zeta = \frac{\omega}{k_{\parallel} v_{\text{th}}}; \\ \text{sign}(k_{\parallel})Z(\zeta), & \zeta = \frac{\omega}{|k_{\parallel}| v_{\text{th}}}, \end{cases} \tag{2.47}$$

where the *A.C.* stands for analytic continuation. It is important to emphasize that some plasma books, such as for example that by Gurnett and Bhattacharjee, take a different approach and call the function $Z_0(\zeta)$ simply $Z(\zeta)$, as is obvious from their expressions for $Z(\zeta)$ (pages 347–348) that contain the $\text{sign}(k_{\parallel})$. Of course, this approach is fully kosher, however, one needs to be extra careful when adopting a numerical routine for the plasma dispersion function. The second choice in (2.47) appears inconvenient, however, it is not, since the expression (2.30) contains

$$\frac{1}{\sqrt{\pi}} \frac{\omega}{k_{\parallel} v_{\text{th}}} \int_C \frac{e^{-x^2}}{x - \frac{\omega}{k_{\parallel} v_{\text{th}}}} dx = \begin{cases} \zeta Z_0(\zeta), & \zeta = \frac{\omega}{k_{\parallel} v_{\text{th}}}; \\ \frac{\omega}{k_{\parallel} v_{\text{th}}} \text{sign}(k_{\parallel})Z(\zeta) = \zeta Z(\zeta), & \zeta = \frac{\omega}{|k_{\parallel}| v_{\text{th}}}. \end{cases} \tag{2.48}$$

The book by Peter Gary, and many Landau fluid papers prefer the second choice, since this small trick with redefining ζ allows the use of the original plasma dispersion function $Z(\zeta)$, that was tabulated by Fried & Conte (1961).⁴ We prefer it too, and therefore, the integral that we will use frequently in the kinetic hierarchy is

$$\frac{x_0}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx = \zeta Z(\zeta), \quad \text{where } x_0 = \frac{\omega}{k_{\parallel} v_{\text{th}}}; \quad \zeta = \frac{\omega}{|k_{\parallel}| v_{\text{th}}}, \tag{2.49}$$

and obviously $x_0 = \text{sign}(k_{\parallel})\zeta$. Now we are able to finish the calculation of the density $n^{(1)}$, equation (2.29), that yields

$$n^{(1)} = -\frac{q_r}{T^{(0)}} \Phi (n_0 + n_0 \zeta Z(\zeta)) = -\frac{q_r n_0}{T^{(0)}} \Phi (1 + \zeta Z(\zeta)). \tag{2.50}$$

⁴Peter Gary’s book indeed appears to be the only ‘recent’ plasma book, where $|k_{\parallel}|$ is used for the definition of ζ . The only caveat of the book, which could be confusing, is the exclusion of the $\sqrt{2}$ in the definition of the thermal speed v_{th} . However, some Landau fluid papers (Hammett & Perkins 1990; Snyder *et al.* 1997) use the same definition without the $\sqrt{2}$.

The result can also be expressed by using the derivative $Z'(\zeta) = -2(1 + \zeta Z(\zeta))$. The quantity $1 + \zeta Z(\zeta)$ appears very frequently in kinetic calculations with Maxwellian distribution and it is called the plasma response function

$$R(\zeta) = 1 + \zeta Z(\zeta). \quad (2.51)$$

For a different (general) distribution function f_0 , the plasma response function $R(\zeta)$ can be defined according to what is obtained after calculating the density $n^{(1)} = -(q_e n_0 / T^{(0)}) \Phi R(\zeta)$. The name is very appropriate, since the $R(\zeta)$ describes, how a plasma with some distribution function ‘responds’ to an applied electric field (or a scalar potential).

2.3. Short afterthoughts, after the Landau integral

Why does some ‘analytic continuation’ have to be done? Even though we did not manage to express the Landau integral (2.30) through elementary functions, the integral appears to be well defined in both upper and lower halves of the complex plane, regardless of where the x_0 is. And it indeed is. So why the analytic continuation? The very-deep reason why the analytic continuation is necessary, is that the integral is not continuous when crossing the real axis $\text{Im}(x_0) = 0$ in the complex plane.⁵ If a function is not continuous, it is not analytic (a fancy well-defined language that says that the function is not infinitely differentiable, basically meaning that it matters from what direction that point is approached in the complex plane, very similarly to a derivative of function $|x|$ on the real axis). And if a function is analytic in some area, and not analytic outside of that area, we can sometimes push/extend the area of where the function is analytic, to/through the area where the function is not analytic, therefore the term ‘analytic continuation’.

Why is the analytic continuation so important? Why is it a big problem that the integral is not continuous when crossing the real axis? Because it directly relates to the causality principle, that is, if something happens, then the response to this incident must come after, and not before, the time in which that incident happened. This can be perhaps more intuitively addressed by performing the Laplace transforms in time (instead of the Fourier transforms), and considering an initial value problem, as was done by Landau (1946). For more information, see plasma physics books, for example Stix (1992), chapter 3 on causality etc.

The necessity of analytic continuation and the definition of the plasma dispersion function can be nicely clarified by a formula from a higher complex analysis, known as the Plemelj formula (Plemelj 1908), which can be written in the following convenient form

$$\lim_{\epsilon \rightarrow 0^+} \frac{1}{x - x_0 \pm i\epsilon} = V.P. \frac{1}{x - x_0} \mp i\pi\delta(x - x_0). \quad (2.52)$$

The formula (2.52) is meant to be applied on a function $f(x)$ and integrated ‘through’ the pole, i.e. along the horizontal line $\text{Im}(x_0)$. The easiest is to consider $x_0 = 0$ (or $\text{Im}(x_0) = 0$) with integration along the real axis. The Dirac delta function $\delta(x - x_0)$ in (2.52) represents contributions of the Landau residue. If the Landau residue is neglected, i.e. if only the V.P. part in (2.52) is considered, as done by Vlasov (1945),

⁵What actually matters is not the x_0 , but the frequency ω , and the crossing of the real axis $\text{Im}(\omega) = 0$. This unfortunately yields that two separate cases for $k_{\parallel} > 0$ and for $k_{\parallel} < 0$ have to be considered.

yields that there is no damping present. In § 3.3, we will construct Padé approximants of $Z(\zeta)$ and $R(\zeta)$. One can easily check that, by neglecting the Landau residue in the power-series expansions (the residue will be neglected in the asymptotic-series expansions), yields no collisionless damping. Therefore, as shown by van Kampen (1955), it is indeed possible to derive Landau damping by using Fourier analysis (an approach adopted here), provided the Landau residue in (2.52) is retained. The formula (2.52) is often attributed only to Plemelj (1908), for his rigorous proof. Sometimes it is called the Sokhotski–Plemelj formula, because it is argued the formula was derived in the doctoral thesis of Y. V. Sokhotski in 1873, with a proof that can be viewed as sufficiently rigorous for mathematical standards that existed at those times, i.e. 35 years before the rigorous proof of Plemelj. The Sokhotski–Plemelj formula is used in many areas of physics, from the theory of elasticity to quantum field theory.

2.4. *Easy Landau integrals* $\int x^n e^{-x^2} / (x - x_0) dx$

We want to calculate moments in velocity space all the way up to the fourth-order moment r , and (including the 3-D geometry) we will need integrals only up to $n = 5$. To this aim, we will use frequently (2.49), where we find it convenient to use x_0 and ζ instead of chasing the sign(k_{\parallel}), and in the end we will just use the definition $x_0 = \text{sign}(k_{\parallel})\zeta$. We already saw that the zeroth-order moment was

$$\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx = \text{sign}(k_{\parallel})Z(\zeta). \tag{2.53}$$

Let us now calculate the higher-order moments. Since we talked so much in the last pages, we will remain silent for a moment and we will just enjoy the calculation,

$$\begin{aligned} \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x e^{-x^2}}{x - x_0} dx &= \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x - x_0 + x_0}{x - x_0} e^{-x^2} dx \\ &= \underbrace{\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-x^2} dx}_{=1} + \underbrace{\frac{x_0}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx}_{=\zeta Z(\zeta)} \\ &= 1 + \zeta Z(\zeta) = R(\zeta). \end{aligned} \tag{2.54}$$

$$\begin{aligned} \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^2 e^{-x^2}}{x - x_0} dx &= \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^2 - x_0^2 + x_0^2}{x - x_0} e^{-x^2} dx \\ &= \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} (x + x_0) e^{-x^2} dx + \underbrace{\frac{x_0^2}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx}_{x_0 \zeta Z(\zeta)} \\ &= \underbrace{\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} x e^{-x^2} dx}_{=0} + \underbrace{\frac{x_0}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-x^2} dx}_{=x_0} + x_0 \zeta Z(\zeta) = x_0(1 + \zeta Z(\zeta)) \\ &= \text{sign}(k_{\parallel})\zeta R(\zeta). \end{aligned} \tag{2.55}$$

$$\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^3 e^{-x^2}}{x - x_0} dx = \underbrace{\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^3 - x_0^3}{x - x_0} e^{-x^2} dx}_{=(1/2)+x_0^2} + \underbrace{\frac{x_0^3}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx}_{=\zeta^3 Z(\zeta)} = \frac{1}{2} + \zeta^2 R(\zeta). \tag{2.56}$$

$$\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^4 e^{-x^2}}{x - x_0} dx = \text{sign}(k_{\parallel}) \left(\frac{1}{2} \zeta + \zeta^3 R(\zeta) \right). \quad (2.57)$$

$$\frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^5 e^{-x^2}}{x - x_0} dx = \frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta). \quad (2.58)$$

That was easy! If we ever need a higher order, we will just blindly calculate

$$\begin{aligned} \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^n e^{-x^2}}{x - x_0} dx &= \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^n - x_0^n}{x - x_0} e^{-x^2} dx + \underbrace{\frac{x_0^n}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{e^{-x^2}}{x - x_0} dx}_{=x_0^n \text{sign}(k_{\parallel}) Z(\zeta)} \\ &= \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} (x^{n-1} + x^{n-2}x_0 + x^{n-3}x_0^2 + \cdots + x x_0^{n-2} + x_0^{n-1}) e^{-x^2} dx \\ &\quad + \text{sign}(k_{\parallel})^{n+1} \zeta^n Z(\zeta), \end{aligned} \quad (2.59)$$

and we do not worry right now if this general case can be expressed in some smarter way. Now we know how to calculate the kinetic Landau integrals, so let us use this knowledge to calculate the first few integrals of the linear ‘kinetic hierarchy’.

3. One-dimensional geometry (electrostatic)

3.1. Kinetic moments for Maxwellian f_0

With the previous integrals already calculated, the calculation of the linear kinetic hierarchy is an easy process. However, it is important to emphasize that the hierarchy is linear, and must be calculated as such. Again, as emphasized before, the kinetic velocity v is an independent quantity, and is not linearized. The total density $n = \int f dv$, and at the first order of course $n_0 = \int f_0 dv$. The expansion $n_0 + n^{(1)} = \int (f_0 + f^{(1)}) dv$ implies $n^{(1)} = \int f^{(1)} dv$. The density $n^{(1)}$, already calculated in (2.50), was therefore calculated correctly, and using the plasma response function

$$\frac{n^{(1)}}{n_0} = -\frac{q_r}{T^{(0)}} \Phi R(\zeta). \quad (3.1)$$

The velocity moment is $nu = \int v f dv$ and at the first order $n_0 u_0 = \int v f_0 dv$. In our specific case, because we do not consider any drifts in the distribution function, $u_0 = 0$. Expanding $(n_0 + n^{(1)})(u_0 + u^{(1)}) = \int v (f_0 + f^{(1)}) dv$ and neglecting the nonlinear quantity $n^{(1)} u^{(1)}$, yields $n_0 u^{(1)} = \int v f^{(1)} dv$. The velocity moment calculates as

$$\begin{aligned} n_0 u^{(1)} &= \int v f^{(1)} dv = -\frac{q_r}{T^{(0)}} \Phi \int v \left(1 + \frac{\frac{\omega}{k_{\parallel}}}{v - \frac{\omega}{k_{\parallel}}} \right) f_0 dv \\ &= -\frac{q_r}{T^{(0)}} \Phi \left(\underbrace{\int v f_0 dv}_{=n_0 u_0=0} + \int \frac{v \frac{\omega}{k_{\parallel}}}{v - \frac{\omega}{k_{\parallel}}} f_0 dv \right) \\ &= -\frac{q_r}{T^{(0)}} \Phi n_0 \sqrt{\frac{\alpha}{\pi}} \frac{\omega}{k_{\parallel}} \int \frac{v e^{-\alpha v^2}}{v - \frac{\omega}{k_{\parallel}}} dv = \left[\frac{\sqrt{\alpha} v = x}{\sqrt{\alpha} dv = dx} \right] \end{aligned}$$

$$\begin{aligned}
 &= -\frac{q_r}{T^{(0)}} \Phi \frac{n_0}{\sqrt{\pi}} \frac{\sqrt{\alpha}}{\sqrt{\alpha}} \frac{\omega}{k_{\parallel}} \int \frac{x e^{-x^2}}{x - \frac{\omega}{k_{\parallel}} \sqrt{\alpha}} dx \\
 &= \left[x_0 = \frac{\omega}{k_{\parallel}} \sqrt{\alpha} \right] = -\frac{q_r}{T^{(0)}} \Phi \frac{n_0}{\sqrt{\alpha}} \frac{x_0}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x e^{-x^2}}{x - x_0} dx \\
 &= -\frac{q_r}{T^{(0)}} \Phi \frac{n_0}{\sqrt{\alpha}} \text{sign}(k_{\parallel}) \zeta R(\zeta), \tag{3.2}
 \end{aligned}$$

and cancelling n_0 and using $1/\sqrt{\alpha} = v_{th} = \sqrt{2T^{(0)}/m}$ yields

$$u^{(1)} = -\frac{q_r}{T^{(0)}} \Phi \sqrt{\frac{2T^{(0)}}{m}} \text{sign}(k_{\parallel}) \zeta R(\zeta). \tag{3.3}$$

The definition of the scalar pressure is $p = m \int (v - u)^2 f dv$ and at the first order $p_0 = m \int v^2 f_0 dv$, because again $u_0 = 0$. The quantity $(v - u)^2 = v^2 - 2vu + u^2$ is linearized as $v^2 - 2vu^{(1)}$, and expanding $p_0 + p^{(1)} = m \int (v^2 - 2vu^{(1)})(f_0 + f^{(1)}) dv$, further linearizing by neglecting $u^{(1)}f^{(1)}$ and using $u_0 = 0$ yields $p^{(1)} = m \int v^2 f^{(1)} dv$. The pressure calculates as

$$\begin{aligned}
 p^{(1)} &= m \int v^2 f^{(1)} dv = -\frac{q_r}{T^{(0)}} \Phi \left(\underbrace{m \int v^2 f_0 dv}_{=p_0} + m \int \frac{v^2 \frac{\omega}{k_{\parallel}}}{v - \frac{\omega}{k_{\parallel}}} f_0 dv \right) = \left[\frac{\sqrt{\alpha} v = x}{\sqrt{\alpha} dv = dx} \right] \\
 &= -\frac{q_r}{T^{(0)}} \Phi \left(p_0 + m \frac{n_0}{\sqrt{\pi}} \frac{\sqrt{\alpha}}{\alpha} \frac{\omega}{k_{\parallel}} \int \frac{x^2 e^{-x^2}}{x - \frac{\omega}{k_{\parallel}} \sqrt{\alpha}} dx \right) = \left[x_0 = \frac{\omega}{k_{\parallel}} \sqrt{\alpha} \right] \\
 &= -\frac{q_r}{T^{(0)}} \Phi \left(p_0 + m \frac{n_0}{\alpha} \frac{x_0}{\sqrt{\pi}} \int \frac{x^2 e^{-x^2}}{x - x_0} dx \right) = -\frac{q_r}{T^{(0)}} \Phi \left(p_0 + m \frac{n_0}{\alpha} \zeta^2 R(\zeta) \right), \tag{3.4}
 \end{aligned}$$

and dividing by p_0 and using $p_0 = n_0 T^{(0)}$ to calculate $mn_0/(p_0\alpha) = 2$, the pressure moment reads

$$\frac{p^{(1)}}{p_0} = -\frac{q_r}{T^{(0)}} \Phi (1 + 2\zeta^2 R(\zeta)). \tag{3.5}$$

We will also need the temperature $T^{(1)}$. The general temperature is defined as $T = p/n$, i.e. the definition is nonlinear. The process of linearization is essentially like doing a derivative

$$T = \frac{p}{n} \xrightarrow{\text{lin.}} T^{(1)} = \frac{p^{(1)}}{n_0} - \frac{p_0}{n_0^2} n^{(1)}, \tag{3.6}$$

and dividing by $T^{(0)} = p_0/n_0$ yields

$$\frac{T^{(1)}}{T^{(0)}} = \frac{p^{(1)}}{p_0} - \frac{n^{(1)}}{n_0}. \tag{3.7}$$

If one does not like the ‘derivative’, the same result is obtained by writing $p = Tn$ instead, and linearizing $(p_0 + p^{(1)}) = (T^{(0)} + T^{(1)})(n_0 + n^{(1)})$. Which after subtracting

$p_0 = T^{(0)}n_0$, neglecting $T^{(1)}n^{(1)}$, yields $p^{(1)} = T^{(1)}n_0 + T^{(0)}n^{(1)}$, which after dividing by p_0 yields (3.7). The temperature is therefore easily calculated as

$$\frac{T^{(1)}}{T^{(0)}} = -\frac{q_r}{T^{(0)}}\Phi(1 + 2\zeta^2R(\zeta) - R(\zeta)). \tag{3.8}$$

The scalar heat flux is defined as $q = m \int (v - u)^3 f dv$ and at the first order $q_0 = m \int v^3 f_0 dv$, and for our case $q_0 = 0$. The quantity $(v - u)^3 = v^3 - 3v^2u + 3vu^2 - u^3$ is linearized as $v^3 - 3v^2u^{(1)}$. Expanding $q_0 + q^{(1)} = m \int (v^3 - 3v^2u^{(1)})(f_0 + f^{(1)}) dv$, neglecting $u^{(1)}f^{(1)}$, yields one contribution that is very easy to overlook, and that is of the same order as the expected $m \int v^3 f^{(1)} dv$, and that is proportional to $m \int v^2 f_0 dv = p_0$. Therefore, the linearized heat flux $q^{(1)}$ must be correctly calculated according to

$$q^{(1)} = m \int v^3 f^{(1)} dv - 3p_0 u^{(1)}. \tag{3.9}$$

The first term calculates as

$$\begin{aligned} m \int v^3 f^{(1)} dv &= -\frac{q_r}{T^{(0)}}\Phi \left(\underbrace{m \int v^3 f_0 dv}_{=q_0=0} + m \int \frac{v^3 \frac{\omega}{k_{\parallel}}}{v - \frac{\omega}{k_{\parallel}}} f_0 dv \right) = \left[\frac{\sqrt{\alpha}v = x}{\sqrt{\alpha} dv = dx} \right] \\ &= -\frac{q_r}{T^{(0)}}\Phi m \frac{n_0}{\sqrt{\pi}} \frac{\sqrt{\alpha}}{\alpha^{3/2}} \frac{\omega}{k_{\parallel}} \int \frac{x^3 e^{-x^2}}{x - \frac{\omega}{k_{\parallel}} \sqrt{\alpha}} dx = \left[x_0 = \frac{\omega}{k_{\parallel}} \sqrt{\alpha} \right] \\ &= -\frac{q_r}{T^{(0)}}\Phi m \frac{n_0}{\alpha^{3/2}} \frac{x_0}{\sqrt{\pi}} \int \frac{x^3 e^{-x^2}}{x - x_0} dx \\ &= -q_r n_0 \Phi \sqrt{\frac{2T^{(0)}}{m}} \text{sign}(k_{\parallel}) (\zeta + 2\zeta^3 R(\zeta)), \end{aligned} \tag{3.10}$$

where we used $\alpha^{-3/2} = (2T^{(0)}/m)\sqrt{2T^{(0)}/m}$. And the entire heat flux (3.9) then reads

$$q^{(1)} = -q_r n_0 \Phi \sqrt{\frac{2T^{(0)}}{m}} \text{sign}(k_{\parallel}) (\zeta + 2\zeta^3 R(\zeta) - 3\zeta R(\zeta)). \tag{3.11}$$

The scalar fourth-order moment is defined as $r = m \int (v - u)^4 f dv$ and at the first order of course $r_0 = m \int v^4 f_0 dv$, since again $u_0 = 0$. Also, $r_0 = 3p_0^2/\rho_0$, where $\rho_0 = mn_0$. The quantity $(v - u)^4$ is linearized as $v^4 - 4v^3u^{(1)}$. Expanding $r_0 + r^{(1)} = m \int (v^4 - 4v^3u^{(1)})(f_0 + f^{(1)}) dv$, the quantity $m \int v^3 f_0 = q_0 = 0$, which yields a simple $r^{(1)} = m \int v^4 f^{(1)} dv$. The fourth-order moment calculates as

$$\begin{aligned} r^{(1)} &= m \int v^4 f^{(1)} dv = -\frac{q_r}{T^{(0)}}\Phi \left(\underbrace{m \int v^4 f_0 dv}_{=r_0} + m \int \frac{v^4 \frac{\omega}{k_{\parallel}}}{v - \frac{\omega}{k_{\parallel}}} f_0 dv \right) = \left[\frac{\sqrt{\alpha}v = x}{\sqrt{\alpha} dv = dx} \right] \\ &= -\frac{q_r}{T^{(0)}}\Phi \left(r_0 + m \frac{n_0}{\sqrt{\pi}} \frac{\sqrt{\alpha}}{\alpha^2} \frac{\omega}{k_{\parallel}} \int \frac{x^4 e^{-x^2}}{x - \frac{\omega}{k_{\parallel}} \sqrt{\alpha}} dx \right) = \left[x_0 = \frac{\omega}{k_{\parallel}} \sqrt{\alpha} \right] \end{aligned}$$

$$= -\frac{q_r}{T^{(0)}}\Phi\left(r_0 + m\frac{n_0}{\alpha^2}\frac{x_0}{\sqrt{\pi}}\int\frac{x^4e^{-x^2}}{x-x_0}dx\right) = -\frac{q_r p_0}{m}\Phi(3 + 2\zeta^2 + 4\zeta^4 R(\zeta)), \tag{3.12}$$

where we have used $1/\alpha^2 = 4T^{(0)2}/m^2$, and $mn_0/\alpha^2 = 4p_0^2/\rho_0$.

The entire nonlinear r is decomposed as $r = 3p^2/\rho + \tilde{r}$. The first term can be linearized in a number of ways, and of course, all techniques must yield the same result, since linearization must be unique. For example, by using the derivative

$$\left(\frac{p^2}{\rho}\right)' = \frac{1}{\rho}2pp' - \frac{p^2}{\rho^2}\rho' = \frac{p^2}{\rho}\left(\frac{2p'}{p} - \frac{\rho'}{\rho}\right), \tag{3.13}$$

the term is easily linearized as

$$\frac{p^2}{\rho} \stackrel{\text{lin.}}{=} \frac{p_0^2}{\rho_0}\left(\frac{2p^{(1)}}{p_0} - \frac{\rho^{(1)}}{\rho_0}\right) = \frac{p_0^2}{\rho_0}\left(\frac{2p^{(1)}}{p_0} - \frac{n^{(1)}}{n_0}\right), \tag{3.14}$$

and by further using (3.7), also alternatively as

$$\frac{p^2}{\rho} \stackrel{\text{lin.}}{=} \frac{p_0^2}{\rho_0}\left(\frac{2T^{(1)}}{T^{(0)}} + \frac{n^{(1)}}{n_0}\right). \tag{3.15}$$

Using $r_0 = 3p_0^2/\rho_0$ therefore yields useful relations (valid for a Maxwellian)

$$\frac{r^{(1)}}{r_0} = 2\frac{p^{(1)}}{p_0} - \frac{n^{(1)}}{n_0} + \frac{\tilde{r}^{(1)}}{r_0} = 2\frac{T^{(1)}}{T^{(0)}} + \frac{n^{(1)}}{n_0} + \frac{\tilde{r}^{(1)}}{r_0}. \tag{3.16}$$

Another possibility (to double check the linearization), is to rewrite $p^2/\rho = (1/m)pT$, so that $r = (3/m)pT + \tilde{r}$, and to linearize that one instead. Expanding that expression into $r_0 + r^{(1)} = (3/m)((p_0 + p^{(1)})(T^{(0)} + T^{(1)})) + \tilde{r}^{(1)}$ (where by definition/construction $\tilde{r}^{(0)} = 0$), after subtracting $r_0 = (3/m)p_0T^{(0)}$, and neglecting $p^{(1)}T^{(1)}$, yields $r^{(1)} = (3/m)(p^{(1)}T^{(0)} + p_0T^{(1)}) + \tilde{r}^{(1)}$. Dividing this expression by r_0 yields

$$\frac{r^{(1)}}{r_0} = \frac{p^{(1)}}{p_0} + \frac{T^{(1)}}{T^{(0)}} + \frac{\tilde{r}^{(1)}}{r_0}, \tag{3.17}$$

which when used with (3.7), is equivalent to (3.16). Now we can easily calculate the $\tilde{r}^{(1)}$ component as

$$\tilde{r}^{(1)} = r^{(1)} - 3\frac{p_0^2}{\rho_0}\left(\frac{2p^{(1)}}{p_0} - \frac{n^{(1)}}{n_0}\right), \tag{3.18}$$

that directly yields

$$\tilde{r}^{(1)} = -\frac{q_r p_0}{m}\Phi(2\zeta^2 + 4\zeta^4 R(\zeta) + 3R(\zeta) - 3 - 12\zeta^2 R(\zeta)). \tag{3.19}$$

Now we are ready to explore the possible closures.

3.2. Exploring possibilities of a closure

Let us summarize the obtained linear hierarchy so that we can directly see the similarities. Let us also for a moment introduce back the species index r , so that we are completely clear

$$\frac{n_r^{(1)}}{n_{0r}} = -\frac{q_r}{T_r^{(0)}} \Phi R(\zeta_r); \quad (3.20)$$

$$u_r^{(1)} = -\frac{q_r}{T_r^{(0)}} \Phi \sqrt{\frac{2T_r^{(0)}}{m_r}} \text{sign}(k_{\parallel}) \zeta_r R(\zeta_r); \quad (3.21)$$

$$\frac{p_r^{(1)}}{p_{0r}} = -\frac{q_r}{T_r^{(0)}} \Phi (1 + 2\zeta_r^2 R(\zeta_r)); \quad (3.22)$$

$$\frac{T_r^{(1)}}{T_r^{(0)}} = -\frac{q_r}{T_r^{(0)}} \Phi (1 + 2\zeta_r^2 R(\zeta_r) - R(\zeta_r)); \quad (3.23)$$

$$q_r^{(1)} = -q_r n_{0r} \Phi \sqrt{\frac{2T_r^{(0)}}{m_r}} \text{sign}(k_{\parallel}) (\zeta_r + 2\zeta_r^3 R(\zeta_r) - 3\zeta_r R(\zeta_r)); \quad (3.24)$$

$$r_r^{(1)} = -\frac{q_r p_{0r}}{m_r} \Phi (3 + 2\zeta_r^2 + 4\zeta_r^4 R(\zeta_r)); \quad (3.25)$$

$$\tilde{r}_r^{(1)} = -\frac{q_r p_{0r}}{m_r} \Phi (2\zeta_r^2 + 4\zeta_r^4 R(\zeta_r) + 3R(\zeta_r) - 3 - 12\zeta_r^2 R(\zeta_r)), \quad (3.26)$$

with an emphasis that the charge q_r should not be confused with the heat flux $q_r^{(1)}$. The $\zeta_r = \omega/(|k_{\parallel}|v_{\text{thr}})$ and the thermal speed $v_{\text{thr}} = \sqrt{2T_r^{(0)}/m_r}$. Note the presence of $\text{sign}(k_{\parallel})$ in the expressions for $u_r^{(1)}$ and $q_r^{(1)}$. The presence of $\text{sign}(k_{\parallel})$ can be verified *a posteriori*, for example by considering the simplest situation when the Landau damping is neglected, and the $R(\zeta_r)$ function yields only real numbers for real valued ζ_r (i.e. the $R(\zeta_r)$ function can be approximated with Padé approximants that contain only powers of ζ_r^2). Simultaneously changing the signs of k_{\parallel} and ω in a Fourier mode should give its complex conjugate, i.e. the real part of expressions (3.20)–(3.26) cannot change its sign in that transformation. This is indeed true because the expressions for $u_r^{(1)}$ and $q_r^{(1)}$ contain $\text{sign}(k_{\parallel})\zeta_r = \omega/(k_{\parallel}v_{\text{thr}})$.

To better understand what is meant by ‘a closure’, let us first examine what is not a closure. Let us examine the density $n^{(1)}$ equation. Since in this specific example we used the electrostatic electric field $\mathbf{E}^{(1)} = -\nabla\phi$, the only Maxwell equation left is $\nabla \cdot \mathbf{E}^{(1)} = 4\pi \sum_r q_r n_r$, where q_r is the charge and n_r is the total density. Linearization of this equation, and using the natural charge neutrality that must be satisfied at the zeroth order $\sum_r q_r n_{0r} = 0$, yields $\nabla \cdot \mathbf{E}^{(1)} = 4\pi \sum_r q_r n_r^{(1)}$, or written with the scalar potential $-\nabla^2 \Phi = 4\pi \sum_r q_r n_r^{(1)}$, and transformed to Fourier space, $k_{\parallel}^2 \Phi = 4\pi \sum_r q_r n_r^{(1)}$. We consider 1-D propagation parallel to \mathbf{B}_0 with wavenumber k_{\parallel} , and to be consistent, we therefore continue with k_{\parallel} and

$$k_{\parallel}^2 \Phi = 4\pi \sum_r q_r n_r^{(1)} = 4\pi \sum_r q_r n_{0r} \frac{n_r^{(1)}}{n_{0r}} = -4\pi \sum_r n_{0r} \frac{q_r^2}{T_r^{(0)}} \Phi R(\zeta_r), \quad (3.27)$$

which can be rewritten as

$$\left(k_{\parallel}^2 + 4\pi \sum_r n_{0r} \frac{q_r^2}{T_r^{(0)}} R(\zeta_r) \right) \Phi = 0. \quad (3.28)$$

Even though the system is now ‘closed’, the equation (3.28) does not represent a fluid closure, and should be viewed only as a kinetic ‘dispersion relation’. To have a non-trivial solution for the potential Φ , the expression inside of the bracket must be equal to zero. By declaring that $k_{\parallel} \neq 0$ (the case $k_{\parallel} = 0$ is trivial since we need some wavenumber), we can divide by k_{\parallel}^2 . By using the definition of the Debye length of r -species $\lambda_{Dr} = 1/k_{Dr}$, where $k_{Dr}^2 = 4\pi n_{0r} q_r^2 / T_r^{(0)}$, one obtains a dispersion relation⁶

$$1 + \sum_r \frac{1}{k_{\parallel}^2 \lambda_{Dr}^2} R(\zeta_r) = 0. \tag{3.29}$$

If one replaces here $k_{\parallel} \rightarrow k$, the expression is actually equivalent to a multi-species dispersion relation, usually found in plasma physics books under the electrostatic waves in hot unmagnetized plasmas, with Maxwellian f_{0r} . See for example Gurnett & Bhattacharjee, page 353, equation (9.4.18). We are not interested here in studying unmagnetized plasmas, and instead, we will just remember (3.29) as the dispersion relation of the parallel propagating (to \mathbf{B}_0) electrostatic mode in a magnetized plasma, since this mode indeed does not contain any magnetic field fluctuations.

Let us consider only the proton and electron species, $r = p, e$, so that

$$1 + \frac{1}{k_{\parallel}^2 \lambda_{De}^2} \left[\frac{T_e^{(0)}}{T_p^{(0)}} R(\zeta_p) + R(\zeta_e) \right] = 0, \tag{3.30}$$

where the proton Debye length was rewritten with the electron Debye length $\lambda_{De} = \lambda_{Dp} \sqrt{T_e^{(0)} / T_p^{(0)}}$. For a general case, the dispersion relation has to be solved numerically, and again, cannot be much simplified, unless one wants to consider the long-wavelength limit $k_{\parallel} \lambda_{De} \ll 1$, where only the expression inside of the big brackets can be used. The solution contains the usual Langmuir waves, that are obtained by neglecting the ion term (by making the ions immobile) and by expanding the $R(\zeta_e)$ in the limit $|\zeta_e| \gg 1$, i.e. in the limit when the wave phase speed ω/k is much larger than the electron thermal speed v_{the} . Langmuir waves propagate with speeds that are higher than the electron plasma frequency $\omega_{pe} = \sqrt{4\pi n_{e0} e^2 / m_e}$, which for us are extremely high frequencies. The solution also contains the ‘ion-acoustic mode’, which in plasma books is obtained in the limit $|\zeta_p| \gg 1$ and $|\zeta_e| \ll 1$, i.e. in the limit where the wave phase speed is much larger than the proton thermal speed, $\omega/k \gg v_{thp}$, but also where the phase speed is much smaller than the electron thermal speed, $\omega/k \ll v_{the}$, for the result see for example Gurnett and Bhattacharjee, page 356, equation (9.4.28-29).

So what about the limit $|\zeta_p| \ll 1$, when the phase speed is much smaller than the proton thermal speed $\omega/k \ll v_{thp}$? Does the ion-acoustic mode not exist in this limit? Unfortunately, in the classical long-wavelength limit, the phase speeds do not become smaller and smaller, the phase speeds ω/k just become non-dispersive and constant. In the CGL description (with cold electrons), the parallel propagating ion-acoustic mode has a phase speed $\omega/k_{\parallel} = \pm C_{\parallel}$, where the parallel sound speed $C_{\parallel}^2 = 3p_{\parallel p}^{(0)} / \rho_0 = 3T_{\parallel p}^{(0)} / m_p$. The limit $|\zeta_p| \ll 1$ is never satisfied, because $C_{\parallel} \ll v_{thp}$ means $\sqrt{3T_{\parallel p}^{(0)} / m_p} \ll \sqrt{2T_{\parallel p}^{(0)} / m_p}$, which is never true. One can estimate the lowest possible value of $|\zeta_p|$ to be roughly in the neighbourhood of $|\zeta_p|_{\min} \approx C_{\parallel}^{\text{CGL}} / v_{thp} = \sqrt{3/2}$, or in another words

⁶An interesting observation (that is perhaps obvious if one considers how the Debye length is derived), is that the Debye length of r -species λ_{Dr} does not depend on the mass m_r .

$|\zeta_p|_{\min} \approx 1$. There is no expansion of the $Z(\zeta)$ for $|\zeta| \approx 1$ and the result has to be found numerically.

So what constitutes a Landau fluid closure? We will use the following definition: express the last retained moment through lower-order moments in such a way, that the kinetic $R(\zeta)$ function is eliminated (for example by using Padé approximation), so that the closure is expressed only through fluid variables and it is prescribed for all ζ values.

3.2.1. Preliminary closures for $|\zeta| \ll 1$

As explained above, the limit $|\zeta| \ll 1$ is actually a bit unphysical for the proton species in the electrostatic limit, and is physically plausible only for the electron species. Nevertheless, briefly exploring the linear kinetic hierarchy in this limit allows us to explore what kind of closures might be possible. In this limit, the plasma dispersion function can be expanded as

$$Z(\zeta) = i\sqrt{\pi}e^{-\zeta^2} - 2\zeta \left[1 - \frac{2}{3}\zeta^2 + \frac{4}{15}\zeta^4 - \frac{8}{105}\zeta^6 + \dots + \frac{(-2)^n \zeta^{2n}}{(2n+1)!!} + \dots \right]; \quad |\zeta| \ll 1, \quad (3.31)$$

$$Z(\zeta) = i\sqrt{\pi}e^{-\zeta^2} - 2\zeta + \frac{4}{3}\zeta^3 - \frac{8}{15}\zeta^5 + \frac{16}{105}\zeta^7 + \dots; \quad (3.32)$$

and the plasma response function as

$$R(\zeta) = 1 + i\zeta\sqrt{\pi}e^{-\zeta^2} + \left[-2\zeta^2 + \frac{4}{3}\zeta^4 - \frac{8}{15}\zeta^6 + \frac{16}{105}\zeta^8 + \dots + \frac{(-2)^{n+1}\zeta^{2n+2}}{(2n+1)!!} + \dots \right]; \quad |\zeta| \ll 1, \quad (3.33)$$

and where for small ζ , $e^{-\zeta^2}$ is naturally expanded as

$$e^{-\zeta^2} = 1 - \zeta^2 + \frac{\zeta^4}{2!} - \frac{\zeta^6}{3!} + \dots + \frac{(-1)^n \zeta^{2n}}{n!} + \dots; \quad |\zeta| \ll 1, \quad (3.34)$$

yielding

$$|\zeta| \ll 1: \quad Z(\zeta) = i\sqrt{\pi} - 2\zeta - i\sqrt{\pi}\zeta^2 + \frac{4}{3}\zeta^3 + i\frac{\sqrt{\pi}}{2}\zeta^4 - \frac{8}{15}\zeta^5 - i\frac{\sqrt{\pi}}{6}\zeta^6 + \frac{16}{105}\zeta^7 + \dots; \quad (3.35)$$

$$R(\zeta) = 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 + i\frac{\sqrt{\pi}}{2}\zeta^5 - \frac{8}{15}\zeta^6 - i\frac{\sqrt{\pi}}{6}\zeta^7 + \frac{16}{105}\zeta^8 + \dots \quad (3.36)$$

For our purposes it is sufficient to keep the series only up to ζ^3 , i.e. to work with the precision $o(\zeta^3)$. The expressions entering the kinetic hierarchy in (3.20)–(3.26) are

$$R(\zeta) = 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \dots; \tag{3.37}$$

$$\zeta R(\zeta) = \zeta + i\sqrt{\pi}\zeta^2 - 2\zeta^3; \tag{3.38}$$

$$1 + 2\zeta^2 R(\zeta) = 1 + 2\zeta^2 + 2i\sqrt{\pi}\zeta^3; \tag{3.39}$$

$$1 - R(\zeta) + 2\zeta^2 R(\zeta) = -i\sqrt{\pi}\zeta + 4\zeta^2 + 3i\sqrt{\pi}\zeta^3; \tag{3.40}$$

$$\zeta + 2\zeta^3 R(\zeta) - 3\zeta R(\zeta) = -2\zeta - 3i\sqrt{\pi}\zeta^2 + 8\zeta^3; \tag{3.41}$$

$$3 + 2\zeta^2 + 4\zeta^4 R(\zeta) = 3 + 2\zeta^2 + 4\zeta^4; \tag{3.42}$$

$$2\zeta^2 + 4\zeta^4 R(\zeta) + 3R(\zeta) - 3 - 12\zeta^2 R(\zeta) = 3i\sqrt{\pi}\zeta - 16\zeta^2 - 15i\sqrt{\pi}\zeta^3. \tag{3.43}$$

An interesting observation is that for small ζ , moments $n^{(1)}$, $p^{(1)}$ and $r^{(1)}$ are finite, and moments $u^{(1)}$, $T^{(1)}$, $q^{(1)}$ and $\tilde{r}^{(1)}$ are proportional to ζ and therefore small. We want to make a simple closure for the heat flux $q^{(1)}$ or the fourth-order correction $\tilde{r}^{(1)}$, and thus, let us concentrate on the moments that are small. To clarify how the closure is performed, let us write them down only up to the precision $o(\zeta_r^2)$, so

$$u_r^{(1)} = -\frac{q_r}{T_r^{(0)}} \Phi \sqrt{\frac{2T_r^{(0)}}{m_r}} \text{sign}(k_{\parallel}) (\zeta_r + i\sqrt{\pi}\zeta_r^2); \tag{3.44}$$

$$T_r^{(1)} = -q_r \Phi (-i\sqrt{\pi}\zeta_r + 4\zeta_r^2); \tag{3.45}$$

$$q_r^{(1)} = -q_r n_{0r} \Phi \sqrt{\frac{2T_r^{(0)}}{m_r}} \text{sign}(k_{\parallel}) (-2\zeta_r - 3i\sqrt{\pi}\zeta_r^2); \tag{3.46}$$

$$\tilde{r}_r^{(1)} = -\frac{q_r p_{0r}}{m_r} \Phi (3i\sqrt{\pi}\zeta_r - 16\zeta_r^2). \tag{3.47}$$

If we further restrict ourselves to only precision $o(\zeta_r)$ and neglect the ζ_r^2 terms, we can find an amazing result that we can express the heat flux $q_r^{(1)}$ with respect to temperature $T_r^{(1)}$ according to

$$o(\zeta_r) : \quad q_r^{(1)} = -i \frac{n_{0r}}{\sqrt{\pi}} \sqrt{\frac{8T_r^{(0)}}{m_r}} \text{sign}(k_{\parallel}) T_r^{(1)} = -i \frac{2n_{0r}}{\sqrt{\pi}} v_{\text{thr}} \text{sign}(k_{\parallel}) T_r^{(1)}. \tag{3.48}$$

The above result is of utmost importance, because it emphasizes the major difference between collisionless and collisional systems. At this point, the result is derived only with the assumption $|\zeta| \ll 1$, even though we will see later that the result is not restricted to this limit, and the result has a much wider applicability. The result is the famous expression for collisionless heat flux, that here reads $q \sim -i \text{sign}(k_{\parallel}) T$, which is in strong contrast to the usual collisional heat flux $q \sim -\nabla_{\parallel} T$ that in Fourier space reads $q \sim -ik_{\parallel} T$. We will come to this expression later.

With the precision $o(\zeta_r)$, other obvious possibilities are to express $q_r^{(1)}$ with respect to velocity $u_r^{(1)}$, or to express $\tilde{r}^{(1)}$ through $u_r^{(1)}$, $T_r^{(1)}$, $q_r^{(1)}$ according to

$$o(\zeta_r) : \quad q_r^{(1)} = -2n_{0r} T_r^{(0)} u_r^{(1)} = -2p_{0r} u_r^{(1)}; \tag{3.49}$$

$$\tilde{r}_r^{(1)} = i \frac{3}{2} \sqrt{\pi} v_{\text{thr}} p_{0r} \text{sign}(k_{\parallel}) u_r^{(1)}; \tag{3.50}$$

$$\tilde{r}_r^{(1)} = -\frac{3}{2} v_{\text{thr}}^2 n_{0r} T_r^{(1)}; \tag{3.51}$$

$$\tilde{r}_r^{(1)} = -i \frac{3}{4} \sqrt{\pi} v_{\text{thr}} \text{sign}(k_{\parallel}) q_r^{(1)}. \tag{3.52}$$

However, if we did so much work that we consider the fourth-order moment, it would be a shame not to increase the precision to $o(\zeta_r^2)$. Obviously, we need to use a combination of at least 2 different lower-order moments. For example, by trying

$$o(\zeta_r^2): \quad \tilde{r}_r^{(1)} = \alpha_q q_r^{(1)} + \alpha_T T_r^{(1)}. \quad (3.53)$$

The proportionality constants α_q, α_T are easily obtained by separation to two equations for ζ_r and ζ_r^2 that must be satisfied

$$-\frac{p_{0r}}{m_r} 3i\sqrt{\pi} = +2\alpha_q n_{0r} v_{\text{thr}} \text{sign}(k_{\parallel}) + i\alpha_T \sqrt{\pi}; \quad (3.54)$$

$$16\frac{p_{0r}}{m_r} = +\alpha_q n_{0r} v_{\text{thr}} \text{sign}(k_{\parallel}) 3i\sqrt{\pi} - 4\alpha_T. \quad (3.55)$$

Playing with the algebra little bit (for example $p_{0r}/m_r = T_r^{(0)} n_{0r}/m_r = v_{\text{thr}}^2 n_{0r}/2$), the two equations can be solved easily for the unknown quantities α_q, α_T , and the final result is

$$o(\zeta_r^2): \quad \tilde{r}_r^{(1)} = -i\frac{2\sqrt{\pi}}{3\pi - 8} v_{\text{thr}} \text{sign}(k_{\parallel}) q_r^{(1)} + \frac{32 - 9\pi}{2(3\pi - 8)} v_{\text{thr}}^2 n_{0r} T_r^{(1)}. \quad (3.56)$$

There are naturally other possibilities and with the precision $o(\zeta_r^2)$, one can search for closures

$$o(\zeta_r^2): \quad q_r^{(1)} = \alpha_T T_r^{(1)} + \alpha_u u_r^{(1)}; \quad (3.57)$$

$$\tilde{r}_r^{(1)} = \alpha_q q_r^{(1)} + \alpha_u u_r^{(1)}; \quad (3.58)$$

$$\tilde{r}_r^{(1)} = \alpha_T T_r^{(1)} + \alpha_u u_r^{(1)}, \quad (3.59)$$

where the first choice yields a closure

$$o(\zeta_r^2): \quad q_r^{(1)} = -i\frac{\sqrt{\pi}}{4 - \pi} n_{0r} v_{\text{thr}} \text{sign}(k_{\parallel}) T_r^{(1)} + \frac{3\pi - 8}{4 - \pi} n_{0r} T_r^{(0)} u_r^{(1)}, \quad (3.60)$$

and the other two choices yield

$$o(\zeta_r^2): \quad \tilde{r}_r^{(1)} = -i\frac{16 - 3\pi}{2\sqrt{\pi}} v_{\text{thr}} \text{sign}(k_{\parallel}) q_r^{(1)} - i\frac{32 - 9\pi}{2\sqrt{\pi}} v_{\text{thr}} n_{0r} T_r^{(0)} \text{sign}(k_{\parallel}) u_r^{(1)}; \quad (3.61)$$

$$\tilde{r}_r^{(1)} = -\frac{16 - 3\pi}{8 - 2\pi} v_{\text{thr}}^2 n_{0r} T_r^{(1)} + i\frac{2\sqrt{\pi}}{\pi - 4} v_{\text{thr}} n_{0r} T_r^{(0)} \text{sign}(k_{\parallel}) u_r^{(1)}. \quad (3.62)$$

For completeness, one can easily find a closure for $\tilde{r}_r^{(1)}$ with precision $o(\zeta_r^3)$ (after updating (3.44)–(3.47) to precision $o(\zeta_r^3)$) by searching for a solution

$$o(\zeta_r^3): \quad \tilde{r}_r^{(1)} = \alpha_q q_r^{(1)} + \alpha_T T_r^{(1)} + \alpha_u u_r^{(1)}, \quad (3.63)$$

and the solution reads

$$o(\zeta_r^3): \quad \tilde{r}_r^{(1)} = -i\sqrt{\pi} \frac{10 - 3\pi}{16 - 5\pi} v_{\text{thr}} \text{sign}(k_{\parallel}) q_r^{(1)} + \frac{21\pi - 64}{2(16 - 5\pi)} v_{\text{thr}}^2 n_{0r} T_r^{(1)} + i\sqrt{\pi} \frac{9\pi - 28}{16 - 5\pi} v_{\text{thr}} p_{0r} \text{sign}(k_{\parallel}) u_r^{(1)}. \quad (3.64)$$

We purposely kept the species index r in the calculations, to clearly show that the closures are performed for each species separately, and no Maxwell equations or other physical principles are used. The equations would be perhaps easier to read without the index r .

3.2.2. *Exploring the case $|\zeta| \gg 1$*

For large value of $|\zeta|$, we need to use an asymptotic expansion of the plasma dispersion function that reads

$$Z(\zeta) = i\sigma\sqrt{\pi}e^{-\zeta^2} - \frac{1}{\zeta} \left[1 + \frac{1}{2\zeta^2} + \frac{3}{4\zeta^4} + \frac{15}{8\zeta^6} + \frac{105}{16\zeta^8} \dots + \frac{(2n-1)!!}{(2\zeta^2)^n} + \dots \right]; \quad |\zeta| \gg 1, \tag{3.65}$$

where

$$\sigma = \begin{cases} 0, & \text{Im}(\zeta) > 0; \\ 1, & \text{Im}(\zeta) = 0; \\ 2, & \text{Im}(\zeta) < 0. \end{cases} \tag{3.66}$$

The term with σ comes directly from the definition of $Z(\zeta)$ and there is not much one can do further about it, since there is no further asymptotic expansion for $\exp(-\zeta^2)$ when ζ is large. The term is zero in the upper half of complex plane ($\sigma = 0$). When very close to the real axis, i.e. when $\sigma = 1$, the term mainly contributes to the imaginary part of $Z(\zeta)$ (even though only very weakly) and for the real part of $Z(\zeta)$, its contribution can be neglected. However, when deeply down in the lower half of complex plane, the term can become very large (for example if $\zeta = -iy$, $\exp(-\zeta^2) = \exp(y^2)$ and if y is large the term obviously explodes). Deeply down in the lower complex plane the term is a real trouble, and even some kinetic solvers such as WHAMP (Rönmark 1982) have trouble with calculations when the damping is too large.

We will see shortly, that for our purposes the term can be completely neglected, but let us keep it for a moment. The expansion of the Maxwellian plasma response function therefore reads

$$R(\zeta) = i\sigma\sqrt{\pi}\zeta e^{-\zeta^2} - \frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} - \frac{15}{8\zeta^6} - \frac{105}{16\zeta^8} - \frac{945}{32\zeta^{10}} \dots; \quad |\zeta| \gg 1. \tag{3.67}$$

Let us calculate the kinetic hierarchy, at least up to $1/\zeta^4$. After a short inspection, one immediately sees that the hierarchy calculates a bit differently than in the previous case, and to get the fourth-order moments with the precision $o(1/\zeta^4)$, it is important to keep all the terms up to $\sim 1/\zeta^8$ in the $R(\zeta)$ expression, since the fourth-order moments contain $\zeta^4 R(\zeta)$ terms. The expressions entering the kinetic hierarchy dully calculate as

$$n^{(1)} \sim R(\zeta) = i\sigma\sqrt{\pi}\zeta e^{-\zeta^2} - \frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} + o\left(\frac{1}{\zeta^4}\right); \tag{3.68}$$

$$u^{(1)} \sim \zeta R(\zeta) = i\sigma\sqrt{\pi}\zeta^2 e^{-\zeta^2} - \frac{1}{2\zeta} - \frac{3}{4\zeta^3} - \frac{15}{8\zeta^5}; \tag{3.69}$$

$$p^{(1)} \sim 1 + 2\zeta^2 R(\zeta) = 2i\sigma\sqrt{\pi}\zeta^3 e^{-\zeta^2} - \frac{3}{2\zeta^2} - \frac{15}{4\zeta^4}; \tag{3.70}$$

$$T^{(1)} \sim 1 - R(\zeta) + 2\zeta^2 R(\zeta) = i\sigma\sqrt{\pi}e^{-\zeta^2}(2\zeta^3 - \zeta) - \frac{1}{\zeta^2} - \frac{3}{\zeta^4}; \tag{3.71}$$

$$q^{(1)} \sim \zeta + 2\zeta^3 R(\zeta) - 3\zeta R(\zeta) = i\sigma\sqrt{\pi}e^{-\zeta^2}(2\zeta^4 - 3\zeta^2) - \frac{3}{2\zeta^3} - \frac{15}{2\zeta^5}; \tag{3.72}$$

$$r^{(1)} \sim 3 + 2\zeta^2 + 4\zeta^4 R(\zeta) = 4i\sigma\sqrt{\pi}\zeta^5 e^{-\zeta^2} - \frac{15}{2\zeta^2} - \frac{105}{4\zeta^4}; \quad (3.73)$$

$$\tilde{r}^{(1)} \sim 2\zeta^2 + 4\zeta^4 R(\zeta) + 3R(\zeta) - 3 - 12\zeta^2 R(\zeta) = i\sigma\sqrt{\pi}e^{-\zeta^2}(4\zeta^5 - 12\zeta^3 + 3\zeta) - \frac{6}{\zeta^4}, \quad (3.74)$$

where for brevity we suppressed the proportionality constants, including the $\text{sign}(k_{\parallel})$. Interestingly, the velocity $u^{(1)}$ decreases the slowest, only as $1/\zeta$. The $n^{(1)}$, $p^{(1)}$, $r^{(1)}$ and also the temperature $T^{(1)}$, decrease as $1/\zeta^2$. The heat flux $q^{(1)}$ decreases as $1/\zeta^3$ and the cumulant $\tilde{r}^{(1)}$ decreases the fastest, as $1/\zeta^4$. This is not good news, since it is obvious that the direct closures that were easily obtained for the small ζ case, cannot be easily done here.

To understand how the terms contribute to the real frequency and damping, it is useful to separate $\zeta = x + iy$ and calculate expressions with y being small, i.e. the weak growth-rate (actually weak damping) approximation. The exponential term entering (3.67) can be approximated as

$$\begin{aligned} \zeta^2 &= (x + iy)^2 = (x^2 - y^2) + 2ixy \approx x^2 + 2ixy; \\ e^{-\zeta^2} &\approx e^{-x^2} e^{-2ixy}; \\ i\zeta e^{-\zeta^2} &= i(x + iy)e^{-(x+iy)^2} \approx (-y + ix)e^{-x^2} e^{-2ixy}, \end{aligned} \quad (3.75)$$

and the fractions of ζ are approximately

$$\frac{1}{\zeta} = \frac{1}{x + iy} = \frac{1}{x \left(1 + i\frac{y}{x}\right)} \approx \frac{1}{x} \left(1 - i\frac{y}{x}\right) = \frac{1}{x} - i\frac{y}{x^2}; \quad (3.76)$$

$$\frac{1}{\zeta^2} = \frac{1}{x^2 \left(1 + i\frac{y}{x}\right)^2} \approx \frac{1}{x^2} \left(1 - 2i\frac{y}{x}\right) = \frac{1}{x^2} - 2i\frac{y}{x^3}; \quad (3.77)$$

$$\frac{1}{\zeta^3} \approx \frac{1}{x^3} - 3i\frac{y}{x^4}; \quad (3.78)$$

$$\frac{1}{\zeta^4} \approx \frac{1}{x^4} - 4i\frac{y}{x^5}, \quad (3.79)$$

etc. For large x , the exponential term (3.75) is strongly suppressed as e^{-x^2} (with oscillations e^{i2xy}). Additionally, the real part of (3.75) is proportional to y , which is also small, and its contribution to the real part of $R(\zeta)$ can be therefore completely neglected. The imaginary part of the exponential term (3.75) has to be kept, if one wants to match the approximate kinetic dispersion relations from plasma books (usually calculated in the weak growth rate/damping approximation), for example for the damping of the Langmuir mode or the ion-acoustic mode. However, even smart plasma physics books have trouble analytically reproducing the full kinetic dispersion relations that have to be solved numerically, see for example figures in Gurnett and Bhattacharjee on pages 341 and 355, that compare the analytic and full solutions for the Langmuir mode and the ion-acoustic mode. The trouble is that the damping can become large, and the entire approach with the weak damping invalid. If kinetic plasma books have trouble analytically reproducing the damping with full accuracy under these conditions, we would be naive to think that we can do better with a fluid model and we know we cannot be analytically exact for $|\zeta| \gg 1$ if the damping is

too large. If the damping is far too large, and the imaginary frequency starts to be comparable to real frequency, the mode will be damped away very quickly.

In fact, even the well-known kinetic solver WHAMP, neglects this term in calculation of $Z(\zeta)$ for large ζ values, as can be verified in the WHAMP full manual (Rönmark 1982) from the asymptotic expansion of $Z(\zeta)$, equation (III-6) on page 10, and the discussion of numerical errors on page 13. The WHAMP solver uses an eight-pole Padé approximant of $Z(\zeta)$, which is a very precise approximant, and imprecision starts to show up only if the damping become too large. For example, in the very damped regime when the $\text{Im}(\zeta) = -\text{Re}(\zeta)/2$, the error in real and imaginary values of $Z(\zeta)$ is still less than 2%–3%, where the calculation should be stopped (in a less damped regime, the precision is much higher).

If a full kinetic solver can neglect the exponential term for large ζ values, we can surely neglect it as well. It should be emphasized that the term is neglected only for large ζ values (i.e. in the asymptotic expansion), the exponential term is otherwise fully retained and enters the Padé approximation through the power series expansion for small ζ . To summarize, the ‘ideal’ large ζ asymptotic behaviour that we would like to obtain reads

$$\frac{n_r^{(1)}}{n_{0r}} = -\frac{q_r}{T_r^{(0)}} \Phi \left[-\frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} - \dots \right]; \tag{3.80}$$

$$u_r^{(1)} = -\frac{q_r}{T_r^{(0)}} \Phi v_{\text{thr}} \text{sign}(k_{\parallel}) \left[-\frac{1}{2\zeta} - \frac{3}{4\zeta^3} - \dots \right]; \tag{3.81}$$

$$\frac{p_r^{(1)}}{p_{0r}} = -\frac{q_r}{T_r^{(0)}} \Phi \left[-\frac{3}{2\zeta^2} - \frac{15}{4\zeta^4} - \dots \right]; \tag{3.82}$$

$$\frac{T_r^{(1)}}{T_r^{(0)}} = -\frac{q_r}{T_r^{(0)}} \Phi \left[-\frac{1}{\zeta^2} - \frac{3}{\zeta^4} - \dots \right]; \tag{3.83}$$

$$q_r^{(1)} = -q_r n_{0r} \Phi v_{\text{thr}} \text{sign}(k_{\parallel}) \left[-\frac{3}{2\zeta^3} - \frac{15}{2\zeta^5} - \dots \right]; \tag{3.84}$$

$$r_r^{(1)} = -\frac{q_r p_{0r}}{m_r} \Phi \left[-\frac{15}{2\zeta^2} - \frac{105}{4\zeta^4} - \dots \right]; \tag{3.85}$$

$$\tilde{T}_r^{(1)} = -\frac{q_r p_{0r}}{m_r} \Phi \left[-\frac{6}{\zeta^4} - \dots \right]. \tag{3.86}$$

3.3. A brief introduction to Padé approximants

Padé approximants, i.e. Padé series approximation/expansion, is a very powerful mathematical technique, comparable to the usual Taylor series and the Laurent series. Nevertheless, for some unknown reason, Padé series seems to somehow disappear from the modern educational system that a typical physicist encounters. The lack of Padé series in classes is even more surprising, if one realizes that the technique is in fact very simple, and anybody can fully grasp it in very short time. We therefore make a quick introduction to the technique here.

Padé series consist of approximating a function as a ratio of two polynomials. If a power series (e.g. Taylor series) of a function $f(x)$ is known around some point with coefficients c_n , the goal is to express it as a ratio of two polynomials

$$c_0 + c_1x + c_2x^2 + c_3x^3 + c_4x^4 + \dots = \frac{a_0 + a_1x + a_2x^2 + \dots}{1 + b_1x + b_2x^2 + \dots} \tag{3.87}$$

The choice of $b_0 = 1$ is an *ad hoc* choice and the entire decomposition can be done without it, leading to the same results at the end. Multiplying the left-hand side by the denominator $1 + b_1x + b_2x^2 + \dots$, and grouping the x^n contributions together, that must be satisfied independently, leads to the system of equations

$$\begin{aligned} a_0 &= c_0; \\ a_1 &= c_1 + c_0b_1; \\ a_2 &= c_2 + c_1b_1 + c_0b_2; \\ a_3 &= c_3 + c_2b_1 + c_1b_2 + c_0b_3; \\ a_4 &= c_4 + c_3b_1 + c_2b_2 + c_1b_3 + c_0b_4; \\ a_5 &= c_5 + c_4b_1 + c_3b_2 + c_2b_3 + c_1b_4 + c_0b_5; \\ a_6 &= c_6 + c_5b_1 + c_4b_2 + c_3b_3 + c_2b_4 + c_1b_5 + c_0b_6, \end{aligned} \quad (3.88)$$

etc. The necessary condition for the system being solvable, is that the number of variables is equivalent to the number of equations. Therefore, if we want to approximate function $f(x)$ with a ratio of two polynomials P_m/Q_n , of degrees m and n , we will need the Taylor series on the left-hand side of (3.87) up to the order $m+n$. The Padé approximation is sometimes denoted as $R_{m,n}$ or using a function $f(x)$ that is being approximated as $f(x)_{m,n}$ or $[f(x)]_{m,n}$. If the Padé approximation exists, it is unique.

For example, the function e^x has a Taylor series around the point $x=0$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots \quad (3.89)$$

Let us say we want to approximate e^x as a ratio of two polynomials of zeroth and first order $e^x \approx a_0/(1 + b_1x)$, i.e. we want to find the Padé approximant $[e^x]_{0,1}$. Respecting the $n+m$ rule, the approximation therefore consists of equating

$$\underbrace{c_0}_{=1} + \underbrace{c_1}_{=1}x = \frac{a_0}{1 + b_1x}, \quad (3.90)$$

that leads to the system of equations

$$\begin{aligned} a_0 &= c_0 = 1; \\ a_1 = 0 &= c_1 + b_1 \Rightarrow b_1 = -c_1 = -1, \end{aligned} \quad (3.91)$$

yielding the Padé approximation

$$[e^x]_{0,1} = \frac{1}{1-x}. \quad (3.92)$$

To feel confident with the Padé approximations, let us find another approximant of e^x , for example $[e^x]_{1,2}$. The system is written as

$$\underbrace{1}_{=c_0} + \underbrace{1}_{=c_1}x + \underbrace{\frac{1}{2}}_{=c_2}x^2 + \underbrace{\frac{1}{6}}_{=c_3}x^3 = \frac{a_0 + a_1x}{1 + b_1x + b_2x^2}, \quad (3.93)$$

and yields a system of equations

$$\begin{aligned}
 a_0 &= 1; \\
 a_1 &= 1 + b_1; \\
 a_2 &= 0 = \frac{1}{2} + b_1 + b_2; \\
 a_3 &= 0 = \frac{1}{6} + \frac{1}{2}b_1 + b_2 + 0,
 \end{aligned}
 \tag{3.94}$$

which have a solution $b_1 = -2/3, b_2 = 1/6, a_1 = 1/3$ and the Padé approximant

$$[e^x]_{1,2} = \frac{1 + \frac{1}{3}x}{1 - \frac{2}{3}x + \frac{1}{6}x^2} = \frac{6 + 2x}{6 - 4x + x^2}.
 \tag{3.95}$$

It is just a straightforward algebraic exercise to find other Padé approximations, for example

$$\begin{aligned}
 [e^x]_{1,1} &= \frac{1 + \frac{1}{2}x}{1 - \frac{1}{2}x} = \frac{2 + x}{2 - x}; \\
 [e^x]_{2,1} &= \frac{1 + \frac{2}{3}x + \frac{1}{6}x^2}{1 - \frac{1}{3}x} = \frac{6 + 4x + x^2}{6 - 2x}; \\
 [e^x]_{3,1} &= \frac{1 + \frac{3}{4}x + \frac{1}{4}x^2 + \frac{1}{24}x^3}{1 - \frac{1}{4}x} = \frac{24 + 18x + 6x^2 + x^3}{24 - 6x},
 \end{aligned}
 \tag{3.96}$$

etc. Similarly, it is easy to find Padé approximations to a function e^{-x} , and for example (obviously)

$$[e^{-x}]_{1,2} = \frac{6 - 2x}{6 + 4x + x^2}; \quad [e^{-x}]_{1,1} = \frac{2 - x}{2 + x}; \quad [e^{-x}]_{2,1} = \frac{6 - 4x + x^2}{6 + 2x}.
 \tag{3.97}$$

The approximations were derived from Taylor expansion of e^{-x} around $x=0$, and all 3 choices naturally have the correct limit $\lim_{x \rightarrow 0} e^{-x} = 1$. However, we can see that, by choosing the degree of the Padé approximation, we can also control what the function is doing for large values of x . For example, for large values of x the Padé approximations (3.97) go to 0, -1 and $+\infty$. Obviously, the smart choice is $[e^{-x}]_{1,2}$ which approximately reproduces the behaviour of e^{-x} also for large x . The usefulness of Padé approximation becomes especially apparent when considering analytically difficult functions, for example the e^{-x^2} , where the ‘smart’ lowest Padé approximants are

$$[e^{-x^2}]_{0,2} = \frac{1}{1 + x^2}; \quad [e^{-x^2}]_{0,4} = \frac{1}{1 + x^2 + \frac{1}{2}x^4}; \quad [e^{-x^2}]_{2,4} = \frac{6 - 2x^2}{6 + 4x^2 + x^4}.
 \tag{3.98}$$

Therefore, depending on the required precision of a physical problem, instead of working with e^{-x^2} (which for example does not have an indefinite integral that can be expressed in elementary functions), one can approximate the function e^{-x^2} for all x , as $1/(1 + x^2)$, that is much easier to work with. Curiously, the reader might recognize that the $1/(1 + x^2)$ is the Cauchy distribution function, often used in plasma physics books to get a better understanding of the complicated Landau damping. The Cauchy distribution therefore can be thought of as the simplest Padé approximation of the Maxwellian distribution.

