

ON THE NUMBER OF EIGENVALUES IN THE SPECTRAL GAP OF A DIRAC SYSTEM

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1. Introduction

We consider the one-dimensional operator,

$$Ly := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \left\{ y' - \begin{pmatrix} p(x) & c_1 + V_1(x) \\ c_2 - V_2(x) & -p(x) \end{pmatrix} y \right\}, \tag{1.1}$$

on $0 < x < \infty$ with $y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$. The coefficients p , V_1 , and V_2 are assumed to be real, locally Lebesgue integrable functions; c_1 and c_2 are positive numbers. The operator L acts in the Hilbert space H of all equivalence classes of complex vector-value functions $f = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix}$ such that $\int_0^\infty (|f_1|^2 + |f_2|^2) dx < \infty$. L has domain $D(L)$ consisting of all $y \in H$ such that y is locally absolutely continuous and $Ly \in H$; thus in the language of differential operators L is a maximal operator. Associated with L is the minimal operator L_0 defined as the closure of L'_0 where L'_0 is the restriction of L to the functions with compact support in $(0, \infty)$.

The singular structure of the coefficients at 0 determine whether $L = L_0$ (and hence L is selfadjoint—the limit-point case) or L contains L_0 properly (the limit-circle case). In the latter case the selfadjoint operators L_1 generated by L satisfy $L_0 \subset L_1 \subset L$ and are determined by imposing a boundary condition at $x=0$ on the elements of $D(L)$. The limit-point and limit-circle terminology arises from the geometric method of Weyl and is discussed in [18]. We use L_1 to denote a selfadjoint extension of L_0 in either case. In any event the essential spectra of L_0, L_1 , and L coincide. Essential selfadjointness criteria and construction of selfadjoint extensions of L_0 have been discussed in many papers, e.g. [1, 8, 9, 10, 11, 12, 20, 22, 23, 24].

Under rather general conditions with p, V_1, V_2 “small” at infinity and sufficiently “regular” at 0, the essential spectrum of L_1 is $(-\infty, -c_1] \cup [c_2, \infty)$. Results on location of essential spectra are given in [3, 8, 9, 14, 23]. When the gap $(-c_1, c_2)$ contains no essential spectrum of L_1 , it can contain only eigenvalues of L_1 . The purpose of this paper is to obtain conditions on the coefficients which determine if the gap contains finitely or infinitely many eigenvalues of L_1 . Since L_1 is a finite dimensional extension of L_0 , the finiteness of the gap spectra is independent of L_1 . Another problem, also independent of L_1 , is to determine when the gap spectrum is infinite which of the endpoints $-c_1$ and c_2 are cluster points of eigenvalues. While our theorems do not assume the existence of a gap, it is the case of primary interest.

For $V_1 = V_2$, equation (1.1) arises from the three-dimensional Dirac equation with a spherically symmetric potential after a separation of variables. For the choices $p(x) = k/x$, $V_1(x) = V_2(x) = z/x$, and $c_1 = c_2 = c$, (1.1) is the radial wave equation in relativistic quantum mechanics for a particle in a field of potential $V(x) = z/x$. When the anomalous magnetic moment of the particle is considered, $p(x) = k/x$ is replaced by $p(x) = k_1/x + k_2/x^2$.

The discreteness of the spectrum of L_1 in $(-c_1, c_2)$ was studied by Birman [3, Section 5]. Using the methods of Birman, Kurbenin [15] gave criteria for the spectrum in the gap to be finite or to be infinite. The work of Kurbenin requires $p(x) = k/x$ and $V_1(x) = V_2(x)$ to be uniformly bounded on $(0, \infty)$. The one-dimensional results of Kurbenin will follow from the results given below. Further discussion is given in [7, Section 62].

In the three-dimensional Dirac equation with gap $[-1, 1]$ and with a regularly growing potential that decays like $|x|^{-m}$, $0 < m < 2$, as $|x| \rightarrow \infty$, Tamura [21] has given asymptotic behavior for the number of eigenvalues in $(0, 1 - r)$ as $r \rightarrow 0$. Also in the three-dimensional case with a parameter Λ multiplying the potential, Klaus [13] has given an asymptotic formula for the number of eigenvalues in the gap as $\Lambda \rightarrow \infty$.

In Section 2 below we give conditions for gap spectra to be infinite. By means of oscillation theory we generate a family of second order scalar differential equations for which the oscillation of one of them at 0 or ∞ is sufficient to give infinite gap spectra. Section 3 treats the converse problem and gives a comparison second order vector equation whose non-oscillation implies a finite gap spectra. Additional results are given by treating the operator L directly. An interesting corollary of the latter method is a sufficient condition for the length of the gap to be "infinite", i.e. L_1 has empty essential spectrum. Finally in Section 4, we use a shifting technique which for certain equations permits one to determine which endpoint of a gap is a cluster point of eigenvalues.

We use the following notation: (\cdot, \cdot) represents the inner product in both H and R^n with corresponding norm $\|\cdot\|$, I is an identity operator or matrix, $\sigma(A)$ is the spectrum of A , and if J is an interval, $C_0(J)$ is the set of all continuously differentiable 2-vector-valued functions with compact support contained in J .