Now we are ready to use the Padé approximation for the plasma dispersion function $Z(\zeta)$ or the plasma response function $R(\zeta)$. We do not have to explore all the possibilities, and we can immediately pick up only the smart choices. For large ζ (by neglecting the exponential term as discussed in the previous section), at the first order $Z(\zeta) \sim 1/\zeta$ and $R(\zeta) \sim 1/\zeta^2$, and both functions approach zero as ζ increases. Obviously, a smart choice worth exploring will always be a Padé approximant $[]_{m,n}$ where $n > m$. In fact, we can be even more specific. We know the asymptotic behaviour for large ζ , and obviously, even smarter choice is to concentrate only on approximants $[Z(\zeta)]_{n-1,n}$ and $[R(\zeta)]_{n-2,n}$, since such a choice will naturally lead to the correct asymptotic behaviour

$$\zeta \gg 1: [Z(\zeta)]_{n-1,n} \sim \frac{1}{\zeta}; \quad [R(\zeta)]_{n-2,n} \sim \frac{1}{\zeta^2}. \quad (3.99)$$

Any other choice is not really interesting and therefore, the usual 2-digit notation of the Padé approximation becomes redundant. We can just use 1-digit notation with ‘ n ’, that represents the degree of a chosen polynomial in the denominator, and we can omit writing the $(n-1)$ and $(n-2)$, since this will always be the case (except for the $R_1(\zeta)$). The ‘ n ’ represents the number of poles, and we therefore talk about an ‘ n -pole Padé approximation’ of $Z(\zeta)$ or $R(\zeta)$, and

$$Z_n(\zeta) = \frac{a_0 + a_1\zeta + \dots + a_{n-1}\zeta^{n-1}}{1 + b_1\zeta + \dots + b_n\zeta^n}; \quad R_n(\zeta) = \frac{a_0 + a_1\zeta + \dots + a_{n-2}\zeta^{n-2}}{1 + b_1\zeta + \dots + b_n\zeta^n}. \quad (3.100)$$

Note that one can directly work with Padé approximants for both $Z_n(\zeta)$ and $R_n(\zeta)$, and that in general, according to definitions (3.100), the approximants are not automatically equivalent. The difference is as if one does approximations to a function $f(x)$ or its derivative $f'(x)$. Usually in papers, the approximant $Z_n(\zeta)$ is calculated, and $R_n(\zeta)$ is just defined according to $R_n(\zeta) = 1 + \zeta Z_n(\zeta)$. One can choose another (and better approach in our opinion) and to calculate directly approximants $R_n(\zeta)$, and if really required (which should not be the case), obtain $Z_n(\zeta)$ approximants as $Z_n(\zeta) = (R_n(\zeta) - 1)/\zeta$.

Moreover, we can do even better than (3.100). We shall not be satisfied just by approximating the asymptotic trend $\sim 1/\zeta$ for $\zeta \gg 1$, and hope for the best. For large ζ , the correct asymptotic expansions are $Z(\zeta) \rightarrow -1/\zeta$ and $R(\zeta) \rightarrow -1/(2\zeta^2)$. By prescribing $a_{n-1}/b_n = -1$ for $Z(\zeta)$, and $a_{n-2}/b_n = -1/2$ for $R(\zeta)$, we will obtain correct asymptotic behaviour of these functions, at least at the first order. By doing this, we are not ‘destroying’ the Padé approximation, since it is easy to argue that if an n -pole approximation is determined to be sufficient for small ζ values, we can just add one more pole and use that one to control the asymptotic behaviour for large ζ values. Of course, we will always use at least the first term in the expansion for $\zeta \ll 1$, that yields $a_0 = i\sqrt{\pi}$ for $Z_n(\zeta)$ and $a_0 = 1$ for $R_n(\zeta)$, otherwise the functions will have incorrect values at $\zeta = 0$. The ‘smart’ choices worth considering therefore can be summarized as

$$\begin{aligned} Z_n(\zeta) &= \frac{i\sqrt{\pi} + a_1\zeta + \dots + a_{n-1}\zeta^{n-1}}{1 + b_1\zeta + \dots + b_{n-1}\zeta^{n-1} - a_{n-1}\zeta^n}; \\ R_n(\zeta) &= \frac{1 + a_1\zeta + \dots + a_{n-2}\zeta^{n-2}}{1 + b_1\zeta + \dots + b_{n-1}\zeta^{n-1} - 2a_{n-2}\zeta^n}, \end{aligned} \quad (3.101)$$

and have a property to correctly match the Z and R functions at $\zeta = 0$ and, have the correct first-order asymptotic expansion at $\zeta \gg 1$. The one-pole approximant $R_1(\zeta)$ is an exception, and can be defined only as $R_1(\zeta) = 1/(1 + b_1\zeta)$. This function obviously cannot have correct asymptotic expansion $\sim 1/\zeta^2$ and the only possibility is to use $\zeta \ll 1$ expansion $R_1(\zeta) = 1/(1 + b_1\zeta) = 1 + i\sqrt{\pi}\zeta$, which yields $b_1 = -i\sqrt{\pi}$ and

$$R_1(\zeta) = \frac{1}{1 - i\sqrt{\pi}\zeta}. \tag{3.102}$$

The one-pole approximant $Z_1(\zeta)$ can be obtained directly from the definition (3.101), that yields

$$Z_1(\zeta) = \frac{i\sqrt{\pi}}{1 - i\sqrt{\pi}\zeta}, \tag{3.103}$$

and that has correct asymptotic behaviour $Z_1(\zeta) \rightarrow -1/\zeta$ for large ζ values, even though it has only precision $o(\zeta^0)$ for small ζ values. Perhaps curiously, in this case $R_1(\zeta) = 1 + \zeta Z_1(\zeta)$ exactly. Alternatively, if the precision for small ζ is more important than the exact asymptotic expansion for large ζ , it is possible to increase the Z_1 precision to $o(\zeta^1)$ and write $Z_1(\zeta) = i\sqrt{\pi}/(1 - 2i\zeta/\sqrt{\pi})$. In this case $R_1(\zeta) \neq 1 + \zeta Z_1(\zeta)$ exactly, and the functions are equal only for small ζ and only with precision $o(\zeta^1)$.

Right now, in the definition (3.101), we just used 1 pole for the asymptotic series of $Z(\zeta)$ and $R(\zeta)$, but one can naturally use more poles. By opening the possibility of increasing the number of matching asymptotic points in the n -pole Padé approximation (3.101), the number of possible approximants for a given n naturally increases. To keep track of all the possibilities, we obviously need some kind of classification scheme. It is useful to modify the usual 1-index Padé series notation for $Z_n(\zeta)$ and $R_n(\zeta)$ functions (that only specify the number of poles), to a two index notation $Z_{n,n'}(\zeta)$, $R_{n,n'}(\zeta)$. Now we have a wide range of possibilities how to define n, n' and there is no clear ‘natural’ winner.

There are two different existing notations (likely more), introduced by Martín *et al.* (1980) and by Hedrick & Leboeuf (1992), that consider $Z_{n,n'}(\zeta)$ Padé approximants. The first reference defines n = number of points (equations) used in the power-series expansion, and n' = number of points (equations) used in the asymptotic series expansion. Even though perhaps clear, for example three-pole approximants in this notation are expressed as $Z_{5,1}, Z_{4,2}, Z_{3,3}$ etc., to get the number of poles (which is the most important information), one has to calculate $(n + n')/2$. When using a lot of different approximants, this notation is a bit confusing and is rarely used.

The notation of Hedrick & Leboeuf (1992) can be interpreted as defining $Z_{n,n'}$ with n = number of poles (which we like), and n' = number of additional poles in the asymptotic expansion that is used, compared to some ‘minimally interesting’ or ‘basic’ definition Z_n , that can be denoted as $Z_{n,0}$ (which we like too). The problem with the notation of Hedrick & Leboeuf (1992) is with the definition of the ‘basic’ $Z_{n,0}$, since the number of asymptotic points used in the definition of $Z_{n,0}$ keeps changing with n (and is actually equal to n). The notation is physically motivated, but the motivation is difficult to follow. The $Z_{2,0}$ is defined with 2 asymptotic points, $Z_{3,0}$ with 3 asymptotic points and so on. This can be easily deduced from their definitions of $Z_2 - Z_5$, as we will discuss later. We find this notation confusing.

Importantly, both mentioned notations consider the Padé approximants to $Z(\zeta)$. We do not really care about $Z(\zeta)$, since all the kinetic moments are formulated with $R(\zeta)$

at this stage. We want to calculate direct Padé approximants to $R(\zeta)$, which is actually slightly less analytically complicated for a given n . Here we define the 2-index Padé approximation to the plasma response function $R(\zeta)$ simply as

$$R_{n,0}(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2 + \cdots + a_{n-2}\zeta^{n-2}}{1 + b_1\zeta + b_2\zeta^2 + \cdots + b_{n-1}\zeta^{n-1} - 2a_{n-2}\zeta^n}, \quad (3.104)$$

i.e. as having asymptote $-1/(2\zeta^2)$ for large ζ , and notation $R_{n,n'}(\zeta)$ means that n' additional asymptotic points are used compared to the basic definition $R_{n,0}(\zeta)$. The notation feels natural, and the $n'=0$ index helps us to orient in the hierarchy of many possible $R(\zeta)$ approximants. It is easy to remember that this asymptotic profile is the minimum ‘desired’ profile that correctly captures the zeroth-order (density) moment, and any profile with less asymptotic points should be avoided if possible. The $R_{n,0}(\zeta)$ has power-series precision $o(\zeta^{2n-3})$ and asymptotic-series precision $o(\zeta^{-2})$, so $R_{n,n'}(\zeta)$ has precision $o(\zeta^{2n-3-n'})$ and $o(\zeta^{-2-n'})$.

Of course, we want to make the $R_{n,n'}(\zeta)$ and $Z_{n,n'}(\zeta)$ definitions fully consistent, and $Z_{n,n'}(\zeta)$ is defined so that

$$R_{n,n'}(\zeta) = 1 + \zeta Z_{n,n'}(\zeta), \quad (3.105)$$

is satisfied. This dictates that in comparison to $Z_n(\zeta)$ definition (3.101), two additional asymptotic points must be used to define the $Z_{n,0}(\zeta)$. We have no other choice and when calculating the $Z_{n,n'}(\zeta)$, we have to start counting from $n' = -2$, and we define

$$Z_{n,-2}(\zeta) = \frac{i\sqrt{\pi} + a_1\zeta + \cdots + a_{n-1}\zeta^{n-1}}{1 + b_1\zeta + \cdots + b_{n-1}\zeta^{n-1} - a_{n-1}\zeta^n}. \quad (3.106)$$

When calculating the hierarchy of plasma dispersion functions $Z(\zeta)$, the -2 index is actually a nice reminder that we are two asymptotic points short of the ‘desired’ profile (3.104) for the plasma response function $R(\zeta)$. We want to feel fully confident that we understand both Padé approximants $R(\zeta)$ and $Z(\zeta)$, and we will calculate two-pole and three-pole approximants for both functions. For four-pole approximants and above, we will only work with $R(\zeta)$.

Padé approximants were also used for other interesting physical problems, such as developing analytic models for the Rayleigh–Taylor and Richtmyer–Meshkov instabilities (Zhou 2017a,b).

3.3.1. Two-pole approximants of $R(\zeta)$ and $Z(\zeta)$

Let us be patient and go slowly. A general two-pole Padé approximant to $R(\zeta)$ is

$$R_2(\zeta) = \frac{a_0}{1 + b_1\zeta + b_2\zeta^2}, \quad (3.107)$$

where $a_0 = 1$. The asymptotic expansion for large ζ values calculates as

$$\begin{aligned} \frac{a_0}{1 + b_1\zeta + b_2\zeta^2} &= \frac{a_0}{b_2\zeta^2 \left(\frac{1}{b_2\zeta^2} + \frac{b_1}{b_2\zeta} + 1 \right)} \\ &= \frac{a_0}{b_2\zeta^2} \left[1 - \left(\frac{b_1}{b_2\zeta} + \frac{1}{b_2\zeta^2} \right) + \left(\frac{b_1}{b_2\zeta} + \frac{1}{b_2\zeta^2} \right)^2 + \cdots \right] \\ &= \frac{a_0}{b_2\zeta^2} - a_0 \frac{b_1}{b_2^2\zeta^3} + a_0 \frac{b_1^2 - b_2}{b_2^3\zeta^4} + \cdots; \quad \zeta \gg 1, \end{aligned} \quad (3.108)$$

and must be matched with the asymptotic expansion (3.67)

$$R(\zeta) = -\frac{1}{2\zeta^2} - \frac{0}{\zeta^3} - \frac{3}{4\zeta^4} + \dots; \quad \zeta \gg 1. \tag{3.109}$$

Matching the first point implies $b_2 = -2a_0$, and this is how $R_{2,0}(\zeta)$ is defined. Then, matching with 2 equations for the small ζ expansion, equation (3.36), the classical Padé approach yields

$$R_{2,0}(\zeta) = \frac{a_0}{1 + b_1\zeta - 2a_0\zeta^2} = \underbrace{1}_{=c_0} + \underbrace{i\sqrt{\pi}\zeta}_{=c_1}; \quad \Rightarrow \quad R_{2,0}(\zeta) = \frac{1}{1 - i\sqrt{\pi}\zeta - 2\zeta^2}. \tag{3.110}$$

To match additional asymptotic point (and to potentially find $R_{2,1}(\zeta)$), dictates that $b_1 = 0$. However, the resulting function $R_{2,1}(\zeta) = 1/(1 - 2\zeta^2)$ does not have any imaginary part for real valued ζ , since it uses too many asymptotic points and the Landau residue is not accounted for. Therefore, the $R_{2,1}(\zeta)$ does not represent a valuable approximation of $R(\zeta)$, and this approximant is eliminated.

Let us now explore possible two-pole approximations of $Z(\zeta)$. A general two-pole approximant is defined as

$$Z_2(\zeta) = \frac{a_0 + a_1\zeta}{1 + b_1\zeta + b_2\zeta^2}, \tag{3.111}$$

and has the following asymptotic expansion for large ζ values

$$\begin{aligned} \frac{a_0 + a_1\zeta}{1 + b_1\zeta + b_2\zeta^2} &= \left(\frac{a_1}{b_2}\right) \frac{1}{\zeta} + \left(\frac{a_0}{b_2} - \frac{a_1b_1}{b_2^2}\right) \frac{1}{\zeta^2} \\ &+ \left(-\frac{a_0b_1}{b_2^2} + \frac{a_1(b_1^2 - b_2)}{b_2^3}\right) \frac{1}{\zeta^3} + \dots; \quad \zeta \gg 1. \end{aligned} \tag{3.112}$$

The $Z(\zeta)$ has asymptotic expansion

$$Z(\zeta) = -\frac{1}{\zeta} - \frac{0}{\zeta^2} - \frac{1}{2\zeta^3} + \dots; \quad \zeta \gg 1, \tag{3.113}$$

so by matching with $1/\zeta$ implies $b_2 = -a_1$ (as already used previously) that defines $Z_{2,-2}$ (remember, we are starting to count with $n' = -2$). By further matching with $1/\zeta^2$ implies $b_1 = -a_0$, that defines $Z_{2,-1}$, and by further matching with $1/\zeta^3$ implies $a_1 = 2$, that defines $Z_{2,0}$.

The calculation is continued by matching with the power series for small ζ values, i.e. by using the classical Padé approach, that is described as

$$Z_{2,-2}(\zeta) = \frac{a_0 + a_1\zeta}{1 + b_1\zeta - a_1\zeta^2} = \underbrace{i\sqrt{\pi}}_{=c_0} \underbrace{-2}_{=c_1} \zeta \underbrace{-i\sqrt{\pi}}_{=c_2} \zeta^2, \tag{3.114}$$

and the solution is

$$Z_{2,-2}(\zeta) = \frac{i\sqrt{\pi} + \frac{4 - \pi}{\pi - 2}\zeta}{1 - \frac{i\sqrt{\pi}}{\pi - 2}\zeta - \frac{4 - \pi}{\pi - 2}\zeta^2}. \tag{3.115}$$

Continuing with $Z_{2,-1}(\zeta)$, i.e. by using one more additional asymptotic term that dictates $b_1 = -a_0$, the matching with the power series yields

$$Z_{2,-1}(\zeta) = \frac{a_0 + a_1\zeta}{1 - a_0\zeta - a_1\zeta^2} = i\sqrt{\pi} - 2\zeta; \Rightarrow Z_{2,-1}(\zeta) = \frac{i\sqrt{\pi} + (\pi - 2)\zeta}{1 - i\sqrt{\pi}\zeta - (\pi - 2)\zeta^2}. \tag{3.116}$$

Similarly, considering $Z_{2,0}(\zeta)$ yields

$$Z_{2,0}(\zeta) = \frac{a_0 + 2\zeta}{1 - a_0\zeta - 2\zeta^2} = i\sqrt{\pi}; \Rightarrow Z_{2,0}(\zeta) = \frac{i\sqrt{\pi} + 2\zeta}{1 - i\sqrt{\pi}\zeta - 2\zeta^2}. \tag{3.117}$$

Obviously, $R_{2,0}(\zeta) = 1 + \zeta Z_{2,0}(\zeta)$ exactly.

3.3.2. Three-pole approximants of $R(\zeta)$ and $Z(\zeta)$

A general three-pole approximant of $R(\zeta)$ is

$$R_3(\zeta) = \frac{a_0 + a_1\zeta}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3}. \tag{3.118}$$

The asymptotic expansion calculates as

$$\begin{aligned} \frac{1}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3} &= \frac{1}{b_3\zeta^3 \left(\frac{1}{b_3\zeta^3} + \frac{b_1}{b_3\zeta^2} + \frac{b_2}{b_3\zeta} + 1 \right)} \\ &= \frac{1}{b_3\zeta^3} \left[1 - \left(\frac{b_2}{b_3\zeta} + \frac{b_1}{b_3\zeta^2} + \frac{1}{b_3\zeta^3} \right) \right. \\ &\quad \left. + \left(\frac{b_2}{b_3\zeta} + \frac{b_1}{b_3\zeta^2} + \frac{1}{b_3\zeta^3} \right)^2 + \dots \right] \\ &= \frac{1}{b_3\zeta^3} \left[1 - \frac{1}{\zeta} \frac{b_2}{b_3} + \frac{1}{\zeta^2} \left(-\frac{b_1}{b_3} + \frac{b_2^2}{b_3^2} \right) + \dots \right] \\ &= \frac{1}{b_3\zeta^3} - \frac{b_2}{b_3^2\zeta^4} + \frac{b_2^2 - b_1b_3}{b_3^3\zeta^5} + \dots, \end{aligned} \tag{3.119}$$

so that

$$\begin{aligned} \frac{a_0 + a_1\zeta}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3} &= \frac{a_1}{b_3\zeta^2} + \frac{1}{\zeta^3} \left(\frac{a_0}{b_3} - \frac{a_1b_2}{b_3^2} \right) \\ &\quad + \frac{1}{\zeta^4} \left(-\frac{a_0b_2}{b_3^2} + a_1 \frac{b_2^2 - b_1b_3}{b_3^3} \right) + \dots \end{aligned} \tag{3.120}$$

For $R_{3,0}(\zeta)$ this implies $b_3 = -2a_1$, for $R_{3,1}(\zeta)$ additionally $b_2 = -2a_0$ and for $R_{3,2}(\zeta)$ also $b_1 = 3a_1$. The asymptotic expansions (3.120) can become very long for higher orders of ζ , especially when more poles are considered. It is beneficial to write down the following scheme, where in each line, we advance the matching with one more asymptotic point,

$$\frac{a_0 + a_1\zeta}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3} = \underbrace{\frac{a_1}{b_3}}_{=-1/2} \frac{1}{\zeta^2} + \dots \Rightarrow b_3 = -2a_1; \tag{3.121}$$

$$\begin{aligned}
 R_{3,0}(\zeta) &= \frac{a_0 + a_1\zeta}{1 + b_1\zeta + b_2\zeta^2 - 2a_1\zeta^3} \\
 &= -\frac{1}{2\zeta^2} - \underbrace{\frac{a_0 + \frac{b_2}{2}}{2a_1}}_{=0} \frac{1}{\zeta^3} + \dots \Rightarrow b_2 = -2a_0; \tag{3.122}
 \end{aligned}$$

$$\begin{aligned}
 R_{3,1}(\zeta) &= \frac{a_0 + a_1\zeta}{1 + b_1\zeta - 2a_0\zeta^2 - 2a_1\zeta^3} \\
 &= -\frac{1}{2\zeta^2} - \underbrace{\frac{b_1}{4a_1}}_{=3/4} \frac{1}{\zeta^4} + \dots \Rightarrow b_1 = 3a_1; \tag{3.123}
 \end{aligned}$$

$$\begin{aligned}
 R_{3,2}(\zeta) &= \frac{a_0 + a_1\zeta}{1 + 3a_1\zeta - 2a_0\zeta^2 - 2a_1\zeta^3} \\
 &= -\frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} - \underbrace{\frac{1 - 3a_0}{4a_1}}_{=0} \frac{1}{\zeta^5} + \dots \Rightarrow a_1 \rightarrow \infty. \tag{3.124}
 \end{aligned}$$

In the last expression the $a_1 \rightarrow \infty$ since $a_0 = 1$, implying the $R_{3,3}(\zeta)$ does not make sense and it is not defined. The scheme can be very quickly verified by using Maple (or Mathematica) software, by using command *asympt(expression(ζ), ζ, n)*, where ζ is the variable, and n prescribes the precision of the expansion that is calculated up to the $o(\zeta^{-n})$ order. Now by matching with the power series for small ζ values

$$R_{3,0}(\zeta) = \frac{a_0 + a_1\zeta}{1 + b_1\zeta + b_2\zeta^2 - 2a_1\zeta^3} = 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3; \tag{3.125}$$

$$R_{3,1}(\zeta) = \frac{a_0 + a_1\zeta}{1 + b_1\zeta - 2a_0\zeta^2 - 2a_1\zeta^3} = 1 + i\sqrt{\pi}\zeta - 2\zeta^2; \tag{3.126}$$

$$R_{3,2}(\zeta) = \frac{a_0 + a_1\zeta}{1 + 3a_1\zeta - 2a_0\zeta^2 - 2a_1\zeta^3} = 1 + i\sqrt{\pi}\zeta; \tag{3.127}$$

and the solutions are

$$R_{3,0}(\zeta) = \frac{1 - i\sqrt{\pi}\frac{\pi - 3}{4 - \pi}\zeta}{1 - i\frac{\sqrt{\pi}}{4 - \pi}\zeta - \frac{3\pi - 8}{4 - \pi}\zeta^2 + 2i\sqrt{\pi}\frac{\pi - 3}{4 - \pi}\zeta^3}; \tag{3.128}$$

$$R_{3,1}(\zeta) = \frac{1 - i\frac{4 - \pi}{\sqrt{\pi}}\zeta}{1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4 - \pi}{\sqrt{\pi}}\zeta^3}; \tag{3.129}$$

$$R_{3,2}(\zeta) = \frac{1 - \frac{i\sqrt{\pi}}{2}\zeta}{1 - \frac{3i\sqrt{\pi}}{2}\zeta - 2\zeta^2 + i\sqrt{\pi}\zeta^3}. \tag{3.130}$$

A general three-pole approximant of $Z(\zeta)$ is

$$Z_3(\zeta) = \frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3}, \tag{3.131}$$

and has the following asymptotic expansion

$$\frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3} = \frac{a_2}{b_3\zeta} + \left(\frac{a_1}{b_3} - \frac{a_2b_2}{b_3^2}\right) \frac{1}{\zeta^2} + \left(\frac{a_0}{b_3} - \frac{a_1b_2}{b_3^2} + \frac{a_2(b_2^2 - b_1b_3)}{b_3^3}\right) \frac{1}{\zeta^3} + \dots \quad (3.132)$$

Matching the first asymptotic term implies $b_3 = -a_2$, which defines $Z_{3,-2}(\zeta)$. For $Z_{3,-1}(\zeta)$ the second term is matched as well and $b_2 = -a_1$. For $Z_{3,0}(\zeta)$ the third term is also matched and $b_1 = -a_0 + a_2/2$. To go higher requires higher-order expansion (3.132). It is again easier to write down the asymptotic expansion scheme step by step

$$\frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3} = \underbrace{\frac{a_2}{b_3}}_{=-1} \frac{1}{\zeta} + \dots; \Rightarrow b_3 = -a_2; \quad (3.133)$$

$$Z_{3,-2}(\zeta) = \frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 - a_2\zeta^3} = -\frac{1}{\zeta} - \underbrace{\frac{a_1 + b_2}{a_2}}_{=0} \frac{1}{\zeta^2} + \dots \Rightarrow b_2 = -a_1; \quad (3.134)$$

$$\begin{aligned} Z_{3,-1}(\zeta) &= \frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta - a_1\zeta^2 - a_2\zeta^3} \\ &= -\frac{1}{\zeta} - \frac{0}{\zeta^2} - \underbrace{\frac{a_0 + b_1}{a_2}}_{=1/2} \frac{1}{\zeta^3} + \dots \Rightarrow b_1 = \frac{a_2}{2} - a_0; \end{aligned} \quad (3.135)$$

$$\begin{aligned} Z_{3,0}(\zeta) &= \frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + \left(\frac{a_2}{2} - a_0\right)\zeta - a_1\zeta^2 - a_2\zeta^3} \\ &= -\frac{1}{\zeta} - \frac{1}{2\zeta^3} - \underbrace{\frac{2 - a_1}{2a_2}}_{=0} \frac{1}{\zeta^4} + \dots \Rightarrow a_1 = 2; \end{aligned} \quad (3.136)$$

$$\begin{aligned} Z_{3,1}(\zeta) &= \frac{a_0 + 2\zeta + a_2\zeta^2}{1 + \left(\frac{a_2}{2} - a_0\right)\zeta - 2\zeta^2 - a_2\zeta^3} \\ &= -\frac{1}{\zeta} - \frac{1}{2\zeta^3} - \underbrace{\frac{a_2 - 2a_0}{4a_2}}_{=3/4} \frac{1}{\zeta^5} + \dots \Rightarrow a_2 = -a_0; \end{aligned} \quad (3.137)$$

$$Z_{3,2}(\zeta) = \frac{a_0 + 2\zeta - a_0\zeta^2}{1 - \frac{3}{2}a_0\zeta - 2\zeta^2 + a_0\zeta^3}. \quad (3.138)$$

Matching these results with an expansion for small ζ values is done according to

$$Z_{3,-2}(\zeta) = \frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 - a_2\zeta^3} = i\sqrt{\pi} - 2\zeta - i\sqrt{\pi}\zeta^2 + \frac{4}{3}\zeta^3 + i\frac{\sqrt{\pi}}{2}\zeta^4; \quad (3.139)$$

$$Z_{3,-1}(\zeta) = \frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta - a_1\zeta^2 - a_2\zeta^3} = i\sqrt{\pi} - 2\zeta - i\sqrt{\pi}\zeta^2 + \frac{4}{3}\zeta^3; \quad (3.140)$$

$$Z_{3,0}(\zeta) = \frac{a_0 + a_1\zeta + a_2\zeta^2}{1 + \left(-a_0 + \frac{a_2}{2}\right)\zeta - a_1\zeta^2 - a_2\zeta^3} = i\sqrt{\pi} - 2\zeta - i\sqrt{\pi}\zeta^2; \quad (3.141)$$

$$Z_{3,1}(\zeta) = \frac{a_0 + 2\zeta + a_2\zeta^2}{1 + \left(\frac{a_2}{2} - a_0\right)\zeta - 2\zeta^2 - a_2\zeta^3} = i\sqrt{\pi} - 2\zeta; \quad (3.142)$$

$$Z_{3,2}(\zeta) = \frac{a_0 + 2\zeta - a_0\zeta^2}{1 - \frac{3}{2}a_0\zeta - 2\zeta^2 + a_0\zeta^3} = i\sqrt{\pi}, \quad (3.143)$$

and the solutions are

$$Z_{3,-2}(\zeta) = \frac{i\sqrt{\pi} + \frac{3\pi^2 - 30\pi + 64}{2(5\pi - 16)}\zeta + \frac{i\sqrt{\pi}(9\pi - 28)}{6(5\pi - 16)}\zeta^2}{1 - \frac{i\sqrt{\pi}(3\pi - 10)}{2(5\pi - 16)}\zeta + \frac{21\pi - 64}{6(5\pi - 16)}\zeta^2 - \frac{i\sqrt{\pi}(9\pi - 28)}{6(5\pi - 16)}\zeta^3}; \quad (3.144)$$

$$Z_{3,-1}(\zeta) = \frac{i\sqrt{\pi} + \frac{10 - 3\pi}{3(\pi - 3)}\zeta + \frac{i(5\pi - 16)}{3\sqrt{\pi}(\pi - 3)}\zeta^2}{1 - \frac{i(3\pi - 8)}{3\sqrt{\pi}(\pi - 3)}\zeta - \frac{10 - 3\pi}{3(\pi - 3)}\zeta^2 - \frac{i(5\pi - 16)}{3\sqrt{\pi}(\pi - 3)}\zeta^3}; \quad (3.145)$$

$$Z_{3,0}(\zeta) = \frac{i\sqrt{\pi} + \frac{3\pi - 8}{4 - \pi}\zeta - 2i\sqrt{\pi}\frac{\pi - 3}{4 - \pi}\zeta^2}{1 - \frac{i\sqrt{\pi}}{4 - \pi}\zeta - \frac{3\pi - 8}{4 - \pi}\zeta^2 + 2i\sqrt{\pi}\frac{\pi - 3}{4 - \pi}\zeta^3}. \quad (3.146)$$

$$Z_{3,1}(\zeta) = \frac{i\sqrt{\pi} + 2\zeta - 2i\frac{4 - \pi}{\sqrt{\pi}}\zeta^2}{1 - i\frac{4}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4 - \pi}{\sqrt{\pi}}\zeta^3}; \quad (3.147)$$

$$Z_{3,2}(\zeta) = \frac{i\sqrt{\pi} + 2\zeta - i\sqrt{\pi}\zeta^2}{1 - \frac{3}{2}i\sqrt{\pi}\zeta - 2\zeta^2 + i\sqrt{\pi}\zeta^3}. \quad (3.148)$$

Of course, the following relations now hold exactly

$$R_{3,0}(\zeta) = 1 + \zeta Z_{3,0}(\zeta); \quad (3.149)$$

$$R_{3,1}(\zeta) = 1 + \zeta Z_{3,1}(\zeta); \quad (3.150)$$

$$R_{3,2}(\zeta) = 1 + \zeta Z_{3,2}(\zeta). \quad (3.151)$$

3.3.3. Four-pole approximants of $R(\zeta)$ and $Z(\zeta)$

As before, the procedure of matching with asymptotic expansion yields (for simplicity already assuming $a_0 = 1$)

$$\frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 + b_4\zeta^4} = \underbrace{\frac{a_2}{b_4}}_{=-1/2} \frac{1}{\zeta^2} + \dots \Rightarrow b_4 = -2a_2; \quad (3.152)$$

$$\begin{aligned}
 R_{4,0}(\zeta) &= \frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 - 2a_2\zeta^4} \\
 &= -\frac{1}{2\zeta^2} - \underbrace{\frac{a_1 + \frac{b_3}{2}}{2a_2}}_{=0} \frac{1}{\zeta^3} + \dots \Rightarrow b_3 = -2a_1; \quad (3.153)
 \end{aligned}$$

$$\begin{aligned}
 R_{4,1}(\zeta) &= \frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 - 2a_1\zeta^3 - 2a_2\zeta^4} \\
 &= -\frac{1}{2\zeta^2} - \underbrace{\frac{1 + \frac{b_2}{2}}{2a_2}}_{=3/4} \frac{1}{\zeta^4} + \dots \Rightarrow b_2 = 3a_2 - 2; \quad (3.154)
 \end{aligned}$$

$$\begin{aligned}
 R_{4,2}(\zeta) &= \frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + (3a_2 - 2)\zeta^2 - 2a_1\zeta^3 - 2a_2\zeta^4} \\
 &= -\frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} - \underbrace{\frac{b_1 - 3a_1}{4a_2}}_{=0} \frac{1}{\zeta^5} + \dots \Rightarrow b_1 = 3a_1; \quad (3.155)
 \end{aligned}$$

$$\begin{aligned}
 R_{4,3}(\zeta) &= \frac{1 + a_1\zeta + a_2\zeta^2}{1 + 3a_1\zeta + (3a_2 - 2)\zeta^2 - 2a_1\zeta^3 - 2a_2\zeta^4} \\
 &= -\frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} - \underbrace{\frac{\frac{9}{2}a_2 - 2}{4a_2}}_{=15/8} \frac{1}{\zeta^6} + \dots \Rightarrow a_2 = -\frac{2}{3}; \quad (3.156)
 \end{aligned}$$

$$\begin{aligned}
 R_{4,4}(\zeta) &= \frac{1 + a_1\zeta - \frac{2}{3}\zeta^2}{1 + 3a_1\zeta - 4\zeta^2 - 2a_1\zeta^3 + \frac{4}{3}\zeta^4} \\
 &= -\frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} - \frac{15}{8\zeta^6} - \underbrace{\frac{9a_1}{8}}_{=0} \frac{1}{\zeta^7} \Rightarrow a_1 = 0, \quad (3.157)
 \end{aligned}$$

where the last relation implies a possible approximant $R_{4,5}(\zeta) = (1 - \frac{2}{3}\zeta^2)/(1 - 4\zeta^2 + \frac{4}{3}\zeta^4)$. However, such an approximant is not well behaved (it has zero imaginary part for real valued ζ) and the $R_{4,5}(\zeta)$ is eliminated. Matching with the power series is performed according to

$$\begin{aligned}
 R_{4,0}(\zeta) &= \frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 - 2a_2\zeta^4} \\
 &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 + i\frac{\sqrt{\pi}}{2}\zeta^5; \quad (3.158)
 \end{aligned}$$

$$R_{4,1}(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 - 2a_1\zeta^3 - 2a_2\zeta^4} = 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4; \quad (3.159)$$

$$R_{4,2}(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + (3a_2 - 2)\zeta^2 - 2a_1\zeta^3 - 2a_2\zeta^4} = 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3; \quad (3.160)$$

$$R_{4,3}(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2}{1 + 3a_1\zeta + (3a_2 - 2)\zeta^2 - 2a_1\zeta^3 - 2a_2\zeta^4} = 1 + i\sqrt{\pi}\zeta - 2\zeta^2; \quad (3.161)$$

$$R_{4,4}(\zeta) = \frac{1 + a_1\zeta - \frac{2}{3}\zeta^2}{1 + 3a_1\zeta - 4\zeta^2 - 2a_1\zeta^3 + \frac{4}{3}\zeta^4} = 1 + i\sqrt{\pi}\zeta, \quad (3.162)$$

and the results are

$$R_{4,0}(\zeta) = \frac{1 + i\frac{\sqrt{\pi}}{2} \frac{(12\pi^2 - 67\pi + 92)}{(6\pi^2 - 29\pi + 32)} \zeta - \frac{(9\pi^2 - 69\pi + 128)}{6(6\pi^2 - 29\pi + 32)} \zeta^2}{1 - i\frac{\sqrt{\pi}}{2} \frac{(9\pi - 28)}{(6\pi^2 - 29\pi + 32)} \zeta + \frac{(36\pi^2 - 195\pi + 256)}{6(6\pi^2 - 29\pi + 32)} \zeta^2 - i\frac{\sqrt{\pi}(33\pi - 104)}{6(6\pi^2 - 29\pi + 32)} \zeta^3 + \frac{(9\pi^2 - 69\pi + 128)}{3(6\pi^2 - 29\pi + 32)} \zeta^4}; \quad (3.163)$$

$$R_{4,1}(\zeta) = \frac{1 - i\frac{\sqrt{\pi}}{3} \frac{(9\pi - 28)}{(16 - 5\pi)} \zeta - \frac{(6\pi^2 - 29\pi + 32)}{3(16 - 5\pi)} \zeta^2}{1 - i\frac{2\sqrt{\pi}}{3} \frac{(10 - 3\pi)}{(16 - 5\pi)} \zeta - \frac{(21\pi - 64)}{3(16 - 5\pi)} \zeta^2 + i\frac{2\sqrt{\pi}}{3} \frac{(9\pi - 28)}{(16 - 5\pi)} \zeta^3 + \frac{2(6\pi^2 - 29\pi + 32)}{3(16 - 5\pi)} \zeta^4}; \quad (3.164)$$

$$R_{4,2}(\zeta) = \frac{1 - i\sqrt{\pi} \frac{(10 - 3\pi)}{(3\pi - 8)} \zeta - \frac{(16 - 5\pi)}{(3\pi - 8)} \zeta^2}{1 - i\sqrt{\pi} \frac{2}{(3\pi - 8)} \zeta - \frac{(32 - 9\pi)}{(3\pi - 8)} \zeta^2 + i\sqrt{\pi} \frac{2(10 - 3\pi)}{(3\pi - 8)} \zeta^3 + \frac{2(16 - 5\pi)}{(3\pi - 8)} \zeta^4}; \quad (3.165)$$

$$R_{4,3}(\zeta) = \frac{1 - i\frac{\sqrt{\pi}}{2} \zeta - \frac{(3\pi - 8)}{4} \zeta^2}{1 - i\frac{3\sqrt{\pi}}{2} \zeta - \frac{(9\pi - 16)}{4} \zeta^2 + i\sqrt{\pi} \zeta^3 + \frac{(3\pi - 8)}{2} \zeta^4}; \quad (3.166)$$

$$R_{4,4}(\zeta) = \frac{1 - i\frac{\sqrt{\pi}}{2} \zeta - \frac{2}{3} \zeta^2}{1 - i\frac{3\sqrt{\pi}}{2} \zeta - 4\zeta^2 + i\sqrt{\pi} \zeta^3 + \frac{4}{3} \zeta^4}. \quad (3.167)$$

Of the four-pole approximants, perhaps the most well-known one is $R_{4,3}(\zeta)$ used for example by Hammett & Perkins (1990), Passot & Sulem (2007) etc., and which can be written in a convenient form

$$R_{4,3}(\zeta) = \frac{4 - 2i\sqrt{\pi}\zeta - (3\pi - 8)\zeta^2}{4 - 6i\sqrt{\pi}\zeta - (9\pi - 16)\zeta^2 + 4i\sqrt{\pi}\zeta^3 + 2(3\pi - 8)\zeta^4}. \quad (3.168)$$

Here we do not double check the derivation of the $Z_4(\zeta)$ approximants ‘from scratch’, and for a given R_4 coefficients, the Z_4 coefficients are of course easily obtained by

$$R_4(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 + b_4\zeta^4} \Rightarrow Z_4(\zeta) = \frac{(a_1 - b_1) + (a_2 - b_2)\zeta - b_3\zeta^2 - b_4\zeta^3}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 + b_4\zeta^4}. \quad (3.169)$$

For completeness, the corresponding results are

$$Z_{4,0}(\zeta) = \frac{i\sqrt{\pi} - \frac{(15\pi^2 - 88\pi + 128)}{2(6\pi^2 - 29\pi + 32)} \zeta + i\frac{\sqrt{\pi}(33\pi - 104)}{6(6\pi^2 - 29\pi + 32)} \zeta^2 - \frac{(9\pi^2 - 69\pi + 128)}{3(6\pi^2 - 29\pi + 32)} \zeta^3}{1 - i\frac{\sqrt{\pi}}{2} \frac{(9\pi - 28)}{(6\pi^2 - 29\pi + 32)} \zeta + \frac{(36\pi^2 - 195\pi + 256)}{6(6\pi^2 - 29\pi + 32)} \zeta^2 - i\frac{\sqrt{\pi}(33\pi - 104)}{6(6\pi^2 - 29\pi + 32)} \zeta^3 + \frac{(9\pi^2 - 69\pi + 128)}{3(6\pi^2 - 29\pi + 32)} \zeta^4}; \quad (3.170)$$

$$Z_{4,1}(\zeta) = \frac{i\sqrt{\pi} - \frac{2(3\pi^2 - 25\pi + 48)}{3(16 - 5\pi)}\zeta - i\frac{2\sqrt{\pi}}{3}\frac{(9\pi - 28)}{(16 - 5\pi)}\zeta^2 - \frac{2(6\pi^2 - 29\pi + 32)}{3(16 - 5\pi)}\zeta^3}{1 - i\frac{2\sqrt{\pi}}{3}\frac{(10 - 3\pi)}{(16 - 5\pi)}\zeta - \frac{(21\pi - 64)}{3(16 - 5\pi)}\zeta^2 + i\frac{2\sqrt{\pi}}{3}\frac{(9\pi - 28)}{(16 - 5\pi)}\zeta^3 + \frac{2(6\pi^2 - 29\pi + 32)}{3(16 - 5\pi)}\zeta^4}; \tag{3.171}$$

$$Z_{4,2}(\zeta) = \frac{i\sqrt{\pi} + \frac{4(4 - \pi)}{(3\pi - 8)}\zeta - i\sqrt{\pi}\frac{2(10 - 3\pi)}{(3\pi - 8)}\zeta^2 - \frac{2(16 - 5\pi)}{(3\pi - 8)}\zeta^3}{1 - i\sqrt{\pi}\frac{2}{(3\pi - 8)}\zeta - \frac{(32 - 9\pi)}{(3\pi - 8)}\zeta^2 + i\sqrt{\pi}\frac{2(10 - 3\pi)}{(3\pi - 8)}\zeta^3 + \frac{2(16 - 5\pi)}{(3\pi - 8)}\zeta^4} \tag{3.172}$$

$$Z_{4,3}(\zeta) = \frac{i\sqrt{\pi} + \frac{3\pi - 4}{2}\zeta - i\sqrt{\pi}\zeta^2 - \frac{(3\pi - 8)}{2}\zeta^3}{1 - i\frac{3\sqrt{\pi}}{2}\zeta - \frac{(9\pi - 16)}{4}\zeta^2 + i\sqrt{\pi}\zeta^3 + \frac{(3\pi - 8)}{2}\zeta^4}; \tag{3.173}$$

$$Z_{4,4}(\zeta) = \frac{i\sqrt{\pi} + \frac{10}{3}\zeta - i\sqrt{\pi}\zeta^2 - \frac{4}{3}\zeta^3}{1 - i\frac{3\sqrt{\pi}}{2}\zeta - 4\zeta^2 + i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4}. \tag{3.174}$$

3.4. Conversion of our 2-index $R_{n,n'}(\zeta)$ notation to other notations

For clarity, we provide conversion tables of Padé approximants in the notation of Martín *et al.* (1980) and Hedrick & Leboeuf (1992) to our notation. Comparing our analytic results to those of Martín *et al.* (1980) (introducing superscript M), can be done easily according to

$$Z_{3,1}^M = Z_{2,-2}; \quad Z_{2,2}^M = Z_{2,-1}; \quad Z_{1,3}^M = Z_{2,0}; \tag{3.175}$$

$$Z_{5,1}^M = Z_{3,-2}; \quad Z_{4,2}^M = Z_{3,-1}; \quad Z_{3,3}^M = Z_{3,0}; \tag{3.176}$$

$$Z_{5,3}^M = Z_{4,0}, \tag{3.177}$$

and the general conversion can be written as

$$Z_{n,n'}^M = Z_{n+n'/2,n'-3}. \tag{3.178}$$

The table 1 of Martín *et al.* (1980) can be now easily verified, which reveals a small obvious typo in their $Z_{4,2}^M$, where the coefficient p_2 is missing the imaginary i number.

To compare our results to those of Hedrick & Leboeuf (1992), it is useful to calculate asymptotic expansions of their Z_n definitions (that is defined as $Z_{n,0}$), that calculate as

$$Z_2^{HL} = -\frac{a_1 - \zeta}{a_0 + a_1\zeta - \zeta^2} = -\frac{1}{\zeta} - \frac{0}{\zeta^2} + o\left(\frac{1}{\zeta^2}\right); \tag{3.179}$$

$$Z_3^{HL} = -\frac{\zeta^2 - a_2\zeta - a_1 + \frac{1}{2}}{\zeta^3 - a_2\zeta^2 - a_1\zeta - a_0} = -\frac{1}{\zeta} - \frac{1}{2\zeta^3} + o\left(\frac{1}{\zeta^3}\right); \tag{3.180}$$

$$Z_4^{HL} = -\frac{\zeta^3 - a_3\zeta^2 - (a_2 - \frac{1}{2}\zeta) - (a_1 + a_3/2)}{\zeta^4 - a_3\zeta^3 - a_2\zeta^2 - a_1\zeta - a_0} = -\frac{1}{\zeta} - \frac{1}{2\zeta^3} - \frac{0}{\zeta^4} + o\left(\frac{1}{\zeta^4}\right); \tag{3.181}$$

$$\begin{aligned}
 Z_5^{HL} &= -\frac{\zeta^4 - a_4\zeta^3 - (a_3 - \frac{1}{2})\zeta^2 - (a_2 + a_4/2)\zeta - (a_1 + a_3/2 - \frac{3}{4})}{\zeta^5 - a_4\zeta^4 - a_3\zeta^3 - a_2\zeta^2 - a_1\zeta - a_0} \\
 &= -\frac{1}{\zeta} - \frac{1}{2\zeta^3} - \frac{3}{4\zeta^5} + o\left(\frac{1}{\zeta^5}\right),
 \end{aligned} \tag{3.182}$$

where ‘HL’ stands for Hedrick & Leboeuf (1992). As one can see, the number of asymptotic points used in their basic definition of Z_n , increases with the number of poles n . Compared to our definition, their $Z_{2,0}$ is defined as having another asymptotic point (for a total of 2), $Z_{3,0}$ has another asymptotic point (for a total of 3), $Z_{4,0}$ another one (for a total of 4), and so on. Essentially, in their notation the basic $Z_{n,0}$ is defined as having ‘ n ’ asymptotic points, and asymptotic precision $o(1/\zeta^n)$. The conversion between their and our notation is easy, and

$$Z_{2,0}^{HL} = Z_{2,-1}; \quad Z_{2,1}^{HL} = Z_{2,0}; \tag{3.183}$$

$$Z_{3,1}^{HL} = Z_{3,1}; \quad Z_{3,2}^{HL} = Z_{3,2}; \tag{3.184}$$

$$Z_{4,1}^{HL} = Z_{4,2}; \quad Z_{4,2}^{HL} = Z_{4,3}; \quad Z_{4,3}^{HL} = Z_{4,4}; \tag{3.185}$$

$$Z_{5,1}^{HL} = Z_{5,3}; \quad Z_{5,2}^{HL} = Z_{5,4}; \quad Z_{5,3}^{HL} = Z_{5,5}; \quad Z_{5,4}^{HL} = Z_{5,6}, \tag{3.186}$$

or the general conversion can be written as

$$Z_{n,n'}^{HL} = Z_{n,n'+n-3}. \tag{3.187}$$

We checked the table 1 of Hedrick & Leboeuf (1992) that provides coefficients for the Padé approximants (3.183)–(3.186) and we can confirm that the table is essentially correct, except for one coefficient.⁷ The coefficient where a simple typo is suspected is the coefficient a_1 in $Z_{3,1}$. Rewriting our three-pole approximant $R_3(\zeta)$ to the form used by Passot & Sulem (2007) and Hedrick & Leboeuf (1992) (that corresponds to the Z_3^{HL} as written in (3.180)) yields

$$R_3(\zeta) = \frac{-\frac{1}{2}\zeta - a_0}{\zeta^3 - a_2\zeta^2 - a_1\zeta - a_0}, \tag{3.188}$$

which further yields

$$R_{3,1}(\zeta) = \frac{-\frac{1}{2}\zeta - \frac{i\sqrt{\pi}}{2(4-\pi)}}{\zeta^3 + \frac{i\sqrt{\pi}}{(4-\pi)}\zeta^2 - \frac{2}{(4-\pi)}\zeta - \frac{i\sqrt{\pi}}{2(4-\pi)}}; \tag{3.189}$$

$$R_{3,2}(\zeta) = \frac{-\frac{1}{2}\zeta - \frac{i}{\sqrt{\pi}}}{\zeta^3 + \frac{2i}{\sqrt{\pi}}\zeta^2 - \frac{3}{2}\zeta - \frac{i}{\sqrt{\pi}}}, \tag{3.190}$$

and our approximants are

$$R_{3,1}(\zeta) : \quad a_0 = \frac{i\sqrt{\pi}}{2(4-\pi)} = 1.03241i; \quad a_1 = \frac{2}{4-\pi} = 2.32990;$$

⁷Compared to our exact analytic expressions, there are also some rounding errors in the last 1–2 digits in $Z_{4,1}^{HL}$, $Z_{5,1}^{HL}$, $Z_{5,2}^{HL}$.

$$a_2 = -\frac{i\sqrt{\pi}}{4-\pi} = -2.06482i; \quad (3.191)$$

$$R_{3,2}(\zeta): \quad a_0 = \frac{i}{\sqrt{\pi}} = 0.56419i; \quad a_1 = \frac{3}{2};$$

$$a_2 = -\frac{2i}{\sqrt{\pi}} = -1.12838i. \quad (3.192)$$

For the a_1 coefficient in $R_{3,1}$, both Hedrick & Leboeuf (1992) and Passot & Sulem (2007) use $a_1 = 2.23990$ instead of the correct $a_1 = 2.32990$. The differences are of course small. Nevertheless, the new correct value explains the observation made by Passot & Sulem (2007), in the paragraph below their figure 1, where they write: ‘It is conspicuous that $R_{3,2}$ provides a fit that is slightly better for small ζ , but turns out to be globally less accurate than $R_{3,1}$ ’. The authors obviously noticed that something is not right, since for small ζ , the $R_{3,1}$ has precision $o(\zeta^2)$ and $R_{3,2}$ only $o(\zeta)$, so the $R_{3,1}$ should be more precise. And it indeed is, the authors were just misguided by the wrong value of a_1 introduced by Hedrick & Leboeuf (1992).

3.5. Precision of $R(\zeta)$ approximants

It is useful to compare the Padé approximants to the exact $R(\zeta) = 1 + \zeta Z(\zeta)$, where the plasma dispersion function can be conveniently calculated (for example in Maple) according to

$$Z(\zeta) = i\sqrt{\pi}e^{-\zeta^2} (1 + \operatorname{erf}(i\zeta)), \quad (3.193)$$

where $\operatorname{erf}(z) = (2/\sqrt{\pi}) \int_0^z e^{-t^2} dt$ is the well-known error function, defined for any complex z . We plot only approximants for which we were able to obtain closures. The exact $R(\zeta)$ is plotted as a black solid line in all the figures. Figure 2 top shows one-pole and two-pole approximants $R_1(\zeta)$ (red dashed line) and $R_{2,0}(\zeta)$ (blue dot-dashed line). Figure 2 bottom shows three-pole approximants $R_{3,0}(\zeta)$ (red dashed line), $R_{3,1}(\zeta)$ (green dotted line) and $R_{3,2}(\zeta)$ (blue dot-dashed line). Figures in the left column show the imaginary part and figures in the right column show the real part. The input variable ζ plotted on the x -axis is prescribed to be real, i.e. states in the weak growth-rate/damping approximation are explored (one might as well prescribe $\operatorname{Im}(\zeta) = \pm 0.01 \operatorname{Re}(\zeta)$ and plot essentially the same graphs, with only small differences in solutions).

As expected, the very simple approximant $R_1(\zeta)$ is unprecise for larger values of ζ , and above $\zeta > 1$, the $\operatorname{Re}R_1(\zeta)$ even has a wrong sign. Nevertheless, the approximant is still a good approximant for small $\zeta \ll 1$ values, and it is also very valuable from a theoretical perspective, since it is the only approximant that provides a quasi-static closure for the perpendicular heat flux q_\perp (see the 3-D geometry § 4, closure (4.108)). This has one important implication:

If one renders the approximant R_1 as not satisfactory (which is true unless $\zeta \ll 1$ or at least $\zeta < 1$), 3-D simulations with fluid models that contain Landau damping can be only performed with time-dependent heat flux equations. All other approximants in figure 2 perform reasonably well, and the most precise is $R_{3,0}(\zeta)$, followed by $R_{3,1}(\zeta)$.

Figure 3 shows selected four-pole and five-pole approximants for which we were able to obtain closures. Unfortunately, approximants $R_{4,4}(\zeta)$ and $R_{5,6}(\zeta)$ show a bit unpleasant behaviour, and the associated closures obtained with these approximants are therefore difficult to recommend, unless the considered domain is $\zeta \ll 1$ or

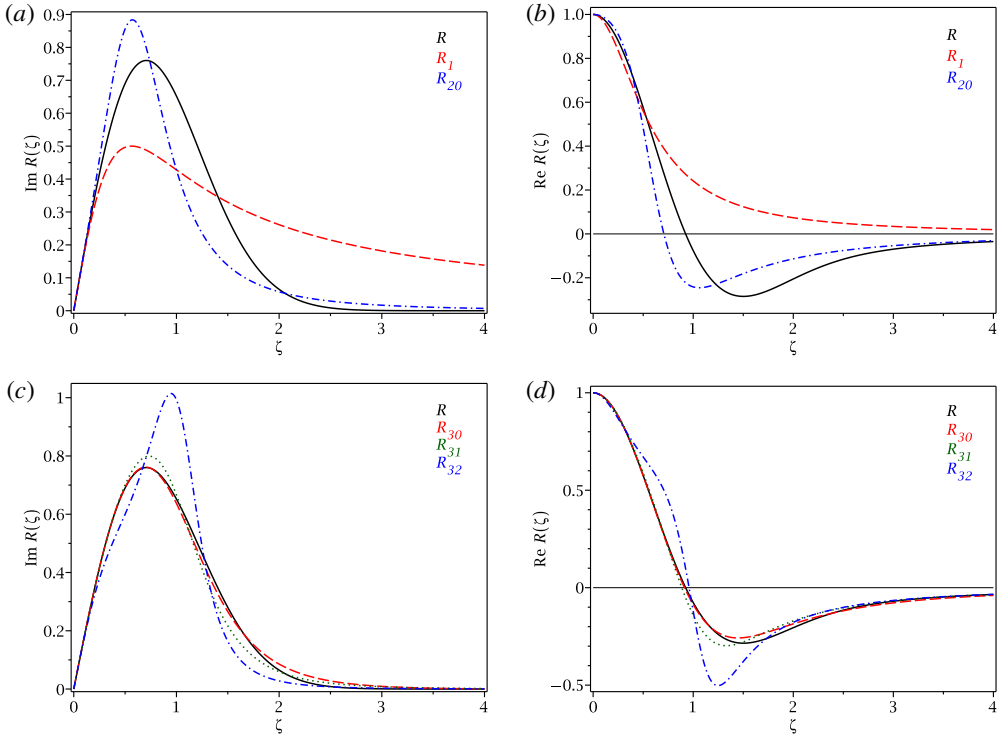


FIGURE 2. One-pole, two-pole (a,b) and three-pole (c,d) Padé approximants of $R(\zeta)$. (a,c) $\text{Im}R(\zeta)$, (b,d) $\text{Re}R(\zeta)$, for ζ being real.

$\zeta \gg 1$, or more specifically, at least $\zeta < 0.5$ or $\zeta > 2$. The behaviour is not surprising, since approximants $R_{4,4}(\zeta)$ and $R_{5,6}(\zeta)$ have the maximum available number of poles devoted to the asymptotic expansion $\zeta \gg 1$, without being ill posed. The closures are therefore specifically suitable for $\zeta \gg 1$ regime, for example in the low-temperature limit, or, in the high-frequency (actually high phase speed) limit (since $\zeta = \omega/(|k_{\parallel}|v_{th\parallel})$). For $R_{4,4}(\zeta)$, the corresponding closures are the quasi-static closure (3.268) and time-dependent closures (3.295), (3.297), (3.299). For $R_{5,6}(\zeta)$, the corresponding closure is time dependent (3.325) and naturally, this is the most precise closure in the $\zeta \gg 1$ regime, with precision $o(\zeta^{-8})$. Noticeably, the asymptotic precision is even better than the $R_{8,3}(\zeta)$ approximant used in the WHAMP code, which has a precision $o(\zeta^{-5})$.

All other approximants in figure 3 are very precise in the entire considered range of ζ . To clearly see the precision, it is useful to calculate the maximum relative errors

$$\text{Im} \left(\frac{R_{n,n'}(\zeta) - R(\zeta)}{R(\zeta)} \right) 100\%; \quad \text{Re} \left(\frac{R_{n,n'}(\zeta) - R(\zeta)}{R(\zeta)} \right) 100\%, \quad (3.194)$$

which we define this way instead of for example $\text{Re}(R_{n,n'}(\zeta) - R(\zeta))/\text{Re}R(\zeta)$, since the real part of $R(\zeta)$ is going through zero. The maximum relative errors typically appear for $\zeta \in (0, 4)$, even though some reported values are outside of this range. The $R_1(\zeta)$ approximant is excluded from the table since its relative error of the imaginary part increases with ζ . We omit if errors are positive or negative and the results are:

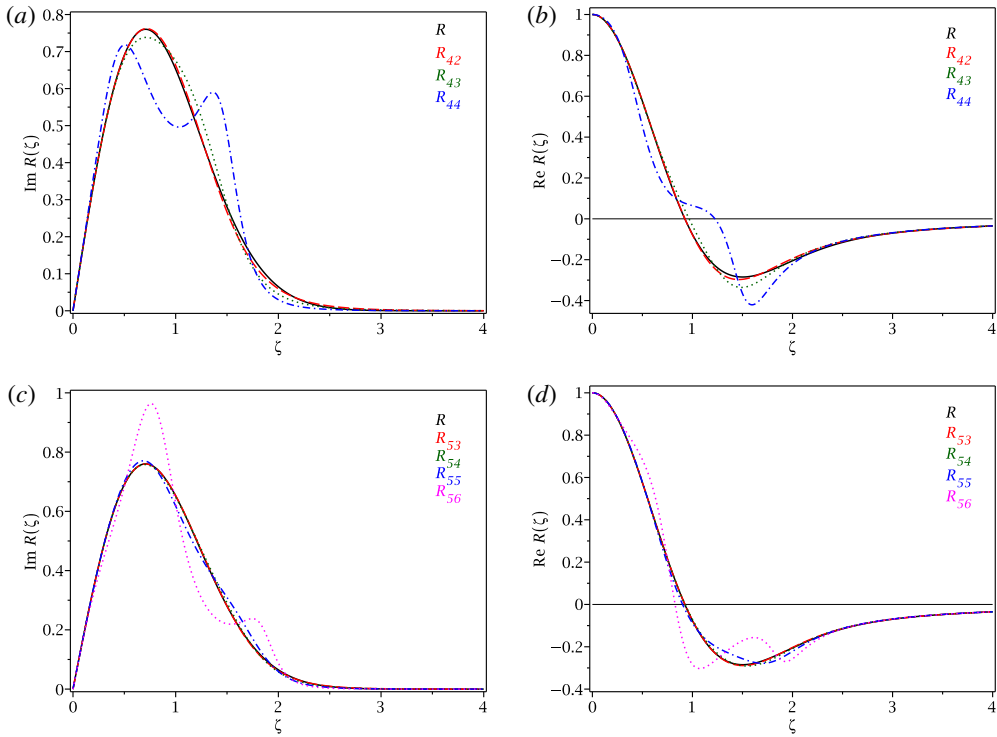


FIGURE 3. Four-pole (a,b) and five-pole (c,d) Padé approximants of $R(\zeta)$.

Two-pole and three-pole approximants

	$R_{2,0}$	$R_{3,0}$	$R_{3,1}$	$R_{3,2}$
error Im %	35	16.4	13.3	44
error Re %	44	14.7	16.6	53

Four-pole approximants

	$R_{4,0}$	$R_{4,1}$	$R_{4,2}$	$R_{4,3}$	$R_{4,4}$
error Im %	6.2	4.66	4.57	11.6	49
error Re %	5.3	4.3	5.7	12.3	51

Five-pole approximants

	$R_{5,0}$	$R_{5,1}$	$R_{5,2}$	$R_{5,3}$	$R_{5,4}$	$R_{5,5}$	$R_{5,6}$
error Im %	1.9	1.42	1.34	1.46	3.4	10.3	40
error Re %	2.0	1.26	1.26	1.81	3.4	10.0	31

Six-pole approximants

	$R_{6,0}$	$R_{6,1}$	$R_{6,2}$	$R_{6,3}$	$R_{6,4}$	$R_{6,5}$	$R_{6,6}$	$R_{6,7}$	$R_{6,8}$
error Im %	0.58	0.37	0.35	0.38	0.45	1.0	2.5	7.6	30
error Re %	0.64	0.40	0.31	0.36	0.54	0.9	2.5	7.7	39

Seven-pole approximants

	$R_{7,0}$	$R_{7,1}$	$R_{7,2}$	$R_{7,3}$	$R_{7,4}$	$R_{7,5}$	$R_{7,6}$	$R_{7,7}$	$R_{7,8}$	$R_{7,9}$	$R_{7,10}$
error Im %	0.18	0.10	0.080	0.087	0.10	0.13	0.29	0.65	1.8	6.2	35
error Re %	0.2	0.11	0.089	0.080	0.10	0.16	0.26	0.65	1.9	6.6	33

Eight-pole approximants

	$R_{8,0}$	$R_{8,1}$	$R_{8,2}$	$R_{8,3}$	$R_{8,4}$	$R_{8,5}$	$R_{8,6}$	$R_{8,7}$	$R_{8,8}$	$R_{8,9}$
error Im %	0.06	0.03	0.021	0.018	0.022	0.028	0.04	0.08	0.17	0.43
error Re %	0.06	0.03	0.022	0.020	0.020	0.027	0.04	0.07	0.17	0.46

The numbers of course do not reveal the entire story, since the maximum error can occur for different ζ values. For example, from the plots of $\text{Im}R(\zeta)$ in figure 2, the approximant $R_{3,0}(\zeta)$ captures the maximum (the peak around $\zeta \sim 1$) with much better accuracy than the approximant $R_{3,1}(\zeta)$. However, according to the above table, the $R_{3,1}(\zeta)$ appears to be more precise globally. The discrepancy is easily understood from figure 4, where % errors of both approximants are plotted with respect to ζ . A similar table and figures can be created for the heavily damped regime, for example for ζ with the imaginary part $\text{Im}(\zeta) = -\text{Re}(\zeta)/2$, where the Padé approximants are less precise.

3.6. Landau fluid closures – fascinating closures for all ζ

Now, let us use various Padé approximations of the plasma response function $R(\zeta)$, and calculate the kinetic moments. Let us start with the simplest choice of replacing the exact $R(\zeta)$ with approximant $R_1(\zeta) = 1/(1 - i\sqrt{\pi}\zeta)$. Let us drop the index r . The linear kinetic moments (3.20)–(3.26) calculate as

$$R_1(\zeta) : \frac{n^{(1)}}{n_0} = -\frac{q_r}{T^{(0)}} \Phi \frac{1}{1 - i\sqrt{\pi}\zeta} [1]; \tag{3.195}$$

$$u^{(1)} = -\frac{q_r}{T^{(0)}} \Phi v_{\text{th}} \text{sign}(k_{\parallel}) \frac{1}{1 - i\sqrt{\pi}\zeta} [\zeta]; \tag{3.196}$$

$$\frac{p^{(1)}}{p_0} = -\frac{q_r}{T^{(0)}} \Phi \frac{1}{1 - i\sqrt{\pi}\zeta} [2\zeta^2 - i\sqrt{\pi}\zeta + 1]; \tag{3.197}$$

$$T^{(1)} = -q_r \Phi \frac{1}{1 - i\sqrt{\pi}\zeta} [2\zeta^2 - i\sqrt{\pi}\zeta]; \tag{3.198}$$

$$q^{(1)} = -q_r n_0 \Phi v_{\text{th}} \text{sign}(k_{\parallel}) \frac{1}{1 - i\sqrt{\pi}\zeta} [2\zeta^3 - i\sqrt{\pi}\zeta^2 - 2\zeta]; \tag{3.199}$$

$$r^{(1)} = -q_r \frac{n_0}{2} v_{\text{th}}^2 \Phi \frac{1}{1 - i\sqrt{\pi}\zeta} [4\zeta^4 - 2i\sqrt{\pi}\zeta^3 + 2\zeta^2 - 3i\sqrt{\pi}\zeta + 3]; \tag{3.200}$$

$$\tilde{r}^{(1)} = -q_r \frac{n_0}{2} v_{\text{th}}^2 \Phi \frac{1}{1 - i\sqrt{\pi}\zeta} [4\zeta^4 - 2i\sqrt{\pi}\zeta^3 - 10\zeta^2 + 3i\sqrt{\pi}\zeta]. \tag{3.201}$$

We are looking for a closure, and we want to express either $q^{(1)}$ or $\tilde{r}^{(1)}$, as a linear combination of lower-order moments. To immediately see possible closures, it is always useful to pull the denominator of the Padé approximant out (as done above), and concentrate only on the expressions inside the big brackets. Also, similarly to the closures explored for small ζ , it is useful to forget the $n^{(1)}$, $p^{(1)}$ and $r^{(1)}$ moments, and just concentrate at the $u^{(1)}$, $T^{(1)}$, $q^{(1)}$ and $\tilde{r}^{(1)}$ moments. Nevertheless, we will keep the $n^{(1)}$ moment, since it helps us to understand the expressions and to somehow ‘maintain touch with reality’.

By exploring the expressions inside of the brackets, it is obvious that it is impossible to express $q^{(1)}$ or $\tilde{r}^{(1)}$ as a linear combination of lower-order moments that eliminate the ζ dependence. Moreover, for large ζ , the moments $q^{(1)} \sim \zeta^2$ and $\tilde{r}^{(1)} \sim \zeta^3$, which does not make physical sense, since these quantities should converge to zero with increasing ζ , as explored in the $\zeta \gg 1$ limit, see equations (3.80)–(3.86). The $R_1(\zeta)$ approximant therefore does not yield a closure. The same conclusion is obtained by using the $R_{2,0}(\zeta)$ approximant, where no closure for $q^{(1)}$ or $\tilde{r}^{(1)}$ is possible. We note that the approximant $R_{2,1}(\zeta)$, that was eliminated because it is not

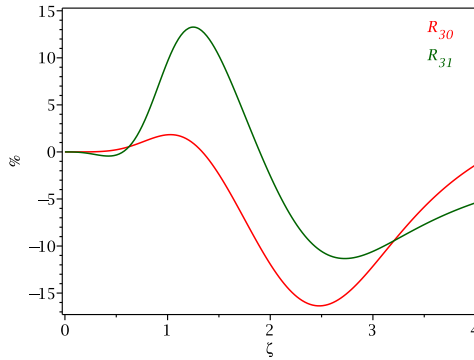


FIGURE 4. The % error of the imaginary parts of $R_{3,0}(\zeta)$ (red line), and $R_{3,1}(\zeta)$ (green line).

a good approximant of $R(\zeta)$ yields a closure $q^{(1)} = -2p_0u^{(1)}$, which is equivalent to the closure (3.49), that was obtained for small ζ with the precision $o(\zeta)$. This closure is therefore disregarded.

Let us try the three-pole Padé approximants. The moments with $R_{3,1}(\zeta)$ approximant are proportional to

$$R_{3,1}(\zeta) : n^{(1)} \sim \frac{1}{1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4-\pi}{\sqrt{\pi}}\zeta^3} \left[1 + \frac{i}{\sqrt{\pi}}(\pi - 4)\zeta \right]; \tag{3.202}$$

$$u^{(1)} \sim \frac{1}{1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4-\pi}{\sqrt{\pi}}\zeta^3} \left[\frac{i}{\sqrt{\pi}}(\pi - 4)\zeta^2 + \zeta \right]; \tag{3.203}$$

$$T^{(1)} \sim \frac{1}{1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4-\pi}{\sqrt{\pi}}\zeta^3} [-i\sqrt{\pi}\zeta]; \tag{3.204}$$

$$q^{(1)} \sim \frac{1}{1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4-\pi}{\sqrt{\pi}}\zeta^3} \left[-\frac{i}{\sqrt{\pi}}(3\pi - 8)\zeta^2 - 2\zeta \right]; \tag{3.205}$$

$$\tilde{r}^{(1)} \sim \frac{1}{1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4-\pi}{\sqrt{\pi}}\zeta^3} \left[-\frac{2i}{\sqrt{\pi}}(3\pi - 8)\zeta^3 - 4\zeta^2 + 3i\sqrt{\pi}\zeta \right], \tag{3.206}$$

where we have suppressed writing all the multiplicative factors including the minus signs (it does not mean that these were neglected, full expressions are considered, we are just not writing down the full expressions, which helps in spotting the possible closures). There is a possibility of expressing $q^{(1)}$ through the combination of the lower moments $T^{(1)}$ and $u^{(1)}$. The full expressions of these moments are

$$R_{3,1}(\zeta) : D = \left(1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{4-\pi}{\sqrt{\pi}}\zeta^3 \right); \tag{3.207}$$

$$u^{(1)} = -\frac{q_r}{T^{(0)}} \Phi v_{th} \text{sign}(k_{\parallel}) \frac{1}{D} \left[\frac{i}{\sqrt{\pi}} (\pi - 4) \zeta^2 + \zeta \right]; \tag{3.208}$$

$$T^{(1)} = -q_r \Phi \frac{1}{D} [-i\sqrt{\pi}\zeta]; \tag{3.209}$$

$$q^{(1)} = -q_r n_0 \Phi v_{th} \text{sign}(k_{\parallel}) \frac{1}{D} \left[-\frac{i}{\sqrt{\pi}} (3\pi - 8) \zeta^2 - 2\zeta \right], \tag{3.210}$$

where we have used a convenient notation D for the denominator of the plasma response function, and the closure is

$$R_{3,1}(\zeta) : \quad q^{(1)} = \frac{3\pi - 8}{4 - \pi} n_0 T^{(0)} u^{(1)} - i \frac{\sqrt{\pi}}{4 - \pi} n_0 v_{th} \text{sign}(k_{\parallel}) T^{(1)}, \tag{3.211}$$

which is equivalent to the (3.60) closure (which was obtained for small ζ with the precision $o(\zeta^2)$). Continuing with the next approximant $R_{3,2}(\zeta)$, the moments calculate as

$$R_{3,2}(\zeta) : \quad D = \left(1 - \frac{3i\sqrt{\pi}}{2} \zeta - 2\zeta^2 + i\sqrt{\pi}\zeta^3 \right); \tag{3.212}$$

$$n^{(1)} \sim \frac{1}{D} \left[1 - \frac{i\sqrt{\pi}}{2} \zeta \right]; \tag{3.213}$$

$$u^{(1)} \sim \frac{1}{D} \left[-\frac{i\sqrt{\pi}}{2} \zeta^2 + \zeta \right]; \tag{3.214}$$

$$T^{(1)} \sim \frac{1}{D} [-i\sqrt{\pi}\zeta]; \tag{3.215}$$

$$q^{(1)} \sim \frac{1}{D} [-2\zeta]; \tag{3.216}$$

$$\tilde{r}^{(1)} \sim \frac{1}{D} [-4\zeta^2 + 3i\sqrt{\pi}\zeta]. \tag{3.217}$$

It is possible to express (1) $q^{(1)}$ through $T^{(1)}$; (2) $\tilde{r}^{(1)}$ through the combination of $u^{(1)}$ and $q^{(1)}$; (3) $\tilde{r}^{(1)}$ through the combination of $u^{(1)}$ and $T^{(1)}$. The first choice yields a closure

$$R_{3,2}(\zeta) : \quad q^{(1)} = -i \frac{2}{\sqrt{\pi}} n_0 v_{th} \text{sign}(k_{\parallel}) T^{(1)}, \tag{3.218}$$

that is equivalent to the (3.48) closure obtained for small ζ with the precision $o(\zeta)$. This is indeed the famous simplest possible Landau fluid closure that expresses the collisionless heat flux with respect to temperature, and it equivalent to equation (7) of Hammett & Perkins (1990).⁸ The closure is written here in Fourier space. The important part is the $i\text{sign}(k_{\parallel})$ that typically written as $ik_{\parallel}/|k_{\parallel}|$, and that in real space rewrites as a Hilbert transform, which we will address later. The $R_{3,2}(\zeta)$ was obtained with $o(\zeta)$ power-series expansion, and $o(1/\zeta^4)$ asymptotic-series expansion. How good is this closure? By exploring expressions (3.212)–(3.216), the quantities $n^{(1)}$, $u^{(1)}$, $T^{(1)}$ have all correct asymptotic expansion for large ζ (including the proportionality

⁸With their later found constant $\chi_1 = 2/\sqrt{\pi}$, and remembering that their thermal speeds are defined as $v_{th} = \sqrt{T^{(0)}/m}$, whereas ours are $v_{th} = \sqrt{2T^{(0)}/m}$.

constants), however, the heat flux decreases only as $q^{(1)} \sim 1/\zeta^2$ instead of the correct $\sim 1/\zeta^3$, see (3.84). For large ζ , the heat flux is therefore overestimated by this simple closure, which typically leads to an overestimation of the Landau damping in fluid models that use this simplest closure. Nevertheless, the closure is very beneficial because it clarifies the distinction between the collisional and collisionless heat fluxes.

The other two possible closures with $R_{3,2}(\zeta)$ are

$$R_{3,2}(\zeta): \quad \tilde{r}^{(1)} = -\frac{4i}{\sqrt{\pi}}v_{\text{th}}n_0T^{(0)}\text{sign}(k_{\parallel})u^{(1)} - i\frac{(3\pi+8)}{4\sqrt{\pi}}v_{\text{th}}\text{sign}(k_{\parallel})q^{(1)}; \quad (3.219)$$

$$\tilde{r}^{(1)} = -\frac{4i}{\sqrt{\pi}}v_{\text{th}}n_0T^{(0)}\text{sign}(k_{\parallel})u^{(1)} - \frac{(3\pi+8)}{2\pi}v_{\text{th}}^2n_0T^{(1)}, \quad (3.220)$$

and one can go from (3.219) to (3.220) by using (3.218). Obviously, it would be also possible to construct a closure $\tilde{r}^{(1)} = \alpha_u u^{(1)} + \alpha_q q^{(1)} + \alpha_T T^{(1)}$, where $\alpha_u = -(4i/\sqrt{\pi})v_{\text{th}}n_0T^{(0)}\text{sign}(k_{\parallel})$, and where α_q and α_T are related by satisfying $2n_0v_{\text{th}}\text{sign}(k_{\parallel})\alpha_q + i\sqrt{\pi}\alpha_T = -iv_{\text{th}}^2n_0((3\pi+8)/2\sqrt{\pi})$, i.e. one could consider a closure with a free parameter, which we will not consider. Additionally, all constructed closures should be checked with respect to obtained dispersion relations, and closures (3.219), (3.220) will be later disregarded as not well behaved (see the discussion below equations (3.242), (3.382) and (3.399)).

For $R_{4,2}(\zeta)$, the kinetic moments calculate as

$$R_{4,2}(\zeta): \quad D = \left(1 - i\sqrt{\pi}\frac{2}{(3\pi-8)}\zeta - \frac{(32-9\pi)}{(3\pi-8)}\zeta^2 + i\sqrt{\pi}\frac{2(10-3\pi)}{(3\pi-8)}\zeta^3 + \frac{2(16-5\pi)}{(3\pi-8)}\zeta^4 \right); \quad (3.221)$$

$$n^{(1)} \sim \frac{1}{D} \left[\frac{(5\pi-16)}{(3\pi-8)}\zeta^2 + i\sqrt{\pi}\frac{(3\pi-10)}{(3\pi-8)}\zeta + 1 \right]; \quad (3.222)$$

$$u^{(1)} \sim \frac{1}{D} \left[\frac{(5\pi-16)}{(3\pi-8)}\zeta^3 + i\sqrt{\pi}\frac{(3\pi-10)}{(3\pi-8)}\zeta^2 + \zeta \right]; \quad (3.223)$$

$$T^{(1)} \sim \frac{1}{D} \left[\frac{2(5\pi-16)}{(3\pi-8)}\zeta^2 - i\sqrt{\pi}\zeta \right]; \quad (3.224)$$

$$q^{(1)} \sim \frac{1}{D} \left[-i\sqrt{\pi}\frac{(9\pi-28)}{(3\pi-8)}\zeta^2 - 2\zeta \right]; \quad (3.225)$$

$$\tilde{r}^{(1)} \sim \frac{1}{D} \left[-i\sqrt{\pi}\frac{2(9\pi-28)}{(3\pi-8)}\zeta^3 - \frac{2(21\pi-64)}{(3\pi-8)}\zeta^2 + 3i\sqrt{\pi}\zeta \right]. \quad (3.226)$$

The only possibility is to express $\tilde{r}^{(1)}$ through a combination of $u^{(1)}$, $T^{(1)}$ and $q^{(1)}$, and the solution is

$$R_{4,2}(\zeta): \quad \tilde{r}^{(1)} = -i\sqrt{\pi}\frac{(10-3\pi)}{(16-5\pi)}v_{\text{th}}\text{sign}(k_{\parallel})q^{(1)} + \frac{(21\pi-64)}{2(16-5\pi)}v_{\text{th}}^2n_0T^{(1)} + i\sqrt{\pi}\frac{(9\pi-28)}{(16-5\pi)}v_{\text{th}}T^{(0)}n_0\text{sign}(k_{\parallel})u^{(1)}, \quad (3.227)$$

which is equivalent to the closure (3.64), that was obtained for small ζ with precision $o(\zeta^3)$. Obviously such a closure is precise for small values of ζ , however for large

values of ζ , the asymptotic behaviour of $q^{(1)} \sim \zeta^{-2}$ and $\tilde{r}^{(1)} \sim \zeta^{-1}$, instead of the correct ζ^{-3} , ζ^{-4} profiles (see (3.84), (3.86)), and these quantities will be therefore overestimated. Nevertheless, the solution is interesting and we are not aware of it being reporting in any literature.

Continuing with $R_{4,3}(\zeta)$, the kinetic moments calculate as

$$R_{4,3}(\zeta): \quad D = \left(1 - i\frac{3\sqrt{\pi}}{2}\zeta - \frac{(9\pi - 16)}{4}\zeta^2 + i\sqrt{\pi}\zeta^3 + \frac{(3\pi - 8)}{2}\zeta^4 \right); \tag{3.228}$$

$$n^{(1)} \sim \frac{1}{D} \left[\frac{(8 - 3\pi)}{4}\zeta^2 - i\frac{\sqrt{\pi}}{2}\zeta + 1 \right]; \tag{3.229}$$

$$u^{(1)} \sim \frac{1}{D} \left[\frac{(8 - 3\pi)}{4}\zeta^3 - i\frac{\sqrt{\pi}}{2}\zeta^2 + \zeta \right]; \tag{3.230}$$

$$T^{(1)} \sim \frac{1}{D} \left[\frac{(8 - 3\pi)}{2}\zeta^2 - i\sqrt{\pi}\zeta \right]; \tag{3.231}$$

$$q^{(1)} \sim \frac{1}{D} [-2\zeta]; \tag{3.232}$$

$$\tilde{r}^{(1)} \sim \frac{1}{D} \left[\frac{(9\pi - 32)}{2}\zeta^2 + 3i\sqrt{\pi}\zeta \right]. \tag{3.233}$$

It is possible to express $\tilde{r}^{(1)}$ through the combination of $q^{(1)}$ and $T^{(1)}$ and the result is

$$R_{4,3}(\zeta): \quad \tilde{r}^{(1)} = -i\frac{2\sqrt{\pi}}{(3\pi - 8)}v_{th}\text{sign}(k_{\parallel})q^{(1)} + \frac{(32 - 9\pi)}{2(3\pi - 8)}v_{th}^2n_0T^{(1)}, \tag{3.234}$$

which is equivalent to the closure (3.56), that was obtained for small ζ with the precision $o(\zeta^2)$. The heat flux has a correct asymptotic behaviour $q^{(1)} \sim \zeta^{-3}$ (even though with incorrect proportionality constant), and the quantity $\tilde{r}^{(1)} \sim \zeta^{-2}$ instead of the correct $\sim \zeta^{-4}$. The closure was first reported by Hammett & Perkins (1990), and is equivalent to the (non-numbered) expression between their equations (10) and (11).

Continuing with $R_{4,4}(\zeta)$ approximant, the kinetic moments are (let us stop writing down $n^{(1)}$ from now on since we know we can get it from $u^{(1)}$)

$$R_{4,4}(\zeta): \quad D = \left(1 - i\frac{3\sqrt{\pi}}{2}\zeta - 4\zeta^2 + i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 \right); \tag{3.235}$$

$$u^{(1)} \sim \frac{1}{D} \left[-\frac{2}{3}\zeta^3 - \frac{i}{2}\sqrt{\pi}\zeta^2 + \zeta \right]; \tag{3.236}$$

$$T^{(1)} \sim \frac{1}{D} \left[-\frac{4}{3}\zeta^2 - i\sqrt{\pi}\zeta \right]; \tag{3.237}$$

$$q^{(1)} \sim \frac{1}{D} [-2\zeta]; \tag{3.238}$$

$$\tilde{r}^{(1)} \sim \frac{1}{D} [3i\sqrt{\pi}\zeta]. \tag{3.239}$$

It is possible to express $\tilde{r}^{(1)}$ through $q^{(1)}$ and the closure is

$$R_{4,4}(\zeta): \quad \tilde{r}^{(1)} = -i\frac{3}{4}\sqrt{\pi}v_{th}\text{sign}(k_{\parallel})q^{(1)}. \tag{3.240}$$

The result is equivalent to the (3.52) closure, that was obtained for small ζ with precision $o(\zeta)$. This very simple closure has only precision $o(\zeta)$, however, it does have the correct asymptotic behaviour of the heat flux $q^{(1)} \sim -3/(2\zeta^3)$ (including the proportionality constant), and $\tilde{r}^{(1)} \sim \zeta^{-3}$ that is closer to the correct ζ^{-4} than the previous closure.

3.7. Table of moments ($u_{\parallel}, T_{\parallel}, q_{\parallel}, \tilde{r}_{\parallel}$) for various Padé approximants

To clearly see possibilities of a closure, it is useful to create the following summarizing table, that is self-explanatory after reading the previous section, i.e. all the proportionality constants (including the minus signs) are suppressed. Even though the table here is created for a 1-D geometry, we will see that exactly the same table is constructed for a 3-D geometry, where all the quantities are given a ‘parallel’ sub-index, i.e. $u^{(1)} \rightarrow u_{\parallel}^{(1)}, T^{(1)} \rightarrow T_{\parallel}^{(1)}, q^{(1)} \rightarrow q_{\parallel}^{(1)}$ and $\tilde{r}^{(1)} \rightarrow \tilde{r}_{\parallel}^{(1)}$. The table is therefore useful to spot all the possible closures that can be constructed in a 1-D geometry for quantities $q^{(1)}, \tilde{r}^{(1)}$, as well as in a 3-D geometry for quantities $q_{\parallel}^{(1)}$ and $r_{\parallel}^{(1)}$. The approximants $R_{2,1}, R_{4,5}, R_{6,9}$ and $R_{8,13}$ are marked with an asterisk ‘*’. These approximants are not well behaved (because the Landau residue is not accounted for) and are provided only for completeness, these approximants should be disregarded.

One-pole and two-pole approximants

	$R_{1,0}$	$R_{2,0}$	$R_{2,1}^*$
$u^{(1)}$	ζ	ζ	ζ
$T^{(1)}$	ζ^2, ζ	ζ	0
$q^{(1)}$	ζ^3, ζ^2, ζ	ζ^2, ζ	ζ
$\tilde{r}^{(1)}$	$\zeta^4 \dots \zeta$	ζ^3, ζ^2, ζ	ζ^2

Three-pole approximants

	$R_{3,0}$	$R_{3,1}$	$R_{3,2}$
$u^{(1)}$	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ
$T^{(1)}$	ζ^2, ζ	ζ	ζ
$q^{(1)}$	ζ^3, ζ^2, ζ	ζ^2, ζ	ζ
$\tilde{r}^{(1)}$	$\zeta^4 \dots \zeta$	ζ^3, ζ^2, ζ	ζ^2, ζ

Four-pole approximants

	$R_{4,0}$	$R_{4,1}$	$R_{4,2}$	$R_{4,3}$	$R_{4,4}$	$R_{4,5}^*$
$u^{(1)}$	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ
$T^{(1)}$	ζ^3, ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2
$q^{(1)}$	$\zeta^4 \dots \zeta$	ζ^3, ζ^2, ζ	ζ^2, ζ	ζ	ζ	ζ
$\tilde{r}^{(1)}$	$\zeta^5 \dots \zeta$	$\zeta^4 \dots \zeta$	ζ^3, ζ^2, ζ	ζ^2, ζ	ζ	0

Five-pole approximants

	$R_{5,0}$	$R_{5,1}$	$R_{5,2}$	$R_{5,3}$	$R_{5,4}$	$R_{5,5}$	$R_{5,6}$
$u^{(1)}$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$
$T^{(1)}$	$\zeta^4 \dots \zeta$	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ
$q^{(1)}$	$\zeta^5 \dots \zeta$	$\zeta^4 \dots \zeta$	ζ^3, ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ
$\tilde{r}^{(1)}$	$\zeta^6 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^4 \dots \zeta$	ζ^3, ζ^2, ζ	ζ^2, ζ	ζ	ζ

Six-pole approximants

	$R_{6,0}$	$R_{6,1}$	$R_{6,2}$	$R_{6,3}$	$R_{6,4}$	$R_{6,5}$	$R_{6,6}$	$R_{6,7}$	$R_{6,8}$	$R_{6,9}^*$
$u^{(1)}$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$	ζ^5, ζ^3, ζ
$T^{(1)}$	$\zeta^5 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	ζ^4, ζ^2
$q^{(1)}$	$\zeta^6 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	ζ^3, ζ
$\tilde{r}^{(1)}$	$\zeta^7 \dots \zeta$	$\zeta^6 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^3 \dots \zeta$	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2

It is obvious by now that any higher-order Padé approximants will not help to achieve a closure. Or is it? One might still hope for ‘a miracle’ thinking that perhaps the seven-pole and eight-pole approximants with the maximum possible number of poles devoted to the asymptotic series – $R_{7,10}$ and $R_{8,12}$ – might yield a closure. However, this is unfortunately not the case, and the table for seven-pole and eight-pole approximants reads

	$R_{7,0}$	$R_{7,1}$...	$R_{7,10}$	$R_{8,0}$	$R_{8,1}$...	$R_{8,12}$	$R_{8,13}^*$
$u^{(1)}$	$\zeta^6 \dots \zeta$	$\zeta^6 \dots \zeta$...	$\zeta^6 \dots \zeta$	$\zeta^7 \dots \zeta$	$\zeta^7 \dots \zeta$...	$\zeta^7 \dots \zeta$	$\zeta^7, \zeta^5, \zeta^3, \zeta$
$T^{(1)}$	$\zeta^6 \dots \zeta$	$\zeta^5 \dots \zeta$...	$\zeta^5 \dots \zeta$	$\zeta^7 \dots \zeta$	$\zeta^6 \dots \zeta$...	$\zeta^6 \dots \zeta$	$\zeta^6, \zeta^4, \zeta^2$
$q^{(1)}$	$\zeta^7 \dots \zeta$	$\zeta^6 \dots \zeta$...	$\zeta^4 \dots \zeta$	$\zeta^8 \dots \zeta$	$\zeta^7 \dots \zeta$...	$\zeta^5 \dots \zeta$	ζ^5, ζ^3, ζ
$\tilde{r}^{(1)}$	$\zeta^8 \dots \zeta$	$\zeta^7 \dots \zeta$...	$\zeta^3 \dots \zeta$	$\zeta^9 \dots \zeta$	$\zeta^8 \dots \zeta$...	$\zeta^4 \dots \zeta$	ζ^4, ζ^2

By observing the entire table, there are 7 possible quasi-static closures (that were already addressed),

$$\begin{aligned}
 R_{3,1}: \quad q^{(1)} &\stackrel{\checkmark}{=} \alpha_u u^{(1)} + \alpha_T T^{(1)}; \\
 R_{3,2}: \quad q^{(1)} &\stackrel{\checkmark}{=} \alpha_T T^{(1)}; \quad \tilde{r}^{(1)} \stackrel{!}{=} \cancel{\alpha_u u^{(1)} + \alpha_q q^{(1)}}; \quad \tilde{r}^{(1)} \stackrel{x}{=} \cancel{\alpha_u u^{(1)} + \alpha_T T^{(1)}}; \\
 R_{4,2}: \quad \tilde{r}^{(1)} &\stackrel{\checkmark}{=} \alpha_u u^{(1)} + \alpha_T T^{(1)} + \alpha_q q^{(1)}; \\
 R_{4,3}: \quad \tilde{r}^{(1)} &\stackrel{\checkmark}{=} \alpha_T T^{(1)} + \alpha_q q^{(1)}; \\
 R_{4,4}: \quad \tilde{r}^{(1)} &\stackrel{\checkmark}{=} \alpha_q q^{(1)}.
 \end{aligned}
 \tag{3.241}$$

There are also 13 time-dependent closures (that are addressed in the next section),

$$\begin{aligned}
 R_{3,2}: \quad \zeta q^{(1)} + \alpha_q q^{(1)} &\stackrel{\checkmark}{=} \alpha_u u^{(1)}; \quad \zeta q^{(1)} \stackrel{x}{=} \cancel{\alpha_u u^{(1)} + \alpha_T T^{(1)}}; \\
 R_{4,2}: \quad \zeta q^{(1)} + \alpha_q q^{(1)} &\stackrel{\checkmark}{=} \alpha_u u^{(1)} + \alpha_T T^{(1)}; \\
 R_{4,3}: \quad \zeta q^{(1)} + \alpha_q q^{(1)} &\stackrel{\checkmark}{=} \alpha_T T^{(1)}; \quad \zeta \tilde{r}^{(1)} + \alpha_r \tilde{r}^{(1)} \stackrel{!}{=} \cancel{\alpha_u u^{(1)} + \alpha_q q^{(1)}}; \quad \zeta \tilde{r}^{(1)} \stackrel{x}{=} \cancel{\alpha_u u^{(1)} + \alpha_T T^{(1)} + \alpha_q q^{(1)}}; \\
 R_{4,4}: \quad \zeta q^{(1)} + \alpha_q q^{(1)} &\stackrel{\checkmark}{=} \alpha_T T^{(1)}; \quad \zeta \tilde{r}^{(1)} + \alpha_r \tilde{r}^{(1)} \stackrel{\checkmark}{=} \alpha_T T^{(1)}; \quad \zeta \tilde{r}^{(1)} \stackrel{x}{=} \cancel{\alpha_T T^{(1)} + \alpha_q q^{(1)}}; \\
 R_{5,3}: \quad \zeta \tilde{r}^{(1)} + \alpha_r \tilde{r}^{(1)} &\stackrel{\checkmark}{=} \alpha_u u^{(1)} + \alpha_T T^{(1)} + \alpha_q q^{(1)}; \\
 R_{5,4}: \quad \zeta \tilde{r}^{(1)} + \alpha_r \tilde{r}^{(1)} &\stackrel{\checkmark}{=} \alpha_T T^{(1)} + \alpha_q q^{(1)}; \\
 R_{5,5}: \quad \zeta \tilde{r}^{(1)} + \alpha_r \tilde{r}^{(1)} &\stackrel{\checkmark}{=} \alpha_q q^{(1)}; \\
 R_{5,6}: \quad \zeta \tilde{r}^{(1)} + \alpha_r \tilde{r}^{(1)} &\stackrel{\checkmark}{=} \alpha_q q^{(1)}.
 \end{aligned}
 \tag{3.242}$$

New closures should be always checked. Later on, we will consider propagation of the ion-acoustic mode, satisfying kinetic dispersion relation (3.366). We believe that a good ‘reliable’ closure of a fluid model obtained with the $R_{n,n'}(\zeta)$ approximant, should yield a fluid dispersion relation that is equivalent to (3.366), after $R(\zeta)$ is replaced with $R_{n,n'}(\zeta)$ (equivalent to the numerator of (3.366) once both terms are written with the common denominator). Closures that satisfy this requirement are marked with ‘✓’ in the above table. Closures that do not satisfy this requirement were eliminated, and can be further split to two categories. Both eliminated categories actually appear to describe the ion-acoustic mode with the same accuracy as a corresponding ‘reliable’ closure satisfying (3.366), however, the difference is in the higher-order modes. The first category of eliminated closures, marked with ‘x’, produces higher-order modes with positive growth rate, and these closures cannot be used for numerical simulations. The second category, marked with ‘!’, produces higher-order modes that are damped, and these closures can still be useful. However, there is no guarantee that these closures will behave well in different circumstances (for example when used in a 3-D geometry) and these closures were therefore eliminated.

3.8. Going back from Fourier space to real space – the Hilbert transform

The quasi-static Landau fluid closures explored in the previous section were constructed in Fourier space. For direct numerical simulations that can use Fourier transforms (that are usually restricted to periodic boundaries), or for solving dispersion relations $\omega(\mathbf{k})$, this is the easiest and natural way how to implement these closures. Nevertheless, it is very beneficial to see how these advanced fluid closures translate to real space.

Provided all equations are linear (and homogeneous), transformation between real and Fourier space is usually very easy and so far we just needed

$$\frac{\partial}{\partial t} \rightarrow -i\omega; \quad \nabla \rightarrow i\mathbf{k}; \quad f(\mathbf{x}, t) \rightarrow \hat{f}(\mathbf{k}, \omega), \quad (3.243)$$

where we did not even bother to write the hat symbol on the quantities in Fourier space, since it was obvious and not necessary.

With equations encountered in simple fluid models, transformation back to real space is easy and one can usually just flip the direction of the arrow in relations (3.243). However, the constructed Landau fluid closures contain an unusual operator $i\text{sign}(k_{\parallel}) = ik_{\parallel}/|k_{\parallel}|$. How does this operator transforms to real space? Considering spatial 1-D transformation between coordinates $z \leftrightarrow k_{\parallel}$, a general function Fourier transforms according to

$$f(z) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{f}(k_{\parallel}) e^{ik_{\parallel}z} dk_{\parallel} \equiv \mathcal{F}^{-1}\hat{f}(k_{\parallel}); \quad (3.244)$$

$$\hat{f}(k_{\parallel}) = \int_{-\infty}^{\infty} f(z) e^{-ik_{\parallel}z} dz \equiv \mathcal{F}f(z), \quad (3.245)$$

where the first equation is the inverse/backward Fourier transform and the second equation is the forward Fourier transform. As usual, we often do not bother to write the hat symbols on quantities in Fourier space. The location of the normalization factor $1/(2\pi)$ is an *ad hoc* choice, but one has to be consistent, especially when calculating convolutions. As a first step, we need to calculate \mathcal{F}^{-1} of a function $\text{sign}(k_{\parallel})$. However, if such an integral is calculated directly, one will find out that the result is not clearly defined.

It is beneficial to use a small trick, where instead of a function $\text{sign}(k_{\parallel})$, one considers the function $\text{sign}(k_{\parallel})e^{-\alpha|k_{\parallel}|}$, where α is some small positive constant $\alpha > 0$. And after the calculation, one performs the limit $\alpha \rightarrow 0$. The considered function is

$$\text{sign}(k_{\parallel})e^{-\alpha|k_{\parallel}|} = \begin{cases} -e^{+\alpha k_{\parallel}}; & k_{\parallel} < 0; \\ +e^{-\alpha k_{\parallel}}; & k_{\parallel} > 0, \end{cases} \quad (3.246)$$

and the integral calculates as

$$\begin{aligned} \int_{-\infty}^{\infty} \text{sign}(k_{\parallel})e^{-\alpha|k_{\parallel}|} e^{ik_{\parallel}z} dk_{\parallel} &= \int_{-\infty}^0 (-1)e^{+\alpha k_{\parallel}} e^{ik_{\parallel}z} dk_{\parallel} + \int_0^{\infty} (+1)e^{-\alpha k_{\parallel}} e^{ik_{\parallel}z} dk_{\parallel} \\ &= - \int_{-\infty}^0 e^{(+\alpha+iz)k_{\parallel}} dk_{\parallel} + \int_0^{\infty} e^{(-\alpha+iz)k_{\parallel}} dk_{\parallel} \\ &= - \frac{1}{(\alpha+iz)} e^{(+\alpha+iz)k_{\parallel}} \Big|_{k_{\parallel}=-\infty}^0 + \frac{1}{(-\alpha+iz)} e^{(-\alpha+iz)k_{\parallel}} \Big|_{k_{\parallel}=0}^{\infty} \end{aligned}$$

$$\begin{aligned}
 &= -\frac{1}{(\alpha + iz)} - \frac{1}{(-\alpha + iz)} \\
 &= \frac{-(-\alpha - iz) + (\alpha + iz)}{(\alpha + iz)(\alpha - iz)} = \frac{2iz}{\alpha^2 + z^2},
 \end{aligned} \tag{3.247}$$

further yielding

$$\mathcal{F}^{-1} [i \operatorname{sign}(k_{\parallel}) e^{-\alpha|k_{\parallel}|}] = \frac{1}{2\pi} \int_{-\infty}^{\infty} i \operatorname{sign}(k_{\parallel}) e^{-\alpha|k_{\parallel}|} e^{ik_{\parallel}z} dk_{\parallel} = -\frac{z}{\pi(\alpha^2 + z^2)}. \tag{3.248}$$

By taking the limit $\alpha \rightarrow 0$,

$$\mathcal{F}^{-1} [i \operatorname{sign}(k_{\parallel})] = \frac{1}{2\pi} \int_{-\infty}^{\infty} i \operatorname{sign}(k_{\parallel}) e^{ik_{\parallel}z} dk_{\parallel} = -\frac{1}{\pi z}. \tag{3.249}$$

In Landau fluid closures, the operator $i \operatorname{sign}(k_{\parallel})$ acts on a variable $\hat{f}(k_{\parallel})$, and to transform this to real space, we need to use a convolution theorem for Fourier transforms. To make sure that we get the normalization factors right, let us calculate it in detail. The convolution between two real functions is defined as

$$f(z) * g(z) \equiv \int_{-\infty}^{\infty} f(z - z')g(z') dz'. \tag{3.250}$$

For brevity, let us temporarily suppress the parallel subscript on k_{\parallel} and use only k . By decomposing the function $f(z - z')$ to waves (using the inverse Fourier transform), $f(z - z') = (1/2\pi) \int_{-\infty}^{\infty} \hat{f}(k_{\parallel}) e^{ik(z-z')} dk$, splitting the $e^{ik(z-z')} = e^{ikz} e^{-ikz'}$ and changing the order of integrals

$$\begin{aligned}
 \int_{-\infty}^{\infty} f(z - z')g(z') dz' &= \int_{-\infty}^{\infty} \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{f}(k) e^{ik(z-z')} dk \right] g(z') dz' \\
 &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \underbrace{\left[\int_{-\infty}^{\infty} g(z') e^{-ikz'} dz' \right]}_{=\hat{g}(k)} \hat{f}(k) e^{ikz} dk \\
 &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{f}(k)\hat{g}(k) e^{ikz} dk = \mathcal{F}^{-1}[\hat{f}(k)\hat{g}(k)].
 \end{aligned} \tag{3.251}$$

For normalizations (3.244), (3.245), the required convolution theorem therefore reads

$$\mathcal{F}^{-1}[\hat{f}(k_{\parallel})\hat{g}(k_{\parallel})] = [\mathcal{F}^{-1}\hat{f}(k_{\parallel})] * [\mathcal{F}^{-1}\hat{g}(k_{\parallel})] = f(z) * g(z), \tag{3.252}$$

and of course, $f(z) * g(z) = g(z) * f(z)$. Now it is straightforward to calculate how $i \operatorname{sign}(k_{\parallel})\hat{f}(k_{\parallel})$ transforms to real space

$$\mathcal{F}^{-1}[i \operatorname{sign}(k_{\parallel})\hat{f}(k_{\parallel})] = [\mathcal{F}^{-1}i \operatorname{sign}(k_{\parallel})] * [\mathcal{F}^{-1}\hat{f}(k_{\parallel})] = -\frac{1}{\pi z} * f(z). \tag{3.253}$$

The convolution of $1/\pi z$ with a function $f(z)$ is a famous transformation, called the Hilbert transform. According to the definition (3.250), the convolution $(1/z) * f(z)$ should be defined as $\int_{-\infty}^{\infty} f(z')/(z - z') dz'$. However, because of the singularity $1/(z - z')$, such an integral will likely not exist, and the convolution integral is

defined with a principal value. The definition of the Hilbert transform ‘ H ’ that is acting on a function $f(z)$ reads

$$Hf(z) \equiv \frac{1}{\pi z} * f(z) \equiv \frac{1}{\pi} V.P. \int_{-\infty}^{\infty} \frac{f(z')}{z - z'} dz'. \quad (3.254)$$

The use of the Hilbert transform allows a very elegant notation for how the $i\text{sign}(k_{\parallel})\hat{f}(k_{\parallel})$ transforms to real space, it is

$$\mathcal{F}^{-1}[i\text{sign}(k_{\parallel})\hat{f}(k_{\parallel})] = -\frac{1}{\pi z} * f(z) = -Hf(z). \quad (3.255)$$

Performing a lot of calculations, we like shortcuts, and the quantity $i\text{sign}(k_{\parallel})$ can be viewed as an operator, that is acting on many possible $\hat{f}(k_{\parallel})$ variables, such as the velocity $u^{(1)}$, the heat flux $q^{(1)}$, etc. (see the Landau fluid closures). Therefore, in addition to the usual shortcuts (3.243), we can write an elegant shortcut for the operator $i\text{sign}(k_{\parallel})$, that is very useful for advanced fluid models when transforming from Fourier to real space, and that reads

$$\boxed{i\text{sign}(k_{\parallel}) \rightarrow -H.} \quad (3.256)$$

Thus, the operator $i\text{sign}(k_{\parallel})$ in Fourier space, is the negative Hilbert transform operator in real space. Curiously, does the Hilbert transform integral $\int_{-\infty}^{\infty} f(z')/(z - z') dz'$ remind us of something? What about if we prescribe the quantity $f(z')$ to be a Maxwellian $f(z') = e^{-z'^2}$? Oh yes, this is the dreadful Landau integral! This is how the plasma dispersion function was essentially defined. This is indeed the reason, why the paper by Fried & Conte (1961), that is well known for tabulating the properties of the plasma dispersion function, has a full title: ‘*The Plasma Dispersion Function. The Hilbert Transform of the Gaussian*’.

Now we are ready to reformulate the Landau fluid closures in real space. Purely for convenience, often in modern Landau fluid papers another operator \mathcal{H} is defined that is equivalent to the negative Hilbert transform, and that absorbs the minus sign, i.e.

$$\boxed{\mathcal{H} = -H.} \quad (3.257)$$

This ‘ \mathcal{H} ’ operator is therefore defined as

$$\begin{aligned} \mathcal{H}f(z) &\equiv -\frac{1}{\pi z} * f(z) \equiv -\frac{1}{\pi} V.P. \int_{-\infty}^{\infty} \frac{f(z')}{z - z'} dz' = \frac{1}{\pi} V.P. \int_{-\infty}^{\infty} \frac{f(z')}{z' - z} dz' \\ &= -\frac{1}{\pi} V.P. \int_{-\infty}^{\infty} \frac{f(z - z')}{z'} dz', \end{aligned} \quad (3.258)$$

and allows us to write

$$\mathcal{F}^{-1}[i\text{sign}(k_{\parallel})\hat{f}(k_{\parallel})] = \mathcal{H}f(z), \quad (3.259)$$

or in the operator shortcut

$$\boxed{i\text{sign}(k_{\parallel}) \rightarrow \mathcal{H}.} \quad (3.260)$$

This new definition is of course not necessary. However, it is often used in Landau fluid papers, and there is indeed some logic behind it. First of all, we do not have

to remember another minus sign, and we will make less typos, perhaps. Second, the definition is consistent with another ‘spatial’ operator Fourier shortcut $ik_{\parallel} \rightarrow \partial_z$. Third, the Landau integral and the plasma dispersion function were defined with integrals $\int f(x)/(x - x_0) dx$, and not as $\int f(x)/(x_0 - x) dx$, and the \mathcal{H} operator therefore can feel more natural than H . Whatever the choice, we now talked about it in detail, and all possible confusion between H and \mathcal{H} should be clarified. We will use the \mathcal{H} operator henceforth.

3.9. Quasi-static closures in real space

With our new shortcut (3.260) as discussed above, the transformation of closures from Fourier space to real space is very easy. For example, the heat flux closure obtained for $R_{3,2}(\zeta)$ that in Fourier space reads $q^{(1)} = -i(2/\sqrt{\pi})n_0v_{th}\text{sign}(k_{\parallel})T^{(1)}$, is transferred to real space as

$$R_{3,2}(\zeta) : \quad q^{(1)}(z) = -\frac{2}{\sqrt{\pi}}n_0v_{th}\mathcal{H}T^{(1)}(z). \tag{3.261}$$

Again, the \mathcal{H} operator shows its slight advantage over H operator, because it is easy to remember that for the usual collisional heat flux $q \sim -\partial_z T$, whereas for the collisionless heat flux $q \sim -\mathcal{H}T$.

Let us rewrite the Hilbert transform a bit further, so that we can clearly see what this distinction means physically. Rewriting the principal value

$$\mathcal{H}f(z) = -\frac{1}{\pi}V.P. \int_{-\infty}^{\infty} \frac{f(z-z')}{z'} dz' = -\frac{1}{\pi} \lim_{\epsilon \rightarrow +0} \left[\int_{-\infty}^{-\epsilon} + \int_{\epsilon}^{\infty} \right] \frac{f(z-z')}{z'} dz', \tag{3.262}$$

using the substitution $z' = -y$ in the first integral (so that $dz' = -dy$ and $-\infty \rightarrow \infty, -\epsilon \rightarrow \epsilon$),

$$\mathcal{H}f(z) = -\frac{1}{\pi} \lim_{\epsilon \rightarrow +0} \left[\int_{\infty}^{\epsilon} \frac{f(z+y)}{-y} (-dy) + \int_{\epsilon}^{\infty} \frac{f(z-z')}{z'} dz' \right], \tag{3.263}$$

and renaming back $y \rightarrow z'$, the \mathcal{H} operator reads

$$\begin{aligned} \mathcal{H}f(z) &= -\frac{1}{\pi} \lim_{\epsilon \rightarrow +0} \int_{\epsilon}^{\infty} \left[-\frac{f(z+z')}{z'} dz' + \frac{f(z-z')}{z'} dz' \right] \\ &= \frac{1}{\pi} \lim_{\epsilon \rightarrow +0} \int_{\epsilon}^{\infty} \frac{f(z+z') - f(z-z')}{z'} dz'. \end{aligned} \tag{3.264}$$

Instead of remembering the limit, it is more elegant to write the final result as $V.P. \int_0^{\infty}$. In the simplest closure (3.261), the collisionless heat flux is therefore expressed with respect to the temperature as

$$R_{3,2}(\zeta) : \quad q^{(1)}(z) = -\frac{2}{\pi^{3/2}}n_0v_{th}V.P. \int_0^{\infty} \frac{T^{(1)}(z+z') - T^{(1)}(z-z')}{z'} dz', \tag{3.265}$$

which is equivalent to the equation (8) of Hammett & Perkins (1990). Writing the Hilbert transform and the collisionless heat flux in this form is very useful, because it reveals what the Hilbert transform of the temperature means physically.

The equation says that to obtain the heat flux in real space, one has to calculate integrals – and sum the differences between temperatures according to (3.265) – along the entire considered coordinate z . Here, we calculated the expressions in the linear setting/approximation, and in reality, the integrals (3.265) should be performed along the magnetic field lines.

What is perhaps most non-intuitive and most surprising about the expression (3.265), is that the expression is telling us that the entire temperature profile along a magnetic field line is important, since it will be encountered in the integral (3.265). Therefore, the collisionless heat flux $q(z)$ at some spatial point z , depends on the temperature difference between that point, and the temperature along the entire magnetic field line. This effect is summarized with an appropriate word of non-locality of the collisionless heat flux, since it is in strong contrast with the usual collisional heat flux, that depends only at the local gradient of the temperature at that point. For time-evolving systems, this effect is also directly associated with the ‘isotropization’ of temperature along the magnetic field lines. Physically, the effect of non-locality in collisionless plasma is caused by particles that can freely stream along the magnetic field lines. Locality in collisional transport is caused by collisions, which introduces a mean free path.

To rewrite the other quasi-static closures that were explored in the previous section to the real space is trivial, and for example the quasi-static closure (3.234) of Hammett & Perkins (1990) obtained with $R_{4,3}(\zeta)$ reads

$$R_{4,3}(\zeta): \quad \tilde{r}^{(1)}(z) = -\frac{2\sqrt{\pi}}{(3\pi - 8)}v_{\text{th}}\mathcal{H}q^{(1)}(z) + \frac{(32 - 9\pi)}{2(3\pi - 8)}v_{\text{th}}^2n_0T^{(1)}(z). \quad (3.266)$$

The closure (3.227) obtained with four-pole approximant $R_{4,2}(\zeta)$ is rewritten to real space as

$$R_{4,2}(\zeta): \quad \tilde{r}^{(1)}(z) = -\frac{\sqrt{\pi}(10 - 3\pi)}{(16 - 5\pi)}v_{\text{th}}\mathcal{H}q^{(1)}(z) + \frac{(21\pi - 64)}{2(16 - 5\pi)}v_{\text{th}}^2n_0T^{(1)}(z) + \frac{\sqrt{\pi}(9\pi - 28)}{(16 - 5\pi)}v_{\text{th}}T^{(0)}n_0\mathcal{H}u^{(1)}(z), \quad (3.267)$$

the closure (3.240) obtained with $R_{4,4}(\zeta)$ is rewritten as

$$R_{4,4}(\zeta): \quad \tilde{r}^{(1)}(z) = -\frac{3}{4}\sqrt{\pi}v_{\text{th}}\mathcal{H}q^{(1)}(z), \quad (3.268)$$

and the closure (3.211) obtained with $R_{3,1}(\zeta)$ reads

$$R_{3,1}(\zeta): \quad q^{(1)} = \frac{(3\pi - 8)}{(4 - \pi)}n_0T^{(0)}u^{(1)} - \frac{\sqrt{\pi}}{(4 - \pi)}n_0v_{\text{th}}\mathcal{H}T^{(1)}. \quad (3.269)$$

The closures (3.219), (3.220) obtained with $R_{3,2}(\zeta)$ read

$$R_{3,2}(\zeta): \quad \tilde{r}^{(1)} = -\frac{4}{\sqrt{\pi}}v_{\text{th}}n_0T^{(0)}\mathcal{H}u^{(1)} - \frac{(3\pi + 8)}{4\sqrt{\pi}}v_{\text{th}}\mathcal{H}q^{(1)}; \quad (3.270)$$

$$R_{3,2}(\zeta): \quad \tilde{r}^{(1)} = -\frac{4}{\sqrt{\pi}}v_{\text{th}}n_0T^{(0)}\mathcal{H}u^{(1)} - \frac{(3\pi + 8)}{2\pi}v_{\text{th}}^2n_0T^{(1)}, \quad (3.271)$$

however, these closures are not ‘reliable’ and will be eliminated, see the discussion below equations (3.242), (3.382) and (3.399). To summarize, we obtained altogether 7 quasi-static closures. Additionally, one closure was disregarded since it was obtained with approximant $R_{2,1}(\zeta)$ that is not a well-behaved approximant.

3.10. *Time-dependent (dynamic) closures*

In addition to the ‘quasi-static’ closures explored above (sometimes called simply ‘static’), it is possible to construct a different class of closures that we can call ‘time-dependent’ closures, or ‘dynamic’ closures. For example, for the approximant $R_{4,3}(\zeta)$, the temperature $T^{(1)}$ and the heat flux $q^{(1)}$ read

$$R_{4,3}(\zeta) : T^{(1)} = -q_r \frac{\Phi}{D} \left[\frac{8 - 3\pi}{2} \zeta^2 - i\sqrt{\pi}\zeta \right]; \tag{3.272}$$

$$q^{(1)} = -q_r \frac{\Phi}{D} n_0 v_{th} \text{sign}(k_{\parallel}) [-2\zeta], \tag{3.273}$$

where D is the denominator of $R_{4,3}(\zeta)$ defined in (3.228). Calculating the ratio

$$\frac{T^{(1)}}{q^{(1)}} = \frac{1}{n_0 v_{th} \text{sign}(k_{\parallel})} \left[\frac{3\pi - 8}{4} \zeta + \frac{i\sqrt{\pi}}{2} \right], \tag{3.274}$$

using the definition $\zeta = \omega/|k_{\parallel}|v_{th}$ and multiplying by $|k_{\parallel}|v_{th}$ and $n_0 v_{th} \text{sign}(k_{\parallel})$, allows us to formulate a closure

$$R_{4,3}(\zeta) : \left[\frac{3\pi - 8}{4} \omega + i\frac{\sqrt{\pi}}{2} v_{th} |k_{\parallel}| \right] q^{(1)} = n_0 v_{th}^2 k_{\parallel} T^{(1)}, \tag{3.275}$$

that is further rewritten as

$$R_{4,3}(\zeta) : \left[-i\omega + \frac{2\sqrt{\pi}}{(3\pi - 8)} v_{th} |k_{\parallel}| \right] q^{(1)} = -\frac{4n_0 v_{th}^2}{(3\pi - 8)} ik_{\parallel} T^{(1)}. \tag{3.276}$$

To go back to real space, we need a recipe for the inverse Fourier transform of operator $|k_{\parallel}|$, that acts on a general quantity $\hat{f}(k_{\parallel})$. The transform calculates easily by using $|k_{\parallel}| = -(ik_{\parallel})i\text{sign}(k_{\parallel})$ and writing

$$\begin{aligned} \mathcal{F}^{-1} \left[|k_{\parallel}| \hat{f}(k_{\parallel}) \right] &= \frac{1}{2\pi} \int_{-\infty}^{\infty} (-1)(ik_{\parallel})i\text{sign}(k_{\parallel}) \hat{f}(k_{\parallel}) e^{ik_{\parallel}z} dk_{\parallel} \\ &= -\frac{\partial}{\partial z} \frac{1}{2\pi} \int_{-\infty}^{\infty} i\text{sign}(k_{\parallel}) \hat{f}(k_{\parallel}) e^{ik_{\parallel}z} dk_{\parallel} \\ &= -\frac{\partial}{\partial z} \mathcal{F}^{-1} \left[i\text{sign}(k_{\parallel}) \hat{f}(k_{\parallel}) \right] = -\frac{\partial}{\partial z} \mathcal{H}f(z), \end{aligned} \tag{3.277}$$

that allows us to write a useful shortcut

$$\boxed{|k_{\parallel}| \rightarrow -\frac{\partial}{\partial z} \mathcal{H}.} \tag{3.278}$$

The closure (3.276) therefore transforms to real space as

$$\left[\frac{\partial}{\partial t} - \frac{2\sqrt{\pi}}{(3\pi - 8)} v_{th} \frac{\partial}{\partial z} \mathcal{H} \right] q^{(1)}(z) = -\frac{4n_0 v_{th}^2}{(3\pi - 8)} \frac{\partial}{\partial z} T^{(1)}(z), \tag{3.279}$$

and represents the time-dependent evolution equation for the heat flux. The last step in these types of Landau fluid closures is to recover Galilean invariance, that is achieved by substituting $\partial/\partial t$ with the convective derivative d/dt , and the final closure reads

$$R_{4,3}(\zeta) : \left[\frac{d}{dt} - \frac{2\sqrt{\pi}}{(3\pi - 8)} v_{\text{th}} \frac{\partial}{\partial z} \mathcal{H} \right] q^{(1)}(z) = - \frac{4n_0 v_{\text{th}}^2}{(3\pi - 8)} \frac{\partial}{\partial z} T^{(1)}(z). \quad (3.280)$$

To easily compare this expression with the existing literature, a small rearrangement yields

$$\left[\frac{d}{dt} + \frac{\sqrt{\pi}}{4 \left(1 - \frac{3\pi}{8}\right)} v_{\text{th}} \frac{\partial}{\partial z} \mathcal{H} \right] q^{(1)}(z) = \frac{n_0 v_{\text{th}}^2}{2 \left(1 - \frac{3\pi}{8}\right)} \frac{\partial}{\partial z} T^{(1)}(z). \quad (3.281)$$

The expression is equal for example to equation (57) in Passot & Sulem (2003) for the parallel heat flux q_{\parallel} (where in that paper $v_{\text{th}} = \sqrt{T^{(0)}/m}$ is used, whereas ours here is $v_{\text{th}} = \sqrt{2T^{(0)}/m}$).

The time-dependent closure (3.280) was obtained with the approximant $R_{4,3}(\zeta)$. Interestingly, if the derivative d/dt is neglected, the closure is equivalent to the quasi-static closure (3.261) obtained with $R_{3,2}(\zeta)$ (which can be easily seen in Fourier space, or by using $\mathcal{H}\mathcal{H} = -1$). Also, it is useful to compare the time-dependent (3.280) with the quasi-static closure (3.266), that was obtained for the same approximant $R_{4,3}(\zeta)$. To compare these closures, we need to use a time-dependent heat flux equation where the closure for \tilde{r} will be applied. In Part 1 of this guide, we derived nonlinear ‘fluid’ equation for the parallel heat flux q_{\parallel} (see Part 1, section ‘Collisionless damping in fluid models – Landau fluid models’). Quickly rewriting it in the 1-D parallel geometry that we use here yields (dropping the parallel subscript)

$$\frac{\partial q}{\partial t} + \partial_z(qu) + \partial_z \tilde{r} + 3p \partial_z \left(\frac{p}{\rho} \right) + 3q \partial_z u = 0, \quad (3.282)$$

where for brevity $\partial/\partial z = \partial_z$. The equation can be of course obtained by direct integration of the 1-D Vlasov equation $\partial f/\partial t + v \partial_z f + (q_r/m_r) E \partial f/\partial v = 0$, as done by Hammett & Perkins (1990), and prescribing a Maxwellian by $r = 3p^2/\rho + \tilde{r}$. The equation is nonlinear and to compare closures that were done at the linear level, we need to linearize the heat flux equation. This eliminates the second and the last term, the fourth term is linearized as $3(p_0/m) \partial_z T^{(1)}$, and since $p_0/m = n_0 v_{\text{th}}^2/2$, the linearized equation reads

$$\frac{\partial q^{(1)}}{\partial t} + \partial_z \tilde{r}^{(1)} + \frac{3}{2} n_0 v_{\text{th}}^2 \partial_z T^{(1)} = 0. \quad (3.283)$$

This is just a 1-D linear heat flux equation, where no closure was imposed yet. The quantities $q^{(1)}$, $\tilde{r}^{(1)}$, $T^{(1)}$ were not calculated from kinetic theory by using approximants to $R(\zeta)$, etc. The equation was obtained by a general ‘fluid approach’, that we heavily used before we started to consider kinetic calculations (perturbations around a Maxwellian are assumed here because of the prescribed r). The equation (3.283) greatly clarifies relations between the quasi-static and time-dependent Landau fluid

closures. For example, by using the quasi-static closure (3.266) in the heat flux equation (3.283), the time-dependent closure (3.279) is immediately recovered.

Often, time-dependent closures cannot be straightforwardly constructed by a simple division of two moments, as done above. It is useful to learn a new technique that will allow us to see and construct possible closures in a quicker way. Let us explore the closure (3.276). It is apparent that whenever we attempt to use $\partial/\partial t$ of some moment (in this case $\partial q^{(1)}/\partial t$), it is logical to also use the same moment without the time derivative ($q^{(1)}$) in the construction of the considered closure, i.e. in this case we search for a closure

$$R_{4,3}(\zeta) : (\zeta + \alpha_q) q^{(1)} = \alpha_T T^{(1)}, \tag{3.284}$$

where α_q, α_T need to be determined. By using expressions for $q^{(1)}, T^{(1)}$, the above closure is separated to 2 equations for ζ and ζ^2 that must be satisfied independently if the closure is valid for all ζ , and solving these 2 equations yields

$$\alpha_q = i \frac{2\sqrt{\pi}}{(3\pi - 8)}; \quad \alpha_T = \frac{4n_0 v_{th}}{(3\pi - 8)} \text{sign}(k_{\parallel}). \tag{3.285}$$

The closure therefore reads

$$R_{4,3}(\zeta) : \left[\zeta + i \frac{2\sqrt{\pi}}{(3\pi - 8)} \right] q^{(1)} = \frac{4n_0 v_{th}}{(3\pi - 8)} \text{sign}(k_{\parallel}) T^{(1)}, \tag{3.286}$$

and is of course equivalent to (3.276).

We are now ready to construct all other possible time-dependent closures. Still considering the $R_{4,3}(\zeta)$ approximant, another possible closure is

$$R_{4,3}(\zeta) : (\zeta + \alpha_r) \tilde{r}^{(1)} = \alpha_u u^{(1)} + \alpha_q q^{(1)}, \tag{3.287}$$

which when separated into 3 equations for ζ, ζ^2 and ζ^3 that must each be satisfied yields

$$\begin{aligned} \alpha_r &= \frac{i16\sqrt{\pi}}{(32 - 9\pi)(3\pi - 8)}; & \alpha_u &= \frac{(32 - 9\pi)}{(3\pi - 8)} v_{th} n_0 T^{(0)} \text{sign}(k_{\parallel}); \\ \alpha_q &= \frac{(81\pi^2 - 552\pi + 1024)}{2(32 - 9\pi)(3\pi - 8)} v_{th} \text{sign}(k_{\parallel}), \end{aligned} \tag{3.288}$$

the closure reads

$$\begin{aligned} R_{4,3}(\zeta) : \left[-i\omega + \frac{16\sqrt{\pi}}{(32 - 9\pi)(3\pi - 8)} v_{th} |k_{\parallel}| \right] \tilde{r}^{(1)} &= -\frac{(32 - 9\pi)}{(3\pi - 8)} v_{th}^2 n_0 T^{(0)} i k_{\parallel} u^{(1)} - \frac{(81\pi^2 - 552\pi + 1024)}{2(32 - 9\pi)(3\pi - 8)} v_{th}^2 i k_{\parallel} q^{(1)}; \\ \left[\frac{d}{dt} - \frac{16\sqrt{\pi}}{(32 - 9\pi)(3\pi - 8)} v_{th} \partial_z \mathcal{H} \right] \tilde{r}^{(1)} &= -\frac{(32 - 9\pi)}{(3\pi - 8)} v_{th}^2 n_0 T^{(0)} \partial_z u^{(1)} - \frac{(81\pi^2 - 552\pi + 1024)}{2(32 - 9\pi)(3\pi - 8)} v_{th}^2 \partial_z q^{(1)}, \end{aligned} \tag{3.289}$$

and this closure will be eliminated.

Another closure with $R_{4,3}(\zeta)$ can be constructed as

$$\begin{aligned} R_{4,3}(\zeta) : \zeta \tilde{r}^{(1)} &= \alpha_u u^{(1)} + \alpha_T T^{(1)} + \alpha_q q^{(1)}; \\ \alpha_u &= \frac{(32 - 9\pi)}{(3\pi - 8)} v_{th} n_0 T^{(0)} \text{sign}(k_{\parallel}); & \alpha_T &= -i \frac{8\sqrt{\pi}}{(3\pi - 8)^2} v_{th}^2 n_0; \end{aligned} \tag{3.290}$$

$$\alpha_q = -\frac{(27\pi^2 - 160\pi + 256)}{2(3\pi - 8)^2} v_{th} \text{sign}(k_{\parallel}),$$

so the closure reads

$$\begin{aligned} R_{4,3}(\zeta): \quad -i\omega \tilde{r}^{(1)} &= -\frac{(32 - 9\pi)}{(3\pi - 8)} v_{th}^2 n_0 T^{(0)} i k_{\parallel} u^{(1)} - \frac{8\sqrt{\pi}}{(3\pi - 8)^2} v_{th}^3 n_0 |k_{\parallel}| T^{(1)} + \frac{(27\pi^2 - 160\pi + 256)}{2(3\pi - 8)^2} v_{th}^2 i k_{\parallel} q^{(1)}; \\ \frac{d}{dt} \tilde{r}^{(1)} &= -\frac{(32 - 9\pi)}{(3\pi - 8)} v_{th}^2 n_0 T^{(0)} \partial_z u^{(1)} + \frac{8\sqrt{\pi}}{(3\pi - 8)^2} v_{th}^3 n_0 \partial_z \mathcal{H} T^{(1)} + \frac{(27\pi^2 - 160\pi + 256)}{2(3\pi - 8)^2} v_{th}^2 \partial_z q^{(1)}, \end{aligned} \tag{3.291}$$

and this closure will be eliminated as well. The time-dependent closures (3.290) and (3.287) are of course closely related, and one can go from one to another by using the quasi-static closure (3.266) that expresses $\tilde{r}^{(1)}$ as a combination of $T^{(1)}$ and $q^{(1)}$.

Continuing with the $R_{4,2}(\zeta)$ approximant, it is possible to construct the following closure

$$\begin{aligned} R_{4,2}(\zeta): \quad (\zeta + \alpha_q) q^{(1)} &= \alpha_T T^{(1)} + \alpha_u u^{(1)}; \tag{3.292} \\ \alpha_q &= i\sqrt{\pi} \frac{10 - 3\pi}{16 - 5\pi}; \quad \alpha_T = n_0 v_{th} \text{sign}(k_{\parallel}) \frac{3\pi - 8}{16 - 5\pi}; \quad \alpha_u = i n_0 T^{(0)} \sqrt{\pi} \frac{9\pi - 28}{16 - 5\pi}, \end{aligned}$$

that implies

$$\left[-i\omega + \sqrt{\pi} \frac{10 - 3\pi}{16 - 5\pi} v_{th} |k_{\parallel}| \right] q^{(1)} = -n_0 v_{th}^2 \frac{3\pi - 8}{16 - 5\pi} i k_{\parallel} T^{(1)} + n_0 T^{(0)} v_{th} \sqrt{\pi} \frac{9\pi - 28}{16 - 5\pi} |k_{\parallel}| u^{(1)};$$

$$R_{4,2}(\zeta): \quad \left[\frac{d}{dt} - \sqrt{\pi} \frac{10 - 3\pi}{16 - 5\pi} v_{th} \partial_z \mathcal{H} \right] q^{(1)} = -n_0 v_{th}^2 \frac{3\pi - 8}{16 - 5\pi} \partial_z T^{(1)} - n_0 T^{(0)} v_{th} \sqrt{\pi} \frac{9\pi - 28}{16 - 5\pi} \partial_z \mathcal{H} u^{(1)},$$

(3.293)

and the result is consistent with using the quasi-static closure (3.267) in the linearized heat flux equation (3.283).

Continuing with $R_{4,4}(\zeta)$, it is possible to construct

$$\begin{aligned} R_{4,4}(\zeta): \quad (\zeta + \alpha_q) q^{(1)} &= \alpha_T T^{(1)}; \tag{3.294} \\ \alpha_q &= i \frac{3\sqrt{\pi}}{4}; \quad \alpha_T = \frac{3}{2} n_0 v_{th} \text{sign}(k_{\parallel}), \end{aligned}$$

and the closure reads

$$\left[-i\omega + \frac{3\sqrt{\pi}}{4} v_{th} |k_{\parallel}| \right] q^{(1)} = -\frac{3}{2} n_0 v_{th}^2 i k_{\parallel} T^{(1)};$$

$$R_{4,4}(\zeta): \quad \left[\frac{d}{dt} - \frac{3\sqrt{\pi}}{4} v_{th} \partial_z \mathcal{H} \right] q^{(1)} = -\frac{3}{2} n_0 v_{th}^2 \partial_z T^{(1)}.$$

(3.295)

The obtained closure is related to the quasi-static closure (3.268), since by using the quasi-static closure (3.268) in the linear heat flux equation (3.283), the time-dependent closure (3.295) is recovered.

Another closure with $R_{4,4}(\zeta)$ is

$$R_{4,4}(\zeta) : \quad (\zeta + \alpha_r)\tilde{r}^{(1)} = \alpha_T T^{(1)}; \tag{3.296}$$

$$\alpha_r = i\frac{3\sqrt{\pi}}{4}; \quad \alpha_T = -i\frac{9\sqrt{\pi}}{8}v_{th}^2 n_0;$$

$$\left[-i\omega + \frac{3\sqrt{\pi}}{4}v_{th}|k_{\parallel}| \right] \tilde{r}^{(1)} = -\frac{9\sqrt{\pi}}{8}v_{th}^3 n_0 |k_{\parallel}| T^{(1)};$$

$$R_{4,4}(\zeta) : \quad \left[\frac{d}{dt} - \frac{3\sqrt{\pi}}{4}v_{th}\partial_z \mathcal{H} \right] \tilde{r}^{(1)} = +\frac{9\sqrt{\pi}}{8}v_{th}^3 n_0 \partial_z \mathcal{H} T^{(1)}. \tag{3.297}$$

And yet another closure with $R_{4,4}(\zeta)$

$$R_{4,4}(\zeta) : \quad \zeta \tilde{r}^{(1)} = \alpha_T T^{(1)} + \alpha_q q^{(1)}; \tag{3.298}$$

$$\alpha_T = -i\frac{9\sqrt{\pi}}{8}v_{th}^2 n_0; \quad \alpha_q = -\frac{9\pi}{16}v_{th}\text{sign}(k_{\parallel});$$

$$-i\omega \tilde{r}^{(1)} = -\frac{9\sqrt{\pi}}{8}v_{th}^3 n_0 |k_{\parallel}| T^{(1)} + \frac{9\pi}{16}v_{th}^2 i k_{\parallel} q^{(1)};$$

$$\frac{d}{dt} \tilde{r}^{(1)} = \frac{9\sqrt{\pi}}{8}v_{th}^3 n_0 \partial_z \mathcal{H} T^{(1)} + \frac{9\pi}{16}v_{th}^2 \partial_z q^{(1)}. \tag{3.299}$$

The closure (3.299) is related to the closure (3.297), because one can use the quasi-static closure (3.268) to express $\tilde{r}^{(1)}$ through $q^{(1)}$, however, the closure (3.299) will be eliminated.

The $R_{4,5}(\zeta)$ was eliminated because it is not a well-behaved approximant (see discussion above), nevertheless, for completeness the following closure can be constructed

$$R_{4,5}(\zeta) : \quad \zeta q^{(1)} = \alpha_T T^{(1)}; \quad \alpha_T = \frac{3}{2}n_0 v_{th}\text{sign}(k_{\parallel}); \tag{3.300}$$

$$-i\omega q^{(1)} = -\frac{3}{2}n_0 v_{th}^2 i k_{\parallel} T^{(1)}; \quad \frac{d}{dt} q^{(1)} = -\frac{3}{2}n_0 v_{th}^2 \partial_z T^{(1)}.$$

With $R_{3,2}(\zeta)$, the following time-dependent closure can be constructed

$$R_{3,2}(\zeta) : \quad (\zeta + \alpha_q) q^{(1)} = \alpha_u u^{(1)}; \tag{3.301}$$

$$\alpha_q = \frac{2i}{\sqrt{\pi}}; \quad \alpha_u = -\frac{4i}{\sqrt{\pi}}n_0 T^{(0)};$$

$$\left[-i\omega + \frac{2}{\sqrt{\pi}}v_{th}|k_{\parallel}| \right] q^{(1)} = -\frac{4}{\sqrt{\pi}}n_0 T^{(0)}v_{th}|k_{\parallel}| u^{(1)};$$

$$R_{3,2}(\zeta) : \quad \left[\frac{d}{dt} - \frac{2}{\sqrt{\pi}}v_{th}\partial_z \mathcal{H} \right] q^{(1)} = +\frac{4}{\sqrt{\pi}}n_0 T^{(0)}v_{th}\partial_z \mathcal{H} u^{(1)}, \tag{3.302}$$

and similarly, yet another one

$$R_{3,2}(\zeta) : \quad \zeta q^{(1)} = \alpha_u u^{(1)} + \alpha_T T^{(1)}; \tag{3.303}$$

$$\alpha_u = -\frac{4i}{\sqrt{\pi}}n_0 T^{(0)}; \quad \alpha_T = -\frac{4}{\pi}n_0 v_{th}\text{sign}(k_{\parallel});$$

$$\begin{aligned}
 -i\omega q^{(1)} &= -\frac{4}{\sqrt{\pi}}n_0T^{(0)}v_{\text{th}}|k_{\parallel}|u^{(1)} + \frac{4}{\pi}n_0v_{\text{th}}^2ik_{\parallel}T^{(1)}; \\
 \frac{d}{dt}q^{(1)} &= +\frac{4}{\sqrt{\pi}}n_0T^{(0)}v_{\text{th}}\partial_z\mathcal{H}u^{(1)} + \frac{4}{\pi}n_0v_{\text{th}}^2\partial_zT^{(1)},
 \end{aligned}
 \tag{3.304}$$

however, the last closure will be eliminated.

3.11. Time-dependent closures with five-pole approximants

Now we can use this technique to construct time-dependent closures with five-pole approximants of $R(\zeta)$. Starting with the $R_{5,4}(\zeta)$ approximant

$$R_{5,4}(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2 + a_3\zeta^3}{1 + 3(a_1 + a_3)\zeta + (3a_2 - 2)\zeta^2 + (3a_3 - 2a_1)\zeta^3 - 2a_2\zeta^4 - 2a_3\zeta^5}, \tag{3.305}$$

where the constants a_1, a_2, a_3 are given in (A 8), the kinetic moments calculate as

$$R_{5,4}(\zeta): \quad D = (1 + 3(a_1 + a_3)\zeta + (3a_2 - 2)\zeta^2 + (3a_3 - 2a_1)\zeta^3 - 2a_2\zeta^4 - 2a_3\zeta^5); \tag{3.306}$$

$$u^{(1)} = -\frac{q_r}{T^{(0)}}\Phi v_{\text{th}}\text{sign}(k_{\parallel})\frac{1}{D} [a_3\zeta^4 + a_2\zeta^3 + a_1\zeta^2 + \zeta]; \tag{3.307}$$

$$T^{(1)} = -q_r\Phi\frac{1}{D} [2a_3\zeta^3 + 2a_2\zeta^2 + (2a_1 + 3a_3)\zeta]; \tag{3.308}$$

$$q^{(1)} = -q_r n_0 \Phi v_{\text{th}} \text{sign}(k_{\parallel}) \frac{1}{D} [3a_3\zeta^2 - 2\zeta]; \tag{3.309}$$

$$\tilde{r}^{(1)} = -q_r \frac{n_0}{2} v_{\text{th}}^2 \Phi \frac{1}{D} [-(6a_2 + 4)\zeta^2 - (6a_1 + 9a_3)\zeta]. \tag{3.310}$$

It is possible to construct time-dependent closure for $\tilde{r}^{(1)}$, by searching for a solution

$$(\zeta + \alpha_r)\tilde{r}^{(1)} = \alpha_T T^{(1)} + \alpha_q q^{(1)}. \tag{3.311}$$

Separating the equation to 3 equations for ζ, ζ^2, ζ^3 , the solution is

$$\alpha_r = \frac{a_2}{a_3}; \quad \alpha_T = -n_0 v_{\text{th}}^2 \frac{3a_2 + 2}{2a_3}; \quad \alpha_q = -v_{\text{th}} \text{sign}(k_{\parallel}) \frac{2a_1 + 3a_3}{2a_3}, \tag{3.312}$$

that evaluates as

$$\alpha_r = i \frac{21\pi - 64}{\sqrt{\pi}(9\pi - 28)}; \quad \alpha_T = i n_0 v_{\text{th}}^2 \frac{256 - 81\pi}{2(9\pi - 28)\sqrt{\pi}}; \quad \alpha_q = v_{\text{th}} \text{sign}(k_{\parallel}) \frac{32 - 9\pi}{2(9\pi - 28)}. \tag{3.313}$$

The $R_{5,4}(\zeta)$ closure therefore reads

$$\left[-i\omega + \frac{21\pi - 64}{\sqrt{\pi}(9\pi - 28)} v_{\text{th}} |k_{\parallel}| \right] \tilde{r}^{(1)} = n_0 v_{\text{th}}^3 \frac{256 - 81\pi}{2(9\pi - 28)\sqrt{\pi}} |k_{\parallel}| T^{(1)} - v_{\text{th}}^2 \frac{32 - 9\pi}{2(9\pi - 28)} i k_{\parallel} q^{(1)}, \tag{3.314}$$

and transformation to real space yields

$$\boxed{R_{5,4}(\zeta): \quad \left[\frac{d}{dt} - \frac{21\pi - 64}{\sqrt{\pi}(9\pi - 28)} v_{\text{th}} \partial_z \mathcal{H} \right] \tilde{r}^{(1)} = -n_0 v_{\text{th}}^3 \frac{256 - 81\pi}{2(9\pi - 28)\sqrt{\pi}} \partial_z \mathcal{H} T^{(1)} - v_{\text{th}}^2 \frac{32 - 9\pi}{2(9\pi - 28)} \partial_z q^{(1)}.} \tag{3.315}$$

The closure is interesting, since the $R_{5,4}(\zeta)$ is a very precise $o(\zeta^3)$, $o(1/\zeta^6)$ approximant, and it is therefore only one of two closures that have precision $o(\zeta^3)$. For large ζ , the moments have correct asymptotic behaviour up to the heat flux $q^{(1)} \sim -3/(2\zeta^3)$ (including the proportionality constant) and the $\tilde{r}^{(1)} \sim 1/\zeta^3$, which is not bad either. Additionally, the closure does not contain $u^{(1)}$, which is advantageous.

Constructing a closure with $R_{5,5}(\zeta)$ is done quickly, by using $a_2 = -2/3$ in the kinetic moments for $R_{5,4}(\zeta)$, so

$$R_{5,5}(\zeta): \quad D = (1 + 3(a_1 + a_3)\zeta - 4\zeta^2 + (3a_3 - 2a_1)\zeta^3 + \frac{4}{3}\zeta^4 - 2a_3\zeta^5); \tag{3.316}$$

$$q^{(1)} = -q_r n_0 \Phi v_{th} \text{sign}(k_{\parallel}) \frac{1}{D} \left[i \frac{(32 - 9\pi)}{3\sqrt{\pi}} \zeta^2 - 2\zeta \right]; \tag{3.317}$$

$$\tilde{r}^{(1)} = -q_r \frac{n_0}{2} v_{th}^2 \Phi \frac{1}{D} [3i\sqrt{\pi}\zeta], \tag{3.318}$$

where a_1, a_3 are given in (A 9). Searching for a closure $(\zeta + \alpha_r)\tilde{r}^{(1)} = \alpha_q q^{(1)}$ has a solution

$$\left[\zeta + i \frac{6\sqrt{\pi}}{(32 - 9\pi)} \right] \tilde{r}^{(1)} = \frac{9\pi}{2(32 - 9\pi)} v_{th} \text{sign}(k_{\parallel}) q^{(1)}; \tag{3.319}$$

$$\left[-i\omega + \frac{6\sqrt{\pi}}{(32 - 9\pi)} v_{th} |k_{\parallel}| \right] \tilde{r}^{(1)} = -\frac{9\pi}{2(32 - 9\pi)} v_{th}^2 i k_{\parallel} q^{(1)},$$

and the closure in real space reads

$$R_{5,5}(\zeta): \quad \left[\frac{d}{dt} - \frac{6\sqrt{\pi}}{(32 - 9\pi)} v_{th} \partial_z \mathcal{H} \right] \tilde{r}^{(1)} = -\frac{9\pi}{2(32 - 9\pi)} v_{th}^2 \partial_z q^{(1)}. \tag{3.320}$$

The $R_{5,5}(\zeta)$ approximant has precision $o(\zeta^2)$, $o(1/\zeta^7)$. The increase of the asymptotic precision reproduces the correct asymptote $\tilde{r}^{(1)} \sim 1/\zeta^4$, even though with proportionality constant $\tilde{r}^{(1)} \sim -(27\pi/2(32 - 9\pi)\zeta^4) = -11.38/\zeta^4$ instead of the correct $-6/\zeta^4$.

Continuing with the approximant $R_{5,6}(\zeta)$, the kinetic moments calculate as

$$R_{5,6}(\zeta): \quad D = \left(1 - i\sqrt{\pi} \frac{15}{8} \zeta - 4\zeta^2 + i\sqrt{\pi} \frac{5}{2} \zeta^3 + \frac{4}{3} \zeta^4 - i \frac{\sqrt{\pi}}{2} \zeta^5 \right); \tag{3.321}$$

$$q^{(1)} = -q_r n_0 \Phi v_{th} \text{sign}(k_{\parallel}) \frac{1}{D} \left[\frac{3i\sqrt{\pi}}{4} \zeta^2 - 2\zeta \right]; \tag{3.322}$$

$$\tilde{r}^{(1)} = -q_r \frac{n_0}{2} v_{th}^2 \Phi \frac{1}{D} [3i\sqrt{\pi}\zeta], \tag{3.323}$$

which yields a closure

$$\left[\zeta + i \frac{8}{3\sqrt{\pi}} \right] \tilde{r}^{(1)} = 2v_{th} \text{sign}(k_{\parallel}) q^{(1)}; \tag{3.324}$$

$$\left[-i\omega + \frac{8}{3\sqrt{\pi}} v_{th} |k_{\parallel}| \right] \tilde{r}^{(1)} = -2v_{th}^2 i k_{\parallel} q^{(1)},$$

that in real space reads

$$R_{5,6}(\zeta) : \quad \left[\frac{d}{dt} - \frac{8}{3\sqrt{\pi}} v_{\text{th}} \partial_z \mathcal{H} \right] \tilde{r}^{(1)} = -2v_{\text{th}}^2 \partial_z q^{(1)}. \quad (3.325)$$

The $R_{5,6}(\zeta)$ approximant has precision $o(\zeta)$, $o(1/\zeta^8)$. Even though the precision for small ζ is relatively low, the closure correctly reproduces the asymptotic behaviour $\tilde{r}^{(1)} \sim -6/\zeta^4$ (including the proportionality constant).

Finally, it is indeed possible to construct a closure with precision $o(\zeta^4)$, by using $R_{5,3}(\zeta)$. The approximant $R_{5,3}(\zeta)$ is defined as

$$R_{5,3}(\zeta) = \frac{1 + a_1 \zeta + a_2 \zeta^2 + a_3 \zeta^3}{1 + b_1 \zeta + (3a_2 - 2)\zeta^2 + (3a_3 - 2a_1)\zeta^3 - 2a_2 \zeta^4 - 2a_3 \zeta^5}, \quad (3.326)$$

where the constants a_1, a_2, a_3, b_1 are given in (A 7). Using this approximant, the kinetic moments calculate as

$$R_{5,3}(\zeta) : \quad D = (1 + b_1 \zeta + (3a_2 - 2)\zeta^2 + (3a_3 - 2a_1)\zeta^3 - 2a_2 \zeta^4 - 2a_3 \zeta^5); \quad (3.327)$$

$$u^{(1)} = -\frac{q_r}{T^{(0)}} \Phi v_{\text{th}} \text{sign}(k_{\parallel}) \frac{1}{D} [a_3 \zeta^4 + a_2 \zeta^3 + a_1 \zeta^2 + \zeta]; \quad (3.328)$$

$$T^{(1)} = -q_r \Phi \frac{1}{D} [2a_3 \zeta^3 + 2a_2 \zeta^2 + (b_1 - a_1)\zeta]; \quad (3.329)$$

$$q^{(1)} = -q_r n_0 \Phi v_{\text{th}} \text{sign}(k_{\parallel}) \frac{1}{D} [(b_1 - 3a_1)\zeta^2 - 2\zeta]; \quad (3.330)$$

$$\tilde{r}^{(1)} = -q_r \frac{n_0}{2} v_{\text{th}}^2 \Phi \frac{1}{D} [(2b_1 - 6a_1 - 6a_3)\zeta^3 - (6a_2 + 4)\zeta^2 + (3a_1 - 3b_1)\zeta]. \quad (3.331)$$

It is possible to search for a closure

$$R_{5,3}(\zeta) : \quad (\zeta + \alpha_r) \tilde{r}^{(1)} = \alpha_u u^{(1)} + \alpha_T T^{(1)} + \alpha_q q^{(1)}, \quad (3.332)$$

and the solution is

$$\begin{aligned} \alpha_r &= \frac{a_2}{a_3}; & \alpha_u &= -v_{\text{th}} n_0 T^{(0)} \frac{(3a_1 + 3a_3 - b_1)}{a_3} \text{sign}(k_{\parallel}); \\ \alpha_T &= -n_0 v_{\text{th}}^2 \frac{(3a_2 + 2)}{2a_3}; & \alpha_q &= -v_{\text{th}} \frac{(2a_1 + 3a_3)}{2a_3} \text{sign}(k_{\parallel}). \end{aligned} \quad (3.333)$$

The correctness of the algebra can be quickly checked by prescribing $b_1 = 3a_1 + 3a_3$, which immediately recovers the closure (3.311)–(3.312) that was obtained for $R_{5,4}(\zeta)$ with only asymptotic expansion coefficients (and the power-series coefficients unspecified), which yields $\alpha_u = 0$. The $R_{5,3}(\zeta)$ closure reads

$$\begin{aligned} R_{5,3}(\zeta) : \quad \left[-i\omega - i\frac{a_2}{a_3} v_{\text{th}} |k_{\parallel}| \right] \tilde{r}^{(1)} &= v_{\text{th}}^2 n_0 T^{(0)} \frac{(3a_1 + 3a_3 - b_1)}{a_3} i k_{\parallel} u^{(1)} \\ &+ i n_0 v_{\text{th}}^3 \frac{(3a_2 + 2)}{2a_3} |k_{\parallel}| T^{(1)} + v_{\text{th}}^2 \frac{(2a_1 + 3a_3)}{2a_3} i k_{\parallel} q^{(1)}. \end{aligned} \quad (3.334)$$

By using the calculated coefficients from (A 7),

$$\begin{aligned} \frac{a_2}{a_3} &= i \frac{(104 - 33\pi)\sqrt{\pi}}{2(9\pi^2 - 69\pi + 128)} \equiv i\tilde{\alpha}_r; & \frac{3a_1 + 3a_3 - b_1}{a_3} &= \frac{(135\pi^2 - 750\pi + 1024)}{2(9\pi^2 - 69\pi + 128)} \equiv \tilde{\alpha}_u; \\ \frac{3a_2 + 2}{2a_3} &= i \frac{3(160 - 51\pi)\sqrt{\pi}}{4(9\pi^2 - 69\pi + 128)} \equiv i\tilde{\alpha}_T; & \frac{2a_1 + 3a_3}{2a_3} &= \frac{(54\pi^2 - 333\pi + 512)}{2(9\pi^2 - 69\pi + 128)} \equiv \tilde{\alpha}_q, \end{aligned} \tag{3.335}$$

the closure in Fourier and real space then reads

$$R_{5,3}(\zeta) : \quad [-i\omega + \tilde{\alpha}_r v_{th} |k_{\parallel}|] \tilde{r}^{(1)} = v_{th}^2 n_0 T^{(0)} \tilde{\alpha}_u i k_{\parallel} u^{(1)} - n_0 v_{th}^3 \tilde{\alpha}_T |k_{\parallel}| T^{(1)} + v_{th}^2 \tilde{\alpha}_q i k_{\parallel} q^{(1)}; \tag{3.336}$$

$$\left[\frac{d}{dt} - \tilde{\alpha}_r v_{th} \partial_z \mathcal{H} \right] \tilde{r}^{(1)} = v_{th}^2 n_0 T^{(0)} \tilde{\alpha}_u \partial_z u^{(1)} + n_0 v_{th}^3 \tilde{\alpha}_T \partial_z \mathcal{H} T^{(1)} + v_{th}^2 \tilde{\alpha}_q \partial_z q^{(1)}, \tag{3.337}$$

where the perhaps complicated appearing proportionality constants (that come from the Padé approximation) are just constants, that are numerically evaluated as

$$\tilde{\alpha}_r = 5.13185; \quad \tilde{\alpha}_u = 1.78706; \quad \tilde{\alpha}_T = -5.20074; \quad \tilde{\alpha}_q = -10.53748. \tag{3.338}$$

For numerical simulations, we of course recommend to re-calculate these constants from the above analytic expressions, to fully match the numerical precision of the considered simulation. For complete clarity, the fully expressed closure in real space reads

$$\begin{aligned} R_{5,3}(\zeta) : \quad & \left[\frac{d}{dt} - \frac{(104 - 33\pi)\sqrt{\pi}}{2(9\pi^2 - 69\pi + 128)} v_{th} \partial_z \mathcal{H} \right] \tilde{r}^{(1)} \\ & = v_{th}^2 n_0 T^{(0)} \frac{(135\pi^2 - 750\pi + 1024)}{2(9\pi^2 - 69\pi + 128)} \partial_z u^{(1)} \\ & \quad + n_0 v_{th}^3 \frac{3(160 - 51\pi)\sqrt{\pi}}{4(9\pi^2 - 69\pi + 128)} \partial_z \mathcal{H} T^{(1)} \\ & \quad + v_{th}^2 \frac{(54\pi^2 - 333\pi + 512)}{2(9\pi^2 - 69\pi + 128)} \partial_z q^{(1)}. \end{aligned} \tag{3.339}$$

This is the only closure with precision $o(\zeta^4)$, and the asymptotic precision is $o(1/\zeta^5)$. To conclude, we have altogether obtained 13 time-dependent closures. Additionally, we have also obtained 1 time-dependent closure for $R_{4,5}(\zeta)$ that was disregarded since $R_{4,5}(\zeta)$ is not a well-behaved approximant.

3.12. Parallel ion-acoustic (sound) mode, cold electrons

After all the calculations, it is advisable to verify whether we obtained anything useful. Let us consider only the proton species, make the electrons cold and neglect electron inertia, so we have only a 1-fluid model. Let us continue to work in physical units and later we will switch to normalized units. From Part 1 of this guide, the linearized fluid equations (obtained by direct integration of the Vlasov equation for a general distribution function f) can be written in physical units as

$$-\omega \frac{n^{(1)}}{n_0} + k_{\parallel} u_z^{(1)} = 0; \tag{3.340}$$

$$-\omega u_z^{(1)} + \frac{v_{\text{th}\parallel}^2}{2} k_{\parallel} \frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} = 0; \quad (3.341)$$

$$-\omega \frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} + 3k_{\parallel} u_z^{(1)} + k_{\parallel} \frac{q_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} = 0; \quad (3.342)$$

$$-\omega \frac{q_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} + \frac{3}{2} v_{\text{th}\parallel}^2 k_{\parallel} \left(\frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} - \frac{n^{(1)}}{n_0} \right) + k_{\parallel} \frac{\tilde{r}_{\parallel\parallel}^{(1)}}{p_{\parallel}^{(0)}} = 0, \quad (3.343)$$

where the fluctuating parallel temperature $T_{\parallel}^{(1)}$ is linearized as

$$\frac{T_{\parallel}^{(1)}}{T_{\parallel}^{(0)}} = \frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} - \frac{n^{(1)}}{n_0}. \quad (3.344)$$

The superscript (1) on quantities $n^{(1)}$, $u_z^{(1)}$, $p_{\parallel}^{(1)}$, $q_{\parallel}^{(1)}$ (and $T_{\parallel}^{(1)}$) signifies that these are just fluctuating quantities, the superscript does not mean here that these quantities are obtained by integration over the kinetic $f^{(1)}$. This fluid model is accompanied by a closure for $\tilde{r}_{\parallel\parallel}^{(1)}$, and that one was obtained from linear kinetic theory by integrating over the kinetic $f^{(1)}$. Let us choose the $R_{4,3}(\zeta)$ closure, equation (3.234)

$$\frac{\tilde{r}_{\parallel\parallel}^{(1)}}{p_{\parallel}^{(0)}} = \frac{32 - 9\pi}{2(3\pi - 8)} v_{\text{th}\parallel}^2 \left(\frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} - \frac{n^{(1)}}{n_0} \right) - \frac{2\sqrt{\pi}}{3\pi - 8} v_{\text{th}\parallel} i \text{sign}(k_{\parallel}) \frac{q_{\parallel}^{(1)}}{p_{\parallel}^{(0)}}. \quad (3.345)$$

Now the model is closed, and calculating the determinant yields the following dispersion relation

$$\begin{aligned} \omega^4 + \frac{2i\sqrt{\pi}}{3\pi - 8} k_{\parallel} v_{\text{th}\parallel} \text{sign}(k_{\parallel}) \omega^3 - \frac{(9\pi - 16)}{2(3\pi - 8)} k_{\parallel}^2 v_{\text{th}\parallel}^2 \omega^2 \\ - \frac{3i\sqrt{\pi}}{3\pi - 8} k_{\parallel}^3 v_{\text{th}\parallel}^3 \text{sign}(k_{\parallel}) \omega + \frac{2}{3\pi - 8} k_{\parallel}^4 v_{\text{th}\parallel}^4 = 0. \end{aligned} \quad (3.346)$$

By examining the expression, an obvious substitution offers itself

$$\zeta = \frac{\omega}{\text{sign}(k_{\parallel}) k_{\parallel} v_{\text{th}\parallel}} = \frac{\omega}{|k_{\parallel}| v_{\text{th}\parallel}}, \quad (3.347)$$

that transforms the polynomial to a completely dimensionless form

$$\zeta^4 + \frac{2i\sqrt{\pi}}{3\pi - 8} \zeta^3 - \frac{9\pi - 16}{2(3\pi - 8)} \zeta^2 - \frac{3i\sqrt{\pi}}{3\pi - 8} \zeta + \frac{2}{3\pi - 8} = 0. \quad (3.348)$$

The ζ is obviously a very useful quantity, and one could rewrite the fluid equations (3.340)–(3.343) directly with this quantity. The polynomial (3.348) can be solved numerically, and the approximate solutions are (writing only 3 decimal digits)

$$\zeta = \pm 1.359 - 0.534i; \quad \zeta = \pm 0.392 - 0.710i, \quad (3.349)$$

yielding solutions in physical units

$$\omega = |k_{\parallel}| v_{\text{th}\parallel} (\pm 1.359 - 0.534i); \quad \omega = |k_{\parallel}| v_{\text{th}\parallel} (\pm 0.392 - 0.710i). \quad (3.350)$$

The first solution is the ion-acoustic (sound) mode and the second solution is ‘a higher-order mode’. Both solutions are highly damped, and the higher-order mode has actually a higher damping rate than its real frequency. We can now also see how important was to keep track of the $\text{sign}(k_{\parallel})$, since the modes are damped for both $k_{\parallel} > 0$ and $k_{\parallel} < 0$. If we had ignored the $\text{sign}(k_{\parallel})$, we would obtain that, for $k_{\parallel} < 0$, the sound mode has a positive growth rate and is unstable, which would be unphysical.

Of course, each closure will yield a different dispersion relation. Exploring the simplest closure with quasi-static heat flux $q_{\parallel}^{(1)}$ obtained with $R_{3,2}(\zeta)$, equations (3.340)–(3.342) are closed by

$$\frac{q_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} = -\frac{2}{\sqrt{\pi}} v_{\text{th}\parallel} i \text{sign}(k_{\parallel}) \left(\frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} - \frac{n^{(1)}}{n_0} \right), \tag{3.351}$$

which yields a polynomial

$$\zeta^3 + \frac{2i}{\sqrt{\pi}} \zeta^2 - \frac{3}{2} \zeta - \frac{i}{\sqrt{\pi}} = 0. \tag{3.352}$$

Numerical solutions are $\zeta = \pm 1.041 - 0.327i$; $\zeta = -0.474i$, showing that, in this case, the higher-order mode does not propagate and is purely damped. The ion-acoustic mode is also very damped and has a dispersion relation

$$\omega = |k_{\parallel}| v_{\text{th}\parallel} (\pm 1.041 - 0.327i). \tag{3.353}$$

We examine two more closures. The most precise quasi-static closure (3.227) obtained with $R_{4,2}(\zeta)$ yields the analytic dispersion relation

$$\zeta^4 + i\sqrt{\pi} \frac{10 - 3\pi}{16 - 5\pi} \zeta^3 - \frac{32 - 9\pi}{32 - 10\pi} \zeta^2 - \frac{i\sqrt{\pi}}{16 - 5\pi} \zeta + \frac{3\pi - 8}{32 - 10\pi} = 0, \tag{3.354}$$

and the solutions are

$$\omega = |k_{\parallel}| v_{\text{th}\parallel} (\pm 1.294 - 0.790i); \quad \omega = |k_{\parallel}| v_{\text{th}\parallel} (\pm 0.385 - 0.956i), \tag{3.355}$$

the first one being the ion-acoustic mode. Finally, the only available $o(\zeta^4)$ closure (3.339) obtained with $R_{5,3}(\zeta)$ yields the analytic dispersion relation

$$\zeta^5 + i\tilde{\alpha}_r \zeta^4 + (\tilde{\alpha}_q - 3)\zeta^3 - i(3\tilde{\alpha}_r - \tilde{\alpha}_T)\zeta^2 + \frac{1}{2} \left(\tilde{\alpha}_u - 3\tilde{\alpha}_q + \frac{3}{2} \right) \zeta + \frac{i}{4} (3\tilde{\alpha}_r - 2\tilde{\alpha}_T) = 0, \tag{3.356}$$

where the coefficients are specified in (3.335), and the numerical solutions are

$$\omega = |k_{\parallel}| v_{\text{th}\parallel} (\pm 1.589 - 0.908i); \quad \omega = |k_{\parallel}| v_{\text{th}\parallel} (\pm 0.710 - 1.084i); \quad \omega = |k_{\parallel}| v_{\text{th}\parallel} (-1.147i), \tag{3.357}$$

the first being the ion-acoustic mode.

Let us compare the obtained results. Perhaps curiously, it appears that, as the precision of closures increases, so does the real frequency and the damping rate of the ion-acoustic mode, and the differences are quite significant. So what is the correct kinetic result, i.e. how close did we get to the kinetic theory? That is not as easy a question as it appears to be. By opening kinetic books, there is no such discussion

on the long-wavelength limit of the ion-acoustic mode, when the electrons are cold. Even the exact numerical solutions are usually considered only for $T_e/T_p \geq 1$, see for example figure 9.18 on page 355 in Gurnett and Bhattacharjee.

Let us examine the analytic dispersion relations (3.348), (3.352), (3.354) and (3.356), that were obtained with approximants $R_{4,3}(\zeta)$, $R_{3,2}(\zeta)$, $R_{4,2}(\zeta)$ and $R_{5,3}(\zeta)$. One notices that the dispersion relations exactly match the denominators of the associated Padé approximants! Or in another words, without doing any calculations whatsoever, it appears that if a closure of a 1-D fluid model is available for a $R_{n,n'}(\zeta)$ approximant, the dispersion relation is equivalent to the denominator of that $R_{n,n'}(\zeta)$. How is this possible? The explanation is simple if one considers the electrostatic kinetic dispersion relation for the proton and electron species (3.30), which at scales that are much longer than the Debye length simplifies to (3.366). Prescribing massless electrons yields $R(\zeta_e) = 1$, implying dispersion relation $R(\zeta_p) = -T_p^{(0)}/T_e^{(0)}$. For cold electrons, both real and imaginary parts of $R(\zeta_p)$ obviously diverge, so that

$$\frac{1}{R(\zeta_p)} = 0.$$

The above expression can be considered the electrostatic dispersion relation of a proton–electron plasma, where the electrons are massless and completely cold. The reason why such an expression cannot be found in any plasma book is that, from the kinetic perspective, such an expression cannot be solved and is ill defined. The function $R(\zeta)$ is directly related to the derivative of $Z(\zeta)$ according to $Z'(\zeta) = -2R(\zeta)$. Infinitely large $R(\zeta)$ means that $Z(\zeta)$ has infinitely large derivatives, i.e. that $Z(\zeta)$ is not continuous and not analytic, which contradicts the entire definition of $Z(\zeta)$ and how the function was constructed. However, when Padé approximants of these functions are considered, and when $R(\zeta)$ is replaced by $R_{n,n'}(\zeta)$, so that

$$\frac{1}{R_{n,n'}(\zeta_p)} = 0, \quad (3.358)$$

such an expression does make sense, and is equivalent to the denominator of $R_{n,n'}(\zeta)$ being zero, i.e. it directly yields the dispersion relations of the considered fluid models. We note that while the plasma dispersion function corresponding to a Maxwellian distribution function does not display singularities at finite distance in the complex plane, this is not the case when considering kappa distribution functions, see e.g. Podesta (2004).

3.12.1. The proton Landau damping does not disappear at long wavelengths

There are several extremely interesting phenomena worth discussing. (i) In the dispersion relation for the ion-acoustic (sound) mode (3.350), the usual phase speed ω/k_{\parallel} is constant, implying that the Landau damping (of the parallel propagating sound mode) does not disappear, however long wavelengths are considered. With cold electrons, as considered here, the parallel sound mode is always heavily damped, and disappears in a few wavelengths, even on large astrophysical scales. A very good discussion can be found for example in Howes (2009), who concluded that, in general (unless electrons are hot), the MHD sound mode represents an unphysical spurious wave that does not exist in collisionless plasma. (ii) The equations (3.340)–(3.343) do not even contain the parallel electric field E_{\parallel} . This might sound surprising, but the parallel electric field completely disappears at long wavelengths, even though the

Landau damping (as expressed through the constant phase speed), does not disappear. The parallel electric field does not disappear, if electrons have finite temperature, it also enters (very weakly), if the electron inertia is included. In the 1-D linearized geometry considered here, the contributions will be

$$E_{\parallel} = -\frac{1}{en_0} \partial_z p_{\parallel e} - \frac{m_e}{e} \frac{\partial u_{ze}}{\partial t}. \tag{3.359}$$

(iii) The presence of Landau damping in the long-wavelength limit is exactly the reason why usual fluid models such as MHD, or even the much more sophisticated CGL description, do not converge to the collisionless kinetic theory, whatever long wavelengths and low frequencies are considered. There is always a mismatch in dispersion relations when the phase speed is plotted that, depending on plasma parameters, can be quite large. This does not concern only the damping rate (which in MHD and CGL is of course zero), the differences in the real frequency, which is always coupled to the imaginary frequency (for example through the polynomial (3.348) for that specific closure), can be large too. (iv) If the heat flux $q_{\parallel}^{(1)}$ is prescribed to be zero, i.e. if a CGL model is prescribed, the dispersion relation of the parallel propagating sound mode is determined only by the parallel velocity equation (3.341) and parallel pressure equation (3.342), yielding the CGL result $\omega^2 = \frac{3}{2} v_{th\parallel}^2 k_{\parallel}^2$, so that

$$\omega^{CGL} = \pm |k_{\parallel}| v_{th\parallel} \sqrt{\frac{3}{2}} = \pm |k_{\parallel}| v_{th\parallel} 1.225. \tag{3.360}$$

For comparison, the MHD result can be written with the usual MHD sound speed $C_s^2 = \gamma(p_0/\rho_0) = (\gamma/2)v_{th}^2$ where $\gamma = 5/3$, so

$$\omega^{MHD} = \pm |k_{\parallel}| v_{th} \sqrt{\frac{5}{6}} = \pm |k_{\parallel}| v_{th} 0.913. \tag{3.361}$$

It is important to examine the influence of isothermal electron species.

3.13. Proton Landau damping, influence of isothermal electrons

Let us prescribe electrons to be isothermal, with some finite electron temperature, but let us neglect the electron inertia. The proton momentum equation is changed to (3.372), the electron pressure equation reads

$$-\omega \frac{p_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} + k_{\parallel} \tau u_z^{(1)} = 0; \quad \tau \equiv \frac{T_{\parallel e}^{(0)}}{T_{\parallel p}^{(0)}}, \tag{3.362}$$

where for brevity, we define the ratio of electron and proton temperature as τ . Using the $R_{4,3}(\zeta)$ closure as before, the coupled dispersion relation reads

$$\zeta^4 + \frac{2i\sqrt{\pi}}{3\pi - 8} \zeta^3 - \frac{9\pi - 16 + (3\pi - 8)\tau}{2(3\pi - 8)} \zeta^2 - \frac{i\sqrt{\pi}(3 + \tau)}{3\pi - 8} \zeta + \frac{2(1 + \tau)}{3\pi - 8} = 0. \tag{3.363}$$

The above expression is equivalent to (A6) in Hunana *et al.* (2011).⁹ The $R_{4,2}(\zeta)$ closure yields dispersion relation

⁹Dispersion relations in the Appendix of that paper assumed $k > 0$. We later noticed that (3.363), (3.364) are equivalent to the dispersion relation $\tau R_{n,n'}(\zeta_p) + 1 = 0$. We also noticed that for isothermal electrons the $R_{4,2}(\zeta)$ closure with (3.364), can produce positive growth rate for high electron temperatures. The $R_{4,2}(\zeta)$ behaves correctly when the electron Landau damping is introduced, see the next § 3.14.

$$\zeta^4 + \frac{i\sqrt{\pi}(10 - 3\pi)}{16 - 5\pi}\zeta^3 - \frac{32 - 9\pi + (16 - 5\pi)\tau}{32 - 10\pi}\zeta^2 - \frac{i\sqrt{\pi}(2 + (10 - 3\pi)\tau)}{32 - 10\pi}\zeta + \frac{(3\pi - 8)(1 + \tau)}{32 - 10\pi} = 0. \quad (3.364)$$

Let us use (3.363) and focus on the ion-acoustic mode, since the higher-order mode is always highly damped. Solutions for a few different τ values are

$$\begin{aligned} \tau = 0: & \quad \zeta = \pm 1.359 - 0.534i; \\ \tau = 0.1: & \quad \zeta = \pm 1.367 - 0.514i; \\ \tau = 0.5: & \quad \zeta = \pm 1.409 - 0.439i; \\ \tau = 1.0: & \quad \zeta = \pm 1.481 - 0.361i; \\ \tau = 2.0: & \quad \zeta = \pm 1.640 - 0.260i; \\ \tau = 5.0: & \quad \zeta = \pm 2.054 - 0.131i; \\ \tau = 10.0: & \quad \zeta = \pm 2.591 - 0.061i; \\ \tau = 100.0: & \quad \zeta = \pm 7.180 - 0.001i. \end{aligned} \quad (3.365)$$

This is excellent, as in kinetic books, with increasing electron temperature, the Landau damping of the ion-acoustic mode decreases. Compared to kinetic calculations (see the last column in (3.381)), the total Landau damping is here of course underestimated, especially for high electron temperatures, since here in the fluid model, only the proton Landau damping is contributing, and the electron Landau damping is turned off. Let us turn it on.

3.14. Proton and electron Landau damping

Considering wavelengths much longer than the Debye length, the exact kinetic dispersion relation reads

$$\frac{T_{\parallel e}^{(0)}}{T_{\parallel p}^{(0)}} R(\zeta_p) + R(\zeta_e) = 0, \quad (3.366)$$

where the electron thermal velocity

$$v_{\text{th}||e} = v_{\text{th}||p} \sqrt{\frac{m_p}{m_e}} \sqrt{\frac{T_{\parallel e}^{(0)}}{T_{\parallel p}^{(0)}}}, \quad (3.367)$$

is of course much higher than the proton thermal velocity (unless the electrons are cold), and by using the abbreviated

$$\tau \equiv \frac{T_{\parallel e}^{(0)}}{T_{\parallel p}^{(0)}}; \quad \mu \equiv \frac{m_e}{m_p}, \quad (3.368)$$

so that

$$\zeta_p = \frac{\omega}{|k_{\parallel}| v_{\text{th}||p}}; \quad \zeta_e = \frac{\omega}{|k_{\parallel}| v_{\text{th}||e}} = \zeta_p \sqrt{\frac{\mu}{\tau}}, \quad (3.369)$$

and the exact kinetic dispersion relation reads

$$\tau R(\zeta_p) + R\left(\zeta_p \sqrt{\mu/\tau}\right) = 0. \quad (3.370)$$

Let us see how close we got. One of the greatest advantages of Landau fluid models is that we do not have to resolve electron motion to obtain the correct form of electron Landau damping at long wavelengths, and the electron inertia in the electron momentum equation can be neglected. The correct electron–proton mass ratio can enter equations for the electron heat flux $q_{\parallel e}$ and the fourth-order moment $\tilde{r}_{\parallel\parallel e}$, and the electron inertia influences the solutions only insignificantly. However, let us keep the electron inertia for a moment. The equations for the proton species read

$$-\omega \frac{n^{(1)}}{n_0} + k_{\parallel} u_z^{(1)} = 0; \tag{3.371}$$

$$-\omega u_z^{(1)} + \frac{v_{\text{th}\parallel p}^2}{2} k_{\parallel} \left(\frac{P_{\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} + \frac{P_{\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} \right) - \omega \frac{m_e}{m_p} u_z^{(1)} = 0; \tag{3.372}$$

$$-\omega \frac{P_{\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} + 3k_{\parallel} u_z^{(1)} + k_{\parallel} \frac{q_{\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} = 0; \tag{3.373}$$

$$-\omega \frac{q_{\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} + \frac{3}{2} v_{\text{th}\parallel p}^2 k_{\parallel} \left(\frac{P_{\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} - \frac{n^{(1)}}{n_0} \right) + k_{\parallel} \frac{\tilde{r}_{\parallel\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} = 0, \tag{3.374}$$

and the electron inertia represents the last term in (3.372). The electron equations are written in a form so that they are normalized with respect to the proton pressure

$$-\omega \frac{P_{\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} + 3k_{\parallel} \tau u_z^{(1)} + k_{\parallel} \frac{q_{\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} = 0; \tag{3.375}$$

$$-\omega \frac{q_{\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} + \frac{3}{2} v_{\text{th}\parallel p}^2 \frac{m_p}{m_e} k_{\parallel} \tau \left(\frac{P_{\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} - \tau \frac{n^{(1)}}{n_0} \right) + k_{\parallel} \frac{\tilde{r}_{\parallel\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} = 0. \tag{3.376}$$

Note that the electron fluid speed $u_{ze}^{(1)} = u_{zp}^{(1)}$ (so we omitted the index p). The fluid equations are accompanied by a closure from kinetic theory, for example the $R_{4,3}(\zeta)$ closure

$$\frac{\tilde{r}_{\parallel\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} = \frac{32 - 9\pi}{2(3\pi - 8)} v_{\text{th}\parallel p}^2 \left(\frac{P_{\parallel p}^{(1)}}{P_{\parallel p}^{(0)}} - \frac{n^{(1)}}{n_0} \right) - \frac{2\sqrt{\pi}}{3\pi - 8} v_{\text{th}\parallel p} \text{isign}(k_{\parallel}) \frac{q_{\parallel p}^{(1)}}{P_{\parallel p}^{(0)}}, \tag{3.377}$$

$$\frac{\tilde{r}_{\parallel\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} = \frac{32 - 9\pi}{2(3\pi - 8)} v_{\text{th}\parallel p}^2 \frac{m_p}{m_e} \tau \left(\frac{P_{\parallel e}^{(1)}}{P_{\parallel p}^{(0)}} - \tau \frac{n^{(1)}}{n_0} \right) - \frac{2\sqrt{\pi}}{3\pi - 8} v_{\text{th}\parallel p} \sqrt{\frac{m_p}{m_e}} \sqrt{\tau} \text{isign}(k_{\parallel}) \frac{q_{\parallel e}^{(1)}}{P_{\parallel p}^{(0)}}. \tag{3.378}$$

The equations (3.371)–(3.378) now represents a fluid description of the ion-acoustic mode, and contain both proton and electron Landau damping. It is rather mesmerizing that the relatively complicated dispersion relation of this fluid model can be shown to be equivalent to the ‘simple looking’ kinetic dispersion relation

$$\tau R_{4,3}(\zeta_p) + R_{4,3} \left(\zeta_p \sqrt{\mu/\tau} \right) = 0, \tag{3.379}$$

i.e. equivalent to the full kinetic dispersion relation (3.370), where the exact $R(\zeta)$ is replaced with the $R_{4,3}(\zeta)$ approximant (by transferring the proton and electron terms of

$R_{4,3}(\zeta)$ in the expression (3.379) to the common denominator and making the resulting numerator of that expression equal to zero, Maple is great in this regard).

Nevertheless, here, we want clearly demonstrate that the electron inertia can be neglected and the electron Landau damping still nicely captured, and we use fluid dispersion relations obtained from the system (3.371)–(3.378), where the last term in (3.372) is neglected. It is important to normalize properly and, for example, the $R_{4,2}(\zeta)$ closure for electrons reads

$$\begin{aligned} \frac{\tilde{r}_{\parallel e}^{(1)}}{p_{\parallel p}^{(0)}} &= -i\sqrt{\pi} \frac{(10 - 3\pi)}{(16 - 5\pi)} v_{\text{th}\parallel p} \sqrt{\frac{m_p}{m_e}} \sqrt{\tau} \text{sign}(k_{\parallel}) \frac{q_{\parallel e}^{(1)}}{p_{\parallel p}^{(0)}} \\ &+ \frac{(21\pi - 64)}{2(16 - 5\pi)} v_{\text{th}\parallel p}^2 \frac{m_p}{m_e} \tau \left(\frac{p_{\parallel e}^{(1)}}{p_{\parallel p}^{(0)}} - \tau \frac{n^{(1)}}{n_0} \right) \\ &+ i\sqrt{\pi} \frac{(9\pi - 28)}{(16 - 5\pi)} v_{\text{th}\parallel p} \sqrt{\frac{m_p}{m_e}} \tau^{3/2} \text{sign}(k_{\parallel}) u_z^{(1)}. \end{aligned} \quad (3.380)$$

In the table below, we compare these fluid solutions of the quasi-static $R_{4,3}(\zeta)$ and the $R_{4,2}(\zeta)$ closures, and the time-dependent $R_{5,3}(\zeta)$ closure to the exact kinetic solutions, calculated from (3.366), for various electron temperatures.

	$R_{4,3}(\zeta)$ closure	$R_{4,2}(\zeta)$ closure	$R_{5,3}(\zeta)$ closure	Exact
$\tau = 1.0$	$\zeta = 1.487 - 0.373i$	$1.434 - 0.506i$	$1.511 - 0.591i$	$1.457 - 0.627i$
$\tau = 2.0$	$\zeta = 1.645 - 0.276i$	$1.629 - 0.372i$	$1.691 - 0.393i$	$1.692 - 0.425i$
$\tau = 5.0$	$\zeta = 2.057 - 0.154i$	$2.080 - 0.212i$	$2.116 - 0.188i$	$2.136 - 0.189i$
$\tau = 10.0$	$\zeta = 2.593 - 0.094i$	$2.627 - 0.123i$	$2.635 - 0.089i$	$2.640 - 0.072i$
$\tau = 20.0$	$\zeta = 3.417 - 0.069i$	$3.446 - 0.075i$	$3.432 - 0.052i$	$3.421 - 0.046i$
$\tau = 50.0$	$\zeta = 5.157 - 0.078i$	$5.170 - 0.072i$	$5.156 - 0.070i$	$5.153 - 0.073i$
$\tau = 100.0$	$\zeta = 7.180 - 0.105i$	$7.186 - 0.099i$	$7.179 - 0.102i$	$7.177 - 0.103i$

(3.381)

Instead of a table, we can create a figure. The Landau damping of the ion-acoustic sound mode is nicely demonstrated, for example, in the plasma book of Gurnett and Bhattacharjee (figure 9.18, page 355), where on the x -axis is τ , and on the y -axis (logarithmic), is the ratio of the damping and real frequencies. The same parameters are plotted in figure 5(a), and in figure 5(b) we extend the plot to higher electron temperatures. The figure shows that both new closures are very precise in the very important regime, where the electron temperature τ ranges between $\tau = 1$ and $\tau = 5$. The $R_{5,3}(\zeta)$ closure is the most globally precise closure. If static closures are preferred, the comparison between $R_{4,2}(\zeta)$ and $R_{4,3}(\zeta)$ is more difficult to summarize; $R_{4,2}(\zeta)$ is definitely preferred in the regime $\tau \in [1, 5]$ and perhaps also for $\tau \in [25, 60]$, however, the Hammett and Perkins closure $R_{4,3}(\zeta)$ is the better fit in the regime $\tau \in [5, 25]$ and also for $\tau \in [60, 100]$. We checked that the inclusion of electron inertia is insignificant for all 3 fluid closures, and by eye inspection, it appears that the largest global difference is seen for the $R_{5,3}(\zeta)$ closure, roughly for $\tau \in [30, 60]$, making the closure (very slightly) more precise. In figure 6, we calculate the other selected obtained closures. We use the full dispersion relations with electron inertia included. The figure shows that, if static closures are preferred, for a value of roughly $\tau > 15$, the best closure is actually the static closure $R_{4,4}(\zeta)$. The most precise closure for $\tau > 15$ is by far the time-dependent $R_{5,6}(\zeta)$ closure, which achieves an excellent accuracy for high values of τ . If a global accuracy for all values of τ is required, our favourite closures are $R_{5,3}(\zeta)$ and $R_{5,4}(\zeta)$.

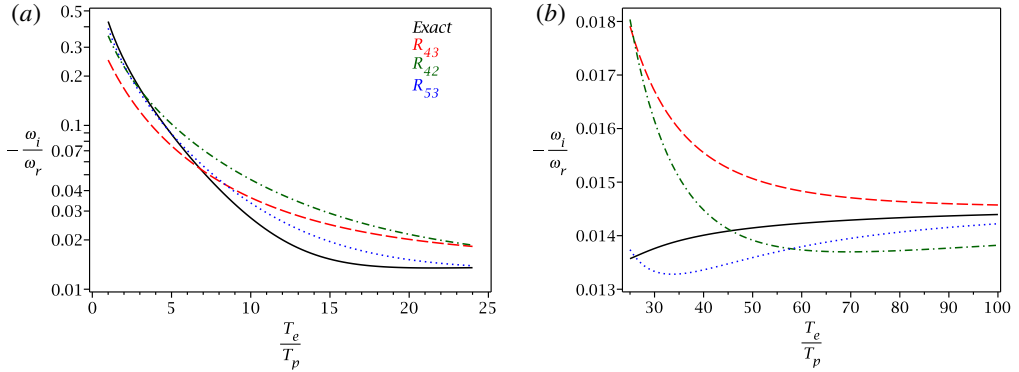


FIGURE 5. Landau damping of the ion-acoustic (sound) mode. The black solid curve is the solution of exact kinetic dispersion relation (3.366). The other curves are dispersion relations of a fluid model (3.371)–(3.376) where the electron inertia is neglected, supplemented by a closure for $r_{\parallel p}^{(1)}$. The red dashed line is the $R_{4,3}(\zeta)$ closure of Hammett & Perkins (1990), the green dash-dotted line is our new static closure $R_{4,2}(\zeta)$ and the blue dotted line is the new time-dependent closure $R_{5,3}(\zeta)$.

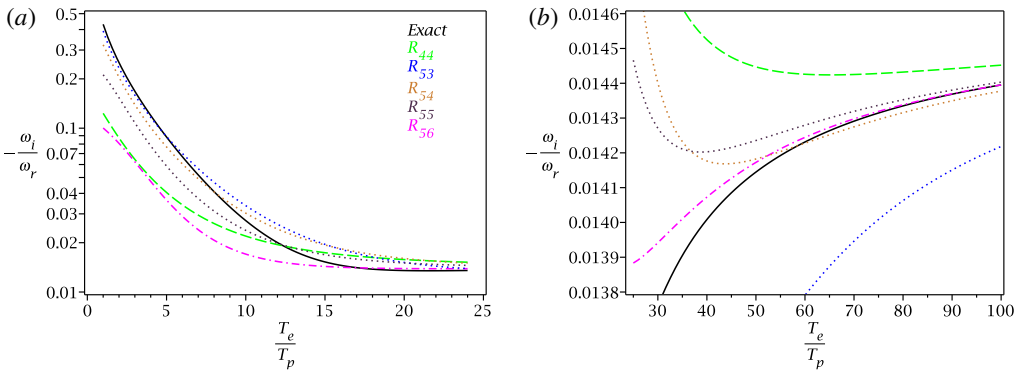


FIGURE 6. Similar to figure 5, but different closures are compared, and electron inertia is retained. The $R_{5,3}(\zeta)$ closure (blue dotted curve) is kept in the figure so that the comparison to other closures can be done easily. Also, by comparing the $R_{5,3}(\zeta)$ solution with figure 5, it is shown that the effect of electron inertia is negligible. The $R_{4,4}(\zeta)$ is only static closure, and all other closures are time dependent.

With the help of Maple software, we analytically investigated dispersion relations of all the obtained fluid closures, and we investigated if the resulting dispersion relation (including the electron inertia) is equivalent to the kinetic result (3.366), after replacing the $R(\zeta)$ with $R_{n,n'}(\zeta)$, i.e. if the fluid dispersion relation is equivalent to the numerator of

$$\frac{T_{\parallel e}^{(0)}}{T_{\parallel p}^{(0)}} R_{n,n'}(\zeta_p) + R_{n,n'}(\zeta_e) = 0. \tag{3.382}$$

All the closures considered in this subsection satisfied this requirement, however, some other previously obtained closures did not. We concluded that satisfying (3.382) should be indeed considered as a strong requirement for a physically meaningful

closure, and closures that did not satisfy this requirement were therefore eliminated. The results are summarized in the § 3.6 ‘Table of moments ($u_{\parallel}, T_{\parallel}, q_{\parallel}, \tilde{r}_{\parallel}$) for various Padé approximants’, equations (3.241), (3.242).

3.15. Electron Landau damping of the Langmuir mode

In addition to the ion-acoustic mode, let us calculate the Landau damping for the second (perhaps first) typical example, of how Landau damping is addressed in plasma physics books, the Langmuir mode. Focusing on the electron species and making the proton species cold and ‘very heavy’ with $m_p \rightarrow \infty$, i.e. immobile with $u_{zp}^{(1)} = 0$, the proton species completely decouples from the system, and their role is just to conserve the leading-order charge neutrality $n_{0p} = n_{0e} = n_0$. Since we have not dealt with such a system so far (not even in Part 1 of the text), let us write down the basic equation nicely in real space in physical units. Neglecting the electron heat flux, the basic system of linearized equations reads

$$\frac{\partial n_e^{(1)}}{\partial t} + n_0 \partial_z u_{ze}^{(1)} = 0; \quad (3.383)$$

$$\frac{\partial u_{ze}^{(1)}}{\partial t} + \frac{1}{m_e n_0} \partial_z p_{\parallel e}^{(1)} + \frac{e}{m_e} E_{\parallel} = 0; \quad (3.384)$$

$$\frac{\partial p_{\parallel e}^{(1)}}{\partial t} + 3p_{\parallel e}^{(0)} \partial_z u_{ze}^{(1)} = 0. \quad (3.385)$$

Using the general electrostatic Maxwell equation for the current (including the displacement current)

$$\mathbf{j} = \sum_r q_r n_r \mathbf{u}_r = \frac{c}{4\pi} \nabla \times \mathbf{B} - \frac{1}{4\pi} \frac{\partial \mathbf{E}}{\partial t}, \quad (3.386)$$

that in our specific 1-D linear case considered here reads

$$j_{\parallel} = -en_0 u_{ze}^{(1)} = -\frac{1}{4\pi} \frac{\partial E_{\parallel}}{\partial t}, \quad (3.387)$$

prescribes the electric field time evolution, and the system of equations is closed. By applying $\partial/\partial t$ to the momentum equation (3.384), the equations can be combined, yielding a wave equation

$$\left[\frac{\partial^2}{\partial t^2} - \frac{3p_{\parallel e}^{(0)}}{m_e n_0} \partial_z^2 + \omega_{pe}^2 \right] u_{ze}^{(1)} = 0, \quad (3.388)$$

where the electron plasma frequency $\omega_{pe}^2 = 4\pi e^2 n_0 / m_e$. This wave equation describes the basic plasma physics mode, known as the Langmuir mode, and the dispersion relation is

$$\omega^2 = \omega_{pe}^2 + \frac{3T_{\parallel e}^{(0)}}{m_e} k_{\parallel}^2. \quad (3.389)$$

If we ignored the displacement current $\partial E_{\parallel} / \partial t$, the ω_{pe}^2 term would be absent. By dividing with ω_{pe}^2 and by using the Debye length $\lambda_{De} = 1/k_{De}$ where $k_{De}^2 = 4\pi e^2 n_{0e} / T_{\parallel e}^{(0)}$, so that the Debye length $\lambda_{De}^2 = T_{\parallel e}^{(0)} / (m_e \omega_{pe}^2)$, the dispersion relation (3.389) reads

$$\frac{\omega^2}{\omega_{pe}^2} = 1 + 3\lambda_{De}^2 k_{\parallel}^2. \quad (3.390)$$

Obviously, the electron plasma frequency and the electron Debye length are the natural normalizing units of this system, and one should use normalized quantities ω/ω_{pe} and $k_{\parallel}\lambda_{De}$. A useful relation also is $\lambda_{De}^2 = v_{th\parallel e}^2/(2\omega_{pe}^2)$.

Often, in plasma physics books, the CGL adiabatic index $\gamma_{\parallel} = 3$ in the above two equations, is substituted with a general adiabatic index γ_e , so that a more ‘general’ case can be considered. This is especially useful if the Langmuir waves, which are the basic waves of plasma physics, are introduced early on (in an early chapter of a book), where the correct CGL value of $\gamma_{\parallel} = 3$ is difficult to introduce. Again, we have an advantage of not being a plasma book, and we are not describing the general electrostatic case, we are describing the fully electromagnetic case, but we are focusing only on one mode – the electrostatic mode that propagates parallel to B_0 . In the view presented here, and as elaborated in Part 1 of the text, playing with adiabatic indices does not make much sense. No adiabatic index can match the CGL and the MHD, the CGL is always different from MHD, even for an isotropic distribution function with $T_{\parallel}^{(0)} = T_{\perp}^{(0)}$. Therefore, we are not introducing any adiabatic index, and the correct CGL value is used, and fixed to 3. Instead, we introduce the electron heat flux and get closer to the kinetic theory in a much more sophisticated way.

The basic linearized fluid equations in Fourier space read

$$\begin{aligned}
 -\omega \frac{n_e^{(1)}}{n_0} + k_{\parallel} u_{ze}^{(1)} &= 0; \\
 -\omega u_{ze}^{(1)} + \frac{1}{2} v_{th\parallel e}^2 k_{\parallel} \frac{p_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} + \frac{1}{2} \frac{v_{th\parallel e}^2}{\lambda_{De}^2} \frac{u_{ze}^{(1)}}{\omega} &= 0; \\
 -\omega \frac{p_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} + 3k_{\parallel} u_{ze}^{(1)} + k_{\parallel} \frac{q_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} &= 0;
 \end{aligned} \tag{3.391}$$

$$-\omega \frac{q_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} + \frac{3}{2} v_{th\parallel e}^2 k_{\parallel} \left(\frac{p_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} - \frac{n_e^{(1)}}{n_0} \right) + k_{\parallel} \frac{\tilde{r}_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} = 0, \tag{3.392}$$

and are accompanied for example by the $R_{4,3}(\zeta)$ closure

$$\frac{\tilde{r}_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} = \frac{32 - 9\pi}{2(3\pi - 8)} v_{th\parallel e}^2 \left(\frac{p_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}} - \frac{n_e^{(1)}}{n_0} \right) - \frac{2\sqrt{\pi}}{3\pi - 8} v_{th\parallel e} i \text{sign}(k_{\parallel}) \frac{q_{\parallel e}^{(1)}}{p_{\parallel e}^{(0)}}. \tag{3.393}$$

The dispersion relation of this fluid model reads (suppressing e in the electron Debye length λ_{De})

$$\zeta_e^4 + \frac{2i\sqrt{\pi}}{3\pi - 8} \zeta_e^3 - \frac{3\pi - 8 + (9\pi - 16)k_{\parallel}^2 \lambda_D^2}{2(3\pi - 8)k_{\parallel}^2 \lambda_D^2} \zeta_e^2 - \frac{i\sqrt{\pi}(1 + 3k_{\parallel}^2 \lambda_D^2)}{(3\pi - 8)k_{\parallel}^2 \lambda_D^2} \zeta_e + \frac{2(1 + k_{\parallel}^2 \lambda_D^2)}{(3\pi - 8)k_{\parallel}^2 \lambda_D^2} = 0, \tag{3.394}$$

where

$$\zeta_e = \frac{\omega}{|k_{\parallel}| v_{th\parallel e}} = \frac{\omega}{\omega_{pe}} \frac{1}{\sqrt{2}|k_{\parallel}| \lambda_D}. \tag{3.395}$$

The exact kinetic dispersion relation reads

$$\boxed{1 + \frac{1}{k_{\parallel}^2 \lambda_D^2} R(\zeta_e) = 0.} \tag{3.396}$$

As can be verified, the fluid dispersion relation (3.394) is equivalent to the kinetic one, if $R(\zeta_e)$ is replaced by $R_{4,3}(\zeta_e)$.

Using the static $R_{4,2}(\zeta)$ closure, the dispersion relation reads

$$\zeta_e^4 + i\sqrt{\pi} \frac{10 - 3\pi}{16 - 5\pi} \zeta_e^3 - \frac{16 - 5\pi + (32 - 9\pi)k_{\parallel}^2 \lambda_D^2}{2(16 - 5\pi)k_{\parallel}^2 \lambda_D^2} \zeta_e^2 - i\sqrt{\pi} \frac{10 - 3\pi + 2k_{\parallel}^2 \lambda_D^2}{2(16 - 5\pi)k_{\parallel}^2 \lambda_D^2} \zeta_e + \frac{(3\pi - 8)(1 + k_{\parallel}^2 \lambda_D^2)}{2(16 - 5\pi)k_{\parallel}^2 \lambda_D^2} = 0, \quad (3.397)$$

using the static $R_{4,4}(\zeta)$ closure yields

$$\zeta_e^4 + i\sqrt{\pi} \frac{3}{4} \zeta_e^3 - \frac{1 + 6k_{\parallel}^2 \lambda_D^2}{2k_{\parallel}^2 \lambda_D^2} \zeta_e^2 - i\sqrt{\pi} \frac{3(1 + 3k_{\parallel}^2 \lambda_D^2)}{8k_{\parallel}^2 \lambda_D^2} \zeta_e + \frac{3(1 + k_{\parallel}^2 \lambda_D^2)}{4k_{\parallel}^2 \lambda_D^2} = 0, \quad (3.398)$$

and the simplest static $R_{3,2}(\zeta)$ closure yields

$$\zeta_e^3 + \frac{2i}{\sqrt{\pi}} \zeta_e^2 - \frac{1 + 3k_{\parallel}^2 \lambda_D^2}{2k_{\parallel}^2 \lambda_D^2} \zeta_e - \frac{i(1 + k_{\parallel}^2 \lambda_D^2)}{\sqrt{\pi} k_{\parallel}^2 \lambda_D^2} = 0. \quad (3.399)$$

All dispersion relations are fully consistent with the kinetic dispersion relation (3.396) when $R(\zeta_e)$ is replaced by the corresponding $R_{4,2}(\zeta_e)$, $R_{4,4}(\zeta_e)$ and $R_{3,2}(\zeta_e)$ (equivalent to the numerator of the resulting expression). We verified that this is also true for the static closure $R_{3,1}(\zeta_e)$ and actually all the ‘reliable’ closures marked in (3.241), (3.242) with ‘✓’, including the time-dependent closures $R_{3,2}(\zeta_e)$, $R_{4,2}(\zeta_e)$, $R_{4,3}(\zeta_e)$, $R_{4,4}(\zeta_e)$, $R_{5,3}(\zeta_e)$, $R_{5,4}(\zeta_e)$, $R_{5,5}(\zeta_e)$, $R_{5,6}(\zeta_e)$. To clearly understand the obtained solutions, let us solve the simple $R_{3,2}(\zeta_e)$ dispersion relation (3.399) for a few values of $k_{\parallel} \lambda_D$,

$$\begin{aligned} k_{\parallel} \lambda_D = 0.001: & \quad \zeta_e = \pm 707.1 - 1.13i \times 10^{-6}; & \quad \zeta_e = -1.13i; \\ k_{\parallel} \lambda_D = 0.01: & \quad \zeta_e = \pm 70.7 - 1.13i \times 10^{-4}; & \quad \zeta_e = -1.13i; \\ k_{\parallel} \lambda_D = 0.1: & \quad \zeta_e = \pm 7.17 - 1.07i \times 10^{-2}; & \quad \zeta_e = -1.11i; \\ k_{\parallel} \lambda_D = 0.2: & \quad \zeta_e = \pm 3.73 - 3.73i \times 10^{-2}; & \quad \zeta_e = -1.05i; \\ k_{\parallel} \lambda_D = 0.3: & \quad \zeta_e = \pm 2.63 - 0.07i; & \quad \zeta_e = -0.99i; \\ k_{\parallel} \lambda_D = 1.0: & \quad \zeta_e = \pm 1.28 - 0.23i; & \quad \zeta_e = -0.67i. \end{aligned}$$

The first mode is the Langmuir mode, and the second mode is a purely damped higher-order mode. In the complete limit $k_{\parallel} \lambda_D \rightarrow 0$, the Langmuir mode becomes undamped with a solution $\zeta_e = 1/(\sqrt{2}|k_{\parallel} \lambda_D|)$, which corresponds to oscillations with electron plasma frequency $\omega = \omega_{pe}$; and the higher-order mode has a solution $\zeta_e = -2i/\sqrt{\pi}$. Considering the weak damping limit $\zeta_e = x + iy$, where $x \gg y$, at the leading order $\zeta_e^2 = x^2 + i2xy$ and $\zeta_e^3 = x^3 + i3x^2y$, which when used in the dispersion relation (3.399) that is separated into real and imaginary parts yields

$$\begin{aligned} x^3 - \frac{4}{\sqrt{\pi}} xy - \frac{1 + 3k_{\parallel}^2 \lambda_D^2}{2k_{\parallel}^2 \lambda_D^2} x &= 0; \\ 3x^2 y + \frac{2}{\sqrt{\pi}} x^2 - \frac{1 + 3k_{\parallel}^2 \lambda_D^2}{2k_{\parallel}^2 \lambda_D^2} y - \frac{1}{\sqrt{\pi}} \frac{1 + k_{\parallel}^2 \lambda_D^2}{k_{\parallel}^2 \lambda_D^2} &= 0, \end{aligned}$$

and for $x \gg y$ at the leading order

$$x^2 = \frac{1 + 3k_{\parallel}^2 \lambda_D^2}{2k_{\parallel}^2 \lambda_D^2}; \quad y = -\frac{1}{\sqrt{\pi} x^2} = -\frac{2}{\sqrt{\pi}} \frac{k_{\parallel}^2 \lambda_D^2}{(1 + 3k_{\parallel}^2 \lambda_D^2)}, \quad (3.400)$$

which approximates the above numerical solutions reasonably well up to let us say $k_{\parallel}\lambda_D = 0.3$, and from (3.395) the x, y expressions are equivalent to

$$\omega_r^2 = \omega_{pe}^2(1 + 3k_{\parallel}^2\lambda_D^2); \quad \omega_i = -\sqrt{\frac{8}{\pi}} \frac{|k_{\parallel}|^3\lambda_D^3}{1 + 3k_{\parallel}^2\lambda_D^2} \omega_{pe}. \quad (3.401)$$

For $k_{\parallel}\lambda_D \ll 1$, the Landau damping of the Langmuir mode goes to zero, however, the damping rate is very overestimated. The approximate kinetic result found in plasma books (see for example Gurnett & Bhattacharjee (2005), page 349) has of course the same real frequency, however, the damping rate reads

$$\omega_r^2 = \omega_{pe}^2(1 + 3k_{\parallel}^2\lambda_D^2); \quad \omega_i = -\sqrt{\frac{\pi}{8}} \frac{\omega_{pe}}{|k_{\parallel}|^3\lambda_D^3} e^{-1+3k_{\parallel}^2\lambda_D^2/2k_{\parallel}^2\lambda_D^2}. \quad (3.402)$$

Since $k_{\parallel}\lambda_D \ll 1$, Landau (1946) writes (see his equations (16) and (17))

$$\omega_r = \omega_{pe} \left(1 + \frac{3}{2}k_{\parallel}^2\lambda_D^2 \right); \quad \omega_i = -\sqrt{\frac{\pi}{8}} \frac{\omega_{pe}}{|k_{\parallel}|^3\lambda_D^3} e^{-1/2k_{\parallel}^2\lambda_D^2}. \quad (3.403)$$

For $k_{\parallel}\lambda_D \ll 1$, i.e. approaching long wavelengths, the exponential term suppresses the Landau damping much quicker than our result (3.401). To understand the discrepancy, let us quickly consider how the kinetic result (3.402) was obtained. The result is obtained by considering asymptotic expansion $|\zeta_e| \gg 1$ of the exact kinetic dispersion relation (3.396), which in the weak growth-rate approximation (see (3.67) with $\sigma = 1$) reads

$$1 + \frac{1}{k_{\parallel}^2\lambda_D^2} \left[-\frac{1}{2\zeta_e^2} - \frac{3}{4\zeta_e^4} + i\sqrt{\pi}\zeta_e e^{-\zeta_e^2} \right] = 0. \quad (3.404)$$

Using $\zeta_e = x + iy$ with $x \gg y$ and $k_{\parallel}\lambda_D \ll 1$ yields at the leading order $x^2 = (1 + 3k_{\parallel}^2\lambda_D^2)/2k_{\parallel}^2\lambda_D^2$ which agrees with (3.400) and the damping rate is $y = -\sqrt{\pi}x^4 e^{-x^2}$, which recovers (3.402). The e^{-x^2} term in the damping rate comes from the last term in (3.404), and as discussed previously, this term is neglected in the asymptotic expansion when constructing the Padé approximants of $R(\zeta)$ (it is however included in the power-series expansion), explaining the discrepancy.

The damping rate of the Langmuir mode is plotted in figure 7 and the real frequency in figure 8, where solutions of various fluid models are compared with exact kinetic dispersion relation (3.396), depicted as the black solid line. Additionally, the asymptotic kinetic solution (3.402) from plasma physics books is plotted as the black dotted line. Figure 7 is plotted in log-log scale and figure 8 uses linear scales. It is shown that for $k_{\parallel}\lambda_D > 0.2$, fluid models can reproduce the damping of the Langmuir mode quite accurately, and the most accurate closure is $R_{5,3}(\zeta)$. This closure also reproduces the real frequency of the Langmuir mode very accurately and actually better than the asymptotic kinetic solution (3.402).

Nevertheless, as discussed above, because of the missing exponential factor in fluid models, the Landau damping becomes very overestimated at scales $k_{\parallel}\lambda_D < 0.2$, i.e. it is the long-wavelength limit (and not the short-wavelength limit) that represents trouble. This is because in the long-wavelength limit, the frequency of Langmuir mode does not go to zero but approaches the electron plasma frequency ω_{pe} , and so the phase speed ω_r/k_{\parallel} (and the variable ζ_e) becomes large and for $k_{\parallel}\lambda_D \rightarrow 0$ goes to infinity, where the fluid closures become imprecise. Landau fluid simulations of the Langmuir

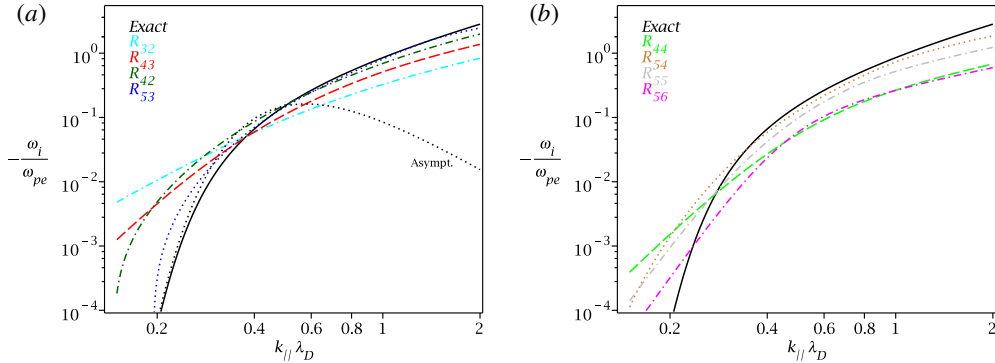


FIGURE 7. Landau damping of the Langmuir mode. Numerical solution of the exact kinetic dispersion relation (3.396) is the black solid line, and asymptotic kinetic solution (3.402) is the black dotted line.

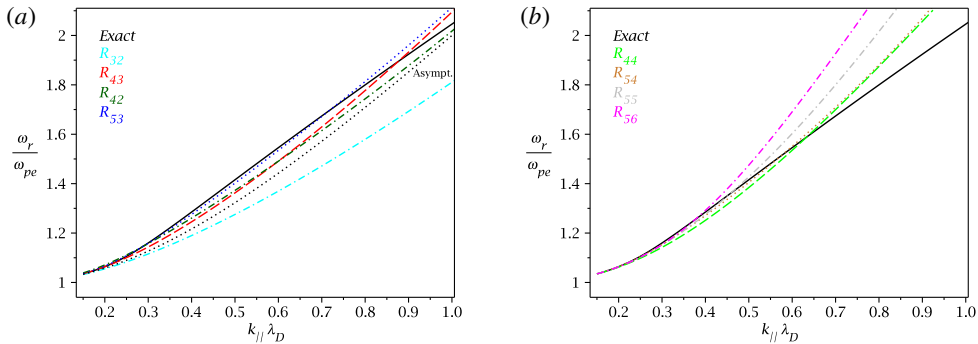


FIGURE 8. Real frequency of the Langmuir mode.

mode should be therefore restricted to scales $k_{\parallel} \lambda_D > 0.2$. At longer wavelengths, some closures can actually become ill posed and instead of Landau damping, can produce a small positive growth rate. For example, if one insists on numerical simulations in the domain below $k_{\parallel} \lambda_D < 0.2$, the closures that have to be eliminated are closures $R_{4,2}(\zeta)$, $R_{5,3}(\zeta)$, $R_{5,4}(\zeta)$, since they produce a small positive growth rate. We briefly checked, and all other closures seems to be well behaved all the way up to $k_{\parallel} \lambda_D = 10^{-4}$. At even longer scales, such as $k_{\parallel} \lambda_D = 10^{-5}$, two other closures become ill posed, the $R_{5,5}(\zeta)$ and $R_{5,6}(\zeta)$, and the remaining closures $R_{3,1}(\zeta)$, $R_{3,2}(\zeta)$, $R_{4,3}(\zeta)$, $R_{4,4}(\zeta)$ do not appear to have a length-scale restriction. It is useful to note that this is not only a problem of Landau fluid closures, but at long wavelengths, it is actually the kinetic theory itself that becomes very difficult to solve, and in the region $k_{\parallel} \lambda_D < 0.1$, we were often not able to obtain correct numerical solution when solving the exact dispersion relation (3.396).

3.16. Selected closures for the fifth-order moment

Let us work in the 1-D geometry and continue with the hierarchy. In Part 1 of this text, we called the n th-order moment $X^{(n)}$. However, when linearizing, we want to use our (1) superscript as before. Therefore, here we move the (n) index of the n th-order

moment down, and refer to the n th moment simply as X_n . The fifth-order moment $X_5 = m \int (v - u)^5 f dv$ is linearized according to

$$X_5^{(1)} = m \int v^5 f^{(1)} dv - 5u^{(1)} \underbrace{m \int v^4 f_0 dv}_{n_0}, \tag{3.405}$$

and direct calculation yields (dropping species index r everywhere except on charge q_r)

$$X_5^{(1)} = -q_r \Phi \sqrt{\frac{2T^{(0)}}{m}} \frac{p_0}{m} \text{sign}(k_{\parallel}) (3\zeta + 2\zeta^3 + 4\zeta^5 R(\zeta) - 15\zeta R(\zeta)), \tag{3.406}$$

and alternatively $p_0/m = n_0 v_{th}^2/2$.

The most precise (power-series) static closure can be constructed with the $R_{5,3}(\zeta)$ approximant

$$\begin{aligned} R_{5,3}(\zeta): \quad X_5^{(1)} = & -\frac{(104 - 33\pi)\sqrt{\pi}}{2(9\pi^2 - 69\pi + 128)} i\text{sign}(k_{\parallel}) v_{th} \tilde{r}^{(1)} - \frac{(81\pi - 256)}{2(9\pi^2 - 69\pi + 128)} v_{th}^2 q^{(1)} \\ & - \frac{3(160 - 51\pi)\sqrt{\pi}}{4(9\pi^2 - 69\pi + 128)} i\text{sign}(k_{\parallel}) v_{th}^3 n_0 T^{(1)} \\ & - \frac{(135\pi^2 - 750\pi + 1024)}{2(9\pi^2 - 69\pi + 128)} v_{th}^2 n_0 T^{(0)} u^{(1)}, \end{aligned} \tag{3.407}$$

and other static closures with the $R_{5,4}(\zeta)$ approximant

$$\begin{aligned} R_{5,4}(\zeta): \quad X_5^{(1)} = & -\frac{(21\pi - 64)}{(9\pi - 28)\sqrt{\pi}} i\text{sign}(k_{\parallel}) v_{th} \tilde{r}^{(1)} + \frac{(45\pi - 136)}{2(9\pi - 28)} v_{th}^2 q^{(1)} \\ & + \frac{(256 - 81\pi)}{2(9\pi - 28)\sqrt{\pi}} i\text{sign}(k_{\parallel}) n_0 v_{th}^3 T^{(1)}, \end{aligned} \tag{3.408}$$

with the $R_{5,5}(\zeta)$ approximant

$$R_{5,5}(\zeta): \quad X_5^{(1)} = \frac{6\sqrt{\pi}}{(9\pi - 32)} i\text{sign}(k_{\parallel}) v_{th} \tilde{r}^{(1)} + \frac{3(15\pi - 64)}{2(9\pi - 32)} v_{th}^2 q^{(1)}, \tag{3.409}$$

and with the $R_{5,6}(\zeta)$ approximant

$$R_{5,6}(\zeta): \quad X_5^{(1)} = -\frac{8}{3\sqrt{\pi}} i\text{sign}(k_{\parallel}) v_{th} \tilde{r}^{(1)} + 5v_{th}^2 q^{(1)}. \tag{3.410}$$

In Part 1 of this guide, we derived directly from fluid hierarchy that at the linear level

$$\frac{\partial}{\partial t} \tilde{r}^{(1)} + \partial_z X_5^{(1)} - 3v_{th}^2 \partial_z q^{(1)} = 0. \tag{3.411}$$

Now, importantly, by using this equation, it is directly shown that the above static closures with $X_5^{(1)}$, are equivalent to time-dependent (dynamic) closures with $\tilde{r}^{(1)}$ obtained for the same $R(\zeta)$ approximants, closures (3.339), (3.315), (3.320), (3.325). The process can be viewed as a verification procedure. Indeed, it should be always

possible to double check a dynamic closure, by calculating a static closure at the next moment with the same Padé approximant.

The most precise (power-series) dynamic closure with X_5 , is constructed with approximant $R_{6,4}(\zeta)$, by searching for a solution

$$[\zeta + \alpha_{x_5}]X_5^{(1)} = \alpha_r \tilde{r}^{(1)} + \alpha_q q^{(1)} + \alpha_T T^{(1)} + \alpha_u u^{(1)}, \tag{3.412}$$

and the closure in real space reads

$$\begin{aligned}
 R_{6,4}(\zeta) : \quad & \left[\frac{d}{dt} - \frac{3(180\pi^2 - 1197\pi + 1984)\sqrt{\pi}}{(801\pi^2 - 5124\pi + 8192)} v_{th} \partial_z \mathcal{H} \right] X_5^{(1)} \\
 & = -v_{th}^2 \frac{3(675\pi^2 - 4728\pi + 8192)}{2(801\pi^2 - 5124\pi + 8192)} \partial_z \tilde{r}^{(1)} \\
 & \quad + v_{th}^3 \frac{3(285\pi - 896)\sqrt{\pi}}{2(801\pi^2 - 5124\pi + 8192)} \partial_z \mathcal{H} q^{(1)} \\
 & \quad - v_{th}^4 n_0 \frac{3(945\pi^2 - 8184\pi + 16384)}{4(801\pi^2 - 5124\pi + 8192)} \partial_z T^{(1)} \\
 & \quad + v_{th}^3 n_0 T_0 \frac{9(450\pi^2 - 2799\pi + 4352)\sqrt{\pi}}{(801\pi^2 - 5124\pi + 8192)} \partial_z \mathcal{H} u^{(1)}.
 \end{aligned} \tag{3.413}$$

The closure has precision $o(\zeta^5)$, $o(\zeta^{-6})$. It was verified that the closure is reliable, i.e. it satisfies (3.366) once $R(\zeta)$ is replaced by $R_{6,4}(\zeta)$. The closure is plotted in figure 9 with the orange line.

3.17. Selected closures for the sixth-order moment

The sixth-order moment $X_6 = m \int (v - u)^6 f dv$ is linearized simply as $X_6^{(1)} = m \int v^6 f^{(1)} dv$, and since

$$\frac{1}{\sqrt{\pi}} \int \frac{x^6 e^{-x^2}}{x - x_0} dx = \text{sign}(k_{\parallel}) \left(\frac{3}{4} \zeta + \frac{1}{2} \zeta^3 + \zeta^5 R(\zeta) \right), \tag{3.414}$$

and direct calculation yields

$$X_6^{(1)} = -q_r \Phi n_0 \frac{p_0^2}{\rho_0^2} (15 + 6\zeta^2 + 4\zeta^4 + 8\zeta^6 R(\zeta)), \tag{3.415}$$

and alternatively $p_0/\rho_0 = v_{th}^2/2$. Separating the deviation of this moment with tilde (similarly to \tilde{r} , see also Part 1 of this guide) is done according to

$$\tilde{X}_6^{(1)} = X_6^{(1)} - 15 \frac{p_0^3}{\rho_0^2} \left(3 \frac{p^{(1)}}{p_0} - 2 \frac{n^{(1)}}{n_0} \right), \tag{3.416}$$

which directly yields

$$\tilde{X}_6^{(1)} = -q_r \Phi n_0 \frac{p_0^2}{\rho_0^2} (30R(\zeta) - 30 + 6\zeta^2 - 90\zeta^2 R(\zeta) + 4\zeta^4 + 8\zeta^6 R(\zeta)). \tag{3.417}$$

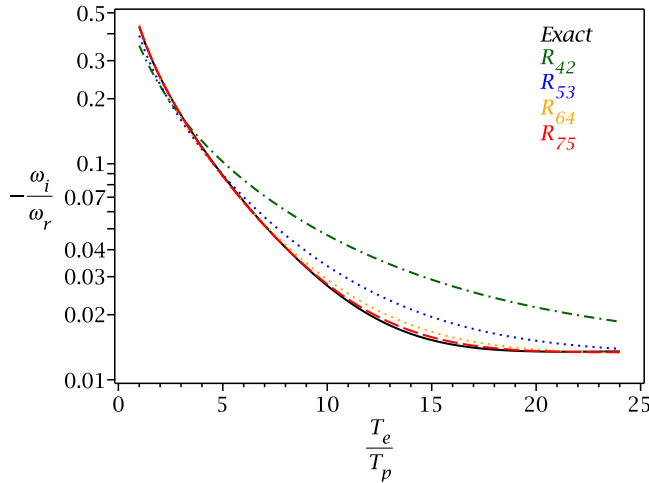


FIGURE 9. Landau damping of the ion-acoustic mode, calculated with exact $R(\zeta)$ – black line; $R_{4,2}(\zeta)$ – green line; $R_{5,3}(\zeta)$ – blue line; $R_{6,4}(\zeta)$ – orange line; and $R_{7,5}(\zeta)$ – red line. The solutions represent the most precise dynamic closures that can be constructed for the third-order moment (heat flux), fourth-order moment, fifth-order moment and sixth-order moment. It was analytically verified that all closures are ‘reliable’, i.e. equivalent to the kinetic dispersion relation once $R(\zeta)$ is replaced by the associated $R_{n,n'}(\zeta)$ approximant. The next most precise closure constructed for the seventh-order moment is $R_{8,6}(\zeta)$, which is not plotted, but we checked that the solution is basically not distinguishable (by eye) from the exact $R(\zeta)$ solution. The figure shows that it is possible to reproduce Landau damping in the fluid framework to any desired precision.

Considering static closures, the most precise power-series closure is constructed with $R_{6,4}(\zeta)$ and the closure reads

$$\begin{aligned}
 R_{6,4}(\zeta) : \quad \tilde{X}_6^{(1)} = & -\frac{3(180\pi^2 - 1197\pi + 1984)\sqrt{\pi}}{(801\pi^2 - 5124\pi + 8192)} v_{th} \mathcal{H}X_5^{(1)} \\
 & + \frac{3(675\pi^2 - 4728\pi + 8192)}{2(801\pi^2 - 5124\pi + 8192)} v_{th}^2 \tilde{r}^{(1)} \\
 & - \frac{3(285\pi - 896)\sqrt{\pi}}{2(801\pi^2 - 5124\pi + 8192)} v_{th}^3 \mathcal{H}q^{(1)} \\
 & - \frac{3(7065\pi^2 - 43056\pi + 65536)}{4(801\pi^2 - 5124\pi + 8192)} n_0 v_{th}^4 T^{(1)} \\
 & - \frac{9(450\pi^2 - 2799\pi + 4352)\sqrt{\pi}}{(801\pi^2 - 5124\pi + 8192)} n_0 T_0 v_{th}^3 \mathcal{H}u^{(1)}. \quad (3.418)
 \end{aligned}$$

This verifies that the dynamic $R_{6,4}(\zeta)$ closure (3.413) was calculated correctly, since from the simple fluid approach (Part 1), the static and dynamics closures (3.418), (3.413) must be related by

$$\frac{\partial}{\partial t} X_5^{(1)} + \partial_z \tilde{X}_6^{(1)} + \frac{15}{2} n_0 v_{th}^4 \partial_z T^{(1)} = 0. \quad (3.419)$$

The most precise (power-series) dynamic closure for $\tilde{X}_6^{(1)}$ can be constructed with approximant $R_{7,5}(\zeta)$, by searching for a solution

$$[\zeta + \alpha_{x_6}] \tilde{X}_6^{(1)} = \alpha_{x_5} X_5^{(1)} + \alpha_r \tilde{r}^{(1)} + \alpha_q q^{(1)} + \alpha_t T^{(1)} + \alpha_u u^{(1)}, \quad (3.420)$$

and the closure in real space reads

$$\begin{aligned} R_{7,5}(\zeta) : & \left[\frac{d}{dt} + \frac{18(1545\pi^2 - 9743\pi + 15360)\sqrt{\pi}}{(10800\pi^3 - 120915\pi^2 + 440160\pi - 524288)} v_{th} \partial_z \mathcal{H} \right] \tilde{X}_6^{(1)} \\ & = + \frac{3(52425\pi^2 - 331584\pi + 524288)}{2(10800\pi^3 - 120915\pi^2 + 440160\pi - 524288)} v_{th}^2 \partial_z X_5^{(1)} \\ & + \frac{3(7875\pi^2 - 50490\pi + 80896)\sqrt{\pi}}{(10800\pi^3 - 120915\pi^2 + 440160\pi - 524288)} v_{th}^3 \partial_z \mathcal{H} \tilde{r}^{(1)} \\ & + \frac{3(162000\pi^3 - 1758825\pi^2 + 6263040\pi - 7340032)}{4(10800\pi^3 - 120915\pi^2 + 440160\pi - 524288)} v_{th}^4 \partial_z q^{(1)} \\ & - \frac{27(15825\pi^2 - 99260\pi + 155648)\sqrt{\pi}}{2(10800\pi^3 - 120915\pi^2 + 440160\pi - 524288)} v_{th}^5 n_0 \partial_z \mathcal{H} T^{(1)} \\ & + \frac{3(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)}{2(10800\pi^3 - 120915\pi^2 + 440160\pi - 524288)} v_{th}^4 n_0 T_0 \partial_z u^{(1)}. \end{aligned} \quad (3.421)$$

The closure has precision $o(\zeta^6)$, $o(\zeta^{-7})$, and it was verified that the closure is reliable. The closure is plotted in figure 9 with the red line.

3.18. Convergence of fluid and kinetic descriptions

In general, for a given X_n , the most precise (power-series) closures are of course dynamic closures, and we have seen that for the third-order moment it is $R_{4,2}(\zeta)$, for the fourth-order moment it is $R_{5,3}(\zeta)$, for the fifth-order moment it is $R_{6,4}(\zeta)$ and for the sixth-order moment it is $R_{7,5}(\zeta)$. Therefore, it is reasonable to make a conjecture that for an n th-order moment X_n , the most precise closure will be constructed with approximant $R_{n+1,n-1}(\zeta)$.

The dynamic closures above are directly related to the most precise (power-series) static closures that can be constructed, and we have seen that for the third-order moment it is with approximant $R_{3,1}(\zeta)$, for the fourth-order moment it is $R_{4,2}(\zeta)$, for the fifth-order moment it is $R_{5,3}(\zeta)$ and for the sixth-order moment it is $R_{6,4}(\zeta)$, and therefore for an n th-order moment, it will be with approximant $R_{n,n-2}(\zeta)$. Regardless if dynamic or static closures are used, this implies that one can reproduce the (linear) Landau damping phenomenon in the fluid framework, to any desired precision, which establishes convergence of fluid and kinetic descriptions.

The convergence was shown here in a 1-D (electrostatic) geometry, by considering the long-wavelength low-frequency ion-acoustic mode. Nevertheless, the 1-D closures have general validity, and are of course valid also for the Langmuir mode, that we considered in § 3.14. However, see the discussion about the limitations of the Langmuir mode modelling at the end of that section, since the closures can become unstable for $k_{\parallel} \lambda_D < 0.2$, i.e. in the long-wavelength limit. For a curious reader, the damping and real frequencies of the Langmuir mode obtained with $R_{7,5}(\zeta)$, are plotted in figure 10.

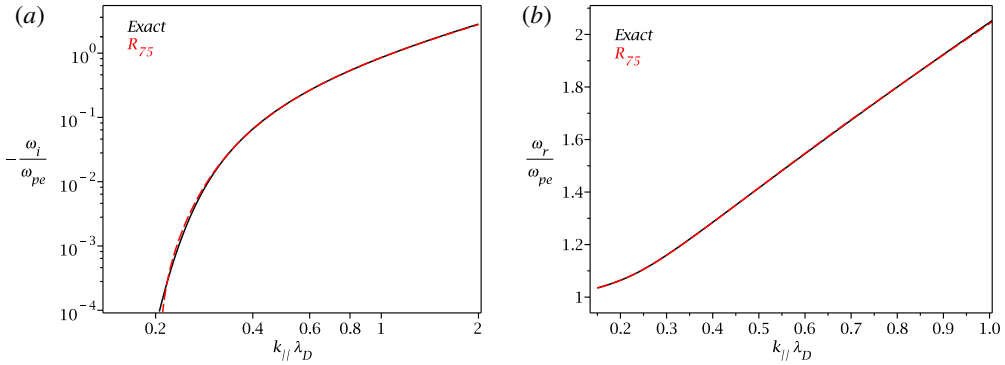


FIGURE 10. Landau damping of the Langmuir mode (a), and real frequency (b), calculated with the exact $R(\zeta)$ – black line, and $R_{7.5}(\zeta)$ – red line.

If one wants to pursue a proof of our conjecture, the general Landau integral with x^n can be calculated, for example by considering separate cases for ‘ n ’ being odd and even. The result can be expressed as

$$\begin{aligned}
 n = \text{odd} : & \quad \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^n e^{-x^2}}{x - x_0} dx = \zeta^{n-1} R(\zeta) + \sum_{l=0}^{(n-3)/2} \frac{(n - 2l - 2)!!}{2^{(n-2l-1)/2}} \zeta^{2l}; \\
 n = \text{even} : & \quad \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} \frac{x^n e^{-x^2}}{x - x_0} dx = \text{sign}(k_{\parallel}) \left[\zeta^{n-1} R(\zeta) + \sum_{l=0}^{(n-4)/2} \frac{(n - 2l - 3)!!}{2^{(n-2l-2)/2}} \zeta^{2l+1} \right],
 \end{aligned}
 \tag{3.422}$$

and it is valid for $n \geq 3$. Alternatively, one could say that the result is valid for $n \geq 1$ and that the sums are zero when the upper index is negative. One can write expressions for the general n th moment $X_n^{(1)}$, and the moment is proportional to $\zeta^n R(\zeta)$. Therefore, considering static closures where the $X_n^{(1)}$ is expressed through all the lower-order moments $X_m^{(1)}$; $m = 1 \dots n - 1$ (for even moments the deviations $\tilde{X}^{(1)}$ have to be considered), it is obvious that the closure has to be achieved with the n th-order Padé approximant of $R(\zeta)$. Similarly, considering dynamic closures where the $\zeta X_n^{(1)} \sim \zeta^{n+1} R(\zeta)$ is expressed through all the lower-order moments, the closure has to be achieved with the $(n + 1)$ th-order Padé approximant of $R(\zeta)$. To finish the proof, one needs to show that the number of required asymptotic points corresponds to $R_{n,n-2}(\zeta)$ and $R_{n+1,n-1}(\zeta)$, and that such a closure is ‘reliable’.

The next logical step would be to establish such analytic convergence of fluid and kinetic descriptions in a 3-D electromagnetic geometry in the gyrotropic limit. However, in three dimensions, for a given n th-order tensor \mathbf{X}_n , the number of its gyrotropic moments is equal to $1 + \text{int}[n/2]$ and increases with n . Therefore, it might be much more difficult to show the convergence in three dimensions, even though the convergence should still exist.

4. Three-dimensional geometry (electromagnetic)

Considering gyrotropic f_0 , let us remind ourselves of the linearized Vlasov equation (2.12), that reads

$$\frac{\partial f^{(1)}}{\partial t} + \mathbf{v} \cdot \nabla f^{(1)} - \frac{q_r B_0}{m_r c} \frac{\partial f^{(1)}}{\partial \phi} = -\frac{q_r}{m_r} \left(\mathbf{E}^{(1)} + \frac{1}{c} \mathbf{v} \times \mathbf{B}^{(1)} \right) \cdot \nabla_v f_0. \quad (4.1)$$

We want to describe the simplest kinetic effects and we demand that $f^{(1)}$ must be gyrotropic as well, so $\partial f^{(1)}/\partial \phi = 0$. This eliminates the third term on the left-hand side of (4.1) that is responsible for complicated non-gyrotropic effects with associated Bessel functions. However, even without this term the equation still appears to be complicated. For gyrotropic f_0 , the operator on the right-hand side can be shown to be (see B, equation (B 9), written in Fourier space)

$$\begin{aligned} \left(\mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{B} \right) \cdot \nabla_v f_0 &= (E_x v_x + E_y v_y) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega} \right) \frac{1}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\ &+ E_z \left[\frac{\partial f_0}{\partial v_{\parallel}} - \frac{v_x k_x + v_y k_y}{\omega} \left(\frac{\partial f_0}{\partial v_{\parallel}} - \frac{v_{\parallel}}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} \right) \right]. \end{aligned} \quad (4.2)$$

Written in the cylindrical coordinate system

$$\mathbf{v} = \begin{pmatrix} v_{\perp} \cos \phi \\ v_{\perp} \sin \phi \\ v_{\parallel} \end{pmatrix}, \quad \mathbf{k} = \begin{pmatrix} k_{\perp} \cos \psi \\ k_{\perp} \sin \psi \\ k_{\parallel} \end{pmatrix}, \quad (4.3)$$

so that

$$v_x k_x + v_y k_y = v_{\perp} k_{\perp} \cos \phi \cos \psi + v_{\perp} k_{\perp} \sin \phi \sin \psi = v_{\perp} k_{\perp} \cos(\phi - \psi); \quad (4.4)$$

$$\mathbf{v} \cdot \mathbf{k} = v_{\parallel} k_{\parallel} + v_{\perp} k_{\perp} \cos(\phi - \psi), \quad (4.5)$$

which yields

$$\begin{aligned} \left(\mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{B} \right) \cdot \nabla_v f_0 &= (E_x \cos \phi + E_y \sin \phi) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega} \right) \frac{\partial f_0}{\partial v_{\perp}} + \frac{v_{\perp} k_{\parallel}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\ &+ E_z \left[\frac{\partial f_0}{\partial v_{\parallel}} - \frac{k_{\perp} \cos(\phi - \psi)}{\omega} \left(v_{\perp} \frac{\partial f_0}{\partial v_{\parallel}} - v_{\parallel} \frac{\partial f_0}{\partial v_{\perp}} \right) \right]. \end{aligned} \quad (4.6)$$

The Vlasov equation in Fourier space now reads

$$\begin{aligned} &-i(\omega - v_{\parallel} k_{\parallel} - v_{\perp} k_{\perp} \cos(\phi - \psi)) f^{(1)} \\ &= -\frac{q_r}{m_r} \left\{ (E_x \cos \phi + E_y \sin \phi) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega} \right) \frac{\partial f_0}{\partial v_{\perp}} + \frac{v_{\perp} k_{\parallel}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \right. \\ &\quad \left. + E_z \left[\frac{\partial f_0}{\partial v_{\parallel}} - \frac{k_{\perp} \cos(\phi - \psi)}{\omega} \left(v_{\perp} \frac{\partial f_0}{\partial v_{\parallel}} - v_{\parallel} \frac{\partial f_0}{\partial v_{\perp}} \right) \right] \right\}. \end{aligned} \quad (4.7)$$

This equation is not very useful. If the equation is divided by $(\omega - \mathbf{v} \cdot \mathbf{k})$ to obtain $f^{(1)}$, and integration over $\int_0^{2\pi} d\phi$ is attempted, this leads to integrals that are not well defined. On the other hand, if (4.7) is directly integrated over $d\phi$ (each side separately), almost all the terms disappear since $\int_0^{2\pi} \cos(\phi - \psi) d\phi = 0$ etc., except

$$-i(\omega - v_{\parallel} k_{\parallel}) f^{(1)} = -\frac{q_r}{m_r} E_z \frac{\partial f_0}{\partial v_{\parallel}}, \quad (4.8)$$

and the system reduces to the simplest case of Landau damping that we have already described in detail (even though only in a 1-D geometry). We could divide (4.8) by $(\omega - v_{\parallel} k_{\parallel})$, integrate the system in a 3-D geometry and consider Landau fluid closures,

but this would be a bit boring right now. We want to get a few more kinetic effects out of the system. We need a different approach and we need to obtain a better gyrotopropic limit for $f^{(1)}$.

It turns out that to obtain the correct gyrotopropic limit for $f^{(1)}$, the third term in the Vlasov equation (4.1) cannot just be straightforwardly neglected. The term has to be kept there, the relatively complicated integration around the unperturbed orbit has to be performed (see appendix C), and only then can the term be removed in a limit. This is very similar to other mathematical techniques that were encountered earlier, for example when calculating the Fourier transform of $\text{sign}(k_{\parallel})$, where instead of that function, one needs to consider $\text{sign}(k_{\parallel})e^{-\alpha|k_{\parallel}|}$, and only after the calculation is the term removed with the limit $\alpha \rightarrow 0$. Without the additional term $e^{-\alpha|k_{\parallel}|}$ that was removed later, the calculations were not clearly defined, and a very similar situation is encountered now. Nevertheless, it is indeed mind boggling that the complicated integration around the unperturbed orbit has to be performed to recover the gyrotopropic limit. This is exactly why the 3-D case is so much more complicated than the previously studied 1-D case, even though the Landau fluid closures will not be more complicated at all, as we will see later. An alternative approach that we will discuss only very briefly, is to use the guiding-centre variables where the gyrotopropic limit is recovered perhaps more naturally. However, we will skip a huge amount of calculations that lead to the guiding-centre approach, so the amount of complexity is probably similar in the end.

4.1. Gyrotopropic limit for $f^{(1)}$

We need to consider the full kinetic $f^{(1)}$ with all non-gyrotopropic effects, that is obtained in appendix C, equation (C47). By using the z -component of the induction equation $\partial \mathbf{B} / \partial t = -c \nabla \times \mathbf{E}$ written in Fourier space (C71) (that is an equation of general validity not introducing any simplifications), the general $f^{(1)}$ (C47) is slightly rewritten as

$$\begin{aligned}
 f_r^{(1)} = & -\frac{iq_r}{m_r} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{+i(m-n)(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - n\Omega_r} J_m(\lambda_r) \left\{ \left[\frac{nJ_n(\lambda_r)}{\lambda_r} (E_x \cos \psi + E_y \sin \psi) \right. \right. \\
 & + iJ'_n(\lambda_r) \frac{\omega}{ck_{\perp}} B_z \left. \right] \left[\left(1 - \frac{k_{\parallel}v_{\parallel}}{\omega} \right) \frac{\partial f_{0r}}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] \\
 & + E_z J_n(\lambda_r) \left[\frac{\partial f_{0r}}{\partial v_{\parallel}} - \frac{n\Omega_r}{\omega} \left(\frac{\partial f_{0r}}{\partial v_{\parallel}} - \frac{v_{\parallel}}{v_{\perp}} \frac{\partial f_{0r}}{\partial v_{\perp}} \right) \right] \left. \right\}. \tag{4.9}
 \end{aligned}$$

This $f^{(1)}$ contains all the information of linear kinetic theory, with associated Bessel functions $J_n(\lambda_r)$, where $\lambda_r = k_{\perp}v_{\perp}/\Omega_r$ and $\Omega_r = q_r B_0/(m_r c)$. Two summations through integers ‘ n ’ and ‘ m ’ are present in (4.9), that originate from using identities (C10), (C11). The general (4.9) contains ‘singularities’ where $\omega - k_{\parallel}v_{\parallel} - n\Omega_r$ becomes zero, that are called wave–particle resonances. For $n=0$ the resonance is called the Landau resonance, and resonances for $n \neq 0$ are called cyclotron resonances. To get rid of the summations and Bessel functions, we want to consider the dynamics at spatial scales that are much larger than the particle gyroradius, which corresponds to limit $\lambda_r \ll 1$. Additionally, we will need to consider low-frequency limit $\omega/\Omega_r \ll 1$. We find it illuminating to first separate the $n=0$ resonance from all the other expressions, without performing any approximations, i.e. we want to separate

$$f_r^{(1)} = f_r^{(1)}|_{n=0} + f_r^{(1)}|_{n \neq 0}. \tag{4.10}$$

Separating the $n = 0$ case directly yields

$$f_r^{(1)}|_{n=0} = -\frac{iq_r}{m_r} \sum_{m=-\infty}^{\infty} \frac{e^{+im(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel}} J_m(\lambda_r) \times \left\{ iJ'_0(\lambda_r) \frac{B_z}{ck_{\perp}} \left[(\omega - k_{\parallel}v_{\parallel}) \frac{\partial f_{0r}}{\partial v_{\perp}} + k_{\parallel}v_{\perp} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] + E_z J_0(\lambda_r) \frac{\partial f_{0r}}{\partial v_{\parallel}} \right\}. \quad (4.11)$$

Note that $nJ_n(x)/x = (J_{n-1}(x) + J_{n+1}(x))/2$, which when evaluated for $n = 0$ is zero exactly, since $J_{-1}(x) + J_1(x) = 0$ exactly. Since there is no dependence on angles ϕ, ψ inside of the big brackets, the sum can be summed (or put to its original form where it came from)

$$f_r^{(1)}|_{n=0} = -\frac{q_r}{m_r} \frac{e^{+i\lambda_r \sin(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel}} \left\{ -J'_0(\lambda_r) \frac{B_z}{ck_{\perp}} \left[(\omega - k_{\parallel}v_{\parallel}) \frac{\partial f_{0r}}{\partial v_{\perp}} + k_{\parallel}v_{\perp} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] + iE_z J_0(\lambda_r) \frac{\partial f_{0r}}{\partial v_{\parallel}} \right\}. \quad (4.12)$$

Very interestingly, for one B_z term, the complicated denominator $\omega - k_{\parallel}v_{\parallel}$ cancels out, yielding

$$f_r^{(1)}|_{n=0} = -\frac{q_r}{m_r} e^{+i\lambda_r \sin(\phi-\psi)} \left\{ -J'_0(\lambda_r) \frac{B_z}{ck_{\perp}} \left[\frac{\partial f_{0r}}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega - k_{\parallel}v_{\parallel}} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] + J_0(\lambda_r) \frac{iE_z}{\omega - k_{\parallel}v_{\parallel}} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right\}. \quad (4.13)$$

This is an exact kinetic expression for $f^{(1)}$ corresponding to $n = 0$ resonances, that is accompanied by an expression for all the other resonances $f^{(1)}|_{n \neq 0}$ (that is equivalent to (4.9) where $n \neq 0$ is added below the sum with n). Now considering the limit $\lambda_r \ll 1$, the Bessel functions $J_0(\lambda_r) = 1, J'_0(\lambda_r) = -\lambda_r/2$, the exponential term disappears, which yields the final $f^{(1)}$ in the gyrotopic limit that reads

$$f_r^{(1)} = -\frac{v_{\perp}}{2} \frac{B_z}{B_0} \left[\frac{\partial f_{0r}}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{(\omega - k_{\parallel}v_{\parallel})} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] - \frac{q_r}{m_r} \frac{iE_z}{(\omega - k_{\parallel}v_{\parallel})} \frac{\partial f_{0r}}{\partial v_{\parallel}}, \quad (4.14)$$

or alternatively

$$f_r^{(1)} = \underbrace{-\frac{B_z}{2B_0} v_{\perp} \frac{\partial f_{0r}}{\partial v_{\perp}}}_{\mu = \text{const.}} - \underbrace{\frac{B_z}{2B_0} \frac{k_{\parallel}v_{\perp}^2}{(\omega - k_{\parallel}v_{\parallel})} \frac{\partial f_{0r}}{\partial v_{\parallel}}}_{\text{magnetic mirror force}} - \underbrace{\frac{q_r}{m_r} \frac{iE_z}{(\omega - k_{\parallel}v_{\parallel})} \frac{\partial f_{0r}}{\partial v_{\parallel}}}_{\text{Coulomb force}}. \quad (4.15)$$

As we will see shortly in § 4.2, the expression has a very nice physical interpretation, where the first term comes from the conservation of the magnetic moment μ , the second term comes from the magnetic mirror force and the third term comes from the Coulomb force. The same expression is obtained by directly picking up the $m = 0, n = 0$ contributions from the general (4.9). Up to replacing B_z with $|\mathbf{B}|$, the expression agrees for example with (19) of Ferrière & André (2002), and is of course equivalent to expressions of Snyder *et al.* (1997) (formulated in the gyrofluid formalism). In

those works, the expression is derived perhaps more elegantly, in the so-called guiding-centre limit of the Vlasov equation (see Kulsrud 1983). The difference between B_z and $|\mathbf{B}|$ arises, because the fully kinetic $f^{(1)}$ in (4.9) is linearized completely.

Note that to obtain the gyrotropic limit (4.14), we did not have to explicitly perform the low-frequency limit $\omega/\Omega_r \ll 1$. However, it is important to emphasize that by only picking up the $n=0$ resonances, we have performed the low-frequency limit implicitly. The power-series expansion of the Bessel functions for $n \geq 0$ reads (with integer n)

$$J_n(x) = \sum_{s=0}^{\infty} \frac{(-1)^s}{s!(n+s)!} \left(\frac{x}{2}\right)^{n+2s}; \quad J_{-n}(x) = \sum_{s=0}^{\infty} \frac{(-1)^{n+s}}{s!(n+s)!} \left(\frac{x}{2}\right)^{n+2s}, \quad (4.16)$$

where the second expression can be easily replaced by $J_{-n}(x) = (-1)^n J_n(x)$. The first few terms are

$$\begin{aligned} J_0(x) &= 1 - \frac{x^2}{4} + \frac{x^4}{64} + \dots; & J_1(x) &= \frac{x}{2} - \frac{x^3}{16} + \dots; & J_2(x) &= \frac{x^2}{8} - \frac{x^4}{96} + \dots; \\ J_{-1}(x) &= -\frac{x}{2} + \frac{x^3}{16} + \dots; & J_{-2}(x) &= \frac{x^2}{8} - \frac{x^4}{96} + \dots, \end{aligned} \quad (4.17)$$

and the derivatives of these functions read

$$\begin{aligned} J'_0(x) &= -\frac{x}{2} + \frac{x^3}{16} + \dots; & J'_1(x) &= \frac{1}{2} - \frac{3x^2}{16} + \dots; & J'_2(x) &= \frac{x}{4} - \frac{x^3}{24} + \dots; \\ J'_{-1}(x) &= -\frac{1}{2} + \frac{3x^2}{16} + \dots; & J'_{-2}(x) &= \frac{x}{4} - \frac{x^3}{24} + \dots, \end{aligned} \quad (4.18)$$

and the derivatives can be also calculated by using identity $J'_n(x) = (J_{n-1}(x) - J_{n+1}(x))/2$. In the full equation (4.9), the term with E_x, E_y components contains $J_m(x)(J_{n-1}(x) + J_{n+1}(x))$, so for $m=0$ terms with resonances $n = \pm 1$ do not disappear in the limit $\lambda_r \ll 1$. Similar situation is for the B_z components (which for $n \neq 0$ is actually easier to reformulate to the original formulation without the B_z induction equation to recover the correct limit). Whether we like it or not, to get rid of these terms and to obtain the gyrotropic limit (4.14), one has to do the low-frequency limit $\omega \ll \Omega_r$ as well.

A few notes are in order. (i) If we now calculate the kinetic moments with $f^{(1)}$ described by (4.14), which was obviously obtained in the low-frequency limit, and find possible fluid closures for the heat fluxes q_{\parallel}, q_{\perp} or the fourth-order moments $\tilde{r}_{\parallel\parallel}, \tilde{r}_{\parallel\perp}, \tilde{r}_{\perp\perp}$, such a fluid model will not become necessarily restricted only to a low-frequency regime $\omega \ll \Omega$. At the linear level, the parallel propagating ion-cyclotron and whistler modes are completely independent of the Landau fluid closures, and these modes remain undamped.¹⁰ For example figure 6 in Part 1 remains unchanged, and the simplest ion-cyclotron resonance where $\omega \rightarrow \Omega$ for high wavenumbers (neglecting FLRs), will not be suddenly ‘removed’ by using a low-frequency Landau fluid closure. All figures for the (strictly) parallel firehose instability remain unchanged, and the same applies to the perpendicular fast mode.

(ii) There is nothing ‘esoteric’ about ion-cyclotron resonances. Similarly to the kinetic effect of Landau damping, the ion-cyclotron resonances just represent some

¹⁰The situation is different in nonlinear numerical simulations, where the modes are damped by nonlinear coupling with the strongly Landau damped ion-acoustic (sound) mode, see for example Landau fluid simulations of Hunana *et al.* (2011).

integral, which indeed has some wave–particle ‘resonance’, i.e. the integral has some singularity in the denominator. Similarly to Landau damping, in the case of a bi-Maxwellian f_0 this singularity can be expressed through the plasma dispersion function $Z(\zeta)$ (similar generalizations exist for a bi-kappa distribution etc.). The variable ζ is only modified to include the resonances, and for $n = \pm 1$ one can work with

$$\zeta_{+1} = \frac{(\omega + \Omega)\sqrt{\alpha_{\parallel}}}{|k_{\parallel}|} = \frac{(\omega + \Omega)}{|k_{\parallel}|v_{\text{th}\parallel}}; \quad \zeta_{-1} = \frac{(\omega - \Omega)\sqrt{\alpha_{\parallel}}}{|k_{\parallel}|} = \frac{(\omega - \Omega)}{|k_{\parallel}|v_{\text{th}\parallel}}, \quad (4.19)$$

or for general n with $\zeta_n = (\omega + n\Omega)/(|k_{\parallel}|v_{\text{th}\parallel})$. No new discussion on how to treat this singularity is required. The singular point x_0 in the complex plane is only moved to some other location, and all the previous discussion about the Landau integral fully applies. We could potentially integrate over all the ion-cyclotron resonances and obtain expressions for the heat flux or the fourth-order moments (with the same techniques as plasma physics books do, even though they usually stop at the first-order velocity moment, since it is enough to obtain the kinetic dispersion relation). Even though complicated in detail, these would be just standard kinetic calculations. The difference between the advanced fluid and kinetic descriptions is that we need to find a closure after all of these kinetic calculations, i.e. we need to find a way to express the last considered moment through lower-order moments, such that the closure is valid for all the ζ values, for example, by using the Padé approximation for $R(\zeta)$. Such a closure remains elusive for the ion-cyclotron resonances.

(iii) Advanced fluid models are not restricted to work with $f^{(1)}$ in the gyrotopic limit (4.14). In the Landau fluid models of Passot & Sulem (2007), no assumption about the size of the gyroradius is made, and only the low-frequency condition is used and, therefore, the $f^{(1)}$ of these fluid models contain Bessel functions $J_n(\lambda_r)$. The integrals over dv_{\perp} are slightly more difficult, and for example if a term proportional to $J_0(\lambda)J_0(\lambda)f_0$ is encountered, the integration over dv_{\perp} ($d^3v = v_{\perp} dv_{\perp} dv_{\parallel} d\phi$) is calculated as

$$\int_0^{\infty} x J_n^2(ax) e^{-x^2} dx = \frac{1}{2} e^{-a^2/2} I_n(a^2/2), \quad (4.20)$$

implying

$$\begin{aligned} \int_0^{\infty} J_0^2\left(\frac{k_{\perp}}{\Omega} v_{\perp}\right) e^{-\alpha_{\perp} v_{\perp}^2} v_{\perp} dv_{\perp} &= [x = \sqrt{\alpha_{\perp}} v_{\perp}] = \frac{1}{\alpha_{\perp}} \int_0^{\infty} J_0^2\left(\frac{k_{\perp}}{\Omega \sqrt{\alpha_{\perp}}} x\right) e^{-x^2} x dx \\ &= \frac{1}{2\alpha_{\perp}} e^{-b} I_0(b), \end{aligned} \quad (4.21)$$

where the new parameter b (which should not be confused with the magnetic field unit vector $\hat{\mathbf{b}}$) is

$$b = \frac{k_{\perp}^2}{2\Omega^2 \alpha_{\perp}} = \frac{k_{\perp}^2 v_{\text{th}\perp}^2}{2\Omega^2} = \frac{k_{\perp}^2 T_{\perp}^{(0)}}{m\Omega^2} = \frac{1}{2} k_{\perp}^2 r_L^2. \quad (4.22)$$

Calculations like this lead to the functions $\Gamma_0(b) = e^{-b} I_0(b)$ and $\Gamma_1(b) = e^{-b} I_1(b)$. We note that the limit $b \rightarrow 0$ yields $\Gamma_0(b) \rightarrow 1$ and $\Gamma_1(b) \rightarrow 0$.

4.2. *Coulomb force and mirror force (Landau damping and transit-time damping)*

The gyrotopic limit (4.14) has a very meaningful physical interpretation. To clearly understand what kind of forces are present in such a system, one needs to consider that a particle quickly gyrates around its slower moving centre, called the ‘guiding centre’, and express the full velocity of a particle \mathbf{v} as being composed of the quick gyration \mathbf{v}_{gyro} , and a motion of the guiding centre, that is further decomposed to its free motion parallel to the magnetic field line $v_{\parallel}\hat{\mathbf{b}}$, and all the possible drifts of the guiding centre: the $E \times B$ drift \mathbf{u}_E , the grad- B drift, the curvature drift, the polarization drift etc. The plasma physics books by Fitzpatrick and Gurnett & Bhattacharjee (2005) have detailed introductions about single-particle motions in the presence of a Lorentz force, where the drifts of the guiding centre are calculated. Then one should follow the gyrofluid approach, and by performing integrals over $d\phi$ (gyro-averaging) and by expanding for example with respect to Larmor radius, one should get the ‘guiding-centre limit’ of the Vlasov equation and the expression for $f^{(1)}$. One should follow Kulsrud (1983), Snyder *et al.* (1997) etc. A very useful paper is also that of Ferrière & André (2002), that explores the discrepancy between the usual CGL and the long-wavelength low-frequency kinetic theory in great detail and that we follow here.

Without going through the lengthy derivation, it can be shown that at the leading order (for low frequencies ω/Ω and long wavelengths kr_L), it is sufficient to consider the motion of the guiding centre with velocity

$$\mathbf{v} = v_{\parallel}\hat{\mathbf{b}} + \mathbf{u}_E; \quad \mathbf{u}_E = c \frac{\mathbf{E} \times \mathbf{B}}{|\mathbf{B}|^2}, \tag{4.23}$$

where the perpendicular equation of motion satisfies the conservation of the magnetic moment

$$\mu = \frac{mv_{\perp}^2}{2|\mathbf{B}|} = \text{const.}; \quad \Rightarrow \quad \frac{d}{dt} \left(\frac{v_{\perp}^2}{|\mathbf{B}|} \right) = 0; \quad \Rightarrow \quad \frac{dv_{\perp}}{dt} = \frac{v_{\perp}}{2|\mathbf{B}|} \frac{d|\mathbf{B}|}{dt}, \tag{4.24}$$

and the parallel equation of motion satisfies

$$m \frac{dv_{\parallel}}{dt} = qE_{\parallel} - \mu \hat{\mathbf{b}} \cdot \nabla |\mathbf{B}| - m \hat{\mathbf{b}} \cdot \frac{d\mathbf{u}_E}{dt}, \tag{4.25}$$

where $E_{\parallel} = \hat{\mathbf{b}} \cdot \mathbf{E}$ and $d/dt = \partial/\partial t + \mathbf{v} \cdot \nabla = \partial/\partial t + (v_{\parallel}\hat{\mathbf{b}} + \mathbf{u}_E) \cdot \nabla$. The first term on the right-hand side of the above equation is the Coulomb force, responsible for acceleration of particles along the magnetic field lines. The second term is the magnetic mirror force, responsible for trapping of particles in the magnetic bottle. The third term is a non-inertial force associated with the time dependence of the $E \times B$ drift of the gyrocentre. The similarity of the Coulomb force and the magnetic mirror force can be emphasized by using the scalar potential Φ and rewriting $E_{\parallel} = -\nabla\Phi$, which yields

$$m \frac{dv_{\parallel}}{dt} = \underbrace{-q\hat{\mathbf{b}} \cdot \nabla\Phi}_{\text{Coulomb}} - \underbrace{\mu\hat{\mathbf{b}} \cdot \nabla|\mathbf{B}|}_{\text{mirror}} - m\hat{\mathbf{b}} \cdot \frac{d\mathbf{u}_E}{dt}. \tag{4.26}$$

The similarity is immediately apparent, one just needs to replace the charge of the particle with its magnetic moment $q \rightarrow \mu$ and replace $\Phi \rightarrow |\mathbf{B}|$. Therefore, in a similar way to a charged particle reacting to electric field, a gyrating particle has a magnetic moment that reacts with the gradient of the strength (absolute value) of the

magnetic field. The damping effects associated with the Coulomb force are called Landau damping. The damping effects associated with the mirror force are called transit-time damping or Barnes damping (Barnes 1966). Therefore, it is often stated that the transit-time damping is a ‘magnetic analogue’ of Landau damping. Often, the two effects are not separated since both represent the $n = 0$ particle resonance and one talks only about Landau damping. Nevertheless, it is emphasized that Landau fluid models in a 3-D geometry contain both damping mechanisms, and these models contain both the Coulomb force and the mirror force.¹¹

The equations of motion (4.24), (4.25) should be used in the gyro-averaged Vlasov equation

$$\frac{\partial f}{\partial t} + (v_{\parallel} \hat{\mathbf{b}} + \mathbf{u}_E) \cdot \nabla f + \left[\frac{dv_{\perp}}{dt} \frac{\partial}{\partial v_{\perp}} + \frac{dv_{\parallel}}{dt} \frac{\partial}{\partial v_{\parallel}} \right] f = 0, \tag{4.27}$$

and the equation should be expanded $f = f_0 + f^{(1)}$. We are interested only in linear solutions, and we can simplify. To avoid discussing compatibility conditions for f_0 (see Kulsrud 1983), we can just simply claim that f_0 does not have any time or spatial dependence. By further noticing that linearization of $\mathbf{u}_E \stackrel{\text{lin}}{=} \mathbf{u}_E^{(0)} + \mathbf{u}_E^{(1)}$ yields $\mathbf{u}_E^{(0)} = c\mathbf{E}_0 \times \mathbf{B}_0/B_0^2 = 0$ since $E_0 = 0$, we can immediately write that at the linear level

$$\frac{\partial f^{(1)}}{\partial t} + v_{\parallel} \partial_z f^{(1)} = - \left[\frac{dv_{\perp}}{dt} \frac{\partial}{\partial v_{\perp}} + \frac{dv_{\parallel}}{dt} \frac{\partial}{\partial v_{\parallel}} \right] f_0. \tag{4.28}$$

Noticing that the \mathbf{ExB} drift \mathbf{u}_E is always perpendicular to the direction of \mathbf{B} (and also \mathbf{E}) implies $\hat{\mathbf{b}} \cdot \mathbf{u}_E = 0$, and the last term in the dv_{\parallel}/dt equation (4.25) rewrites as

$$- \hat{\mathbf{b}} \cdot \frac{d\mathbf{u}_E}{dt} = - \frac{d}{dt} \underbrace{(\hat{\mathbf{b}} \cdot \mathbf{u}_E)}_{=0} + \mathbf{u}_E \cdot \frac{d\hat{\mathbf{b}}}{dt}, \tag{4.29}$$

which at the linear level disappears, since

$$\mathbf{u}_E \cdot \frac{d\hat{\mathbf{b}}}{dt} \stackrel{\text{lin}}{=} \underbrace{\mathbf{u}_E^{(0)}}_{=0} \cdot \frac{d\hat{\mathbf{b}}^{(1)}}{dt} + \mathbf{u}_E^{(1)} \cdot \underbrace{\frac{d\hat{\mathbf{b}}^{(0)}}{dt}}_{=0} = 0. \tag{4.30}$$

The magnetic mirror force contains $\partial_z |\mathbf{B}| = \partial_z \sqrt{B_x^2 + B_y^2 + B_z^2} = \hat{\mathbf{b}} \cdot \partial_z \mathbf{B}$, where linearization yields $\partial_z |\mathbf{B}| \stackrel{\text{lin}}{=} \partial_z B_z$. Similarly, the dv_{\perp}/dt equation (4.24) contains $d|\mathbf{B}|/dt = \hat{\mathbf{b}} \cdot d\mathbf{B}/dt$ that linearizes as $d|\mathbf{B}|/dt \stackrel{\text{lin}}{=}} (\partial/\partial t + v_{\parallel} \partial_z) B_z$. The linearized equations of motion therefore read

$$\frac{dv_{\parallel}}{dt} \stackrel{\text{lin}}{=} \frac{q}{m} E_{\parallel} - \frac{v_{\perp}^2}{2B_0} \partial_z B_z; \tag{4.31}$$

$$\frac{dv_{\perp}}{dt} \stackrel{\text{lin}}{=} \frac{v_{\perp}}{2B_0} \left(\frac{\partial}{\partial t} + v_{\parallel} \partial_z \right) B_z, \tag{4.32}$$

¹¹In the 1-D geometry where only v_{\parallel} is considered, the gyration of particles, the magnetic mirror force and the transit-time damping of course disappears, since these effects naturally require v_{\perp} as well.

yielding the final expression for $f^{(1)}$ in real space

$$\left(\frac{\partial}{\partial t} + v_{\parallel} \partial_z\right) f^{(1)} = -\frac{v_{\perp}}{2B_0} \left(\frac{\partial}{\partial t} + v_{\parallel} \partial_z\right) B_z \frac{\partial f_0}{\partial v_{\perp}} - \left(\frac{q}{m} E_{\parallel} - \frac{v_{\perp}^2}{2B_0} \partial_z B_z\right) \frac{\partial f_0}{\partial v_{\parallel}}, \tag{4.33}$$

which when Fourier transformed recovers the $f^{(1)}$ in the gyrotopic limit (4.14). Instead of fully linearized equations with B_z , one can also work with $|\mathbf{B}|$, i.e. one can write the leading-order equations of motion as

$$\frac{dv_{\parallel}}{dt} = \frac{q}{m} E_{\parallel} - \frac{v_{\perp}^2}{2B_0} \partial_z |\mathbf{B}|; \tag{4.34}$$

$$\frac{dv_{\perp}}{dt} = \frac{v_{\perp}}{2B_0} \left(\frac{\partial}{\partial t} + v_{\parallel} \partial_z\right) |\mathbf{B}|, \tag{4.35}$$

which yields analogous equations (4.33), (4.14) where B_z is just replaced by $|\mathbf{B}|$.

4.3. Kinetic moments for bi-Maxwellian f_0

Since in the Vlasov expansion the gyrotopic f_0 was assumed to depend only on \mathbf{v} , i.e. $f_0(v_{\perp}^2, v_{\parallel}^2)$ and be \mathbf{x}, t independent, the fluid velocity \mathbf{u} is removed from the distribution function and the ‘pure’ bi-Maxwellian is

$$f_0 = n_0 \sqrt{\frac{\alpha_{\parallel}}{\pi}} \frac{\alpha_{\perp}}{\pi} e^{-\alpha_{\parallel} v_{\parallel}^2 - \alpha_{\perp} v_{\perp}^2}, \tag{4.36}$$

where

$$\alpha_{\parallel} = \frac{m}{2T_{\parallel}^{(0)}}; \quad \alpha_{\perp} = \frac{m}{2T_{\perp}^{(0)}}, \tag{4.37}$$

or in the language of thermal speeds,

$$v_{\text{th}\parallel}^2 = \frac{2T_{\parallel}^{(0)}}{m} = \alpha_{\parallel}^{-1}; \quad v_{\text{th}\perp}^2 = \frac{2T_{\perp}^{(0)}}{m} = \alpha_{\perp}^{-1}. \tag{4.38}$$

We prefer the α notation instead of the thermal speed v_{th} , since in long analytic calculations, there is a lesser chance of an error. We work without the species index r except for charge q_r and mass m_r . It is straightforward to calculate that

$$\frac{\partial f_0}{\partial v_{\parallel}} = -2\alpha_{\parallel} v_{\parallel} f_0 = -\frac{m_r}{T_{\parallel}^{(0)}} v_{\parallel} f_0; \tag{4.39}$$

$$\frac{\partial f_0}{\partial v_{\perp}} = -2\alpha_{\perp} v_{\perp} f_0 = -\frac{m_r}{T_{\perp}^{(0)}} v_{\perp} f_0. \tag{4.40}$$

Instead of E_z , we will work with the scalar potential Φ as before

$$E_z = -\nabla_{\parallel} \Phi; \quad \Rightarrow \quad iE_z = k_{\parallel} \Phi. \tag{4.41}$$

The $f^{(1)}$ that we want to integrate reads

$$f^{(1)} = \frac{B_z}{B_0} \alpha_{\perp} \left[v_{\perp}^2 f_0 + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \frac{k_{\parallel} v_{\parallel} v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 \right] + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \frac{k_{\parallel} v_{\parallel}}{(\omega - k_{\parallel} v_{\parallel})} f_0, \tag{4.42}$$

or alternatively expressed with temperatures

$$f^{(1)} = \frac{B_z}{B_0} \frac{m_r}{2T_{\perp}^{(0)}} \left[v_{\perp}^2 f_0 + \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} \frac{k_{\parallel} v_{\parallel} v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 \right] + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \frac{k_{\parallel} v_{\parallel}}{(\omega - k_{\parallel} v_{\parallel})} f_0. \quad (4.43)$$

Now we want to calculate the linear ‘kinetic’ moments over this distribution function. The kinetic moments are

$$n^{(1)} = \int f^{(1)} d^3 v; \quad u_{\parallel}^{(1)} = \frac{1}{n_0} \int v_{\parallel} f^{(1)} d^3 v; \quad (4.44)$$

$$p_{\parallel}^{(1)} = m_r \int v_{\parallel}^2 f^{(1)} d^3 v; \quad p_{\perp}^{(1)} = \frac{m_r}{2} \int v_{\perp}^2 f^{(1)} d^3 v; \quad (4.45)$$

$$q_{\parallel}^{(1)} = m_r \int v_{\parallel}^3 f^{(1)} d^3 v - 3p_{\parallel}^{(0)} u_{\parallel}^{(1)}; \quad q_{\perp}^{(1)} = \frac{m_r}{2} \int v_{\parallel} v_{\perp}^2 f^{(1)} d^3 v - p_{\perp}^{(0)} u_{\parallel}^{(1)}; \quad (4.46)$$

$$r_{\parallel\parallel}^{(1)} = m_r \int v_{\parallel}^4 f^{(1)} d^3 v; \quad r_{\parallel\perp}^{(1)} = \frac{m_r}{2} \int v_{\parallel}^2 v_{\perp}^2 f^{(1)} d^3 v; \quad r_{\perp\perp}^{(1)} = \frac{m_r}{4} \int v_{\perp}^4 f^{(1)} d^3 v. \quad (4.47)$$

We have so far avoided integration in the cylindrical coordinate system, and all the previous integrals were done in the Cartesian coordinate system. In the cylindrical system, $d^3 v = v_{\perp} dv_{\perp} dv_{\parallel} d\phi$ and the integral with respect to v_{\perp} is from 0 to ∞ . The Gaussian integrals are

$$\begin{aligned} \int_0^{\infty} e^{-ax^2} dx &= \frac{1}{2} \sqrt{\frac{\pi}{a}}; & \int_0^{\infty} x e^{-ax^2} dx &= \frac{1}{2a}; \\ \int_0^{\infty} x^2 e^{-ax^2} dx &= \frac{1}{4a} \sqrt{\frac{\pi}{a}}; & \int_0^{\infty} x^3 e^{-ax^2} dx &= \frac{1}{2a^2}; \\ \int_0^{\infty} x^4 e^{-ax^2} dx &= \frac{3}{8a^2} \sqrt{\frac{\pi}{a}}; & \int_0^{\infty} x^5 e^{-ax^2} dx &= \frac{1}{a^3}; \\ \int_0^{\infty} x^6 e^{-ax^2} dx &= \frac{15}{16a^3} \sqrt{\frac{\pi}{a}}; & \int_0^{\infty} x^7 e^{-ax^2} dx &= \frac{3}{a^4}. \end{aligned}$$

Therefore, integrating over $dv_{\perp} d\phi$ is straightforward and

$$\begin{aligned} \int f_0 v_{\perp} dv_{\perp} d\phi &= 2\pi \int_0^{\infty} f_0 v_{\perp} dv_{\perp} \\ &= 2\pi n_0 \sqrt{\frac{\alpha_{\parallel}}{\pi}} e^{-\alpha_{\parallel} v_{\parallel}^2} \frac{\alpha_{\perp}}{\pi} \underbrace{\int_0^{\infty} v_{\perp} e^{-\alpha_{\perp} v_{\perp}^2} dv_{\perp}}_{=1/(2\alpha_{\perp})} = n_0 \sqrt{\frac{\alpha_{\parallel}}{\pi}} e^{-\alpha_{\parallel} v_{\parallel}^2}, \quad (4.48) \end{aligned}$$

and similarly

$$\begin{aligned} \int f_0 v_{\perp}^3 dv_{\perp} d\phi &= n_0 \sqrt{\frac{\alpha_{\parallel}}{\pi}} e^{-\alpha_{\parallel} v_{\parallel}^2} \frac{1}{\alpha_{\perp}}; & \int f_0 v_{\perp}^5 dv_{\perp} d\phi &= n_0 \sqrt{\frac{\alpha_{\parallel}}{\pi}} e^{-\alpha_{\parallel} v_{\parallel}^2} \frac{2}{\alpha_{\perp}^2}; \\ \int f_0 v_{\perp}^7 dv_{\perp} d\phi &= n_0 \sqrt{\frac{\alpha_{\parallel}}{\pi}} e^{-\alpha_{\parallel} v_{\parallel}^2} \frac{6}{\alpha_{\perp}^3}, \quad (4.49) \end{aligned}$$

and these are all of integrals over dv_{\perp} that are needed right now. The basic integrals (without singularity) calculate as

$$\begin{aligned} \int f_0 d^3 v &= n_0; & \int v_{\parallel} f_0 d^3 v &= 0; & \int v_{\perp}^2 f_0 d^3 v &= n_0 \frac{1}{2\alpha_{\parallel}}; \\ \int v_{\parallel}^3 f_0 d^3 v &= 0; & \int v_{\parallel}^4 f_0 d^3 v &= n_0 \frac{3}{4\alpha_{\parallel}^2}, \end{aligned} \tag{4.50}$$

and each integral yields further 3 cases from (4.49) just by multiplying, so

$$\begin{aligned} \int v_{\perp}^2 f_0 d^3 v &= n_0 \frac{1}{\alpha_{\perp}}; & \int v_{\perp}^4 f_0 d^3 v &= n_0 \frac{2}{\alpha_{\perp}^2}; & \int v_{\perp}^6 f_0 d^3 v &= n_0 \frac{6}{\alpha_{\perp}^3}; \\ \int v_{\parallel}^2 v_{\perp}^2 f_0 d^3 v &= n_0 \frac{1}{2\alpha_{\parallel}} \frac{1}{\alpha_{\perp}}; & \int v_{\parallel}^2 v_{\perp}^4 f_0 d^3 v &= n_0 \frac{1}{2\alpha_{\parallel}} \frac{2}{\alpha_{\perp}^2}; \\ \int v_{\parallel}^2 v_{\perp}^6 f_0 d^3 v &= n_0 \frac{1}{2\alpha_{\parallel}} \frac{6}{\alpha_{\perp}^3}; \\ \int v_{\parallel}^4 v_{\perp}^2 f_0 d^3 v &= n_0 \frac{3}{4\alpha_{\parallel}^2} \frac{1}{\alpha_{\perp}}; & \int v_{\parallel}^4 v_{\perp}^4 f_0 d^3 v &= n_0 \frac{3}{4\alpha_{\parallel}^2} \frac{2}{\alpha_{\perp}^2}; \\ \int v_{\parallel}^4 v_{\perp}^6 f_0 d^3 v &= n_0 \frac{3}{4\alpha_{\parallel}^2} \frac{6}{\alpha_{\perp}^3}. \end{aligned} \tag{4.51}$$

By using Landau integrals (2.54)–(2.58), the following integrals can be calculated

$$\begin{aligned} \int \frac{k_{\parallel} v_{\parallel} f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -n_0 R(\zeta); & \int \frac{k_{\parallel} v_{\parallel}^2 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta); \\ \int \frac{k_{\parallel} v_{\parallel}^3 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right); \\ \int \frac{k_{\parallel} v_{\parallel}^4 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^{3/2}} \text{sign}(k_{\parallel}) \left(\frac{1}{2} \zeta + \zeta^3 R(\zeta) \right); \\ \int \frac{k_{\parallel} v_{\parallel}^5 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^2} \left(\frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta) \right), \end{aligned} \tag{4.52}$$

and each of these integrals yields further 3 cases from (4.49) just by multiplying, so that

$$\begin{aligned} \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^2 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -n_0 R(\zeta) \frac{1}{\alpha_{\perp}}; & \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^4 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -n_0 R(\zeta) \frac{2}{\alpha_{\perp}^2}; \\ \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^6 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -n_0 R(\zeta) \frac{6}{\alpha_{\perp}^3}; \\ \int \frac{k_{\parallel} v_{\parallel}^2 v_{\perp}^2 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{1}{\alpha_{\perp}}; \\ \int \frac{k_{\parallel} v_{\parallel}^2 v_{\perp}^4 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{2}{\alpha_{\perp}^2}; \end{aligned} \tag{4.53}$$

$$\int \frac{k_{\parallel} v_{\parallel}^2 v_{\perp}^6 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v = -\frac{n_0}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{6}{\alpha_{\perp}^3}; \quad (4.54)$$

$$\begin{aligned} \int \frac{k_{\parallel} v_{\parallel}^3 v_{\perp}^2 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right) \frac{1}{\alpha_{\perp}}; \\ \int \frac{k_{\parallel} v_{\parallel}^3 v_{\perp}^4 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right) \frac{2}{\alpha_{\perp}^2}; \\ \int \frac{k_{\parallel} v_{\parallel}^3 v_{\perp}^6 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right) \frac{6}{\alpha_{\perp}^3}; \end{aligned} \quad (4.55)$$

$$\begin{aligned} \int \frac{k_{\parallel} v_{\parallel}^4 v_{\perp}^2 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^{3/2}} \text{sign}(k_{\parallel}) \left(\frac{1}{2} \zeta + \zeta^3 R(\zeta) \right) \frac{1}{\alpha_{\perp}}; \\ \int \frac{k_{\parallel} v_{\parallel}^4 v_{\perp}^4 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^{3/2}} \text{sign}(k_{\parallel}) \left(\frac{1}{2} \zeta + \zeta^3 R(\zeta) \right) \frac{2}{\alpha_{\perp}^2}; \\ \int \frac{k_{\parallel} v_{\parallel}^4 v_{\perp}^6 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^{3/2}} \text{sign}(k_{\parallel}) \left(\frac{1}{2} \zeta + \zeta^3 R(\zeta) \right) \frac{6}{\alpha_{\perp}^3}; \end{aligned} \quad (4.56)$$

$$\begin{aligned} \int \frac{k_{\parallel} v_{\parallel}^5 v_{\perp}^2 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^2} \left(\frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta) \right) \frac{1}{\alpha_{\perp}}; \\ \int \frac{k_{\parallel} v_{\parallel}^5 v_{\perp}^4 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^2} \left(\frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta) \right) \frac{2}{\alpha_{\perp}^2}; \\ \int \frac{k_{\parallel} v_{\parallel}^5 v_{\perp}^6 f_0}{\omega - k_{\parallel} v_{\parallel}} d^3 v &= -\frac{n_0}{\alpha_{\parallel}^2} \left(\frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta) \right) \frac{6}{\alpha_{\perp}^3}. \end{aligned} \quad (4.57)$$

Now it is easy to calculate the kinetic moments.

Density

The density calculates as

$$\begin{aligned} n^{(1)} &= \frac{B_z}{B_0} \alpha_{\perp} \left[\int v_{\perp}^2 f_0 d^3 v + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \right] + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel}}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \\ &= \frac{B_z}{B_0} \alpha_{\perp} \left[\frac{n_0}{\alpha_{\perp}} + \frac{\alpha_{\parallel}}{\alpha_{\perp}} (-n_0) R(\zeta) \frac{1}{\alpha_{\perp}} \right] + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} (-n_0) R(\zeta), \end{aligned}$$

so that the ratio

$$\frac{n^{(1)}}{n_0} = \frac{B_z}{B_0} \left[1 - \frac{\alpha_{\parallel}}{\alpha_{\perp}} R(\zeta) \right] - \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} R(\zeta),$$

and the final result reads

$$\frac{n^{(1)}}{n_0} = \frac{B_z}{B_0} \left[1 - \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} R(\zeta) \right] - \Phi \frac{q_r}{T_{\parallel}^{(0)}} R(\zeta). \quad (4.58)$$

Parallel velocity

The parallel velocity calculates as

$$\begin{aligned}
 n_0 u_{\parallel}^{(1)} &= \frac{B_z}{B_0} \alpha_{\perp} \left[\underbrace{\int v_{\parallel} v_{\perp}^2 f_0 \, d^3 v}_{=0} + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel}^2 v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 \, d^3 v \right] \\
 &+ \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 \, d^3 v \\
 &= -\frac{B_z}{B_0} \frac{n_0}{\sqrt{\alpha_{\parallel}}} \frac{\alpha_{\parallel}}{\alpha_{\perp}} \text{sign}(k_{\parallel}) \zeta R(\zeta) - \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \frac{n_0}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \\
 &= -\frac{n_0}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \left[\frac{B_z}{B_0} \frac{\alpha_{\parallel}}{\alpha_{\perp}} + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right], \tag{4.59}
 \end{aligned}$$

so that

$$u_{\parallel}^{(1)} = -\sqrt{\frac{2T_{\parallel}^{(0)}}{m_r}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \left[\frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]. \tag{4.60}$$

Parallel pressure

The parallel pressure calculates as

$$\begin{aligned}
 p_{\parallel}^{(1)} &= m_r \frac{B_z}{B_0} \alpha_{\perp} \left[\int v_{\parallel}^2 v_{\perp}^2 f_0 \, d^3 v + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel}^3 v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 \, d^3 v \right] \\
 &+ m_r \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel}^3}{(\omega - k_{\parallel} v_{\parallel})} f_0 \, d^3 v \\
 &= m_r \frac{B_z}{B_0} \alpha_{\perp} \left[\frac{n_0}{2\alpha_{\parallel} \alpha_{\perp}} - \frac{\alpha_{\parallel}}{\alpha_{\perp}} \frac{n_0}{\alpha_{\parallel}} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right) \frac{1}{\alpha_{\perp}} \right] \\
 &- m_r \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \frac{n_0}{\alpha_{\parallel}} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right),
 \end{aligned}$$

so that

$$\frac{p_{\parallel}^{(1)}}{n_0} = m_r \frac{B_z}{B_0} \frac{1}{2\alpha_{\parallel}} \left[1 - \frac{\alpha_{\parallel}}{\alpha_{\perp}} (1 + 2\zeta^2 R(\zeta)) \right] - \Phi q_r (1 + 2\zeta^2 R(\zeta)),$$

and

$$\begin{aligned}
 \frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} &= \frac{B_z}{B_0} \left[1 - \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} (1 + 2\zeta^2 R(\zeta)) \right] - \Phi \frac{q_r}{T_{\parallel}^{(0)}} (1 + 2\zeta^2 R(\zeta)) \\
 &= \frac{B_z}{B_0} - (1 + 2\zeta^2 R(\zeta)) \left[\frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]. \tag{4.61}
 \end{aligned}$$

Parallel temperature

The parallel temperature calculates (linearizing $p_{\parallel} = T_{\parallel}n$) as

$$\frac{T_{\parallel}^{(1)}}{T_{\parallel}^{(0)}} = \frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} - \frac{n^{(1)}}{n_0}, \quad (4.62)$$

that yields

$$\begin{aligned} \frac{T_{\parallel}^{(1)}}{T_{\parallel}^{(0)}} &= -\frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} (1 + 2\zeta^2 R(\zeta) - R(\zeta)) - \Phi \frac{q_r}{T_{\parallel}^{(0)}} (1 + 2\zeta^2 R(\zeta) - R(\zeta)) \\ &= - (1 + 2\zeta^2 R(\zeta) - R(\zeta)) \left[\frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]. \end{aligned} \quad (4.63)$$

Perpendicular pressure

The perpendicular pressure calculates as

$$\begin{aligned} p_{\perp}^{(1)} &= \frac{m_r B_z}{2 B_0} \alpha_{\perp} \left[\int v_{\perp}^4 f_0 d^3 v + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^4}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \right] \\ &\quad + \frac{m_r}{2} \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \\ &= \frac{m_r B_z}{2 B_0} \alpha_{\perp} \left[n_0 \frac{2}{\alpha_{\perp}^2} + \frac{\alpha_{\parallel}}{\alpha_{\perp}} (-n_0) R(\zeta) \frac{2}{\alpha_{\perp}^2} \right] + \frac{m_r}{2} \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} (-n_0) R(\zeta) \frac{1}{\alpha_{\perp}}, \end{aligned}$$

so that

$$\frac{p_{\perp}^{(1)}}{n_0} = m_r \frac{B_z}{B_0} \frac{1}{\alpha_{\perp}} \left[1 - \frac{\alpha_{\parallel}}{\alpha_{\perp}} R(\zeta) \right] - \Phi q_r \frac{\alpha_{\parallel}}{\alpha_{\perp}} R(\zeta), \quad (4.64)$$

further yielding

$$\frac{p_{\perp}^{(1)}}{p_{\perp}^{(0)}} = \frac{B_z}{B_0} 2 \left[1 - \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} R(\zeta) \right] - \Phi \frac{q_r}{T_{\parallel}^{(0)}} R(\zeta). \quad (4.65)$$

Perpendicular temperature

The perpendicular temperature calculates (linearizing $p_{\perp} = T_{\perp}n$) as

$$\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} = \frac{p_{\perp}^{(1)}}{p_{\perp}^{(0)}} - \frac{n^{(1)}}{n_0}, \quad (4.66)$$

that yields

$$\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} = \frac{B_z}{B_0} \left[1 - \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} R(\zeta) \right]. \quad (4.67)$$

We might be tired of calculations at this stage, but this result nicely shows that (at the linear level and at the long scales and low frequencies considered here) the Landau damping ($\sim E_z$) does not influence the perpendicular temperature, however, the transit-time damping still does.

Parallel heat flux

The parallel heat flux calculates as

$$\begin{aligned}
 q_{\parallel}^{(1)} &= m_r \frac{B_z}{B_0} \alpha_{\perp} \left[\underbrace{\int v_{\parallel}^3 v_{\perp}^2 f_0 d^3 v}_{=0} + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel}^4 v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \right] \\
 &+ m_r \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel}^4}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v - 3p_{\parallel}^{(0)} u_{\parallel}^{(1)} \\
 &= -m_r \frac{B_z}{B_0} \alpha_{\parallel} \frac{n_0}{\alpha_{\parallel}^{3/2}} \text{sign}(k_{\parallel}) \left(\frac{\zeta}{2} + \zeta^3 R(\zeta) \right) \frac{1}{\alpha_{\perp}} \\
 &- m_r \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \frac{n_0}{\alpha_{\parallel}^{3/2}} \text{sign}(k_{\parallel}) \left(\frac{\zeta}{2} + \zeta^3 R(\zeta) \right) - 3p_{\parallel}^{(0)} u_{\parallel}^{(1)} \\
 &= -\frac{n_0 m_r}{\alpha_{\parallel}^{3/2}} \text{sign}(k_{\parallel}) \left(\frac{\zeta}{2} + \zeta^3 R(\zeta) \right) \left[\frac{B_z}{B_0} \frac{\alpha_{\parallel}}{\alpha_{\perp}} + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right] - 3p_{\parallel}^{(0)} u_{\parallel}^{(1)},
 \end{aligned}$$

so that

$$\begin{aligned}
 \frac{q_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} &= -\frac{1}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) (\zeta + 2\zeta^3 R(\zeta)) \left[\frac{B_z}{B_0} \frac{\alpha_{\parallel}}{\alpha_{\perp}} + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right] - 3u_{\parallel}^{(1)} \\
 &= -\frac{1}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) (\zeta + 2\zeta^3 R(\zeta) - 3\zeta R(\zeta)) \left[\frac{B_z}{B_0} \frac{\alpha_{\parallel}}{\alpha_{\perp}} + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right], \tag{4.68}
 \end{aligned}$$

or alternatively

$$q_{\parallel}^{(1)} = -\sqrt{\frac{2T_{\parallel}^{(0)}}{m_r}} n_0 T_{\parallel}^{(0)} \text{sign}(k_{\parallel}) (\zeta + 2\zeta^3 R(\zeta) - 3\zeta R(\zeta)) \left[\frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]. \tag{4.69}$$

Perpendicular heat flux

The perpendicular heat flux calculates as

$$\begin{aligned}
 q_{\perp}^{(1)} &= \frac{m_r}{2} \frac{B_z}{B_0} \alpha_{\perp} \left[\underbrace{\int v_{\parallel} v_{\perp}^4 f_0 d^3 v}_{=0} + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel}^2 v_{\perp}^4}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \right] \\
 &+ \frac{m_r}{2} \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel}^2 v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v - p_{\perp}^{(0)} u_{\parallel}^{(1)} \\
 &= -\frac{m_r}{2} \frac{B_z}{B_0} \alpha_{\parallel} n_0 \frac{1}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{2}{\alpha_{\perp}^2} \\
 &- \frac{m_r}{2} \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} n_0 \frac{1}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{1}{\alpha_{\perp}} - p_{\perp}^{(0)} u_{\parallel}^{(1)} \\
 &= -\frac{m_r}{2} \frac{n_0}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{1}{\alpha_{\perp}} \left[\frac{B_z}{B_0} \frac{2\alpha_{\parallel}}{\alpha_{\perp}} + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right] - p_{\perp}^{(0)} u_{\parallel}^{(1)},
 \end{aligned}$$

so that

$$\begin{aligned} \frac{q_{\perp}^{(1)}}{p_{\perp}^{(0)}} &= -\frac{1}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \left[\frac{B_z}{B_0} \frac{2\alpha_{\parallel}}{\alpha_{\perp}} + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right] - u_{\parallel}^{(1)} \\ &= -\frac{1}{\sqrt{\alpha_{\parallel}}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{B_z}{B_0} \frac{\alpha_{\parallel}}{\alpha_{\perp}}, \end{aligned} \tag{4.70}$$

or alternatively

$$q_{\perp}^{(1)} = -\sqrt{\frac{2T_{\parallel}^{(0)}}{m_r}} p_{\perp}^{(0)} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{B_z}{B_0}. \tag{4.71}$$

The perpendicular heat flux $q_{\perp}^{(1)}$ (similarly to the perpendicular temperature $T_{\perp}^{(1)}$), is also not directly influenced by the Landau damping ($\sim E_z$), even though it is influenced by the transit-time damping ($\sim B_z$).

Fourth-order moment $r_{\parallel\parallel}$

The fourth-order moment $r_{\parallel\parallel}$ calculates as

$$\begin{aligned} r_{\parallel\parallel}^{(1)} &= m_r \frac{B_z}{B_0} \alpha_{\perp} \left[\int v_{\parallel}^4 v_{\perp}^2 f_0 d^3 v + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel}^5 v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \right] \\ &\quad + m_r \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel}^5}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \\ &= m_r \frac{B_z}{B_0} \alpha_{\perp} \left[n_0 \frac{3}{4\alpha_{\parallel}^2 \alpha_{\perp}} + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \frac{(-n_0)}{\alpha_{\parallel}^2} \left(\frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta) \right) \right] \frac{1}{\alpha_{\perp}} \\ &\quad + m_r \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \frac{(-n_0)}{\alpha_{\parallel}^2} \left(\frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta) \right) \\ &= m_r \frac{B_z}{B_0} n_0 \frac{3}{4\alpha_{\parallel}^2} - m_r n_0 \left(\frac{3}{4} + \frac{\zeta^2}{2} + \zeta^4 R(\zeta) \right) \frac{1}{\alpha_{\parallel}^2} \left[\frac{B_z}{B_0} \frac{\alpha_{\parallel}}{\alpha_{\perp}} + \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right], \end{aligned} \tag{4.72}$$

so that

$$r_{\parallel\parallel}^{(1)} = \frac{p_{\parallel}^{(0)} T_{\parallel}^{(0)}}{m_r} \left\{ 3 \frac{B_z}{B_0} - (3 + 2\zeta^2 + 4\zeta^4 R(\zeta)) \left[\frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right] \right\}. \tag{4.73}$$

Fourth-order moment deviation $\tilde{r}_{\parallel\parallel}$

The fourth-order moment ‘deviation’ $\tilde{r}_{\parallel\parallel}^{(1)}$ calculates as (linearizing $r_{\parallel\parallel} = (3/m_r)p_{\parallel}T_{\parallel} + \tilde{r}_{\parallel\parallel}$ with definitions $r_{\parallel\parallel}^{(0)} = (3/m_r)p_{\parallel}^{(0)}T_{\parallel}^{(0)}$ and $\tilde{r}_{\parallel\parallel}^{(0)} = 0$)

$$\frac{r_{\parallel\parallel}^{(1)}}{r_{\parallel\parallel}^{(0)}} = \frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} + \frac{T_{\parallel}^{(1)}}{T_{\parallel}^{(0)}} + \frac{\tilde{r}_{\parallel\parallel}^{(1)}}{r_{\parallel\parallel}^{(0)}}, \tag{4.74}$$

or equivalently

$$\tilde{r}_{\parallel\parallel}^{(1)} = r_{\parallel\parallel}^{(1)} - \frac{3}{m_r} p_{\parallel}^{(0)} T_{\parallel}^{(0)} \left(\frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} + \frac{T_{\parallel}^{(1)}}{T_{\parallel}^{(0)}} \right), \tag{4.75}$$

which yields

$$\tilde{r}_{\parallel\parallel}^{(1)} = -\frac{p_{\parallel}^{(0)} T_{\parallel}^{(0)}}{m_r} (2\zeta^2 + 4\zeta^4 R(\zeta) + 3R(\zeta) - 3 - 12\zeta^2 R(\zeta)) \left[\frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]. \tag{4.76}$$

Fourth-order moment $r_{\parallel\perp}$

The fourth-order moment $r_{\parallel\perp}$ calculates as

$$\begin{aligned}
 r_{\parallel\perp}^{(1)} &= \frac{m_r B_z}{2 B_0} \alpha_{\perp} \left[\int v_{\parallel}^2 v_{\perp}^4 f_0 d^3 v + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel}^3 v_{\perp}^4}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \right] \\
 &+ \frac{m_r \Phi q_r}{2 m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel}^3 v_{\perp}^2}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \\
 &= \frac{m_r B_z}{2 B_0} \alpha_{\perp} \left[\frac{n_0}{\alpha_{\parallel} \alpha_{\perp}^2} - \frac{\alpha_{\parallel}}{\alpha_{\perp}} n_0 \frac{2}{\alpha_{\parallel} \alpha_{\perp}^2} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right) \right] \\
 &- \frac{m_r \Phi q_r}{2 m_r} 2\alpha_{\parallel} \frac{n_0}{\alpha_{\parallel} \alpha_{\perp}} \left(\frac{1}{2} + \zeta^2 R(\zeta) \right) \\
 &= \frac{m_r B_z}{2 B_0} \frac{n_0}{\alpha_{\parallel} \alpha_{\perp}} - m_r n_0 \left(\frac{1}{2} + \zeta^2 R(\zeta) \right) \frac{1}{\alpha_{\parallel} \alpha_{\perp}} \left[\frac{B_z}{B_0} \frac{\alpha_{\parallel}}{\alpha_{\perp}} + \frac{1}{2} \Phi \frac{q_r}{m_r} 2\alpha_{\parallel} \right], \tag{4.77}
 \end{aligned}$$

so that

$$r_{\parallel\perp}^{(1)} = \frac{p_{\parallel}^{(0)} T_{\perp}^{(0)}}{m_r} \left\{ 2 \frac{B_z}{B_0} - (2 + 4\zeta^2 R(\zeta)) \left[\frac{B_z T_{\perp}^{(0)}}{B_0 T_{\parallel}^{(0)}} + \frac{1}{2} \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right] \right\}. \tag{4.78}$$

Fourth-order moment deviation $\tilde{r}_{\parallel\perp}$

The fourth-order moment ‘deviation’ $\tilde{r}_{\parallel\perp}^{(1)}$ calculates as (for example linearizing $r_{\parallel\perp} = (1/m_r)p_{\parallel} T_{\perp} + \tilde{r}_{\parallel\perp}$ with definitions $r_{\parallel\perp}^{(0)} = (1/m_r)p_{\parallel}^{(0)} T_{\perp}^{(0)}$ and $\tilde{r}_{\parallel\perp}^{(0)} = 0$)

$$\begin{aligned}
 r_{\parallel\perp}^{(1)} &= \frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} + \frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \frac{\tilde{r}_{\parallel\perp}^{(1)}}{r_{\parallel\perp}^{(0)}}, \tag{4.79}
 \end{aligned}$$

or equivalently

$$\tilde{r}_{\parallel\perp}^{(1)} = r_{\parallel\perp}^{(1)} - \frac{1}{m_r} p_{\parallel}^{(0)} T_{\perp}^{(0)} \left(\frac{p_{\parallel}^{(1)}}{p_{\parallel}^{(0)}} + \frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} \right), \tag{4.80}$$

and the result is

$$\tilde{r}_{\parallel\perp}^{(1)} = -\frac{p_{\perp}^{(0)} T_{\perp}^{(0)} B_z}{m_r B_0} (1 + 2\zeta^2 R(\zeta) - R(\zeta)). \tag{4.81}$$

Fourth-order moment $r_{\perp\perp}$

The fourth-order moment $r_{\perp\perp}$ calculates as

$$\begin{aligned}
 r_{\perp\perp}^{(1)} &= \frac{m_r B_z}{4 B_0} \alpha_{\perp} \left[\int v_{\perp}^6 f_0 d^3 v + \frac{\alpha_{\parallel}}{\alpha_{\perp}} \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^6}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \right] \\
 &+ \frac{m_r \Phi q_r}{4 m_r} 2\alpha_{\parallel} \int \frac{k_{\parallel} v_{\parallel} v_{\perp}^4}{(\omega - k_{\parallel} v_{\parallel})} f_0 d^3 v \\
 &= \frac{m_r B_z}{4 B_0} \alpha_{\perp} \left[n_0 \frac{6}{\alpha_{\perp}^3} - \frac{\alpha_{\parallel}}{\alpha_{\perp}} n_0 R(\zeta) \frac{6}{\alpha_{\perp}^3} \right] - \frac{m_r \Phi q_r}{4 m_r} 2\alpha_{\parallel} n_0 R(\zeta) \frac{2}{\alpha_{\perp}^2}, \tag{4.82}
 \end{aligned}$$

and the result is

$$r_{\perp\perp}^{(1)} = \frac{2p_{\perp}^{(0)} T_{\perp}^{(0)}}{m_r} \left\{ 3 \frac{B_z}{B_0} \left(1 - \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} R(\zeta) \right) - \Phi \frac{q_r}{T_{\parallel}^{(0)}} R(\zeta) \right\}. \tag{4.83}$$

Fourth-order moment deviation $\tilde{r}_{\perp\perp}$

The fourth-order moment deviation $\tilde{r}_{\perp\perp}^{(1)}$ calculates as (for example linearizing $r_{\perp\perp} = (2/m_r)p_{\perp}T_{\perp} + \tilde{r}_{\perp\perp}$ with definitions $r_{\perp\perp}^{(0)} = (2/m_r)p_{\perp}^{(0)}T_{\perp}^{(0)}$ and $\tilde{r}_{\perp\perp}^{(0)} = 0$)

$$\frac{r_{\perp\perp}^{(1)}}{r_{\perp\perp}^{(0)}} = \frac{p_{\perp}^{(1)}}{p_{\perp}^{(0)}} + \frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \frac{\tilde{r}_{\perp\perp}^{(1)}}{r_{\perp\perp}^{(0)}}, \quad (4.84)$$

or equivalently

$$\tilde{r}_{\perp\perp}^{(1)} = r_{\perp\perp}^{(1)} - \frac{2p_{\perp}^{(0)}T_{\perp}^{(0)}}{m_r} \left(\frac{p_{\perp}^{(1)}}{p_{\perp}^{(0)}} + \frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} \right), \quad (4.85)$$

which yields

$$\tilde{r}_{\perp\perp}^{(1)} = 0. \quad (4.86)$$

This is excellent news, since we will not have to consider closures for $\tilde{r}_{\perp\perp}^{(1)}$.

4.4. Landau fluid closures in three dimensions

Let us separate the kinetic moments into two groups. The first group

$$u_{\parallel}^{(1)} = -\sqrt{\frac{2T_{\parallel}^{(0)}}{m_r}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \left[\frac{B_z T_{\perp}^{(0)}}{B_0 T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]; \quad (4.87)$$

$$\frac{T_{\parallel}^{(1)}}{T_{\parallel}^{(0)}} = - (1 + 2\zeta^2 R(\zeta) - R(\zeta)) \left[\frac{B_z T_{\perp}^{(0)}}{B_0 T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]; \quad (4.88)$$

$$q_{\parallel}^{(1)} = -\sqrt{\frac{2T_{\parallel}^{(0)}}{m_r}} n_0 T_{\parallel}^{(0)} \text{sign}(k_{\parallel}) (\zeta + 2\zeta^3 R(\zeta) - 3\zeta R(\zeta)) \left[\frac{B_z T_{\perp}^{(0)}}{B_0 T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]; \quad (4.89)$$

$$\tilde{r}_{\parallel\parallel}^{(1)} = -\frac{p_{\parallel}^{(0)} T_{\parallel}^{(0)}}{m_r} (2\zeta^2 + 4\zeta^4 R(\zeta) + 3R(\zeta) - 3 - 12\zeta^2 R(\zeta)) \left[\frac{B_z T_{\perp}^{(0)}}{B_0 T_{\parallel}^{(0)}} + \Phi \frac{q_r}{T_{\parallel}^{(0)}} \right]. \quad (4.90)$$

And the second group

$$\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} = \left[1 - \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} R(\zeta) \right] \frac{B_z}{B_0}; \quad (4.91)$$

$$q_{\perp}^{(1)} = -\sqrt{\frac{2T_{\parallel}^{(0)}}{m_r}} p_{\perp}^{(0)} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} \text{sign}(k_{\parallel}) \zeta R(\zeta) \frac{B_z}{B_0}; \quad (4.92)$$

$$\tilde{r}_{\parallel\perp}^{(1)} = -\frac{p_{\perp}^{(0)} T_{\perp}^{(0)}}{m_r} (1 + 2\zeta^2 R(\zeta) - R(\zeta)) \frac{B_z}{B_0}. \quad (4.93)$$

One immediately notices that the moments in the first group, are extremely similar to the moments we obtained in the simplified case of a 1-D geometry, where we neglected the transit-time damping, i.e. in the system (3.20)–(3.26). In fact, the system

is completely the same, if the variable $(B_z/B_0)(T_{\perp}^{(0)}/T_{\parallel}^{(0)}) + \Phi(q_r/T_{\parallel}^{(0)})$ is replaced by $\Phi(q_r/T_{\parallel}^{(0)})$. Therefore, there is nothing more we can do here, and all the discussion and closures from the 1-D geometry, apply here in the 3-D geometry to closures for $q_{\parallel}^{(1)}$ and $\tilde{r}_{\parallel}^{(1)}$ without any changes. So for example,

$$R_{3,2}(\zeta) : q_{\parallel}^{(1)} = -\frac{2}{\sqrt{\pi}} n_0 v_{\text{th}\parallel} \text{isign}(k_{\parallel}) T_{\parallel}^{(1)}; \tag{4.94}$$

$$R_{4,3}(\zeta) : \tilde{r}_{\parallel}^{(1)} = -\frac{2\sqrt{\pi}}{(3\pi - 8)} v_{\text{th}\parallel} \text{isign}(k_{\parallel}) q_{\parallel}^{(1)} + \frac{(32 - 9\pi)}{2(3\pi - 8)} v_{\text{th}\parallel}^2 n_0 T_{\parallel}^{(1)}, \tag{4.95}$$

and similarly for all the other closures that we considered in the 1-D geometry.

4.4.1. *Closures for q_{\perp} and \tilde{r}_{\perp}*

For the second group, we do not have many choices and the calculations are simpler. In comparison to the first group, the expressions for $q_{\perp}^{(1)}$ and $\tilde{r}_{\perp}^{(1)}$ contain only powers ζ and ζ^2 . On one hand, this is good news since the analytic calculations are simpler and we will explore all possible cases of closure very quickly. On the other hand, this means that we will be able to use only relatively low-order Padé approximants to $R(\zeta)$, implying that the closures will be less accurate.

To easily spot closures, it is perhaps beneficial to use

$$v_{\text{th}\parallel} = \sqrt{\frac{2T_{\parallel}^{(0)}}{m_r}}; \quad a_p = \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}}; \quad \tilde{B}_z = \frac{B_z}{B_0}, \tag{4.96}$$

and the moments read

$$\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} = \tilde{B}_z [1 - a_p R(\zeta)]; \tag{4.97}$$

$$q_{\perp}^{(1)} = -v_{\text{th}\parallel} p_{\perp}^{(0)} a_p \text{sign}(k_{\parallel}) \tilde{B}_z [\zeta R(\zeta)]; \tag{4.98}$$

$$\tilde{r}_{\perp}^{(1)} = -v_{\text{th}\parallel}^2 p_{\perp}^{(0)} \frac{a_p}{2} \tilde{B}_z [1 + 2\zeta^2 R(\zeta) - R(\zeta)]. \tag{4.99}$$

Before proceeding with Padé approximants, it is very beneficial to briefly consider the limit $\zeta \ll 1$, where $R(\zeta) \rightarrow 1$. And a problem is immediately apparent. The quantities $q_{\perp}^{(1)}$ and $\tilde{r}_{\perp}^{(1)}$ are small and converge to zero, however, this is in general not true for the perpendicular temperature $T_{\perp}^{(1)}$, where the result depends on the temperature anisotropy ratio a_p . With anisotropic mean temperatures ($a_p \neq 1$), the quantity $T_{\perp}^{(1)}$ will remain finite and will not converge to zero due to coupling with magnetic field perturbations B_z , essentially because of conservation of the magnetic moment. The quantity $T_{\perp}^{(1)}$, at least as it is written now, is therefore not suitable for the construction of closures. Or in another words, the technique with Padé approximants of $R(\zeta)$ will not work, since the technique is based on matching the expressions for all ζ values. To consider closures, we have to separate this finite contribution, so that the Padé technique can be used, i.e. by writing

$$\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} = \tilde{B}_z [1 - a_p + a_p - a_p R(\zeta)] = \tilde{B}_z (1 - a_p) + \tilde{B}_z a_p [1 - R(\zeta)], \tag{4.100}$$

and by moving the finite contribution to the left-hand side

$$\underbrace{\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \tilde{B}_z(a_p - 1)}_{=\mathcal{T}_{\perp}} = \tilde{B}_z a_p [1 - R(\zeta)]. \quad (4.101)$$

Therefore, instead of looking for closures with $T_{\perp}^{(1)}$, we have to look for closures with a quantity that is proportional to the left-hand side of this equation, that we call \mathcal{T}_{\perp} (\mathcal{T} written with the ‘mathcal’ command in latex), and for clarity written with the full notation

$$\boxed{\mathcal{T}_{\perp} \equiv \frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \left(\frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} - 1 \right) \frac{B_z}{B_0};} \quad \boxed{\mathcal{T}_{\perp} = \frac{B_z}{B_0} \frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} [1 - R(\zeta)],} \quad (4.102)$$

where on the left is the definition of the new quantity, and on the right is the kinetic moment that this new quantity satisfies. Only now we are ready to use the Padé approximants of $R(\zeta)$ and construct closures.

4.4.2. One-pole closure

By using approximant $R_1(\zeta)$, the moments calculate as

$$R_1(\zeta): \quad D = (1 - i\sqrt{\pi}\zeta); \quad (4.103)$$

$$\mathcal{T}_{\perp} = a_p \tilde{B}_z \frac{1}{D} [-i\sqrt{\pi}\zeta]; \quad (4.104)$$

$$q_{\perp}^{(1)} = -v_{\text{th}\parallel} p_{\perp}^{(0)} a_p \text{sign}(k_{\parallel}) \tilde{B}_z \frac{1}{D} [\zeta]; \quad (4.105)$$

$$\tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2 p_{\perp}^{(0)} \frac{a_p}{2} \tilde{B}_z \frac{1}{D} [2\zeta^2 - i\sqrt{\pi}\zeta], \quad (4.106)$$

and the heat flux $q_{\perp}^{(1)}$ can be directly expressed through \mathcal{T}_{\perp} according to

$$R_1(\zeta): \quad q_{\perp}^{(1)} = -\frac{p_{\perp}^{(0)}}{\sqrt{\pi}} v_{\text{th}\parallel} i \text{sign}(k_{\parallel}) \mathcal{T}_{\perp}, \quad (4.107)$$

and using full notation and transforming to real space

$$\boxed{R_1(\zeta): \quad q_{\perp}^{(1)} = -\frac{p_{\perp}^{(0)}}{\sqrt{\pi}} v_{\text{th}\parallel} \mathcal{H} \left[\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \left(\frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} - 1 \right) \frac{B_z}{B_0} \right].} \quad (4.108)$$

Up to the replacement of B_z with $|\mathbf{B}|$, the closure is equivalent, for example, to (40) of Snyder *et al.* (1997) (their thermal speeds do not contain the factors of 2). The closure is similar to the corresponding closure for the parallel heat flux (4.94), and for isotropic temperatures the term $\sim B_z$ disappears. The closure is therefore very useful for understanding the collisionless heat flux, however, the closure is not very accurate and for $\zeta \gg 1$, the heat flux (4.105) does not disappear and instead, converges to an

asymptotic value. Alternatively, since later on, the normalization is always done with respect to parallel quantities

$$R_1(\zeta) : \frac{q_{\perp}^{(1)}}{p_{\parallel}^{(0)}} = -\frac{v_{\text{th}\parallel}}{\sqrt{\pi}} \mathcal{H} \left[\frac{T_{\perp}^{(1)}}{T_{\parallel}^{(0)}} + a_p (a_p - 1) \frac{B_z}{B_0} \right], \tag{4.109}$$

and when the temperature $T_{\perp}^{(1)}$ is expressed through the pressure and density, it is useful to note the difference between

$$\begin{aligned} \frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} &= \frac{p_{\perp}^{(1)}}{p_{\perp}^{(0)}} - \frac{n^{(1)}}{n_0}; \\ \frac{T_{\perp}^{(1)}}{T_{\parallel}^{(0)}} &= \frac{p_{\perp}^{(1)}}{p_{\parallel}^{(0)}} - a_p \frac{n^{(1)}}{n_0}. \end{aligned} \tag{4.110}$$

4.4.3. *Two-pole closures*

Continuing with the $R_{2,0}(\zeta)$ approximant, the moments calculate as

$$R_{2,0}(\zeta) : D = (1 - i\sqrt{\pi}\zeta - 2\zeta^2); \tag{4.111}$$

$$\mathcal{T}_{\perp} = a_p \tilde{B}_z \frac{1}{D} [-2\zeta^2 - i\sqrt{\pi}\zeta]; \tag{4.112}$$

$$q_{\perp}^{(1)} = -v_{\text{th}\parallel} p_{\perp}^{(0)} a_p \text{sign}(k_{\parallel}) \tilde{B}_z \frac{1}{D} [\zeta]; \tag{4.113}$$

$$\tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2 p_{\perp}^{(0)} \frac{a_p}{2} \tilde{B}_z \frac{1}{D} [-i\sqrt{\pi}\zeta]. \tag{4.114}$$

The $\tilde{r}_{\parallel\perp}^{(1)}$ can be expressed through $q_{\perp}^{(1)}$ and the closure reads

$$R_{2,0}(\zeta) : \tilde{r}_{\parallel\perp}^{(1)} = -\frac{\sqrt{\pi}}{2} v_{\text{th}\parallel} i \text{sign}(k_{\parallel}) q_{\perp}^{(1)}, \tag{4.115}$$

or in real space

$$\boxed{R_{2,0}(\zeta) : \tilde{r}_{\parallel\perp}^{(1)} = -\frac{\sqrt{\pi}}{2} v_{\text{th}\parallel} \mathcal{H} q_{\perp}^{(1)}}. \tag{4.116}$$

The closure with $R_{2,0}(\zeta)$ is naturally more precise than the closure with $R_1(\zeta)$, and both $q_{\perp}^{(1)}$ and $\tilde{r}_{\parallel\perp}^{(1)}$ at least converge to zero for $\zeta \gg 1$. The closure is equivalent to (35) of Snyder *et al.* (1997).

There are 3 other closures that can be constructed with $R_{2,0}(\zeta)$, all of them time dependent. The first one is obtained by searching for $(\zeta + \alpha_q) q_{\perp}^{(1)} = \alpha_T \mathcal{T}_{\perp}$, and the solution is

$$\begin{aligned} R_{2,0}(\zeta) : \left[\zeta + \frac{i\sqrt{\pi}}{2} \right] q_{\perp}^{(1)} &= \frac{p_{\perp}^{(0)}}{2} v_{\text{th}\parallel} \text{sign}(k_{\parallel}) \mathcal{T}_{\perp}; \\ \left[-i\omega + \frac{\sqrt{\pi}}{2} v_{\text{th}\parallel} |k_{\parallel}| \right] q_{\perp}^{(1)} &= -\frac{p_{\perp}^{(0)}}{2} v_{\text{th}\parallel}^2 i k_{\parallel} \mathcal{T}_{\perp}, \end{aligned} \tag{4.117}$$

and in real space

$$R_{2,0}(\zeta) : \left[\frac{d}{dt} - \frac{\sqrt{\pi}}{2} v_{\text{th}\parallel} \partial_z \mathcal{H} \right] q_{\perp}^{(1)} = -\frac{p_{\perp}^{(0)}}{2} v_{\text{th}\parallel}^2 \partial_z \left[\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \left(\frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} - 1 \right) \frac{B_z}{B_0} \right]. \quad (4.118)$$

Alternatively, considering future normalization with parallel quantities

$$R_{2,0}(\zeta) : \left[\frac{d}{dt} - \frac{\sqrt{\pi}}{2} v_{\text{th}\parallel} \partial_z \mathcal{H} \right] \frac{q_{\perp}^{(1)}}{p_{\parallel}^{(0)}} = -\frac{v_{\text{th}\parallel}^2}{2} \partial_z \left[\frac{T_{\perp}^{(1)}}{T_{\parallel}^{(0)}} + a_p (a_p - 1) \frac{B_z}{B_0} \right]. \quad (4.119)$$

The closures (4.118) and (4.116) are related. In the companion paper (Part 1), we derived a ‘fluid’ nonlinear equation for the perpendicular heat flux $\partial q_{\perp} / \partial t$. Linearizing this equation yields

$$\frac{\partial q_{\perp}^{(1)}}{\partial t} + \partial_z \tilde{r}_{\parallel\perp}^{(1)} + \frac{n_0}{2} v_{\text{th}\parallel}^2 \partial_z T_{\perp}^{(1)} + \frac{p_{\perp}^{(0)}}{2} v_{\text{th}\parallel}^2 (a_p - 1) \partial_z \frac{B_z}{B_0} = 0, \quad (4.120)$$

where since at the linear level $\partial_z \hat{b}_z \stackrel{\text{lin}}{=} 0$, the quantity $\nabla \cdot \hat{\mathbf{b}} \stackrel{\text{lin}}{=} (1/B_0)(\partial_x B_x + \partial_y B_y) = -(1/B_0)\partial_z B_z$. Now, plugging the quasi-static closure (4.116) into the linearized heat flux equation (4.120), immediately recovers the time-dependent closure (4.118). As discussed before, the difference between B_z and $|\mathbf{B}|$ again arises only from how ‘deeply’ the linearization is done. For example, exact calculation of $\nabla \cdot \hat{\mathbf{b}}$ yields

$$\nabla \cdot \hat{\mathbf{b}} = \nabla \cdot \left(\frac{\mathbf{B}}{|\mathbf{B}|} \right) = \frac{1}{|\mathbf{B}|} \underbrace{\nabla \cdot \mathbf{B}}_{=0} + \mathbf{B} \cdot \nabla \left(\frac{1}{|\mathbf{B}|} \right) = -\frac{\hat{\mathbf{b}}}{|\mathbf{B}|} \cdot \nabla |\mathbf{B}|, \quad (4.121)$$

and instead of linearizing completely, it is possible to stop the linearization at the level $\nabla \cdot \hat{\mathbf{b}} \stackrel{\text{lin}}{=} -(1/B_0)\partial_z |\mathbf{B}|$.

Another closure can be constructed by searching for $(\zeta + \alpha_r)r_{\parallel\perp}^{(1)} = \alpha_T \mathcal{T}_{\perp}$, and the solution is

$$\begin{aligned} R_{2,0}(\zeta) : \quad & \left[\zeta + \frac{i\sqrt{\pi}}{2} \right] r_{\parallel\perp}^{(1)} = -\frac{i\sqrt{\pi}}{4} p_{\perp}^{(0)} v_{\text{th}\parallel}^2 \mathcal{T}_{\perp}; \\ & \left[-i\omega + \frac{\sqrt{\pi}}{2} v_{\text{th}\parallel} |k_{\parallel}| \right] r_{\parallel\perp}^{(1)} = -\frac{\sqrt{\pi}}{4} p_{\perp}^{(0)} v_{\text{th}\parallel}^3 |k_{\parallel}| \mathcal{T}_{\perp}; \\ & \left[\frac{d}{dt} - \frac{\sqrt{\pi}}{2} v_{\text{th}\parallel} \partial_z \mathcal{H} \right] r_{\parallel\perp}^{(1)} = +\frac{\sqrt{\pi}}{4} p_{\perp}^{(0)} v_{\text{th}\parallel}^3 \partial_z \mathcal{H} \left[\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \left(\frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} - 1 \right) \frac{B_z}{B_0} \right], \end{aligned} \quad (4.122)$$

and yet another related one by searching for $\zeta r_{\parallel\perp}^{(1)} = \alpha_q q_{\perp}^{(1)} + \alpha_T \mathcal{T}_{\perp}$, with solution

$$\begin{aligned} R_{2,0}(\zeta) : \quad & \zeta r_{\parallel\perp}^{(1)} = -\frac{\pi}{4} v_{\text{th}\parallel} \text{sign}(k_{\parallel}) q_{\perp}^{(1)} - \frac{i\sqrt{\pi}}{4} p_{\perp}^{(0)} v_{\text{th}\parallel}^2 \mathcal{T}_{\perp}; \\ & -i\omega r_{\parallel\perp}^{(1)} = +\frac{\pi}{4} v_{\text{th}\parallel}^2 i k_{\parallel} q_{\perp}^{(1)} - \frac{\sqrt{\pi}}{4} p_{\perp}^{(0)} v_{\text{th}\parallel}^3 |k_{\parallel}| \mathcal{T}_{\perp}; \end{aligned} \quad (4.124)$$

$$\frac{d}{dt}r_{\parallel\perp}^{(1)} = +\frac{\pi}{4}v_{\text{th}\parallel}^2\partial_z q_{\perp}^{(1)} + \frac{\sqrt{\pi}}{4}p_{\perp}^{(0)}v_{\text{th}\parallel}^3\partial_z\mathcal{H}\left[\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \left(\frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} - 1\right)\frac{B_z}{B_0}\right]. \tag{4.125}$$

The last closure (4.125) can also be directly obtained from (4.123) by using the quasi-static closure (4.116) and $\mathcal{H}\mathcal{H} = -1$. Both closures (4.125), (4.123) are not very interesting, since the quasi-static closure (4.116) for $r_{\parallel\perp}^{(1)}$ and the time-dependent closure (4.118) for the heat flux $q_{\perp}^{(1)}$ are of the same precision and much simpler to implement. Importantly, after checking the dispersion relations, closure (4.125) has to be disregarded since it can produce positive growth rate.

For completeness, there is also 1 time-dependent closure with $R_{2,1}$ approximant $\zeta q_{\perp}^{(1)} = \alpha_T \mathcal{T}_{\perp}$ that is not considered and is disregarded, since that approximant is not well behaved.

4.4.4. *Three-pole closures*

As in the 1-D case, we can suppress writing the proportionality constants (including the minus signs) and concentrate only on expressions inside of the big brackets. Continuing with the $R_{3,1}(\zeta)$ approximant

$$R_{3,1}(\zeta) : D = \left(1 - \frac{4i}{\sqrt{\pi}}\zeta - 2\zeta^2 + 2i\frac{(4-\pi)}{\sqrt{\pi}}\zeta^3\right); \tag{4.126}$$

$$\mathcal{T}_{\perp} \sim \frac{1}{D} \left[2i\frac{(4-\pi)}{\sqrt{\pi}}\zeta^3 - 2\zeta^2 - i\sqrt{\pi}\zeta\right]; \tag{4.127}$$

$$q_{\perp}^{(1)} \sim \frac{1}{D} \left[-i\frac{(4-\pi)}{\sqrt{\pi}}\zeta^2 + \zeta\right]; \tag{4.128}$$

$$\tilde{r}_{\parallel\perp}^{(1)} \sim \frac{1}{D} [-i\sqrt{\pi}\zeta]. \tag{4.129}$$

No quasi-static closures are possible. A time-dependent closure can be constructed by searching for $(\zeta + \alpha_r)\tilde{r}_{\parallel\perp}^{(1)} = \alpha_q q_{\perp}^{(1)}$, and the solution reads

$$R_{3,1}(\zeta) : \begin{cases} \left[\zeta + \frac{i\sqrt{\pi}}{4-\pi}\right]\tilde{r}_{\parallel\perp}^{(1)} = v_{\text{th}\parallel}\frac{\pi}{2(4-\pi)}\text{sign}(k_{\parallel})q_{\perp}^{(1)}; \\ \left[-i\omega + \frac{\sqrt{\pi}}{4-\pi}v_{\text{th}\parallel}|k_{\parallel}|\right]\tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2\frac{\pi}{2(4-\pi)}ik_{\parallel}q_{\perp}^{(1)}, \end{cases} \tag{4.130}$$

and in real space

$$R_{3,1}(\zeta) : \left[\frac{d}{dt} - \frac{\sqrt{\pi}}{4-\pi}v_{\text{th}\parallel}\partial_z\mathcal{H}\right]\tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2\frac{\pi}{2(4-\pi)}\partial_z q_{\perp}^{(1)}. \tag{4.131}$$

Continuing with the $R_{3,2}(\zeta)$ approximant

$$R_{3,2}(\zeta) : D = \left(1 - \frac{3}{2}i\sqrt{\pi}\zeta - 2\zeta^2 + i\sqrt{\pi}\zeta^3\right); \tag{4.132}$$

$$\mathcal{T}_{\perp} \sim \frac{1}{D} [i\sqrt{\pi}\zeta^3 - 2\zeta^2 - i\sqrt{\pi}\zeta]; \tag{4.133}$$

$$q_{\perp}^{(1)} \sim \frac{1}{D} \left[-\frac{i}{2} \sqrt{\pi} \zeta^2 + \zeta \right]; \tag{4.134}$$

$$\tilde{r}_{\parallel\perp}^{(1)} \sim \frac{1}{D} [-i\sqrt{\pi}\zeta]. \tag{4.135}$$

Searching for $(\zeta + \alpha_r)\tilde{r}_{\parallel\perp}^{(1)} = \alpha_q q_{\perp}^{(1)}$, yields a closure

$$R_{3,2}(\zeta) : \begin{cases} \left[\zeta + \frac{2i}{\sqrt{\pi}} \right] \tilde{r}_{\parallel\perp}^{(1)} = v_{\text{th}\parallel} \text{sign}(k_{\parallel}) q_{\perp}^{(1)}; \\ \left[-i\omega + \frac{2}{\sqrt{\pi}} v_{\text{th}\parallel} |k_{\parallel}| \right] \tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2 i k_{\parallel} q_{\perp}^{(1)}, \end{cases} \tag{4.136}$$

and in real space

$$R_{3,2}(\zeta) : \left[\frac{d}{dt} - \frac{2}{\sqrt{\pi}} v_{\text{th}\parallel} \partial_z \mathcal{H} \right] \tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2 \partial_z q_{\perp}^{(1)}. \tag{4.137}$$

Closures (4.131), (4.137) are equivalent to the closures of Passot & Sulem (2007), after one prescribes the gyrotropic limit in that paper (and replaces the wrong coefficient in the $R_{3,1}(\zeta)$ closure introduced by Hedrick & Leboeuf (1992)).

Finally, it is indeed possible to construct an $o(\zeta^3)$ closure for the perpendicular quantities considered, by using the $R_{3,0}(\zeta)$ approximant. The moments calculate as

$$R_{3,0}(\zeta) : D = \left(1 - i \frac{\sqrt{\pi}}{4 - \pi} \zeta - \frac{3\pi - 8}{4 - \pi} \zeta^2 + 2i\sqrt{\pi} \frac{\pi - 3}{4 - \pi} \zeta^3 \right); \tag{4.138}$$

$$\mathcal{T}_{\perp} \sim \frac{1}{D} \left[2i\sqrt{\pi} \frac{\pi - 3}{4 - \pi} \zeta^3 - \frac{3\pi - 8}{4 - \pi} \zeta^2 - i\sqrt{\pi} \zeta \right]; \tag{4.139}$$

$$q_{\perp}^{(1)} \sim \frac{1}{D} \left[-i\sqrt{\pi} \frac{\pi - 3}{4 - \pi} \zeta^2 + \zeta \right]; \tag{4.140}$$

$$\tilde{r}_{\parallel\perp}^{(1)} \sim \frac{1}{D} \left[\frac{16 - 5\pi}{4 - \pi} \zeta^2 - i\sqrt{\pi} \zeta \right], \tag{4.141}$$

and by searching for $(\zeta + \alpha_r)\tilde{r}_{\parallel\perp}^{(1)} = \alpha_q q_{\perp}^{(1)} + \alpha_r \mathcal{T}_{\perp}$ yields a closure

$$R_{3,0}(\zeta) : \begin{cases} \left[\zeta + \frac{i}{2\sqrt{\pi}} \frac{(3\pi - 8)}{(\pi - 3)} \right] \tilde{r}_{\parallel\perp}^{(1)} = v_{\text{th}\parallel} \frac{4 - \pi}{2(\pi - 3)} \text{sign}(k_{\parallel}) q_{\perp}^{(1)} \\ \quad + p_{\perp}^{(0)} v_{\text{th}\parallel}^2 \frac{i}{4\sqrt{\pi}} \frac{(16 - 5\pi)}{(\pi - 3)} \mathcal{T}_{\perp}; \\ \left[-i\omega + \frac{(3\pi - 8)}{2\sqrt{\pi}(\pi - 3)} v_{\text{th}\parallel} |k_{\parallel}| \right] \tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2 \frac{4 - \pi}{2(\pi - 3)} i k_{\parallel} q_{\perp}^{(1)} \\ \quad + p_{\perp}^{(0)} v_{\text{th}\parallel}^3 \frac{(16 - 5\pi)}{4\sqrt{\pi}(\pi - 3)} |k_{\parallel}| \mathcal{T}_{\perp}, \end{cases} \tag{4.142}$$

and the full expression in real space reads (Hunana *et al.* 2018)

$$R_{3,0}(\zeta) : \left[\frac{d}{dt} - \frac{(3\pi - 8)}{2\sqrt{\pi}(\pi - 3)} v_{\text{th}\parallel} \partial_z \mathcal{H} \right] \tilde{r}_{\parallel\perp}^{(1)} = -v_{\text{th}\parallel}^2 \frac{4 - \pi}{2(\pi - 3)} \partial_z q_{\perp}^{(1)} - p_{\perp}^{(0)} v_{\text{th}\parallel}^3 \frac{(16 - 5\pi)}{4\sqrt{\pi}(\pi - 3)} \partial_z \mathcal{H} \left[\frac{T_{\perp}^{(1)}}{T_{\perp}^{(0)}} + \left(\frac{T_{\perp}^{(0)}}{T_{\parallel}^{(0)}} - 1 \right) \frac{B_z}{B_0} \right], \tag{4.143}$$

or again considering normalization with respect to parallel quantities

$$R_{3,0}(\zeta) : \left[\frac{d}{dt} - \frac{(3\pi - 8)}{2\sqrt{\pi}(\pi - 3)} v_{\text{th}\parallel} \partial_z \mathcal{H} \right] \frac{\tilde{r}_{\parallel\perp}^{(1)}}{p_{\parallel}^{(0)}} = -v_{\text{th}\parallel}^2 \frac{4 - \pi}{2(\pi - 3)} \partial_z \frac{q_{\perp}^{(1)}}{p_{\parallel}^{(0)}} - v_{\text{th}\parallel}^3 \frac{(16 - 5\pi)}{4\sqrt{\pi}(\pi - 3)} \partial_z \mathcal{H} \left[\frac{T_{\perp}^{(1)}}{T_{\parallel}^{(0)}} + a_p (a_p - 1) \frac{B_z}{B_0} \right]. \tag{4.144}$$

The $R_{3,0}(\zeta)$ has precision $o(\zeta^3)$, $o(1/\zeta^2)$.

4.5. Table of moments (T_{\perp} , q_{\perp} , $\tilde{r}_{\parallel\perp}$) for various Padé approximants

The following summarizing table for quantities $\mathcal{T}_{\perp}(T_{\perp}^{(1)})$, $q_{\perp}^{(1)}$, $\tilde{r}_{\parallel\perp}^{(1)}$ is created to clearly see the possibilities of a closure. All the proportionality constants (including the minus signs) and including the common denominator of $R(\zeta)$, are suppressed here. The approximants $R_{2,1}$, $R_{4,5}$, $R_{6,9}$, $R_{8,13}$ are marked with an asterisk ‘*’, because these do not account for the Landau residue and are not well behaved. These approximants are provided only for completeness and should be disregarded.

One-pole and two-pole approximants

	R_1	$R_{2,0}$	$R_{2,1}^*$
\mathcal{T}_{\perp}	ζ	ζ^2, ζ	ζ^2
$q_{\perp}^{(1)}$	ζ	ζ	ζ
$\tilde{r}_{\parallel\perp}^{(1)}$	ζ^2, ζ	ζ	0

Three-pole approximants

	$R_{3,0}$	$R_{3,1}$	$R_{3,2}$
\mathcal{T}_{\perp}	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ	ζ^3, ζ^2, ζ
$q_{\perp}^{(1)}$	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ
$\tilde{r}_{\parallel\perp}^{(1)}$	ζ^2, ζ	ζ	ζ

Four-pole approximants

	$R_{4,0}$	$R_{4,1}$	$R_{4,2}$	$R_{4,3}$	$R_{4,4}$	$R_{4,5}^*$
\mathcal{T}_{\perp}	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$	ζ^4, ζ^2
$q_{\perp}^{(1)}$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	$\zeta^3 \dots \zeta$	ζ^3, ζ
$\tilde{r}_{\parallel\perp}^{(1)}$	$\zeta^3 \dots \zeta$	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2, ζ	ζ^2

Five-pole and six-pole approximants

	$R_{5,0}$	$R_{5,1}$...	$R_{5,6}$	$R_{6,0}$	$R_{6,1}$...	$R_{6,8}$	$R_{6,9}^*$
\mathcal{T}_{\perp}	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$...	$\zeta^5 \dots \zeta$	$\zeta^6 \dots \zeta$	$\zeta^6 \dots \zeta$...	$\zeta^6 \dots \zeta$	$\zeta^6, \zeta^4, \zeta^2$
$q_{\perp}^{(1)}$	$\zeta^4 \dots \zeta$	$\zeta^4 \dots \zeta$...	$\zeta^4 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^5 \dots \zeta$...	$\zeta^5 \dots \zeta$	ζ^5, ζ^3, ζ
$\tilde{r}_{\parallel\perp}^{(1)}$	$\zeta^4 \dots \zeta$	$\zeta^3 \dots \zeta$...	$\zeta^3 \dots \zeta$	$\zeta^5 \dots \zeta$	$\zeta^4 \dots \zeta$...	$\zeta^4 \dots \zeta$	ζ^4, ζ^2

Seven-pole and eight-pole approximants

	$R_{7,0}$	$R_{7,1}$...	$R_{7,10}$	$R_{8,0}$	$R_{8,1}$...	$R_{8,12}$	$R_{8,13}^*$
\mathcal{T}	$\zeta^7 \dots \zeta$	$\zeta^7 \dots \zeta$...	$\zeta^7 \dots \zeta$	$\zeta^8 \dots \zeta$	$\zeta^8 \dots \zeta$...	$\zeta^8 \dots \zeta$	$\zeta^8, \zeta^6, \zeta^4, \zeta^2$
$q_{\perp}^{(1)}$	$\zeta^6 \dots \zeta$	$\zeta^6 \dots \zeta$...	$\zeta^6 \dots \zeta$	$\zeta^7 \dots \zeta$	$\zeta^7 \dots \zeta$...	$\zeta^7 \dots \zeta$	$\zeta^7, \zeta^5, \zeta^3, \zeta$
$\tilde{r}_{\parallel\perp}^{(1)}$	$\zeta^6 \dots \zeta$	$\zeta^5 \dots \zeta$...	$\zeta^5 \dots \zeta$	$\zeta^7 \dots \zeta$	$\zeta^6 \dots \zeta$...	$\zeta^6 \dots \zeta$	$\zeta^6, \zeta^4, \zeta^2$

By observing the table, there are altogether 2 possible quasi-static closures,

$$\begin{aligned} R_1: \quad q_{\perp}^{(1)} &= \alpha_T \mathcal{T}_{\perp}; \\ R_{2,0}: \quad \tilde{r}_{\parallel\perp}^{(1)} &= \alpha_q q_{\perp}^{(1)}, \end{aligned} \quad (4.145)$$

and 6 time-dependent closures,

$$\begin{aligned} R_{2,0}: \quad (\zeta + \alpha_q) q_{\perp}^{(1)} &= \alpha_T \mathcal{T}_{\perp}; \quad (\zeta + \alpha_r) \tilde{r}_{\parallel\perp}^{(1)} = \alpha_T \mathcal{T}_{\perp}; \quad \zeta \tilde{r}_{\parallel\perp}^{(1)} = \alpha_q q_{\perp}^{(1)} + \alpha_T \mathcal{T}_{\perp}; \\ R_{3,0}: \quad (\zeta + \alpha_r) \tilde{r}_{\parallel\perp}^{(1)} &= \alpha_q q_{\perp}^{(1)} + \alpha_T \mathcal{T}_{\perp}; \\ R_{3,1}: \quad (\zeta + \alpha_r) \tilde{r}_{\parallel\perp}^{(1)} &= \alpha_q q_{\perp}^{(1)}; \\ R_{3,2}: \quad (\zeta + \alpha_r) \tilde{r}_{\parallel\perp}^{(1)} &= \alpha_q q_{\perp}^{(1)}. \end{aligned} \quad (4.146)$$

We briefly checked the dispersion relations that these closures yield for parallel propagation (proton species only, electrons cold), where the $q_{\perp}^{(1)}$ and $\tilde{r}_{\parallel\perp}^{(1)}$ closures produce only higher-order modes. This eliminated one $R_{2,0}$ closure that produced a growing mode. The R_1 closure yields $\zeta = -i/\sqrt{\pi}$; the remaining $R_{2,0}$ closures yield $\zeta = \pm\sqrt{8-\pi}/4 - i\sqrt{\pi}/4$ (result reported also in the Appendix of Hunana *et al.* (2011)), the $R_{3,0}$ closure yields $\zeta = \pm 0.92 - 0.91i$; $\zeta = -1.02i$; the $R_{3,1}$ closure yields $\zeta = \pm 0.96 - 0.64i$; $\zeta = -0.78i$; and the $R_{3,2}$ closure yields $\zeta = \pm 1.04 - 0.33i$; $\zeta = -0.47i$.

5. Conclusions

We offer a brief summary of the major results discussed throughout the text.

- The kinetic Vlasov equation implicitly contains ‘singularities’ in velocity space, referred to as wave–particle resonances. These resonances occur because particles of a given species travelling along magnetic field lines with a velocity component v_{\parallel} interact with plasma waves propagating in that system with a parallel phase speed $(\omega + n\Omega)/k_{\parallel}$, where Ω is the cyclotron frequency for that given species and $n = 0, \pm 1, \pm 2 \dots$ is an integer. Wave–particle resonances can be separated into Landau resonances ($n = 0$) and cyclotron resonances ($n \neq 0$).
- The presence of wave–particle resonances in the Vlasov equation is revealed by considering perturbations $f^{(1)} = f - f_0$ around an equilibrium distribution function f_0 , and by obtaining an explicit expression for $f^{(1)}$ that satisfies the Vlasov equation. For example, in a simplified 1-D electrostatic geometry (which can be viewed as electrostatic propagation along \mathbf{B}_0), the perturbations read $f^{(1)} = -(iqE_{\parallel}/m)(\partial f_0/\partial v_{\parallel})/(\omega - v_{\parallel}k_{\parallel})$, and contain Landau resonances.
- Obtaining $f^{(1)}$ in a general 3-D electromagnetic geometry requires quite a complicated procedure of integration along an unperturbed orbit (zero-order trajectory, from time $t' = -\infty$ to $t' = t$), see (2.15). The procedure can be considered as a core of any plasma book and here it is summarized in appendix C. General $f^{(1)}$ perturbations around a gyrotropic f_0 are given by (C 47). Prescribing a bi-Maxwellian f_0 yields (C 53), and prescribing a bi-kappa f_0 yields (C 57). Obviously, perturbations $f^{(1)} \sim 1/(\omega - v_{\parallel}k_{\parallel} - n\Omega)$, and contain Landau resonances and cyclotron resonances.

- After an $f^{(1)}$ is obtained, integration over velocity space can be performed, eventually yielding an infinite hierarchy of ‘kinetic’ moments. Combining Maxwell’s equations $\nabla \times \mathbf{B} = (4\pi/c)\mathbf{j} + (1/c)\partial\mathbf{E}/\partial t$ and $\nabla \times \mathbf{E} = -(1/c)\partial\mathbf{B}/\partial t$ yields the following wave equation

$$\mathbf{k} \times (\mathbf{k} \times \mathbf{E}) + \frac{\omega^2}{c^2} \left(\frac{4\pi i}{\omega} \mathbf{j} + \mathbf{E} \right) = 0. \quad (5.1)$$

Therefore, to obtain the full dispersion relation of kinetic theory, it is sufficient to stop the hierarchy at the first-order (velocity) moment, which determines the current $\mathbf{j} = \sum_r q_r n_r \mathbf{u}_r = \boldsymbol{\sigma} \cdot \mathbf{E}$. Calculations of pressure or higher-order kinetic moments are not necessary and are thus typically omitted (provided that the full non-gyrotropic $f^{(1)}$ is considered, so that the perpendicular velocity moments \mathbf{u}_\perp are non-zero). In addition to the conductivity tensor $\boldsymbol{\sigma}$, one can also use the susceptibility tensor $\boldsymbol{\chi} = (4\pi i/\omega)\boldsymbol{\sigma}$, and the dielectric tensor $\boldsymbol{\epsilon} = \boldsymbol{\chi} + \mathbf{I}$ (the \mathbf{I} is a unit matrix and here it represents contributions of the displacement current). The definitions of $\boldsymbol{\chi}$ and $\boldsymbol{\epsilon}$ are naturally motivated by the wave equation (5.1).

- In Landau fluid models, the kinetic hierarchy has to be calculated at least up to the third-order (heat flux) moment, or preferably, the fourth-order moment \mathbf{r} (or beyond). Importantly, a closure has to be found where the last retained moment is expressed through lower-order moments. Subsequently, a simplification of $f^{(1)}$ is necessary, and in general one needs to impose a low-frequency limit $\omega/\Omega \ll 1$, which eliminates the $n \neq 0$ cyclotron resonances. The exception is the 1-D electrostatic geometry, where the low-frequency restriction is not required, and closures for arbitrary frequencies (and wavelengths) can be obtained.
- In the 3-D electromagnetic geometry, we restricted our attention to perturbations $f^{(1)}$ in the gyrotropic limit, see (4.14). In this geometry, in addition to the low-frequency limit, one also assumes that the gyroradius is small, which corresponds to the limit $k_\perp v_\perp/\Omega \ll 1$ (the gyroradius is defined as $v_{\text{th}\perp}/\Omega$, but here the limit is applied directly on $f^{(1)}$ before integration over velocity space). It is rather mind boggling that to obtain the correct $f^{(1)}$ in the laboratory reference frame, one needs to first calculate the complicated integration around the unperturbed orbit, and only then prescribe the gyrotropic limit.
- Alternatively, the $f^{(1)}$ in the gyrotropic limit can be derived by using the guiding-centre reference frame, and by imposing the conservation of the magnetic moment in the Vlasov equation from the beginning. Then, it is possible to show that various terms in $f^{(1)}$ correspond to the conservation of magnetic moment, electrostatic Coulomb force (which yields Landau damping), and magnetic mirror force (which yields transit-time damping, also called Barnes damping), see (4.15) and § 4.2.
- We considered Landau fluid closures only for a bi-Maxwellian f_0 (which in the 1-D geometry simplifies to a Maxwellian f_0), even though one should be able to construct closures for a different f_0 with a similar technique.
- In the 1-D electrostatic geometry, the kinetic hierarchy calculated up to the fourth-order moment is given by (3.20)–(3.26). All the moments contain the plasma response function $R(\zeta) = 1 + \zeta Z(\zeta)$, where $Z(\zeta)$ is the plasma dispersion

function defined by (2.35), and the variable $\zeta = \omega/(|k_{\parallel}|v_{th\parallel})$. Importantly, the ζ variable is here defined with $|k_{\parallel}| = \text{sign}(k_{\parallel})k_{\parallel}$. If the ζ variable is defined with k_{\parallel} , the plasma dispersion function has to be redefined to $Z_0(\zeta)$, equation (2.39). The $R(\zeta)$ in the kinetic hierarchy can be quickly interpreted according to (2.49).

- It is impossible to find any ‘direct’ rigorously exact fluid closure in the kinetic hierarchy of moments. In other words, it is impossible to take the last retained n th-order moment, and directly express it through lower-order moments by using exact un-approximated $R(\zeta)$ function, in such a way that the closure eliminates the $R(\zeta)$ function. Technically, such a closure is possible only when $n \rightarrow \infty$.
- To find a closure, the $R(\zeta)$ in the kinetic hierarchy needs to be analytically approximated, for example by a suitable Padé approximant $R_{n,n'}(\zeta)$ (as a ratio of two polynomials in ζ). Approximants $R_{n,n'}(\zeta)$ are constructed by matching power-series expansions $|\zeta| \ll 1$ of $R(\zeta)$, see (3.33), and asymptotic-series expansions $|\zeta| \gg 1$, see (3.67). Perhaps the most convenient is to expand (3.193).
- Importantly, contributions from the Landau residue $\sim \zeta e^{-\zeta^2}$ in $R(\zeta)$ are retained in the power-series expansion, however, the contributions are eliminated in the asymptotic series expansion (since there is no asymptotic expansion of $e^{-\zeta^2}$). The same procedure is used in the kinetic solver WHAMP. Consequently, deeply down in the lower complex plane where damping becomes very large, Padé approximants of $R(\zeta)$ become less accurate.
- Another example is the Langmuir mode, see § 3.15, where in the long-wavelength limit the frequency ω does not decrease, but is equal to the plasma frequency. Thus, $|\zeta| \gg 1$, and the Landau damping of the Langmuir mode in the long-wavelength limit typically disappears much more rapidly in kinetic theory than in Landau fluid models (see figure 7), which is a direct consequence of the missing $\zeta e^{-\zeta^2}$ in the asymptotic expansions of $R(\zeta)$. Nevertheless, at spatial scales that are shorter than five Debye lengths, the damping of the Langmuir mode can be captured very accurately in a fluid framework, see closure (3.421) and figure 10. Notably, it was indeed the example of the Langmuir mode that was used by Landau (1946) to predict this collisionless damping phenomenon.
- We introduced a new classification scheme, that we consider more natural than previous classifications. The n index in $R_{n,n'}(\zeta)$ represents the number of poles, and the ‘basic’ approximant $R_{n,0}(\zeta)$ is defined as having the correct (leading-order) asymptote $-1/(2\zeta^2)$, see (3.104). The $R_{n,0}(\zeta)$ therefore correctly captures the asymptotic profile of the zeroth-order (density) moment, and approximants with less asymptotic points should be avoided if possible. The $R_{n,n'}(\zeta)$ is defined as using n' additional points in the asymptotic-series expansion in comparison to $R_{n,0}(\zeta)$. The exception is the one-pole approximant $R_1(\zeta) = 1/(1 - i\sqrt{\pi}\zeta)$, which obviously does not have the correct asymptote.
- Approximant $R_{n,n'}(\zeta)$ has power-series precision $o(\zeta^{2n-3-n'})$ and asymptotic-series precision $o(\zeta^{-2-n'})$. Analytic forms of two-pole approximants of $R(\zeta)$ and $Z(\zeta)$ are given in § 3.3.1, three-pole approximants in § 3.3.2 and four-pole approximants in § 3.3.3. In appendix A, we provide valuable tables of five-, six-, seven- and eight-pole approximants of $R(\zeta)$, many in an analytic form. The precision of all approximants is compared in § 3.5.

- The limit $|\zeta| \ll 1$ can be viewed as an isothermal limit, and $|\zeta| \gg 1$ can be viewed as an adiabatic limit. Therefore, classical adiabatic fluid models discussed in Part 1 can be obtained by considering a high phase-speed limit $|\omega/k_{\parallel}| \gg v_{\text{th}\parallel}$. The exception is the generalized isothermal ('static') closure used to capture the mirror instability, where a low phase-speed limit $|\omega/k_{\parallel}| \ll v_{\text{th}\parallel}$ must be used.
- In many instances, solely expanding in $|\zeta| \ll 1$ or $|\zeta| \gg 1$ is not appropriate, and the $R(\zeta)$ together with $Z(\zeta)$ can be viewed as the most important functions of kinetic theory. For example, considering a proton–electron plasma at scales that are much longer than the Debye length, the dispersion relation of the parallel ion-acoustic mode is given by (3.366), and for equal proton and electron temperatures it reads $R(\zeta_p) + R(\zeta_e) = 0$. No expansion of $R(\zeta)$ is possible, since the numerical solution is $\zeta_p = \pm 1.46 - 0.63i$. Only when electrons are hot and $T_{\parallel e}^{(0)} \gg T_{\parallel p}^{(0)}$, can a simplified dispersion relation for the ion-acoustic mode be obtained by prescribing $|\zeta_p| \gg 1$ and $|\zeta_e| \ll 1$. By employing Padé approximants $R_{n,n}(\zeta)$ in Landau fluid closures, the $R(\zeta)$ function is analytically approximated for all ζ values, see figures 2 and 3.
- For the 1-D electrostatic geometry, all the Landau fluid closures that can be constructed for the heat flux q and the fourth-order moment perturbation $\tilde{r} = r - 3p^2/\rho$, are summarized in (3.241)–(3.242). The same closures are obtained in the 3-D electromagnetic geometry for parallel moments q_{\parallel} and \tilde{r}_{\parallel} . These closures do not have any restrictions for frequencies and wavenumbers, and are therefore valid from the largest astrophysical scales down to the Debye length.
- Landau fluid closures can be separated into two categories. (I) A closure is called static (or quasi-static), when the last retained moment X_l is directly expressed through lower-order moments. (II) A closure is called dynamic (or time dependent), when $\zeta X_l + \alpha X_l$ is expressed through lower-order moments (where α is a coefficient). After a dynamic closure is transformed to real space, $\partial/\partial t$ is replaced by the convective derivative d/dt to preserve Galilean invariance.
- In real space, all the closures contain the negative Hilbert transform operator \mathcal{H} , defined according to $\mathcal{H}f(z) = -(1/\pi z) * f(z) = -(1/\pi) V.P. \int_{-\infty}^{\infty} f(z-z')/z' dz'$, where $*$ represents convolution. The \mathcal{H} operator in closures comes from Fourier space, where it is equal to $i\text{sign}(k_{\parallel})$. In real space, the \mathcal{H} operator represents non-locality of closures, and, ideally, the integrals in $\mathcal{H}f(z)$ should be calculated along magnetic field lines. The effect is pronounced in numerical simulations, where calculating the Hilbert transform along the ambient magnetic field B_0 can cause instabilities, see Passot *et al.* (2014).
- For example, the simplest closure for the heat flux q_{\parallel} is given by (3.261) of Hammett & Perkins (1990) (or equivalently by (4.94) when written in the 3-D geometry). The simplest closure for the heat flux q_{\perp} is given by (4.108) of Snyder *et al.* (1997). Both closures are proportional to the Hilbert transform of temperatures T_{\parallel} , T_{\perp} . Therefore, Landau fluid closures yield gyrotropic heat fluxes q_{\parallel} , q_{\perp} that are non-local, and influenced by temperatures along the entire magnetic field line. Notably, this is in contrast to 'classical' non-gyrotropic heat flux vectors $\mathbf{S}_{\perp}^{\parallel}$, $\mathbf{S}_{\perp}^{\perp}$ discussed in Part 1, which were local and proportional to the gradient of temperatures.

- In the 3-D electromagnetic geometry in the gyrotopropic limit, the closure for the perturbation $\tilde{r}_{\perp\perp}$ is simply $\tilde{r}_{\perp\perp} = 0$. One needs to consider only closures for q_{\perp} and $\tilde{r}_{\parallel\perp}$, which are given in § 4.4 and summarized in (4.145)–(4.146).
- Only one static closure for q_{\perp} is available, the closure (4.108) of Snyder *et al.* (1997). However, the closure is obtained with the $R_1(\zeta)$ approximant. Since $q_{\perp} \sim \zeta R(\zeta)$, see (4.92) or (4.105), using $R_1(\zeta)$ implies that for large ζ values the heat flux does not disappear and instead converges to a constant value, which is erroneous. Additionally, for $\zeta > 1$ the real part of $R_1(\zeta)$ even has the wrong sign, see figure 2. The $R_1(\zeta)$ is still a valuable approximant for small $|\zeta| \ll 1$ values, and a Landau fluid model with static heat flux closures (4.94), (4.108) recovers the correct mirror threshold.
- If one comes to the conclusion that the $R_1(\zeta)$ approximant is unsatisfactory, then no static closure for q_{\perp} is available. Consequently, 3-D Landau fluid simulations are possible only if the heat fluxes q_{\parallel} , q_{\perp} are described by time-dependent equations. Of course, one could possibly consider a model with a static q_{\parallel} closure and time-dependent q_{\perp} closure.
- Perhaps, the most natural way to perform 3-D Landau fluid simulations is to keep the ‘classical’ nonlinear evolution equations for q_{\parallel} and q_{\perp} obtained in Part 1, and use static Landau fluid closures for the perturbations of the fourth-order moment. Of course, it is easy to imagine that, in some numerical simulations, the heat flux equations might be ‘too nonlinear’, i.e. responsible for instabilities. In such a case, the dynamic (linear) heat flux closures might be useful to verify the instability.
- For the $\tilde{r}_{\parallel\parallel}$ moment, there are 3 static closures available: the $R_{4,2}$ closure (3.227), the $R_{4,3}$ closure (3.234) of Hammett & Perkins (1990) and the $R_{4,4}$ closure (3.240). In real space, the $R_{4,2}$ closure is given by (3.267), the $R_{4,3}$ closure by (3.266) and the $R_{4,4}$ closure by (3.268). The $R_{4,2}$ closure has the highest power-series precision $o(\zeta^3)$, and the $R_{4,4}$ closure has the highest asymptotic-series precision $o(\zeta^{-6})$. It is of course difficult to recommend which closure is clearly better without considering a specific situation.
- We considered the example of the ion-acoustic mode, see figures 5 and 6 and associated discussion. The $R_{4,4}$ closure can be useful for simulations with sufficiently high electron temperatures, namely $\tau = T_e/T_p > 15$, which corresponds to $\zeta_p > 3$. However, such simulations will be perhaps not performed very frequently. In the most interesting regime with comparable proton and electron temperatures (or $\tau \in [1, 5]$) the most precise static closure is by far the $R_{4,2}$ closure. Nevertheless, the $R_{4,3}$ closure is still a globally precise closure. We can only recommend to use both the $R_{4,2}$ closure (3.267) of Hunana *et al.* (2018) and the $R_{4,3}$ closure (3.266) of Hammett & Perkins (1990), and clarify possible differences in numerical simulations. The differences might be more pronounced during nonlinear dynamics.
- As an example, Landau fluid simulations of turbulence typically show a curious behaviour (see e.g. Perrone *et al.* (2018) and references therein), that at sub-proton scales, the spectrum of the parallel velocity field u_{\parallel} is much steeper in kinetic simulations than in Landau fluid simulations. In contrast to the $R_{4,3}$ closure, our $R_{4,2}$ closure contains the parallel velocity u_{\parallel} . It would be interesting to explore if the $R_{4,2}$ closure influences the u_{\parallel} spectrum.

- For the $\tilde{r}_{\parallel\perp}$ moment, there is only one static closure, the $R_{2,0}$ closure (4.116) of Snyder *et al.* (1997).
- If higher precision is desired, one can use dynamic closures for the $\tilde{r}_{\parallel\parallel}$ and $\tilde{r}_{\parallel\perp}$ moments, which however introduces two additional evolution equations. Of course, it is possible to use dynamic closure only for the $\tilde{r}_{\parallel\perp}$ moment. As discussed above, it appears that closures with the highest power-series precision (p.s.p.) are the most desirable (at least for $T_e \sim T_p$). Concerning the $\tilde{r}_{\parallel\parallel}$ moment, the static $R_{4,2}$ closure has p.s.p. $o(\zeta^3)$. Thus, it is possible to have a view that a worthy dynamic closure for $\tilde{r}_{\parallel\parallel}$ should have a p.s.p. $o(\zeta^4)$. There is only one such closure, the $R_{5,3}$ closure (3.339) of Hunana *et al.* (2018).
- Concerning dynamic closures for the $\tilde{r}_{\parallel\perp}$ moment, the static $R_{2,0}$ closure (4.116) has a p.s.p. $o(\zeta)$. Therefore, a worthy dynamic closure for the $\tilde{r}_{\parallel\perp}$ moment should have a p.s.p. $o(\zeta^2)$, or higher. There are only two such closures. One with a p.s.p. $o(\zeta^2)$, the $R_{3,1}$ closure (4.131) of Passot & Sulem (2007); and one with a p.s.p. $o(\zeta^3)$, the $R_{3,0}$ closure (4.143) of Hunana *et al.* (2018).
- To summarize, if one desires the highest power-series precision that is available at the fourth-order moment level, one should use the dynamic $R_{5,3}$ closure (3.339) for the $\tilde{r}_{\parallel\parallel}$ moment, and the dynamic $R_{3,0}$ closure (4.143) for the $\tilde{r}_{\parallel\perp}$ moment. Nevertheless, the dynamic closures might not be worth the computational cost, and it is possible to have a view that the static closures are sufficiently precise. In that case, for the $\tilde{r}_{\parallel\parallel}$ moment one should use either the $R_{4,2}$ closure (3.267), or the $R_{4,3}$ closure (3.266) (see the discussion above) and for the $\tilde{r}_{\parallel\perp}$ moment the $R_{2,0}$ closure (4.116). Alternatively, one can use a dynamic closure only for the $\tilde{r}_{\parallel\perp}$ moment. In that case, it is possible to match the power-series precision of $\tilde{r}_{\parallel\parallel}$ and $\tilde{r}_{\parallel\perp}$ moments. The precision $o(\zeta^2)$ is achieved by using the $R_{4,3}$ closure (3.266) for the $\tilde{r}_{\parallel\parallel}$ moment and the $R_{3,1}$ closure (4.131) for the $\tilde{r}_{\parallel\perp}$ moment. The precision $o(\zeta^3)$ is achieved by using the $R_{4,2}$ closure (3.267) for the $\tilde{r}_{\parallel\parallel}$ moment and the $R_{3,0}$ closure (4.143) for the $\tilde{r}_{\parallel\perp}$ moment.
- The most surprising result discussed in Part 2 is the observation that some closures reproduce a considered kinetic dispersion relation exactly, after $R(\zeta)$ is replaced by the approximant $R_{n,n}(\zeta)$ used to obtain that fluid closure. We consider this observation as highly non-trivial and not obvious. For example, a 1-D fluid model described by (3.371)–(3.378) that uses the $R_{4,3}$ closure for the $\tilde{r}_{\parallel\parallel}$ moment, has a dispersion relation that is equivalent to the kinetic dispersion relation (3.366), after the $R(\zeta)$ is replaced by $R_{4,3}(\zeta)$. The results are equivalent only after the $R_{4,3}(\zeta_p)$ and $R_{4,3}(\zeta_e)$ terms in (3.366) are transferred to the common denominator and the resulting numerator is made to be equal to zero. That example concerns the ion-acoustic mode, but the same observation is true for the Langmuir mode as well, see § 3.15, dispersion relation (3.396). We called such closures ‘reliable’, or physically meaningful.
- We only verified which closures are ‘reliable’ on dispersion relations of the ion-acoustic mode and the Langmuir mode in the 1-D electrostatic geometry, see closures marked with ‘✓’ in (3.241)–(3.242). Nevertheless, it is expected that the same closures will remain ‘reliable’ when the full 1-D electrostatic dispersion relation of a proton–electron plasma (3.30) is considered, and which can be further generalized to multi-species, see (3.29).

- In the 1-D electrostatic geometry, for a given n th-order moment X_n , a closure with the highest possible power-series precision appears to be the dynamic closure constructed with the approximant $R_{n+1,n-1}(\zeta)$. For example, for the third-order (heat flux) moment it is the $R_{4,2}$ closure (3.293), for the fourth-order moment the $R_{5,3}$ closure (3.339), for the fifth-order moment the $R_{6,4}$ closure (3.413) and for the sixth-order moment the $R_{7,5}$ closure (3.421). It was verified that all of these closures are ‘reliable’.
- Similarly, for a given n th-order moment X_n , a static closure with the highest power-series precision is constructed with $R_{n,n-2}(\zeta)$.
- Importantly, by observing the summary of closures (3.241)–(3.242), it appears that closures that are ‘unreliable’ can be constructed only if there are several possibilities in constructing the closure. The dynamic closure with the $R_{n+1,n-1}(\zeta)$ approximant expresses $\zeta X_n + \alpha X_n$ through all the available lower-order moments X_m where $m = 1 \cdots n - 1$ (for even m , deviations \tilde{X}_m are used). Thus, the $R_{n+1,n-1}$ closure for $\zeta X_n + \alpha X_n$ is unique, and it is expected to be ‘reliable’.
- Curiously, it appears that the summary (3.241)–(3.242) suggest that all the dynamic closures $\zeta X_n + \alpha X_n$ with $\alpha = 0$ are ‘unreliable’. Construction of such closures is therefore discouraged. In other words, the ζX_n must be expressed through lower-order moments, including the moment X_n itself, in order to construct a dynamic closure.
- To summarize, it appears that for a given n th-order moment X_n , the dynamic closure with the approximant $R_{n+1,n-1}(\zeta)$ is indeed ‘reliable’. Therefore, one can go higher and higher in the hierarchy of moments and construct ‘reliable’ closures with approximants $R_{n+1,n-1}(\zeta)$ that converge to $R(\zeta)$ with increasing precision. In other words, one can reproduce linear Landau damping in the fluid framework to any desired precision. This establishes the convergence of fluid and collisionless kinetic descriptions.
- It is difficult to imagine that such a convergence of fluid and collisionless kinetic descriptions can be ever established in a general 3-D electromagnetic geometry, since both kinetic and fluid systems must be obviously derived by using the same perturbations $f^{(1)}$. The exception is the 3-D electromagnetic geometry in the gyrotropic limit, where such a convergence should exist. However, for a given moment X_n , the number of its gyrotropic moments is equal to $1 + \text{int}[n/2]$, and increases with n . It will be therefore much more difficult to show such a convergence. Nevertheless, one should at least use the kinetic dispersion relation in the gyrotropic limit (see for example Ferrière & André (2002), Tajiri (1967)), and establish if closures for the $\tilde{r}_{\parallel\perp}$ moment summarized in (4.145)–(4.146) are ‘reliable’, which we did not do. It is expected that all of them are ‘reliable’.
- We considered closures for the $\tilde{r}_{\parallel\perp}$ and $\tilde{r}_{\perp\perp}$ moments only in the gyrotropic limit (closures for $\tilde{r}_{\parallel\parallel}$ have general validity). However, it is possible to keep the low-frequency restriction, but make the size of the gyroradius in $f^{(1)}$ unrestricted. Such closures for the $\tilde{r}_{\parallel\perp}$ and $\tilde{r}_{\perp\perp}$ moments were obtained by Passot & Sulem (2007). In this geometry, it is also possible to obtain the non-gyrotropic (FLR) pressure tensor $\mathbf{\Pi}$ (and other FLR contributions such as the non-gyrotropic heat flux vectors $\mathbf{S}_{\perp}^{\parallel}$, $\mathbf{S}_{\perp}^{\perp}$ and r^{ng}), by integrating over the $f^{(1)}$ and by finding

appropriate closures. The final model is rather complicated, but for sufficiently slow dynamics, such as the highly oblique kinetic Alfvén waves or the mirror instability, the model reproduces linear kinetic theory very accurately on all spatial scales, see Passot & Sulem (2007), Passot *et al.* (2012), Hunana *et al.* (2013), Sulem & Passot (2015) and references therein. Our new $R_{3,0}$ closure (4.143) for the $\tilde{r}_{\perp\perp}$ moment has a higher $o(\zeta^3)$ precision than the $R_{3,1}$ closure (4.131) of Passot & Sulem (2007), and it should be relatively easy to generalize the $R_{3,0}$ closure with FLR effects. By also employing our new more precise closures for the $\tilde{r}_{\parallel\parallel}$ moment (which cannot be generalized with FLR effects), the kinetic theory should be reproduced to a new level of precision.

- Another good example worth exploring might be the electromagnetic propagation along the magnetic field (the slab geometry), where $k_{\perp} = 0$, but where no restriction on the frequency is imposed. In this case, the full kinetic $f^{(1)}$ enormously simplifies to the following form

$$f_r^{(1)} = -\frac{q_r}{m_r} \left\{ \frac{1}{2} \left[\frac{(iE_x + E_y)e^{i\phi}}{\omega - k_{\parallel}v_{\parallel} + \Omega_r} + \frac{(iE_x - E_y)e^{-i\phi}}{\omega - k_{\parallel}v_{\parallel} - \Omega_r} \right] \right. \\ \left. \times \left[\left(1 - \frac{k_{\parallel}v_{\parallel}}{\omega} \right) \frac{\partial f_{0r}}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] + \frac{iE_z}{\omega - k_{\parallel}v_{\parallel}} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right\}. \quad (5.2)$$

By prescribing a bi-Maxwellian f_0 , integration over velocity space yields a hierarchy of moments. In this geometry, the electrostatic dynamics ($\sim E_z$) can be completely separated from the electromagnetic dynamics ($\sim E_x, E_y$). The electromagnetic dynamics with cyclotron resonances $n = \pm 1$ yields a hierarchy of non-gyrotropic moments containing $Z(\zeta_{\pm})$ and $R(\zeta_{\pm})$, where $\zeta_{\pm} = (\omega \pm \Omega)/(|k_{\parallel}|v_{\text{th}\parallel})$. The $Z(\zeta_{\pm})$ and $R(\zeta_{\pm})$ functions can be approximated with the same Padé approximants as discussed here, and by going sufficiently high in the hierarchy, simple closures might become available. Such closures should capture the collisionless cyclotron damping in the fluid framework, even though only in the slab geometry. It should also be possible to verify, if such closures are ‘reliable’, i.e. if the kinetic dispersions of the ion-cyclotron and whistler modes are reproduced exactly, after the $Z(\zeta_{\pm})$ and $R(\zeta_{\pm})$ are replaced by the corresponding Padé approximant.

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Appendix A. Higher-order Padé approximants of $R(\zeta)$

A.1. Five-pole approximants of $R(\zeta)$

A general five-pole approximant of the plasma response function that is worth considering is written as

$$R_5(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2 + a_3\zeta^3}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 + b_4\zeta^4 + b_5\zeta^5}. \quad (\text{A } 1)$$

Additionally, the minimum choice that we consider interesting, and that is defined as $R_{5,0}(\zeta)$, is to match the asymptotic expansion for $|\zeta| \gg 1$ up the first $-1/(2\zeta^2)$ term, that requires $b_5 = -2a_3$. The matching with the asymptotic expansion then proceeds step by step, according to

$$\begin{aligned} R_{5,0}(\zeta) : \quad & b_5 = -2a_3; & o(\zeta^{-2}); \\ R_{5,1}(\zeta) : \quad & b_4 = -2a_2; & o(\zeta^{-3}); \\ R_{5,2}(\zeta) : \quad & b_3 = 3a_3 - 2a_1; & o(\zeta^{-4}); \\ R_{5,3}(\zeta) : \quad & b_2 = 3a_2 - 2; & o(\zeta^{-5}); \\ R_{5,4}(\zeta) : \quad & b_1 = 3(a_1 + a_3); & o(\zeta^{-6}); \\ R_{5,5}(\zeta) : \quad & a_2 = -\frac{2}{3}; & o(\zeta^{-7}); \\ R_{5,6}(\zeta) : \quad & a_3 = -\frac{2}{7}a_1; & o(\zeta^{-8}), \end{aligned} \quad (\text{A } 2)$$

the $R_{5,7}(\zeta)$ does not make sense and is not defined. The matching with the power series is performed according to

$$\begin{aligned} R_{5,0}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 + i\frac{\sqrt{\pi}}{2}\zeta^5 - \frac{8}{15}\zeta^6 - i\frac{\sqrt{\pi}}{6}\zeta^7; \\ R_{5,1}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 + i\frac{\sqrt{\pi}}{2}\zeta^5 - \frac{8}{15}\zeta^6; \\ R_{5,2}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 + i\frac{\sqrt{\pi}}{2}\zeta^5; \\ R_{5,3}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4; \\ R_{5,4}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3; \\ R_{5,5}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2; \\ R_{5,6}(\zeta) &= 1 + i\sqrt{\pi}\zeta; \end{aligned} \quad (\text{A } 3)$$

and the results are

$$\begin{aligned} R_{5,0}(\zeta) : \quad & a_1 = i\sqrt{\pi} \frac{(621\pi^2 - 3927\pi + 6208)}{(801\pi^2 - 5124\pi + 8192)}; \\ & a_2 = \frac{(900\pi^3 - 10665\pi^2 + 40268\pi - 49152)}{5(801\pi^2 - 5124\pi + 8192)}; \\ & a_3 = i\sqrt{\pi} \frac{(450\pi^2 - 2799\pi + 4352)}{10(801\pi^2 - 5124\pi + 8192)}; \\ & b_1 = -i\sqrt{\pi} \frac{(180\pi^2 - 1197\pi + 1984)}{(801\pi^2 - 5124\pi + 8192)}; \end{aligned}$$

$$\begin{aligned}
 b_2 &= \frac{2(1665\pi^2 - 10446\pi + 16384)}{5(801\pi^2 - 5124\pi + 8192)}; \\
 b_3 &= -i\sqrt{\pi} \frac{(1800\pi^2 - 11685\pi + 18944)}{10(801\pi^2 - 5124\pi + 8192)}; \\
 b_4 &= \frac{(7065\pi^2 - 43056\pi + 65536)}{30(801\pi^2 - 5124\pi + 8192)}, \tag{A 4}
 \end{aligned}$$

$$\begin{aligned}
 R_{5,1}(\zeta) : \quad a_1 &= \frac{i}{\sqrt{\pi}} \frac{(360\pi^3 - 2445\pi^2 + 4780\pi - 2048)}{5(72\pi^2 - 435\pi + 656)}; \\
 a_2 &= -\frac{(180\pi^2 - 1197\pi + 1984)}{10(72\pi^2 - 435\pi + 656)}; \\
 a_3 &= \frac{i}{\sqrt{\pi}} \frac{(801\pi^2 - 5124\pi + 8192)}{30(72\pi^2 - 435\pi + 656)}; \\
 b_1 &= -\frac{i}{\sqrt{\pi}} \frac{2(135\pi^2 - 750\pi + 1024)}{5(72\pi^2 - 435\pi + 656)}; \\
 b_2 &= \frac{(720\pi^2 - 4503\pi + 7040)}{10(72\pi^2 - 435\pi + 656)}; \\
 b_3 &= -\frac{i}{\sqrt{\pi}} \frac{2(495\pi^2 - 2859\pi + 4096)}{15(72\pi^2 - 435\pi + 656)}, \tag{A 5}
 \end{aligned}$$

$$\begin{aligned}
 R_{5,2}(\zeta) : \quad a_1 &= i\sqrt{\pi} \frac{3(12\pi^2 - 81\pi + 136)}{4(9\pi^2 - 69\pi + 128)}; \quad a_2 = -\frac{(135\pi^2 - 750\pi + 1024)}{12(9\pi^2 - 69\pi + 128)}; \\
 a_3 &= i\sqrt{\pi} \frac{(72\pi^2 - 435\pi + 656)}{12(9\pi^2 - 69\pi + 128)}; \quad b_1 = i\sqrt{\pi} \frac{(33\pi - 104)}{4(9\pi^2 - 69\pi + 128)}; \\
 b_2 &= \frac{(90\pi^2 - 609\pi + 1024)}{6(9\pi^2 - 69\pi + 128)}, \tag{A 6}
 \end{aligned}$$

$$\begin{aligned}
 R_{5,3}(\zeta) : \quad a_1 &= \frac{i}{\sqrt{\pi}} \frac{(27\pi^2 - 126\pi + 128)}{3(9\pi - 28)}; \quad a_2 = \frac{(33\pi - 104)}{3(9\pi - 28)}; \\
 a_3 &= \frac{i}{\sqrt{\pi}} \frac{2(9\pi^2 - 69\pi + 128)}{3(9\pi - 28)}; \quad b_1 = -\frac{i}{\sqrt{\pi}} \frac{2(21\pi - 64)}{3(9\pi - 28)}, \tag{A 7}
 \end{aligned}$$

$$\begin{aligned}
 R_{5,4}(\zeta) : \quad a_1 &= i\sqrt{\pi} \frac{(9\pi - 26)}{(9\pi - 32)}; \quad a_2 = \frac{(21\pi - 64)}{(9\pi - 32)}; \quad a_3 = -i\sqrt{\pi} \frac{(9\pi - 28)}{(9\pi - 32)}; \tag{A 8}
 \end{aligned}$$

$$\begin{aligned}
 R_{5,5}(\zeta) : \quad a_1 &= -i \frac{(16 - 3\pi)}{3\sqrt{\pi}}; \quad a_3 = i \frac{(32 - 9\pi)}{9\sqrt{\pi}}; \tag{A 9}
 \end{aligned}$$

$$\begin{aligned}
 R_{5,6}(\zeta) : \quad a_1 &= -i\sqrt{\pi} \frac{7}{8}, \tag{A 10}
 \end{aligned}$$

so that for example

$$\boxed{
 \begin{aligned}
 R_{5,3}(\zeta) &= \frac{1 + \frac{i}{\sqrt{\pi}} \frac{(27\pi^2 - 126\pi + 128)}{3(9\pi - 28)} \zeta + \frac{(33\pi - 104)}{3(9\pi - 28)} \zeta^2 + \frac{i}{\sqrt{\pi}} \frac{2(9\pi^2 - 69\pi + 128)}{3(9\pi - 28)} \zeta^3}{1 - \frac{i}{\sqrt{\pi}} \frac{2(21\pi - 64)}{3(9\pi - 28)} \zeta + \frac{3(5\pi - 16)}{(9\pi - 28)} \zeta^2 - \frac{i}{\sqrt{\pi}} \frac{2(81\pi - 256)}{3(9\pi - 28)} \zeta^3 - \frac{2(33\pi - 104)}{3(9\pi - 28)} \zeta^4 - \frac{i}{\sqrt{\pi}} \frac{4(9\pi^2 - 69\pi + 128)}{3(9\pi - 28)} \zeta^5}; \tag{A 11}
 \end{aligned}
 }$$

$$R_{5,4}(\zeta) = \frac{1 + i\sqrt{\pi} \frac{(9\pi - 26)}{(9\pi - 32)}\zeta + \frac{(21\pi - 64)}{(9\pi - 32)}\zeta^2 - i\sqrt{\pi} \frac{(9\pi - 28)}{(9\pi - 32)}\zeta^3}{1 + i\sqrt{\pi} \frac{6}{(9\pi - 32)}\zeta + \frac{(45\pi - 128)}{(9\pi - 32)}\zeta^2 - i\sqrt{\pi} \frac{(45\pi - 136)}{(9\pi - 32)}\zeta^3 - \frac{2(21\pi - 64)}{(9\pi - 32)}\zeta^4 + i\sqrt{\pi} \frac{2(9\pi - 28)}{(9\pi - 32)}\zeta^5}; \tag{A 12}$$

$$R_{5,5}(\zeta) = \frac{1 - i \frac{(16 - 3\pi)}{3\sqrt{\pi}}\zeta - \frac{2}{3}\zeta^2 + i \frac{(32 - 9\pi)}{9\sqrt{\pi}}\zeta^3}{1 - i \frac{16}{3\sqrt{\pi}}\zeta - 4\zeta^2 + i \frac{(64 - 15\pi)}{3\sqrt{\pi}}\zeta^3 + \frac{4}{3}\zeta^4 - i \frac{2(32 - 9\pi)}{9\sqrt{\pi}}\zeta^5}; \tag{A 13}$$

$$R_{5,6}(\zeta) = \frac{1 - i\sqrt{\pi} \frac{7}{8}\zeta - \frac{2}{3}\zeta^2 + i \frac{\sqrt{\pi}}{4}\zeta^3}{1 - i\sqrt{\pi} \frac{15}{8}\zeta - 4\zeta^2 + i\sqrt{\pi} \frac{5}{2}\zeta^3 + \frac{4}{3}\zeta^4 - i \frac{\sqrt{\pi}}{2}\zeta^5}. \tag{A 14}$$

A.2. Six-pole approximants of $R(\zeta)$

A general six-pole Padé approximant to $R(\zeta)$ that we consider is

$$R_6(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2 + a_3\zeta^3 + a_4\zeta^4}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 + b_4\zeta^4 + b_5\zeta^5 + b_6\zeta^6}, \tag{A 15}$$

where as a minimum choice, we match the first asymptotic term by $b_6 = -2a_4$, which defines $R_{6,0}(\zeta)$. The procedure of matching with the asymptotic expansion yields step by step

$$\begin{aligned} R_{6,0}(\zeta) : & \quad b_6 = -2a_4; & \quad o(\zeta^{-2}); \\ R_{6,1}(\zeta) : & \quad b_5 = -2a_3; & \quad o(\zeta^{-3}); \\ R_{6,2}(\zeta) : & \quad b_4 = 3a_4 - 2a_2; & \quad o(\zeta^{-4}); \\ R_{6,3}(\zeta) : & \quad b_3 = 3a_3 - 2a_1; & \quad o(\zeta^{-5}); \\ R_{6,4}(\zeta) : & \quad b_2 = 3(a_2 + a_4) - 2; & \quad o(\zeta^{-6}); \\ R_{6,5}(\zeta) : & \quad b_1 = 3(a_1 + a_3); & \quad o(\zeta^{-7}); \\ R_{6,6}(\zeta) : & \quad a_4 = -\frac{4}{21} - \frac{2}{7}a_2; & \quad o(\zeta^{-8}); \\ R_{6,7}(\zeta) : & \quad a_3 = -\frac{2}{7}a_1; & \quad o(\zeta^{-9}); \\ R_{6,8}(\zeta) : & \quad a_2 = -\frac{8}{5}; & \quad o(\zeta^{-10}); \\ R_{6,9}(\zeta) : & \quad a_1 = 0; & \quad o(\zeta^{-11}), \end{aligned} \tag{A 16}$$

where the approximant $R_{6,9}(\zeta)$ is not a good approximant (no imaginary part for real ζ), and is eliminated. Matching with the power series is performed according to

$$\begin{aligned} R_{6,0}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 + i \frac{\sqrt{\pi}}{2}\zeta^5 - \frac{8}{15}\zeta^6 - i \frac{\sqrt{\pi}}{6}\zeta^7 \\ &\quad + \frac{16}{105}\zeta^8 + i \frac{\sqrt{\pi}}{24}\zeta^9; \\ &\quad \vdots \\ R_{6,8}(\zeta) &= 1 + i\sqrt{\pi}\zeta. \end{aligned} \tag{A 17}$$

Even though analytic results can be obtained with Maple, they are too long to write down, additionally, as we accidentally found out, they are also tricky to evaluate. For example, if the default precision (of 10 digits) is used in Maple, the analytic a_1 in $R_{6,0}(\zeta)$ is evaluated with command evalf as $-0.57i$, whereas the correct value is $-0.69i$. Alternatively, the system can be solved numerically from the onset. We almost erroneously concluded that $R_{6,0}(\zeta)$ is not a very precise approximant, even though its relative precision (for real valued ζ) is better than 0.7% for both real and imaginary parts of $R(\zeta)$. We provide results with 10 correct significant digits, which is a sufficient precision introducing relative numerical errors of less than $3 \times 10^{-7}\%$, i.e. negligible in comparison with the $R_{6,0}(\zeta)$ relative precision to $R(\zeta)$. The results are

$$\begin{aligned}
 R_{6,0}(\zeta) : \quad & a_1 = -i0.6916731200; \quad a_2 = -0.2854457889; \\
 & a_3 = i0.05976861370; \quad a_4 = 0.005619524175; \\
 & b_1 = -i2.464126971; \quad b_2 = -2.652997128; \\
 & b_3 = i1.606283498; \quad b_4 = 0.5809066463; \\
 & b_5 = -i0.1201024988, \tag{A 18}
 \end{aligned}$$

$$\begin{aligned}
 R_{6,1}(\zeta) : \quad & a_1 = -i0.7895801201; \quad a_2 = -0.3391528628; \\
 & a_3 = i0.07728246365; \quad a_4 = 0.007840755018; \\
 & b_1 = -i2.562033971; \quad b_2 = -2.880239841; \\
 & b_3 = i1.830760570; \quad b_4 = 0.7000533404, \tag{A 19}
 \end{aligned}$$

$$\begin{aligned}
 R_{6,2}(\zeta) : \quad & a_1 = -i0.8965446682; \quad a_2 = -0.4102783438; \\
 & a_3 = i0.1015110114; \quad a_4 = 0.01132035970; \\
 & b_1 = -i2.668998519; \quad b_2 = -3.140955047; \\
 & b_3 = i2.103165693, \tag{A 20}
 \end{aligned}$$

$$\begin{aligned}
 R_{6,3}(\zeta) : \quad & a_1 = -i1.012753086; \quad a_2 = -0.5024864543; \\
 & a_3 = i0.1361229028; \quad a_4 = 0.01700049686; \\
 & b_1 = -i2.785206937; \quad b_2 = -3.439137216, \tag{A 21}
 \end{aligned}$$

$$\begin{aligned}
 R_{6,4}(\zeta) : \quad & a_1 = i\sqrt{\pi} \frac{270\pi^2 - 1653\pi + 2528}{2(135\pi^2 - 750\pi + 1024)}; \quad a_2 = \frac{9\pi(7\pi - 22)}{2(135\pi^2 - 750\pi + 1024)}; \\
 & a_3 = i\sqrt{\pi} \frac{180\pi^2 - 1197\pi + 1984}{2(135\pi^2 - 750\pi + 1024)}; \quad a_4 = \frac{801\pi^2 - 5124\pi + 8192}{6(135\pi^2 - 750\pi + 1024)}; \\
 & b_1 = -i\sqrt{\pi} \frac{3(51\pi - 160)}{2(135\pi^2 - 750\pi + 1024)}, \tag{A 22}
 \end{aligned}$$

$$\begin{aligned}
 R_{6,5}(\zeta) : \quad & a_1 = i\sqrt{\pi} \frac{4(9\pi - 28)}{(81\pi - 256)}; \quad a_2 = \frac{3\pi(15\pi - 47)}{(81\pi - 256)}; \\
 & a_3 = -i\sqrt{\pi} \frac{(51\pi - 160)}{(81\pi - 256)}; \quad a_4 = -\frac{135\pi^2 - 750\pi + 1024}{3(81\pi - 256)}, \tag{A 23}
 \end{aligned}$$

$$\begin{aligned}
 R_{6,6}(\zeta) : \quad & a_1 = i\sqrt{\pi} \frac{(45\pi - 152)}{(45\pi - 128)}; \quad a_2 = \frac{(159\pi - 512)}{(45\pi - 128)}; \\
 & a_3 = -9i\sqrt{\pi} \frac{(5\pi - 16)}{(45\pi - 128)}; \tag{A 24}
 \end{aligned}$$

$$R_{6,7}(\zeta) : \quad a_1 = -i\sqrt{\pi} \frac{7}{8}; \quad a_2 = 4 - \frac{105}{64}\pi; \tag{A 25}$$

$$R_{6,8}(\zeta) : \quad a_1 = -i\sqrt{\pi} \frac{7}{8}. \tag{A 26}$$

A.3. Seven-pole approximants of $R(\zeta)$

$$R_7(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2 + a_3\zeta^3 + a_4\zeta^4 + a_5\zeta^5}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 + b_4\zeta^4 + b_5\zeta^5 + b_6\zeta^6 + b_7\zeta^7}, \quad (\text{A } 27)$$

and the procedure of matching with asymptotic expansion yields

$$\begin{aligned} R_{7,0}(\zeta) : \quad & b_7 = -2a_5; & o(\zeta^{-2}); \\ R_{7,1}(\zeta) : \quad & b_6 = -2a_4; & o(\zeta^{-3}); \\ R_{7,2}(\zeta) : \quad & b_5 = 3a_5 - 2a_3; & o(\zeta^{-4}); \\ R_{7,3}(\zeta) : \quad & b_4 = 3a_4 - 2a_2; & o(\zeta^{-5}); \\ R_{7,4}(\zeta) : \quad & b_3 = 3a_5 + 3a_3 - 2a_1; & o(\zeta^{-6}); \\ R_{7,5}(\zeta) : \quad & b_2 = 3a_4 + 3a_2 - 2; & o(\zeta^{-7}); \\ R_{7,6}(\zeta) : \quad & b_1 = \frac{21}{2}a_5 + 3a_3 + 3a_1; & o(\zeta^{-8}); \\ R_{7,7}(\zeta) : \quad & a_4 = -\frac{4}{21} - \frac{2}{7}a_2; & o(\zeta^{-9}); \\ R_{7,8}(\zeta) : \quad & a_5 = -\frac{14}{69}a_3 - \frac{4}{69}a_1; & o(\zeta^{-10}); \\ R_{7,9}(\zeta) : \quad & a_2 = -\frac{8}{5}; & o(\zeta^{-11}); \\ R_{7,10}(\zeta) : \quad & a_3 = -\frac{12}{19}a_1; & o(\zeta^{-12}). \end{aligned} \quad (\text{A } 28)$$

The $R_{7,11}(\zeta)$ is not defined because it would require $a_1 \rightarrow \infty$. Matching with the power series is performed according to

$$\begin{aligned} R_{7,0}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 \\ &\quad + i\frac{\sqrt{\pi}}{2}\zeta^5 - \frac{8}{15}\zeta^6 - i\frac{\sqrt{\pi}}{6}\zeta^7 + \frac{16}{105}\zeta^8 + i\frac{\sqrt{\pi}}{24}\zeta^9 - \frac{32}{945}\zeta^{10} - i\frac{\sqrt{\pi}}{120}\zeta^{11}; \\ &\quad \vdots \\ R_{7,10}(\zeta) &= 1 + i\sqrt{\pi}\zeta. \end{aligned} \quad (\text{A } 29)$$

The results are

$$\begin{aligned} R_{7,0}(\zeta) : \quad & a_1 = -i0.8324695834; \quad a_2 = -0.4049799755; \\ & a_3 = i0.1121082796; \quad a_4 = 0.01799681258; \\ & a_5 = -i0.001293708127; \quad b_1 = -i2.604923434; \\ & b_2 = -3.022086548; \quad b_3 = i2.031224201; \\ & b_4 = 0.8578481138; \quad b_5 = -i0.2288461173; \\ & b_6 = -0.035945334608, \end{aligned} \quad (\text{A } 30)$$

$$\begin{aligned} R_{7,1}(\zeta) : \quad & a_1 = -i0.9178985928; \quad a_2 = -0.4640689249; \\ & a_3 = i0.1364936305; \quad a_4 = 0.02310278605; \\ & a_5 = -i0.001773778511; \quad b_1 = -i2.690352444; \\ & b_2 = -3.232594474; \quad b_3 = i2.257867118; \\ & b_4 = 0.9950713218; \quad b_5 = -i0.2784723967, \end{aligned} \quad (\text{A } 31)$$

$$\begin{aligned}
 R_{7,2}(\zeta): \quad & a_1 = -i1.010198516; \quad a_2 = -0.5369471092; \\
 & a_3 = i0.1677974137; \quad a_4 = 0.03023595150; \\
 & a_5 = -i0.002497479595; \quad b_1 = -i2.782652367; \\
 & b_2 = -3.469070012; \quad b_3 = i2.523713033; \\
 & b_4 = 1.164050381,
 \end{aligned} \tag{A 32}$$

$$\begin{aligned}
 R_{7,3}(\zeta): \quad & a_1 = -i1.109722119; \quad a_2 = -0.6261744648; \\
 & a_3 = i0.2086297926; \quad a_4 = 0.04033869308; \\
 & a_5 = -i0.003624122579; \quad b_1 = -i2.882175970; \\
 & b_2 = -3.734698361; \quad b_3 = i2.836312196,
 \end{aligned} \tag{A 33}$$

$$\begin{aligned}
 R_{7,4}(\zeta): \quad & a_1 = -i1.216585782; \quad a_2 = -0.7344009695; \\
 & a_3 = i0.2623273358; \quad a_4 = 0.05488528512; \\
 & a_5 = -i0.005440857949; \quad b_1 = -i2.989039633; \\
 & b_2 = -4.032335777,
 \end{aligned} \tag{A 34}$$

$$\begin{aligned}
 R_{7,5}(\zeta): \quad & a_1 = -i1.330549030; \quad a_2 = -0.8640648164; \\
 & a_3 = i0.3328884746; \quad a_4 = 0.07606674237; \\
 & a_5 = -i0.008482851988; \quad b_1 = -i3.103002881,
 \end{aligned} \tag{A 35}$$

$$\begin{aligned}
 R_{7,6}(\zeta): \quad & a_1 = -i1.450931895; \quad a_2 = -1.016999244; \\
 & a_3 = i0.4247000792; \quad a_4 = 0.1068986701; \\
 & a_5 = -i0.01378002846,
 \end{aligned} \tag{A 36}$$

$$\begin{aligned}
 R_{7,7}(\zeta): \quad & a_1 = -i1.576631991; \quad a_2 = -1.194087585; \\
 & a_3 = i0.5420816788; \quad a_5 = -i0.02337475294.
 \end{aligned} \tag{A 37}$$

We later found that the most precise (power-series) closure on the sixth-order moment is a dynamic closure constructed with approximant $R_{7,5}(\zeta)$, and therefore, starting with this approximant, we also provide analytic coefficients. The results are

$$\begin{aligned}
 R_{7,5}(\zeta): \quad & a_1 = i \frac{2(3375\pi^3 - 24525\pi^2 + 54168\pi - 32768)}{15(450\pi^2 - 2799\pi + 4352)\sqrt{\pi}}; \\
 & a_2 = \frac{(6030\pi^2 - 37197\pi + 57344)}{30(450\pi^2 - 2799\pi + 4352)}; \\
 & a_3 = i \frac{3(600\pi^2 - 3805\pi + 6032)\sqrt{\pi}}{10(450\pi^2 - 2799\pi + 4352)}; \quad a_4 = \frac{(1545\pi^2 - 9743\pi + 15360)}{5(450\pi^2 - 2799\pi + 4352)}; \\
 & a_5 = i \frac{(10800\pi^3 - 120915\pi^2 + 440160\pi - 524288)}{90(450\pi^2 - 2799\pi + 4352)\sqrt{\pi}}; \\
 & b_1 := -i \frac{(7065\pi^2 - 43056\pi + 65536)}{15(450\pi^2 - 2799\pi + 4352)\sqrt{\pi}},
 \end{aligned} \tag{A 38}$$

$$\begin{aligned}
 R_{7,6}(\zeta): \quad a_1 &= i\sqrt{\pi} \frac{(1350\pi^2 - 8601\pi + 13696)}{2(675\pi^2 - 4728\pi + 8192)}; \\
 a_2 &= -\frac{3(135\pi - 424)\pi}{2(675\pi^2 - 4728\pi + 8192)}; \\
 a_3 &= i\sqrt{\pi} \frac{(1800\pi^2 - 10707\pi + 15872)}{2(675\pi^2 - 4728\pi + 8192)}; \\
 a_4 &= \frac{(7065\pi^2 - 43056\pi + 65536)}{6(675\pi^2 - 4728\pi + 8192)}; \\
 a_5 &= -i\sqrt{\pi} \frac{(450\pi^2 - 2799\pi + 4352)}{(675\pi^2 - 4728\pi + 8192)}, \tag{A 39}
 \end{aligned}$$

$$\begin{aligned}
 R_{7,7}(\zeta): \quad a_1 &= i \frac{(675\pi^2 - 3432\pi + 4096)}{3(-704 + 225\pi)\sqrt{\pi}}; \\
 a_2 &= \frac{(1545\pi - 4864)}{3(-704 + 225\pi)}; \\
 a_3 &= i \frac{4(225\pi^2 - 2010\pi + 4096)}{3(-704 + 225\pi)\sqrt{\pi}}; \\
 a_5 &= -i \frac{2(675\pi^2 - 4728\pi + 8192)}{9(-704 + 225\pi)\sqrt{\pi}}, \tag{A 40}
 \end{aligned}$$

$$\begin{aligned}
 R_{7,8}(\zeta): \quad a_1 &= -i\sqrt{\pi} \frac{3(25\pi - 72)}{256 - 75\pi}; \quad a_2 = -\frac{335\pi - 1024}{256 - 75\pi}; \\
 a_3 &= i\sqrt{\pi} \frac{5(165\pi - 512)}{4(256 - 75\pi)}, \tag{A 41}
 \end{aligned}$$

$$R_{7,9}(\zeta): \quad a_1 = -i \frac{32 - 5\pi}{5\sqrt{\pi}}; \quad a_3 = i \frac{1024 - 275\pi}{100\sqrt{\pi}}, \tag{A 42}$$

$$R_{7,10}(\zeta): \quad a_1 = -i\sqrt{\pi} \frac{19}{16}. \tag{A 43}$$

A.4. Eight-pole approximants of $R(\zeta)$

$$R_8(\zeta) = \frac{1 + a_1\zeta + a_2\zeta^2 + a_3\zeta^3 + a_4\zeta^4 + a_5\zeta^5 + a_6\zeta^6}{1 + b_1\zeta + b_2\zeta^2 + b_3\zeta^3 + b_4\zeta^4 + b_5\zeta^5 + b_6\zeta^6 + b_7\zeta^7 + b_8\zeta^8}, \tag{A 44}$$

and the procedure of matching with the asymptotic expansion step by step

$$R(\zeta) = -\frac{1}{2\zeta^2} - \frac{3}{4\zeta^4} - \frac{15}{8\zeta^6} - \frac{105}{16\zeta^8} - \frac{945}{32\zeta^{10}} - \frac{10395}{64\zeta^{12}} - \frac{135135}{128\zeta^{14}} \cdots; \quad |\zeta| \gg 1 \tag{A 45}$$

yields the following table

$$\begin{aligned}
 R_{8,0}(\zeta) &: b_8 = -2a_6; & o(\zeta^{-2}); \\
 R_{8,1}(\zeta) &: b_7 = -2a_5; & o(\zeta^{-3}); \\
 R_{8,2}(\zeta) &: b_6 = 3a_6 - 2a_4; & o(\zeta^{-4}); \\
 R_{8,3}(\zeta) &: b_5 = 3a_5 - 2a_3; & o(\zeta^{-5}); \\
 R_{8,4}(\zeta) &: b_4 = 3a_6 + 3a_4 - 2a_2; & o(\zeta^{-6}); \\
 R_{8,5}(\zeta) &: b_3 = 3a_5 + 3a_3 - 2a_1; & o(\zeta^{-7}); \\
 R_{8,6}(\zeta) &: b_2 = \frac{21}{2}a_6 + 3a_4 + 3a_2 - 2; & o(\zeta^{-8}); \\
 R_{8,7}(\zeta) &: b_1 = \frac{21}{2}a_5 + 3a_3 + 3a_1; & o(\zeta^{-9}); \\
 R_{8,8}(\zeta) &: a_6 = -\frac{14}{69}a_4 - \frac{4}{69}a_2 - \frac{8}{207}; & o(\zeta^{-10}); \\
 R_{8,9}(\zeta) &: a_5 = -\frac{14}{69}a_3 - \frac{4}{69}a_1; & o(\zeta^{-11}); \\
 R_{8,10}(\zeta) &: a_4 = -\frac{12}{19}a_2 - \frac{212}{285}; & o(\zeta^{-12}); \\
 R_{8,11}(\zeta) &: a_3 = -\frac{12}{19}a_1; & o(\zeta^{-13}); \\
 R_{8,12}(\zeta) &: a_2 = -\frac{94}{35}; & o(\zeta^{-14}); \\
 R_{8,13}(\zeta) &: a_1 = 0; & o(\zeta^{-15}),
 \end{aligned}
 \tag{A 46}$$

where the approximant $R_{8,13}(\zeta)$ is not well behaved and is eliminated. Matching with the power series is performed according to

$$\begin{aligned}
 R_{8,0}(\zeta) &= 1 + i\sqrt{\pi}\zeta - 2\zeta^2 - i\sqrt{\pi}\zeta^3 + \frac{4}{3}\zeta^4 \\
 &\quad + i\frac{\sqrt{\pi}}{2}\zeta^5 - \frac{8}{15}\zeta^6 - i\frac{\sqrt{\pi}}{6}\zeta^7 + \frac{16}{105}\zeta^8 + i\frac{\sqrt{\pi}}{24}\zeta^9 - \frac{32}{945}\zeta^{10} \\
 &\quad - i\frac{\sqrt{\pi}}{120}\zeta^{11} + \frac{64}{10395}\zeta^{12} + i\frac{\sqrt{\pi}}{720}\zeta^{13}; \quad |\zeta| \ll 1; \\
 &\quad \vdots \\
 R_{8,12}(\zeta) &= 1 + i\sqrt{\pi}\zeta.
 \end{aligned}
 \tag{A 47}$$

Such high-order Padé approximants are very precise, and to retain the accuracy, we provide solutions with 16 correct significant digits (even though this is actually not necessary and 10 digits is still fully sufficient). The approximant $R_{8,3}(\zeta)$ is a bit special, since its corresponding $Z_{8,3}(\zeta)$ should be the approximant that is used in the WHAMP code. This is inferred from a sentence on page 12 of the WHAMP manual (Rönmark 1982), where it is stated that an eight-pole approximant was derived, using 10 equations from the power-series expansion and 6 equations from the asymptotic-series expansion. However, the Padé coefficients in the WHAMP manual are given in a different form than we use here, and an alternative Padé approximation is used where for example an eight-pole approximant is given by $Z_8(\zeta) = \sum_{j=0}^8 b_j/(\zeta - c_j)$, and the coefficients b_j, c_j are obtained. We did not bother to re-derive the coefficients in that form, instead, we compare the precision of various approximants in § 3.5.

$$\begin{aligned}
 R_{8,0}(\zeta) &: a_1 = -i0.9690248260959390; \quad a_2 = -0.5368540729623971; \\
 &\quad a_3 = i0.1799961104391385; \\
 &\quad a_4 = 0.03849976076674387; \quad a_5 = -i0.004838817622209550;
 \end{aligned}$$

$$\begin{aligned}
a_6 &= -0.0002789155539114067; \\
b_1 &= -i2.741478677001455; \quad b_2 = -3.395998511188985; \\
b_3 &= i2.488743246168061; \\
b_4 &= 1.183496393867702; \quad b_5 = -i0.3752177277401555; \\
b_6 &= -0.07776565572655091; \\
b_7 &= i0.009681326596560459,
\end{aligned} \tag{A 48}$$

$$\begin{aligned}
R_{8,1}(\zeta) : \quad a_1 &= -i1.045465281824923; \quad a_2 = -0.6004884272987368; \\
a_3 &= i0.2109529643239577; \\
a_4 &= 0.04706936874656537; \quad a_5 = -i0.006214502177680713; \\
a_6 &= -0.0003778071927517807; \\
b_1 &= -i2.817919132730439; \quad b_2 = -3.595120045647135; \\
b_3 &= i2.719752919143475; \\
b_4 &= 1.338764097514731; \quad b_5 = -i0.4407920285051489; \\
b_6 &= -0.0952587572277513,
\end{aligned} \tag{A 49}$$

$$\begin{aligned}
R_{8,2}(\zeta) : \quad a_1 &= -i1.127283578226963; \quad a_2 = -0.6755893264302076; \\
a_3 &= i0.2489222931730291; \\
a_4 &= 0.05823704506630824; \quad a_5 = -i0.008104732774508430; \\
a_6 &= -0.0005229347287036976; \\
b_1 &= -i2.899737429132479; \quad b_2 = -3.815240099310931; \\
b_3 &= i2.984238291966390; \\
b_4 &= 1.523498938607364; \quad b_5 = -i0.5222070688557393,
\end{aligned} \tag{A 50}$$

$$\begin{aligned}
R_{8,3}(\zeta) : \quad a_1 &= -i1.214803859035098; \quad a_2 = -0.7640021842041184; \\
a_3 &= i0.2959160549490394; \\
a_4 &= 0.07292272182826132; \quad a_5 = -i0.01075099173987222; \\
a_6 &= -0.0007415148441966772; \\
b_1 &= -i2.987257709940614; \quad b_2 = -4.058778615835553; \\
b_3 &= i3.287852273584013; \\
b_4 &= 1.744375011977697,
\end{aligned} \tag{A 51}$$

$$\begin{aligned}
R_{8,4}(\zeta) : \quad a_1 &= -i1.308257217643640; \quad a_2 = -0.8677094433207613; \\
a_3 &= i0.3544341617560842; \\
a_4 &= 0.09241987665571996; \quad a_5 = -i0.01452077809048251; \\
a_6 &= -0.001080201271194285; \\
b_1 &= -i3.080711068549157; \quad b_2 = -4.328127640297961; \\
b_3 &= i3.636872378820012,
\end{aligned} \tag{A 52}$$

$$\begin{aligned}
 R_{8,5}(\zeta) : \quad & a_1 = -i1.407720282460896; \quad a_2 = -0.9887147938014795; \\
 & a_3 = i0.4274799329839440; \\
 & a_4 = 0.1185117574638203; \quad a_5 = -i0.01997983676237579; \\
 & a_6 = -0.001621365678069347; \\
 & b_1 = -i3.180174133366412; \quad b_2 = -4.625426683036889, \quad (\text{A } 53)
 \end{aligned}$$

$$\begin{aligned}
 R_{8,6}(\zeta) : \quad & a_1 = -i1.513048776977928; \quad a_2 = -1.128859520019374; \\
 & a_3 = i0.5184905792641649; \\
 & a_4 = 0.1535743993372947; \quad a_5 = -i0.02799183221943639; \\
 & a_6 = -0.002514851707175031; \\
 & b_1 = -i3.285502627883444, \quad (\text{A } 54)
 \end{aligned}$$

$$\begin{aligned}
 R_{8,7}(\zeta) : \quad & a_1 = -i1.623826833670546; \quad a_2 = -1.289590935716420; \\
 & a_3 = i0.6311517791766421; \\
 & a_4 = 0.2006218487856471; \quad a_5 = -i0.03983385915184296; \\
 & a_6 = -0.004041376481615575, \quad (\text{A } 55)
 \end{aligned}$$

$$\begin{aligned}
 R_{8,8}(\zeta) : \quad & a_1 = -i1.739359630417800; \quad a_2 = -1.471743639038102; \\
 & a_3 = i0.7691080574071934; \\
 & a_4 = 0.2632500611991985; \quad a_5 = -i0.05724369164680910, \quad (\text{A } 56)
 \end{aligned}$$

$$\begin{aligned}
 R_{8,9}(\zeta) : \quad & a_1 = -i1.858726543442496; \quad a_2 = -1.675414915338742; \\
 & a_3 = i0.9356405409666494; \\
 & a_4 = 0.3458159069196990, \quad (\text{A } 57)
 \end{aligned}$$

and we provide analytic results for the last 3 approximants,

$$\begin{aligned}
 R_{8,10}(\zeta) : \quad & a_1 = i\sqrt{\pi} \frac{175\pi - 592}{175\pi - 512}; \quad a_2 = \frac{955\pi - 3072}{175\pi - 512}; \\
 & a_3 = i\sqrt{\pi} \frac{6144 - 1925\pi}{4(175\pi - 512)}; \quad (\text{A } 58)
 \end{aligned}$$

$$R_{8,11}(\zeta) : \quad a_1 = -i\sqrt{\pi} \frac{19}{16}; \quad a_2 = 6 - \frac{665}{256}\pi; \quad (\text{A } 59)$$

$$R_{8,12}(\zeta) : \quad a_1 = -i\sqrt{\pi} \frac{19}{16}. \quad (\text{A } 60)$$

We also provide analytic coefficients for $R_{8,6}(\zeta)$, since this approximant can be used to construct the most precise dynamic closure for the seventh-order moment, which we will not do, however, an enthusiastic reader is encouraged to do the calculation as an exercise! The $R_{8,6}(\zeta)$ coefficients read

$$\begin{aligned}
 R_{8,6}(\zeta) : \quad & a_1 = i\sqrt{\pi} \frac{(189000\pi^3 - 1707165\pi^2 + 5130216\pi - 5128192)}{(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)}; \\
 & a_2 = -\frac{2(46125\pi^3 - 715200\pi^2 + 3126720\pi - 4194304)}{5(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)};
 \end{aligned}$$

$$\begin{aligned}
a_3 &= i\sqrt{\pi} \frac{(378000\pi^3 - 3424725\pi^2 + 10324380\pi - 10354688)}{5(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)}; \\
a_4 &= -\frac{(221400\pi^3 - 4788045\pi^2 + 23537664\pi - 33554432)}{30(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)}; \\
a_5 &= i\sqrt{\pi} \frac{(252000\pi^3 - 2506275\pi^2 + 8286200\pi - 9109504)}{5(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)}; \\
a_6 &= \frac{(1028700\pi^3 - 9863235\pi^2 + 31514112\pi - 33554432)}{15(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)}; \\
b_1 &= -i\sqrt{\pi} \frac{6(15825\pi^2 - 99260\pi + 155648)}{(189000\pi^3 - 1612215\pi^2 + 4534656\pi - 4194304)}.
\end{aligned} \tag{A 61}$$

We advise being very careful when evaluating the above analytic expressions, since for example when the default 10-digit precision is used in Maple, yields $a_1 = -i0.63$, whereas the correct value provided in (A 54) is $a_1 = -i1.51$.

Appendix B. Operator $(\mathbf{E} + \frac{1}{c}\mathbf{v} \times \mathbf{B}) \cdot \nabla_v f_0$ for gyrotropic f_0

The magnetic field is transformed to the electric field with induction equation $\partial \mathbf{B}^{(1)} / \partial t = -c \nabla \times \mathbf{E}^{(1)}$ that in Fourier space reads $\omega \mathbf{B}^{(1)} = c \mathbf{k} \times \mathbf{E}^{(1)}$. From now on, for the electric and magnetic field we drop the superscript (1), so in general

$$\begin{aligned}
\mathbf{E} + \frac{1}{c}\mathbf{v} \times \mathbf{B} &= \mathbf{E} + \frac{1}{\omega}\mathbf{v} \times (\mathbf{k} \times \mathbf{E}) \\
&= \mathbf{E} + \frac{1}{\omega}(\mathbf{k}(\mathbf{v} \cdot \mathbf{E}) - \mathbf{E}(\mathbf{v} \cdot \mathbf{k})) \\
&= \mathbf{E} \left(1 - \frac{\mathbf{v} \cdot \mathbf{k}}{\omega}\right) + \frac{\mathbf{k}}{\omega}(\mathbf{v} \cdot \mathbf{E}).
\end{aligned} \tag{B 1}$$

For any general vector $\mathbf{A} = (A_x, A_y, A_z)$, the expression

$$\mathbf{A} \cdot \nabla_v f_0 = A_x \frac{\partial f_0}{\partial v_x} + A_y \frac{\partial f_0}{\partial v_y} + A_z \frac{\partial f_0}{\partial v_z}, \tag{B 2}$$

so a general expression

$$\begin{aligned}
\left(\mathbf{E} + \frac{1}{c}\mathbf{v} \times \mathbf{B}\right) \cdot \nabla_v f_0 &= \left[E_x \left(1 - \frac{\mathbf{v} \cdot \mathbf{k}}{\omega}\right) + \frac{k_x}{\omega}(\mathbf{v} \cdot \mathbf{E})\right] \frac{\partial f_0}{\partial v_x} \\
&+ \left[E_y \left(1 - \frac{\mathbf{v} \cdot \mathbf{k}}{\omega}\right) + \frac{k_y}{\omega}(\mathbf{v} \cdot \mathbf{E})\right] \frac{\partial f_0}{\partial v_y} \\
&+ \left[E_z \left(1 - \frac{\mathbf{v} \cdot \mathbf{k}}{\omega}\right) + \frac{k_z}{\omega}(\mathbf{v} \cdot \mathbf{E})\right] \frac{\partial f_0}{\partial v_z},
\end{aligned} \tag{B 3}$$

and by straightforward grouping of electric field components together

$$\begin{aligned}
 \left(\mathbf{E} + \frac{1}{c}\mathbf{v} \times \mathbf{B}\right) \cdot \nabla_{\mathbf{v}} f_0 &= E_x \left[\left(1 - \frac{v_y k_y + v_z k_z}{\omega}\right) \frac{\partial f_0}{\partial v_x} + \frac{v_x}{\omega} \left(k_y \frac{\partial f_0}{\partial v_y} + k_z \frac{\partial f_0}{\partial v_z}\right) \right] \\
 &+ E_y \left[\left(1 - \frac{v_x k_x + v_z k_z}{\omega}\right) \frac{\partial f_0}{\partial v_y} + \frac{v_y}{\omega} \left(k_x \frac{\partial f_0}{\partial v_x} + k_z \frac{\partial f_0}{\partial v_z}\right) \right] \\
 &+ E_z \left[\left(1 - \frac{v_x k_x + v_y k_y}{\omega}\right) \frac{\partial f_0}{\partial v_z} + \frac{v_z}{\omega} \left(k_x \frac{\partial f_0}{\partial v_x} + k_y \frac{\partial f_0}{\partial v_y}\right) \right].
 \end{aligned}
 \tag{B 4}$$

Since nothing was essentially calculated, the above expression is of general validity and correct for any distribution function f_0 . The expression simplifies by considering a gyrotropic $f_0(v_{\perp}, v_{\parallel})$, that depends only on $v_{\perp} = |\mathbf{v}_{\perp}| = \sqrt{v_x^2 + v_y^2}$, and which allows us to calculate

$$\begin{aligned}
 \frac{\partial v_{\perp}}{\partial v_x} &= \frac{\sqrt{v_x^2 + v_y^2}}{\partial v_x} = \frac{v_x}{\sqrt{v_x^2 + v_y^2}} = \frac{v_x}{v_{\perp}}; \\
 \frac{\partial f_0}{\partial v_x} &= \frac{\partial v_{\perp}}{\partial v_x} \frac{\partial f_0}{\partial v_{\perp}} = \frac{v_x}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}}; \quad \frac{\partial f_0}{\partial v_y} = \frac{\partial v_{\perp}}{\partial v_y} \frac{\partial f_0}{\partial v_{\perp}} = \frac{v_y}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}}.
 \end{aligned}
 \tag{B 5}$$

Or in another words, in the cylindrical coordinate system the f_0 is ϕ independent and $\partial f_0 / \partial \phi = 0$, so that the velocity gradient

$$\nabla_{\mathbf{v}} f_0 = \begin{pmatrix} \frac{v_x}{v_{\perp}} \frac{\partial}{\partial v_{\perp}} \\ \frac{v_y}{v_{\perp}} \frac{\partial}{\partial v_{\perp}} \\ \frac{\partial}{\partial v_{\parallel}} \end{pmatrix} f_0 = \begin{pmatrix} \cos \phi \frac{\partial}{\partial v_{\perp}} \\ \sin \phi \frac{\partial}{\partial v_{\perp}} \\ \frac{\partial}{\partial v_{\parallel}} \end{pmatrix} f_0.
 \tag{B 6}$$

This simplification for f_0 being gyrotropic therefore yields

$$\begin{aligned}
 \left(\mathbf{E} + \frac{1}{c}\mathbf{v} \times \mathbf{B}\right) \cdot \nabla_{\mathbf{v}} f_0 &= E_x \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega}\right) \frac{v_x}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} + \frac{v_x}{\omega} k_{\parallel} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\
 &+ E_y \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega}\right) \frac{v_y}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} + \frac{v_y}{\omega} k_{\parallel} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\
 &+ E_z \left[\left(1 - \frac{v_x k_x + v_y k_y}{\omega}\right) \frac{\partial f_0}{\partial v_{\parallel}} \right. \\
 &\left. + \frac{v_{\parallel}}{\omega} \left(k_x \frac{v_x}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} + k_y \frac{v_y}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}}\right) \right],
 \end{aligned}
 \tag{B 7}$$

that is conveniently rearranged as

$$\begin{aligned}
 \left(\mathbf{E} + \frac{1}{c}\mathbf{v} \times \mathbf{B}\right) \cdot \nabla_{\mathbf{v}} f_0 &= (E_x v_x + E_y v_y) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega}\right) \frac{1}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\
 &+ E_z \left[\left(1 - \frac{v_x k_x + v_y k_y}{\omega}\right) \frac{\partial f_0}{\partial v_{\parallel}} + \frac{v_{\parallel}}{\omega v_{\perp}} (k_x v_x + k_y v_y) \frac{\partial f_0}{\partial v_{\perp}} \right],
 \end{aligned}
 \tag{B 8}$$

or alternatively as

$$\left(\mathbf{E} + \frac{1}{c}\mathbf{v} \times \mathbf{B}\right) \cdot \nabla_v f_0 = (E_x v_x + E_y v_y) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega}\right) \frac{1}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] + E_z \left[\frac{\partial f_0}{\partial v_{\parallel}} - \frac{v_x k_x + v_y k_y}{\omega} \left(\frac{\partial f_0}{\partial v_{\parallel}} - \frac{v_{\parallel}}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} \right) \right]. \quad (\text{B } 9)$$

In the cylindrical coordinate system $d^3v = v_{\perp} dv_{\perp} dv_{\parallel} d\phi$.

Appendix C. General kinetic $f^{(1)}$ distribution (effects of non-gyrotropy)

The calculation is actually not that difficult once the coordinate change is figured out, as elaborated in the plasma physics books by Stix, Swanson, Akheizer etc. In the general equation (2.15) the (1) quantities must be Fourier transformed according to

$$\begin{aligned} f^{(1)}(\mathbf{x}, \mathbf{v}, t) &= f^{(1)} e^{i\mathbf{k} \cdot \mathbf{x} - i\omega t}, \\ \mathbf{E}^{(1)}(\mathbf{x}', t') &= \mathbf{E}^{(1)} e^{i\mathbf{k} \cdot \mathbf{x}' - i\omega' t'}, \\ \mathbf{B}^{(1)}(\mathbf{x}', t') &= \mathbf{B}^{(1)} e^{i\mathbf{k} \cdot \mathbf{x}' - i\omega' t'}, \end{aligned} \quad (\text{C } 1)$$

and the equation (2.15) rewrites

$$f^{(1)} e^{i\mathbf{k} \cdot \mathbf{x} - i\omega t} = -\frac{q_r}{m_r} \int_{-\infty}^t e^{i\mathbf{k} \cdot \mathbf{x}' - i\omega' t'} \left[\mathbf{E}^{(1)} + \frac{1}{c} \mathbf{v}' \times \mathbf{B}^{(1)} \right] \cdot \nabla_{v'} f_0(\mathbf{v}') dt'. \quad (\text{C } 2)$$

In the cylindrical coordinate system with velocity (2.2) and the wave vector

$$\mathbf{k} = \begin{pmatrix} k_{\perp} \cos \psi \\ k_{\perp} \sin \psi \\ k_{\parallel} \end{pmatrix}. \quad (\text{C } 3)$$

The integration is changed to be done with respect to variable

$$\tau = t - t'. \quad (\text{C } 4)$$

The time t is a constant here and since $d\tau = -dt'$, the integration reads $\int_{-\infty}^t dt' = \int_{\infty}^0 (-d\tau) = \int_0^{\infty} d\tau$. The variable transformation is performed according to

$$\mathbf{v}' = \begin{pmatrix} v'_x \\ v'_y \\ v'_z \end{pmatrix} = \begin{pmatrix} v_{\perp} \cos(\phi + \Omega\tau) \\ v_{\perp} \sin(\phi + \Omega\tau) \\ v_{\parallel} \end{pmatrix} \quad (\text{C } 5)$$

$$\mathbf{x}' = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} -\frac{v_{\perp}}{\Omega} [\sin(\phi + \Omega\tau) - \sin\phi] \\ +\frac{v_{\perp}}{\Omega} [\cos(\phi + \Omega\tau) - \cos\phi] \\ -v_{\parallel} \tau \end{pmatrix}, \quad (\text{C } 6)$$

which at time $\tau = 0$ satisfies the initial condition. Now, by straightforward calculation (and by using $\sin(a) \cos(b) - \cos(a) \sin(b) = \sin(a - b)$), the exponential factor is transformed as

$$\mathbf{k} \cdot \mathbf{x}' - \omega' t' = \mathbf{k} \cdot \mathbf{x} - \omega t - \frac{k_{\perp} v_{\perp}}{\Omega} [\sin(\phi - \psi + \Omega\tau) - \sin(\phi - \psi)] + (\omega - k_{\parallel} v_{\parallel}) \tau, \quad (\text{C } 7)$$

so that

$$e^{i\mathbf{k} \cdot \mathbf{x}' - i\omega' t'} = e^{i\mathbf{k} \cdot \mathbf{x} - i\omega t} e^{-i(k_{\perp} v_{\perp} / \Omega) \sin(\phi - \psi + \Omega\tau)} e^{+i(k_{\perp} v_{\perp} / \Omega) \sin(\phi - \psi)} e^{i(\omega - k_{\parallel} v_{\parallel}) \tau}. \quad (\text{C } 8)$$

The complicated expressions encountered in the kinetic dispersion relations originate in using identity

$$e^{iz \sin \phi} = \sum_{n=-\infty}^{\infty} e^{in\phi} J_n(z). \tag{C9}$$

There are two such exponents, and therefore the linear kinetic theory contains two independent summations, usually one through ‘*n*’ and one through ‘*m*’ (which should not be confused with mass), i.e.

$$e^{-i(k_{\perp} v_{\perp} / \Omega) \sin(\phi - \psi + \Omega \tau)} = \sum_{n=-\infty}^{\infty} e^{-in(\phi - \psi + \Omega \tau)} J_n \left(\frac{k_{\perp} v_{\perp}}{\Omega} \right); \tag{C10}$$

$$e^{+i(k_{\perp} v_{\perp} / \Omega) \sin(\phi - \psi)} = \sum_{m=-\infty}^{\infty} e^{+im(\phi - \psi)} J_m \left(\frac{k_{\perp} v_{\perp}}{\Omega} \right), \tag{C11}$$

and together

$$\begin{aligned} & e^{-i(k_{\perp} v_{\perp} / \Omega) \sin(\phi - \psi + \Omega \tau)} e^{+i(k_{\perp} v_{\perp} / \Omega) \sin(\phi - \psi)} \\ &= \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} e^{+i(m-n)(\phi - \psi)} e^{-in\Omega \tau} J_n \left(\frac{k_{\perp} v_{\perp}}{\Omega} \right) J_m \left(\frac{k_{\perp} v_{\perp}}{\Omega} \right). \end{aligned} \tag{C12}$$

It is obvious that the quantity $k_{\perp} v_{\perp} / \Omega$ will be always present and it is useful to use some abbreviations. Each book chooses a different notation, Swanson uses ‘*b*’, Stix uses ‘*z*’, etc. Since we are interested in Landau fluid models, we choose to follow the notation of Passot and Sulem 2006 and call this quantity for *r*-species λ_r , so¹²

$$\lambda_r \equiv \frac{k_{\perp} v_{\perp}}{\Omega_r}, \tag{C13}$$

where for clarity of calculations, we again drop the species index *r*. The transformation of the full exponential factor (C8) therefore yields

$$e^{ik \cdot \mathbf{x}' - i\omega t'} = e^{ik \cdot \mathbf{x} - i\omega t} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} e^{+i(m-n)(\phi - \psi)} e^{+i(\omega - k_{\parallel} v_{\parallel} - n\Omega)\tau} J_n(\lambda) J_m(\lambda). \tag{C14}$$

Using this result in (C2) allows the usual cancellation of the exponential factor $e^{ik \cdot \mathbf{x} - i\omega t}$ on both sides of the Fourier transformed equation, a step that we omitted to explicitly write down many times before. The partially transformed equation (C2) therefore reads

$$\begin{aligned} f^{(1)} = & -\frac{q_r}{m_r} \int_0^{\infty} \left[\sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} e^{+i(m-n)(\phi - \psi)} e^{+i(\omega - k_{\parallel} v_{\parallel} - n\Omega)\tau} \right. \\ & \left. \times J_n(\lambda) J_m(\lambda) \left(\mathbf{E}^{(1)} + \frac{1}{c} \mathbf{v}' \times \mathbf{B}^{(1)} \right) \cdot \nabla_{\mathbf{v}'} f_0(\mathbf{v}') \right] d\tau, \end{aligned} \tag{C15}$$

¹²Note that this notation should not be confused with notation in Peter Gary’s book where λ is reserved for quantities encountered in the final dispersion relation and is $\sim k_{\perp}^2$.

where we still did not perform the coordinate change in the operator at the end of the equation. From now on, for the electric and magnetic fields we drop the superscript (1). Let us first calculate the gradient $\nabla_{v'} f_0(\mathbf{v}')$.

It is useful to emphasize a very important property

$$|\mathbf{v}'_{\perp}|^2 = v_x'^2 + v_y'^2 = v_{\perp}^2 \cos^2(\phi + \Omega\tau) + v_{\perp}^2 \sin^2(\phi + \Omega\tau) = |\mathbf{v}_{\perp}|^2, \quad (\text{C } 16)$$

or in another words $|\mathbf{v}'_{\perp}| = |\mathbf{v}_{\perp}|$ that is often abbreviated with non-bolded $v'_{\perp} = v_{\perp}$ (and since $v'_{\parallel} = v_{\parallel}$ also $|\mathbf{v}'| = |\mathbf{v}|$). At first, it can be perhaps a bit confusing when one writes that the non-bolded $v'_{\perp} = v_{\perp}$, since $v'_x \neq v_x$, $v'_y \neq v_y$ and also the bolded $\mathbf{v}' \neq \mathbf{v}$. The above identity implies that for the gyrotropic f_0 (which is a strict requirement for f_0)

$$f_0(|\mathbf{v}'_{\perp}|^2, v'_{\parallel}) = f_0(|\mathbf{v}_{\perp}|^2, v_{\parallel}), \quad (\text{C } 17)$$

further implying that

$$\frac{\partial f_0}{\partial v'_{\perp}} \equiv \frac{\partial f_0}{\partial |\mathbf{v}'_{\perp}|} = \frac{\partial f_0}{\partial |\mathbf{v}_{\perp}|} \equiv \frac{\partial f_0}{\partial v_{\perp}}. \quad (\text{C } 18)$$

The $\nabla_{v'} f_0$ can now be calculated easily, since

$$\frac{\partial f_0}{\partial v'_x} = \frac{\partial f_0}{\partial |\mathbf{v}'_{\perp}|} \frac{\partial |\mathbf{v}'_{\perp}|}{\partial v'_x} = \frac{\partial f_0}{\partial v_{\perp}} \frac{v'_x}{v_{\perp}}; \quad \frac{\partial f_0}{\partial v'_y} = \frac{\partial f_0}{\partial v_{\perp}} \frac{v'_y}{v_{\perp}}, \quad (\text{C } 19)$$

and the gradient is written as (for gyrotropic $\partial f_0/\partial\phi = 0$)

$$\nabla_{v'} f_0 = \begin{pmatrix} \frac{v'_x}{v_{\perp}} \frac{\partial}{\partial v_{\perp}} \\ \frac{v'_y}{v_{\perp}} \frac{\partial}{\partial v_{\perp}} \\ \frac{\partial}{\partial v_{\parallel}} \end{pmatrix} f_0 = \begin{pmatrix} \cos(\phi + \Omega\tau) \frac{\partial}{\partial v_{\perp}} \\ \sin(\phi + \Omega\tau) \frac{\partial}{\partial v_{\perp}} \\ \frac{\partial}{\partial v_{\parallel}} \end{pmatrix} f_0. \quad (\text{C } 20)$$

It is actually simpler to postpone the introduction of angles ϕ , ψ and for a moment keep a general notation $\mathbf{v}' = (v'_x, v'_y, v'_z)$ and $\mathbf{k} = (k_x, k_y, k_z)$. To transform the $(\mathbf{E} + (1/c)\mathbf{v}' \times \mathbf{B}) \cdot \nabla_{v'} f_0$, one can do the completely same operations as were done in the previous subsection where the operator $(\mathbf{E} + (1/c)\mathbf{v} \times \mathbf{B}) \cdot \nabla_{v'} f_0$ was considered. One can just use the result (B 9), add primes to all velocities and delete those on $v'_{\perp} = v_{\perp}$, $v'_y = v_y$, finally yielding

$$\begin{aligned} \left(\mathbf{E} + \frac{1}{c} \mathbf{v}' \times \mathbf{B} \right) \cdot \nabla_{v'} f_0 &= (E_x v'_x + E_y v'_y) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega} \right) \frac{1}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\ &+ E_z \left[\frac{\partial f_0}{\partial v_{\parallel}} - \frac{v'_x k_x + v'_y k_y}{\omega} \left(\frac{\partial f_0}{\partial v_{\parallel}} - \frac{v_{\parallel}}{v_{\perp}} \frac{\partial f_0}{\partial v_{\perp}} \right) \right], \quad (\text{C } 21) \end{aligned}$$

which is equivalent to equation (4.83) in Swanson. Only now we introduce the angles and finish the transformation. Since

$$\begin{aligned} v'_x k_x + v'_y k_y &= v_{\perp} \cos(\phi + \Omega\tau) k_{\perp} \cos\psi + v_{\perp} \sin(\phi + \Omega\tau) k_{\perp} \sin\psi \\ &= v_{\perp} k_{\perp} \cos(\phi + \Omega\tau - \psi), \quad (\text{C } 22) \end{aligned}$$

the transformation yields

$$\begin{aligned}
 & \left(\mathbf{E} + \frac{1}{c} \mathbf{v}' \times \mathbf{B} \right) \cdot \nabla_v f_0 \\
 &= (E_x \cos(\phi + \Omega \tau) + E_y \sin(\phi + \Omega \tau)) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega} \right) \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel} v_{\perp}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\
 &+ E_z \left[\frac{\partial f_0}{\partial v_{\parallel}} + \frac{k_{\perp}}{\omega} \cos(\phi + \Omega \tau - \psi) \left(v_{\parallel} \frac{\partial f_0}{\partial v_{\perp}} - v_{\perp} \frac{\partial f_0}{\partial v_{\parallel}} \right) \right]. \tag{C 23}
 \end{aligned}$$

To be clear, let us write down the complete result (C 15) that we have for now

$$\begin{aligned}
 f^{(1)} &= -\frac{q_r}{m_r} \int_0^{\infty} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} e^{+i(m-n)(\phi-\psi)} e^{+i(\omega-k_{\parallel}v_{\parallel}-n\Omega)\tau} J_n(\lambda) J_m(\lambda) \\
 &\times \left\{ (E_x \cos(\phi + \Omega \tau) + E_y \sin(\phi + \Omega \tau)) \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega} \right) \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel} v_{\perp}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \right. \\
 &\left. + E_z \left[\frac{\partial f_0}{\partial v_{\parallel}} + \frac{k_{\perp}}{\omega} \left(v_{\parallel} \frac{\partial f_0}{\partial v_{\perp}} - v_{\perp} \frac{\partial f_0}{\partial v_{\parallel}} \right) \cos(\phi + \Omega \tau - \psi) \right] \right\} d\tau, \tag{C 24}
 \end{aligned}$$

where the \times at the beginning of the second line is just a multiplication and not a cross-product (the equation is not written in the vector form anyway). The result agrees with Stix’s expressions (10.38) and (10.39), even though Stix at this stage did not use the Bessel expansion yet. Stix now does not proceed with the evaluation of the integral along τ , and instead goes ahead and already starts to partially calculate the first-order velocity moment with integrals $\int \mathbf{v} f^{(1)} d^3v$ (first integrating over $\int_0^{2\pi} d\phi$) to eventually obtain the kinetic current $\mathbf{j} = \sum_r q_r n_r \mathbf{u}_r = \sum_r q_r \int \mathbf{v}_r f_r^{(1)} d^3v_r$ and the conductivity matrix $(\sigma)_{ij}$ (through $\mathbf{j} = \boldsymbol{\sigma} \cdot \mathbf{E}$) that leads to the kinetic dispersion relation. Stix actually first derives (C 23) plugged into (C 2). After introducing the Bessel expansion, Stix immediately performs the integration over $d\phi$. The integration over τ is done later during other calculations, and this somewhat simplifies the amount of algebra that needs to be written down. The simplified algebra is beneficial and surely appreciated by experienced kinetic researchers, however, especially for new researchers, it somewhat blurs the main point, how the kinetic dispersion relation is derived. The kinetic dispersion relation is derived by obtaining the $f^{(1)}$, and by calculating the current \mathbf{j} . Moreover, we later want to obtain higher-order moments of $f^{(1)}$ than just the first-order velocity moment. We therefore follow Swanson, Akheizer, Passot and Sulem, and finish the calculation of $f^{(1)}$ by evaluating the $\int_0^{\infty} d\tau$ integral in (C 24).

By examining equation (C 24), there is only one factor that is τ dependent in the first line that needs to be integrated, $e^{i(\omega-k_{\parallel}v_{\parallel}-n\Omega)\tau}$, and the factor is multiplied by four different possibilities, $\cos(\phi + \Omega \tau)$, $\sin(\phi + \Omega \tau)$, 1 and $\cos(\phi + \Omega \tau - \psi)$. We first need to examine the following integral

$$\int_0^{\infty} e^{iax} dx = \frac{i}{a}; \quad \text{if } \text{Im}(a) > 0. \tag{C 25}$$

This perhaps surprising integral can be easily verified since an indefinite integral $e^{iax}/(ia)$ exists and the curious limit

$$\lim_{x \rightarrow \infty} e^{iax} = \lim_{x \rightarrow \infty} e^{i[\text{Re}(a)+i\text{Im}(a)]x} = \lim_{x \rightarrow \infty} e^{i\text{Re}(a)x} e^{-\text{Im}(a)x} = 0; \quad \text{if } \text{Im}(a) > 0. \tag{C 26}$$

Obviously, the $\text{Im}(a) > 0$ is a strict requirement. If $\text{Im}(a) = 0$, the limit is undefined since $\cos(x)$ and $\sin(x)$ always oscillate, and if $\text{Im}(a) < 0$ the limit diverges to $\pm\infty$. Therefore, one of the four needed integrals is

$$\int_0^\infty e^{i(\omega - k_{\parallel} v_{\parallel} - n\Omega)\tau} d\tau = \frac{i}{\omega - k_{\parallel} v_{\parallel} - n\Omega}; \quad \text{if } \text{Im}(\omega) > 0, \quad (\text{C } 27)$$

where the $\text{Im}(\omega) > 0$ requirement is obtained, because k_{\parallel} , v_{\parallel} , Ω are real numbers, n is an integer and none of these can have an imaginary part. For the other 3 integrals we need

$$\begin{aligned} \int_0^\infty e^{ia\tau} \cos(\phi + \Omega\tau) d\tau &= \frac{1}{2} \int_0^\infty e^{ia\tau} (e^{i(\phi + \Omega\tau)} + e^{-i(\phi + \Omega\tau)}) d\tau \\ &= \frac{e^{i\phi}}{2} \int_0^\infty e^{i(a + \Omega)\tau} d\tau + \frac{e^{-i\phi}}{2} \int_0^\infty e^{i(a - \Omega)\tau} d\tau \\ &= \frac{e^{i\phi}}{2} \frac{i}{a + \Omega} + \frac{e^{-i\phi}}{2} \frac{i}{a - \Omega} \\ &= \frac{i}{2} \left(\frac{e^{i\phi}}{a + \Omega} + \frac{e^{-i\phi}}{a - \Omega} \right); \quad \text{if } \text{Im}(a) > 0, \quad (\text{C } 28) \end{aligned}$$

and similarly

$$\begin{aligned} \int_0^\infty e^{ia\tau} \sin(\phi + \Omega\tau) d\tau &= \frac{1}{2i} \int_0^\infty e^{ia\tau} (e^{i(\phi + \Omega\tau)} - e^{-i(\phi + \Omega\tau)}) d\tau \\ &= \frac{e^{i\phi}}{2i} \int_0^\infty e^{i(a + \Omega)\tau} d\tau - \frac{e^{-i\phi}}{2i} \int_0^\infty e^{i(a - \Omega)\tau} d\tau \\ &= \frac{e^{i\phi}}{2i} \frac{i}{a + \Omega} - \frac{e^{-i\phi}}{2i} \frac{i}{a - \Omega} \\ &= \frac{1}{2} \left(\frac{e^{i\phi}}{a + \Omega} - \frac{e^{-i\phi}}{a - \Omega} \right); \quad \text{if } \text{Im}(a) > 0. \quad (\text{C } 29) \end{aligned}$$

The 3 required integrals therefore calculate as

$$\begin{aligned} \int_0^\infty e^{i(\omega - k_{\parallel} v_{\parallel} - n\Omega)\tau} \cos(\phi + \Omega\tau) d\tau \\ = \frac{i}{2} \left(\frac{e^{i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n-1)\Omega} + \frac{e^{-i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n+1)\Omega} \right); \quad (\text{C } 30) \end{aligned}$$

$$\begin{aligned} \int_0^\infty e^{i(\omega - k_{\parallel} v_{\parallel} - n\Omega)\tau} \cos(\phi - \psi + \Omega\tau) d\tau \\ = \frac{i}{2} \left(\frac{e^{i(\phi - \psi)}}{\omega - k_{\parallel} v_{\parallel} - (n-1)\Omega} + \frac{e^{-i(\phi - \psi)}}{\omega - k_{\parallel} v_{\parallel} - (n+1)\Omega} \right); \quad (\text{C } 31) \end{aligned}$$

$$\begin{aligned} \int_0^\infty e^{i(\omega - k_{\parallel} v_{\parallel} - n\Omega)\tau} \sin(\phi + \Omega\tau) d\tau \\ = \frac{1}{2} \left(\frac{e^{i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n-1)\Omega} - \frac{e^{-i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n+1)\Omega} \right), \quad (\text{C } 32) \end{aligned}$$

and all 3 results require $\text{Im}(\omega) > 0$. This strictly appearing restriction is removed later by the analytic continuation, once the fluid integrals over the $f^{(1)}$ are calculated. We therefore managed to finish the integration of (C 24) along the unperturbed orbit and our latest full result for $f^{(1)}$ reads

$$\begin{aligned}
 f^{(1)} = & -\frac{q_r}{m_r} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} e^{+i(m-n)(\phi-\psi)} J_n(\lambda) J_m(\lambda) \\
 & \times \left\{ \left[\frac{iE_x}{2} \left(\frac{e^{i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n-1)\Omega} + \frac{e^{-i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n+1)\Omega} \right) \right. \right. \\
 & \left. \left. + \frac{E_y}{2} \left(\frac{e^{i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n-1)\Omega} - \frac{e^{-i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n+1)\Omega} \right) \right] \right. \\
 & \times \left[\left(1 - \frac{v_{\parallel} k_{\parallel}}{\omega} \right) \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel} v_{\perp}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \\
 & + E_z \left[\frac{i}{\omega - k_{\parallel} v_{\parallel} - n\Omega} \frac{\partial f_0}{\partial v_{\parallel}} + \frac{k_{\perp}}{\omega} \left(v_{\parallel} \frac{\partial f_0}{\partial v_{\perp}} - v_{\perp} \frac{\partial f_0}{\partial v_{\parallel}} \right) \right. \\
 & \left. \left. \times \frac{i}{2} \left(\frac{e^{i(\phi-\psi)}}{\omega - k_{\parallel} v_{\parallel} - (n-1)\Omega} + \frac{e^{-i(\phi-\psi)}}{\omega - k_{\parallel} v_{\parallel} - (n+1)\Omega} \right) \right] \right\}. \tag{C 33}
 \end{aligned}$$

Obviously, the result is not very pretty, and we would like somehow to pull out the denominator $\omega - k_{\parallel} v_{\parallel} - n\Omega$ from all the expressions, so that the ‘resonances’ are grouped together. The trouble is the shifted $(n - 1)\Omega$ and $(n + 1)\Omega$. However, all expressions are preceded by $\sum_{n=-\infty}^{\infty}$. It is therefore easy to shift the summation by one index, where terms that contain $(n - 1)\Omega$ require shift $n = l + 1$, and terms that contain $(n + 1)\Omega$ require shift $n = l - 1$. The transformation is easy to calculate, for example the terms proportional to E_x transform as

$$\begin{aligned}
 & \sum_{n=-\infty}^{\infty} e^{+i(m-n)(\phi-\psi)} J_n(\lambda) \frac{e^{i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n-1)\Omega} \\
 & = \sum_{l=-\infty}^{\infty} e^{+i(m-l-1)(\phi-\psi)} J_{l+1}(\lambda) \frac{e^{i\phi}}{\omega - k_{\parallel} v_{\parallel} - l\Omega} \\
 & = \sum_{l=-\infty}^{\infty} e^{+i(m-l)(\phi-\psi)} J_{l+1}(\lambda) \frac{e^{-i(\phi-\psi)} e^{i\phi}}{\omega - k_{\parallel} v_{\parallel} - l\Omega} \\
 & = \sum_{l=-\infty}^{\infty} e^{+i(m-l)(\phi-\psi)} J_{l+1}(\lambda) \frac{e^{+i\psi}}{\omega - k_{\parallel} v_{\parallel} - l\Omega}; \tag{C 34}
 \end{aligned}$$

$$\begin{aligned}
 & \sum_{n=-\infty}^{\infty} e^{+i(m-n)(\phi-\psi)} J_n(\lambda) \frac{e^{-i\phi}}{\omega - k_{\parallel} v_{\parallel} - (n+1)\Omega} \\
 & = \sum_{l=-\infty}^{\infty} e^{+i(m-l+1)(\phi-\psi)} J_{l-1}(\lambda) \frac{e^{-i\phi}}{\omega - k_{\parallel} v_{\parallel} - l\Omega} \\
 & = \sum_{l=-\infty}^{\infty} e^{+i(m-l)(\phi-\psi)} J_{l-1}(\lambda) \frac{e^{-i\psi}}{\omega - k_{\parallel} v_{\parallel} - l\Omega}. \tag{C 35}
 \end{aligned}$$

Adding the two equations together, both E_x terms therefore transform as

$$(C\ 34) + (C\ 35) = \sum_{l=-\infty}^{\infty} \frac{e^{+i(m-l)(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - l\Omega} (J_{l+1}(\lambda)e^{+i\psi} + J_{l-1}(\lambda)e^{-i\psi}). \quad (C\ 36)$$

The transformation of terms proportional to E_y is almost identical since the 2 terms are just subtracted, and it is equivalent to

$$(C\ 34) - (C\ 35) = \sum_{l=-\infty}^{\infty} \frac{e^{+i(m-l)(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - l\Omega} (J_{l+1}(\lambda)e^{+i\psi} - J_{l-1}(\lambda)e^{-i\psi}). \quad (C\ 37)$$

The terms proportional to E_z are now very easy to transform and

$$\begin{aligned} & \sum_{n=-\infty}^{\infty} e^{+i(m-n)(\phi-\psi)} J_n(\lambda) \frac{e^{i(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - (n-1)\Omega} \\ &= \sum_{l=-\infty}^{\infty} e^{+i(m-l)(\phi-\psi)} J_{l+1}(\lambda) \frac{1}{\omega - k_{\parallel}v_{\parallel} - l\Omega}; \end{aligned} \quad (C\ 38)$$

$$\begin{aligned} & \sum_{n=-\infty}^{\infty} e^{+i(m-n)(\phi-\psi)} J_n(\lambda) \frac{e^{-i(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - (n+1)\Omega} \\ &= \sum_{l=-\infty}^{\infty} e^{+i(m-l)(\phi-\psi)} J_{l-1}(\lambda) \frac{1}{\omega - k_{\parallel}v_{\parallel} - l\Omega}, \end{aligned} \quad (C\ 39)$$

and together

$$(C\ 38) + (C\ 39) = \sum_{l=-\infty}^{\infty} \frac{e^{+i(m-l)(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - l\Omega} (J_{l+1}(\lambda) + J_{l-1}(\lambda)). \quad (C\ 40)$$

We therefore managed to rearrange the summation and equation (C33) for $f^{(1)}$ transforms to

$$\begin{aligned} f^{(1)} = & -\frac{q_r}{m_r} \sum_{l=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{+i(m-l)(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - l\Omega} J_m(\lambda) \left\{ \left[\frac{iE_x}{2} (J_{l+1}(\lambda)e^{+i\psi} + J_{l-1}(\lambda)e^{-i\psi}) \right. \right. \\ & + \frac{E_y}{2} (J_{l+1}(\lambda)e^{+i\psi} - J_{l-1}(\lambda)e^{-i\psi}) \left. \left[\left(1 - \frac{v_{\parallel}k_{\parallel}}{\omega} \right) \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \right. \\ & \left. \left. + E_z \left[iJ_l(\lambda) \frac{\partial f_0}{\partial v_{\parallel}} + \frac{k_{\perp}}{\omega} \left(v_{\parallel} \frac{\partial f_0}{\partial v_{\perp}} - v_{\perp} \frac{\partial f_0}{\partial v_{\parallel}} \right) \frac{i}{2} (J_{l+1}(\lambda) + J_{l-1}(\lambda)) \right] \right\}. \end{aligned} \quad (C\ 41)$$

This is much prettier result than (C33) since all the cyclotron resonances of the same order are nicely grouped together. We are essentially done, however, there is one more step that allows further simplification and that is the use of Bessel identities

$$J_{l-1}(z) + J_{l+1}(z) = \frac{2l}{z} J_l(z); \quad (C\ 42)$$

$$J_{l-1}(z) - J_{l+1}(z) = 2J'_l(z), \quad (C\ 43)$$

where the prime represents a derivative, so $J'_l(z) = \partial J_l(z)/\partial z$. The contributions proportional to E_x, E_y are rewritten as

$$\begin{aligned} J_{l+1}(\lambda)e^{+i\psi} + J_{l-1}(\lambda)e^{-i\psi} &= J_{l+1}(\lambda)(\cos \psi + i \sin \psi) + J_{l-1}(\lambda)(\cos \psi - i \sin \psi) \\ &= (J_{l+1}(\lambda) + J_{l-1}(\lambda)) \cos \psi + i (J_{l+1}(\lambda) - J_{l-1}(\lambda)) \sin \psi \\ &= \frac{2l}{\lambda} J_l(\lambda) \cos \psi - 2iJ'_l(\lambda) \sin \psi; \end{aligned} \tag{C 44}$$

$$\begin{aligned} J_{l+1}(\lambda)e^{+i\psi} - J_{l-1}(\lambda)e^{-i\psi} &= J_{l+1}(\lambda)(\cos \psi + i \sin \psi) - J_{l-1}(\lambda)(\cos \psi - i \sin \psi) \\ &= (J_{l+1}(\lambda) - J_{l-1}(\lambda)) \cos \psi + i (J_{l+1}(\lambda) + J_{l-1}(\lambda)) \sin \psi \\ &= -2J'_l(\lambda) \cos \psi + i \frac{2l}{\lambda} J_l(\lambda) \sin \psi, \end{aligned} \tag{C 45}$$

and the contributions proportional to E_z are trivial. The expression for $f^{(1)}$ reads

$$\begin{aligned} f^{(1)} &= -\frac{q_r}{m_r} \sum_{l=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{+i(m-l)(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - l\Omega} J_m(\lambda) \left\{ \left[iE_x \left(\frac{l}{\lambda} J_l(\lambda) \cos \psi - iJ'_l(\lambda) \sin \psi \right) \right. \right. \\ &\quad \left. \left. + iE_y \left(iJ'_l(\lambda) \cos \psi + \frac{l}{\lambda} J_l(\lambda) \sin \psi \right) \right] \left[\left(1 - \frac{v_{\parallel}k_{\parallel}}{\omega} \right) \frac{\partial f_0}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega} \frac{\partial f_0}{\partial v_{\parallel}} \right] \right. \\ &\quad \left. + iE_z J_l(\lambda) \left[\frac{\partial f_0}{\partial v_{\parallel}} + \frac{k_{\perp}}{\omega} \frac{l}{\lambda} \left(v_{\parallel} \frac{\partial f_0}{\partial v_{\perp}} - v_{\perp} \frac{\partial f_0}{\partial v_{\parallel}} \right) \right] \right\}. \end{aligned} \tag{C 46}$$

Pulling the i out to the front, re-grouping the E_x, E_y terms together and renaming $l \rightarrow n$ (since it is somewhat nicer and cannot be confused with imaginary i , even though it can be confused with density n_r), together with reintroducing the species index r for $f_r^{(1)}, f_{0r}, \lambda_r$ and Ω_r , yields the ‘grand-finale’ result of this section, in the form

$$\begin{aligned} f_r^{(1)} &= -\frac{iq_r}{m_r} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{+i(m-n)(\phi-\psi)}}{\omega - k_{\parallel}v_{\parallel} - n\Omega_r} J_m(\lambda_r) \left\{ \left[\frac{nJ_n(\lambda_r)}{\lambda_r} (E_x \cos \psi + E_y \sin \psi) \right. \right. \\ &\quad \left. \left. + iJ'_n(\lambda_r) (-E_x \sin \psi + E_y \cos \psi) \right] \left[\left(1 - \frac{k_{\parallel}v_{\parallel}}{\omega} \right) \frac{\partial f_{0r}}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] \right. \\ &\quad \left. + E_z J_n(\lambda_r) \left[\frac{\partial f_{0r}}{\partial v_{\parallel}} - \frac{n\Omega_r}{\omega} \left(\frac{\partial f_{0r}}{\partial v_{\parallel}} - \frac{v_{\parallel}}{v_{\perp}} \frac{\partial f_{0r}}{\partial v_{\perp}} \right) \right] \right\}. \end{aligned} \tag{C 47}$$

The quantity $\lambda_r \equiv k_{\perp}v_{\perp}/\Omega_r$, and $\Omega_r = q_r B_0/(m_r c)$. The expression is equivalent to equation (4.88) in Swanson.¹³

C.1. *Case $\psi = 0$, propagation in the x - z plane*

If we are interested only in linear dispersion relations (and not in the development of higher-order fluid hierarchy suitable for numerical simulations), we can restrict ourselves to the propagation in the x - z plane, as we have done many times before when solving dispersion relations. In the x - z plane, the wavenumber $\mathbf{k} = (k_x, 0, k_z) = (k_{\perp}, 0, k_{\parallel})$, or equivalently the angle $\psi = 0$. In this case, the expression (C 47) simplifies to

¹³Swanson and others use notation $\partial f_0/\partial v_{\perp} \equiv f_{0\perp}$ and $\partial f_0/\partial v_{\parallel} \equiv f_{0\parallel}$, also in Swanson’s notation $\lambda_r = b$.

$$\begin{aligned}
 f_r^{(1)} &= -\frac{iq_r}{m_r} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{i(m-n)\phi}}{\omega - k_{\parallel}v_{\parallel} - n\Omega_r} J_m(\lambda_r) \\
 &\times \left\{ \left[\frac{nJ_n(\lambda_r)}{\lambda_r} E_x + iJ'_n(\lambda_r) E_y \right] \left[\left(1 - \frac{k_{\parallel}v_{\parallel}}{\omega} \right) \frac{\partial f_{0r}}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] \right. \\
 &\left. + E_z J_n(\lambda_r) \left[\frac{\partial f_{0r}}{\partial v_{\parallel}} - \frac{n\Omega_r}{\omega v_{\perp}} \left(v_{\perp} \frac{\partial f_{0r}}{\partial v_{\parallel}} - v_{\parallel} \frac{\partial f_{0r}}{\partial v_{\perp}} \right) \right] \right\}, \tag{C 48}
 \end{aligned}$$

which is equivalent to the equation (10.3.12) in Gurnett and Bhattacharjee. In this case, the coupling of the electric field components with the sum over index m disappears, and the sum can be left in its original form $\sum_{m=-\infty}^{\infty} e^{+im\phi} J_m(\lambda) = e^{+i\lambda \sin \phi}$, yielding

$$\begin{aligned}
 f_r^{(1)} &= -\frac{iq_r}{m_r} e^{i\lambda_r \sin \phi} \sum_{n=-\infty}^{\infty} \frac{e^{-in\phi}}{\omega - k_{\parallel}v_{\parallel} - n\Omega_r} \\
 &\times \left\{ \left[\frac{nJ_n(\lambda_r)}{\lambda_r} E_x + iJ'_n(\lambda_r) E_y \right] \left[\left(1 - \frac{k_{\parallel}v_{\parallel}}{\omega} \right) \frac{\partial f_{0r}}{\partial v_{\perp}} + \frac{k_{\parallel}v_{\perp}}{\omega} \frac{\partial f_{0r}}{\partial v_{\parallel}} \right] \right. \\
 &\left. + E_z J_n(\lambda_r) \left[\frac{\partial f_{0r}}{\partial v_{\parallel}} - \frac{n\Omega_r}{\omega v_{\perp}} \left(v_{\perp} \frac{\partial f_{0r}}{\partial v_{\parallel}} - v_{\parallel} \frac{\partial f_{0r}}{\partial v_{\perp}} \right) \right] \right\}. \tag{C 49}
 \end{aligned}$$

If the last term proportional to E_z is compared with the expression (5.2.1.9) of Akhiezer, it appears that Akhiezer has a typo, where instead of the correct v_{\perp} there is a typo v_{\parallel} .

C.2. General $f^{(1)}$ for a bi-Maxwellian distribution

Prescribing f_0 to be a bi-Maxwellian distribution function, the general expression (C 47) for $f^{(1)}$ further simplifies. Since in the Vlasov expansion the gyrotropic f_0 was assumed to dependent only on \mathbf{v} , i.e. $f_0(v_{\perp}^2, v_{\parallel}^2)$ and be \mathbf{x}, t independent, the fluid velocity \mathbf{u} is removed from the distribution function and the ‘pure’ bi-Maxwellian is

$$f_0 = n_{0r} \sqrt{\frac{\alpha_{\parallel}}{\pi} \frac{\alpha_{\perp}}{\pi}} e^{-\alpha_{\parallel} v_{\parallel}^2 - \alpha_{\perp} v_{\perp}^2}, \tag{C 50}$$

where $\alpha_{\parallel} \equiv m/(2T_{\parallel}^{(0)})$, $\alpha_{\perp} = m/(2T_{\perp}^{(0)})$, or in the language of thermal speeds, $v_{\text{th}\parallel}^2 = 2T_{\parallel}^{(0)}/m = \alpha_{\parallel}^{-1}$ and $v_{\text{th}\perp}^2 = 2T_{\perp}^{(0)}/m = \alpha_{\perp}^{-1}$. We prefer the α notation instead of the thermal speed v_{th} , since in long analytic calculations, there is a lesser chance of an error.

It is straightforward to calculate that for a bi-Maxwellian

$$\frac{\partial f_0}{\partial v_{\parallel}} = -2\alpha_{\parallel} v_{\parallel} f_0 = -\frac{m_r}{T_{\parallel}^{(0)}} v_{\parallel} f_0; \tag{C 51}$$

$$\frac{\partial f_0}{\partial v_{\perp}} = -2\alpha_{\perp} v_{\perp} f_0 = -\frac{m_r}{T_{\perp}^{(0)}} v_{\perp} f_0. \tag{C 52}$$

The bi-Maxwellian distribution f_0 therefore can be pulled out (together with $-m_r$) and the general expression (C 47) rewrites

$$\begin{aligned}
 f_r^{(1)} = & iq_r f_{0r} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{+i(m-n)(\phi-\psi)}}{\omega - k_{\parallel} v_{\parallel} - n\Omega_r} J_m(\lambda_r) \left\{ \left[nJ_n(\lambda_r) \frac{\Omega_r}{k_{\perp}} (E_x \cos \psi + E_y \sin \psi) \right. \right. \\
 & + iJ'_n(\lambda_r) v_{\perp} (-E_x \sin \psi + E_y \cos \psi) \left. \right] \left[\frac{1}{T_{\perp r}^{(0)}} + \frac{k_{\parallel} v_{\parallel}}{\omega} \left(\frac{1}{T_{\parallel r}^{(0)}} - \frac{1}{T_{\perp r}^{(0)}} \right) \right] \\
 & + E_z J_n(\lambda_r) v_{\parallel} \left[\frac{1}{T_{\parallel r}^{(0)}} - \frac{n\Omega_r}{\omega} \left(\frac{1}{T_{\parallel r}^{(0)}} - \frac{1}{T_{\perp r}^{(0)}} \right) \right] \left. \right\}. \tag{C53}
 \end{aligned}$$

C.3. General $f^{(1)}$ for a bi-kappa distribution

A bi-kappa distribution function (as used previously in Part 1 of the manuscript) reads

$$f_0 = n_{0r} \frac{\Gamma(\kappa + 1)}{\Gamma(\kappa - \frac{1}{2})} \sqrt{\frac{\alpha_{\parallel}}{\pi} \frac{\alpha_{\perp}}{\pi}} [1 + \alpha_{\parallel} v_{\parallel}^2 + \alpha_{\perp} v_{\perp}^2]^{-(\kappa+1)}, \tag{C54}$$

where the abbreviated $\alpha_{\parallel} = 1/(\kappa\theta_{\parallel}^2)$, $\alpha_{\perp} = 1/(\kappa\theta_{\perp}^2)$ and the thermal speeds are $\theta_{\parallel}^2 = (1 - 3/(2\kappa))(2T_{\parallel r}^{(0)}/m_r)$, $\theta_{\perp}^2 = (1 - 3/(2\kappa))(2T_{\perp r}^{(0)}/m_r)$. We have again emphasized the species index r only where necessary, even though in the final expression for $f^{(1)}$ we will use the proper $\alpha_{\parallel r}$, $\alpha_{\perp r}$. Also, the κ -index should be written as κ_r , since the index will be different for each particle species. The derivatives of f_0 are

$$\frac{\partial f_0}{\partial v_{\parallel}} = -\frac{2(\kappa + 1)\alpha_{\parallel} v_{\parallel}}{1 + \alpha_{\parallel} v_{\parallel}^2 + \alpha_{\perp} v_{\perp}^2} f_0; \tag{C55}$$

$$\frac{\partial f_0}{\partial v_{\perp}} = -\frac{2(\kappa + 1)\alpha_{\perp} v_{\perp}}{1 + \alpha_{\parallel} v_{\parallel}^2 + \alpha_{\perp} v_{\perp}^2} f_0, \tag{C56}$$

which yields the $f^{(1)}$ for a bi-kappa distribution

$$\begin{aligned}
 f_r^{(1)} = & \frac{iq_r}{m_r} \frac{2(\kappa_r + 1)f_{0r}}{(1 + \alpha_{\parallel r} v_{\parallel}^2 + \alpha_{\perp r} v_{\perp}^2)} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{+i(m-n)(\phi-\psi)}}{\omega - k_{\parallel} v_{\parallel} - n\Omega_r} J_m(\lambda_r) \\
 & \times \left\{ \left[nJ_n(\lambda_r) \frac{\Omega_r}{k_{\perp}} (E_x \cos \psi + E_y \sin \psi) \right. \right. \\
 & + iJ'_n(\lambda_r) v_{\perp} (-E_x \sin \psi + E_y \cos \psi) \left. \right] \left[\alpha_{\perp r} + \frac{k_{\parallel} v_{\parallel}}{\omega} (\alpha_{\parallel r} - \alpha_{\perp r}) \right] \\
 & + E_z J_n(\lambda_r) v_{\parallel} \left[\alpha_{\parallel r} - \frac{n\Omega_r}{\omega} (\alpha_{\parallel r} - \alpha_{\perp r}) \right] \left. \right\}. \tag{C57}
 \end{aligned}$$

In the limit $\kappa \rightarrow \infty$, (C57) should ‘obviously’ converge to the bi-Maxwellian (C53).

C.4. Formulation with scalar potentials Φ , Ψ

In kinetic theory and especially in the formulation of Landau fluid models, instead of electric fields, it is often useful to work with scalar potentials Φ , Ψ , that should not be confused with azimuthal angles ϕ , ψ for the velocity and wavenumber in the cylindrical coordinate system. The usual decomposition employs the scalar potential Φ and the vector potential \mathbf{A} , according to

$$\mathbf{B} = \mathbf{B}_0 + \nabla \times \mathbf{A}; \quad (\text{C } 58)$$

$$\mathbf{E} = -\nabla\Phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t}, \quad (\text{C } 59)$$

and it is useful to choose the Coulomb gauge $\nabla \cdot \mathbf{A} = 0$. By exploring the equation for $f^{(1)}$, it is noteworthy that the perpendicular electric fields E_x, E_y are ‘coupled’ through the azimuthal angle ψ . In contrast, the parallel electric field component E_z is on its own. Of course, this is partially a consequence of using the cylindrical coordinate system, which has natural coordinates to describe gyrating particle. It turns out that, in this case, the calculations can be simplified, if the (C 59) is kept for the perpendicular components E_x, E_y , but the E_z field is rewritten with another scalar potential Ψ according to

$$E_x = -\partial_x \Phi - \frac{1}{c} \frac{\partial A_x}{\partial t}; \quad (\text{C } 60)$$

$$E_y = -\partial_y \Phi - \frac{1}{c} \frac{\partial A_y}{\partial t}; \quad (\text{C } 61)$$

$$E_z = -\partial_z \Psi. \quad (\text{C } 62)$$

Here we follow the notation of Passot & Sulem (2006, 2007). Note that in §§ 3 and 4, we used variable Φ for the potential of the parallel electric field E_z , which is here referred to as Ψ . This transformation enables the elimination of vector potential \mathbf{A} , as we will see shortly. Since for the E_z component the (C 59) is still valid, implying

$$E_z = -\partial_z \Phi - \frac{1}{c} \frac{\partial A_z}{\partial t} = -\partial_z \Psi; \quad \Rightarrow \quad \frac{\partial A_z}{\partial t} = -c \partial_z (\Phi - \Psi), \quad (\text{C } 63)$$

or in Fourier space

$$A_z = \frac{ck_{\parallel}}{\omega} (\Phi - \Psi). \quad (\text{C } 64)$$

Using the Coulomb gauge in Fourier space $\mathbf{k} \cdot \mathbf{A} = 0$ implies¹⁴

$$k_x A_x + k_y A_y + k_z A_z = 0; \quad (\text{C } 65)$$

$$A_x \cos \psi + A_y \sin \psi = -\frac{k_{\parallel}}{k_{\perp}} A_z = -\frac{ck_{\parallel}^2}{\omega k_{\perp}} (\Phi - \Psi). \quad (\text{C } 66)$$

The electric field components in Fourier space read

$$E_x = i \left[-\Phi k_{\perp} \cos \psi + \frac{\omega}{c} A_x \right]; \quad (\text{C } 67)$$

$$E_y = i \left[-\Phi k_{\perp} \sin \psi + \frac{\omega}{c} A_y \right]; \quad (\text{C } 68)$$

$$E_z = i \left[-k_{\parallel} \Psi \right], \quad (\text{C } 69)$$

and the expression with E_x, E_y components on the first line of (C 53) for $f^{(1)}$ is

¹⁴The Coulomb gauge is sometimes called the ‘perpendicular gauge’ since the vector potential \mathbf{A} is obviously perpendicular to the direction of propagation \mathbf{k} .

$$\begin{aligned}
 E_x \cos \psi + E_y \sin \psi &= i \left[-\Phi k_{\perp} + \frac{\omega}{c} (A_x \cos \psi + A_y \sin \psi) \right] \\
 &= i \left[-\Phi k_{\perp} - \frac{\omega}{c} \frac{ck_{\parallel}^2}{k_{\perp}\omega} (\Phi - \Psi) \right] = i \left[-\Phi k_{\perp} - \frac{k_{\parallel}^2}{k_{\perp}} (\Phi - \Psi) \right] \\
 &= ik_{\perp} \left[- \left(1 + \frac{k_{\parallel}^2}{k_{\perp}^2} \right) \Phi + \frac{k_{\parallel}^2}{k_{\perp}^2} \Psi \right]. \tag{C70}
 \end{aligned}$$

Furthermore, since $\partial B_z / \partial t = -c(\partial_x E_y - \partial_y E_x)$, which in Fourier space rewrites $(\omega/c)B_z = k_x E_y - k_y E_x$, implying

$$-E_x \sin \psi + E_y \cos \psi = \frac{\omega}{ck_{\perp}} B_z. \tag{C71}$$

The bi-Maxwellian equation (C53) then reads

$$\begin{aligned}
 f_r^{(1)} &= q_r f_{0r} \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{e^{+i(m-n)(\phi-\psi)}}{\omega - k_{\parallel} v_{\parallel} - n\Omega_r} J_m(\lambda_r) \\
 &\times \left\{ \left[nJ_n(\lambda_r) \Omega_r \left(\left(1 + \frac{k_{\parallel}^2}{k_{\perp}^2} \right) \Phi - \frac{k_{\parallel}^2}{k_{\perp}^2} \Psi \right) - J'_n(\lambda_r) \frac{\omega v_{\perp}}{ck_{\perp}} B_z \right] \right. \\
 &\times \left[\frac{1}{T_{\perp r}^{(0)}} + \frac{k_{\parallel} v_{\parallel}}{\omega} \left(\frac{1}{T_{\parallel r}^{(0)}} - \frac{1}{T_{\perp r}^{(0)}} \right) \right] \\
 &\left. + \Psi J_n(\lambda_r) k_{\parallel} v_{\parallel} \left[\frac{1}{T_{\parallel r}^{(0)}} - \frac{n\Omega_r}{\omega} \left(\frac{1}{T_{\parallel r}^{(0)}} - \frac{1}{T_{\perp r}^{(0)}} \right) \right] \right\}, \tag{C72}
 \end{aligned}$$

which verifies (7) of Passot & Sulem (2006) (their preceding (6) contains a small misprint, and on the right-hand side should have $f_r^{(0)}$ instead of $f_r^{(1)}$).

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