2. Infinite gap spectra

First we consider the square of L given by

$$L^2y = -(y' + JPy)' - P(Jy' - Py) \tag{2.1}$$

where

$$J = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad P = \begin{pmatrix} V_2 - c_2 & p \\ p & V_1 + c_1 \end{pmatrix}.$$

The gap spectrum of L_1 has a close connection with L^2 which we now describe. For $d > 0$, set $M_d(y) = L^2y - d^2y$; we say M_d is *non-oscillatory* at $\infty(0)$ provided that there is a number $b > 0$ such that on (b, ∞) ($(0, b)$) no nontrivial solution y of $M_d y = 0$ vanishes twice, i.e., satisfies $y(b_1) = 0 = y(b_2)$ for $b < b_1 < b_2$. Let K_0 be the minimal operator associated with L^2 . By the spectral theorem for self-adjoint operators, the spectrum of a self-adjoint extension K of K_0 has infinitely many points in $(-\infty, d^2)$ if, and only if,

there is an infinite dimensional subspace $G \subset D(K)$ such that $(Ky, y) < d^2(y, y)$ for all $y \in G$ [7, Section 3]. By standard arguments (cf. [7, Sections 10, 12, 13]) this is equivalent to M_d being oscillatory at either 0 or ∞ . Note that L_1^2 is a self-adjoint extension of K_0 . By the spectral mapping theorem [5, p. 604], $\sigma(L_1^2) = \{\lambda^2 : \lambda \in \sigma(L_1)\}$; hence $\sigma(L_1) \cap (-d, d)$ is finite if, and only if, $\sigma(L_1^2) \cap (-\infty, d^2)$ is finite. Thus we have the criterion:

Theorem 2.1. *For $d > 0$, $\sigma(L_1) \cap (-d, d)$ is finite if, and only if, M_d is nonoscillatory at both 0 and ∞ .*

A further useful object is the quadratic form Q_d of M_d given by

$$\begin{aligned}
 Q_d(y) &= \int_0^\infty y^* M_d(y) dx \\
 &= \int_0^\infty [(y')^* y' + (y')^* J P y - y^* (P J) y' + y^* (P^2 - d^2 I) y] dx
 \end{aligned}
 \tag{2.2}$$

where the domain of Q_d is all y which have compact support in $(0, \infty)$, are absolutely continuous, and satisfy $\int_0^\infty (y')^* y' dx < \infty$. The basic connection between the oscillatory properties of M_d and Q_d is (cf. [4, 7]):

Theorem 2.2. *M_d is nonoscillatory at $\infty(0)$ if, and only if, there is a number $b > 0$ such that $Q_d(y) > 0$ for all nontrivial y in domain Q_d with support in (b, ∞) ($(0, b)$).*

To establish oscillation criteria for M_d we use positive linear functionals. These were first introduced in oscillation theory by Etgen and Pawlowski [6]. A nontrivial linear functional g defined on the real $n \times n$ matrices is said to be *positive* if $g(B) \geq 0$ whenever B is symmetric and positive semidefinite ($B \geq 0$). All such g have the representation $g(B) = \sum_{i=1}^k (B u_i, u_i)$ where u_i are non-zero n -vectors [cf. 17]. Recall a second-order scalar differential operator l is said to be oscillatory at $\infty(0)$ if all solutions of $l(z) = 0$ have infinitely many zeros in a neighborhood of $\infty(0)$.

Theorem 2.3. *Let $d > 0$, g be a nontrivial positive linear functional and assume P of (2.1) is locally absolutely continuous. Then $\sigma(L_1) \cap (-d, d)$ is infinite if the scalar differential equation,*

$$-g(I)z'' + g(P^2 - d^2 I + [P'J - JP']/2)z = 0
 \tag{2.3}$$

is oscillatory either at 0 or at ∞ .

Proof. Suppose to the contrary that $\sigma(L_1) \cap (-d, d)$ is finite. Let (2.3) be oscillatory say at ∞ . Then by Theorems 2.1 and 2.2 there is a number b such that $Q_d(y) > 0$ for all nontrivial y in domain Q_d with support in (b, ∞) . Since (2.3) is oscillatory at ∞ there is a real nontrivial solution z such that $z(b_1) = z(b_2) = 0$ with $b < b_1 < b_2$. Thus multiplying

(2.3) by z and integrating by parts yields

$$\int_{b_1}^{b_2} [g(I)|z'|^2 + g(P^2 - d^2I + [P'J - JP']/2)z^2] dx = 0.$$

Thus by the above representation for g there is a non-zero vector u_i such that

$$\int_{b_1}^{b_2} \{ (u_i, u_i) |z'|^2 + [(P^2 - d^2I + (P'J - JP')/2)u_i, u_i]z^2 \} dx \leq 0. \tag{2.4}$$

Set $y(x) = z(x)u_i$ on $[b_1, b_2]$ and zero elsewhere. Then y is in domain Q_d with support in (b, ∞) . Further, an integration by parts in (2.2) gives that

$$Q_d(y) = \int_{b_1}^{b_2} \{ u_i^* u_i |z'|^2 + u_i^* [(P'J - JP')/2 + P^2 - d^2I] u_i z^2 \} dx$$

which is the same as (2.4). Thus $Q_d(y) \leq 0$ contrary to $Q_d(y) > 0$; hence $\sigma(L_1) \cap (-d, d)$ is infinite.

For $g(B) = (Bu, u)$, $u = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \neq \begin{pmatrix} 0 \\ 0 \end{pmatrix}$, equation (2.3) reduces to

$$-z'' + \Gamma(x)z = 0 \tag{2.5}$$

with

$$\begin{aligned} \Gamma(x) &= (\alpha^2 + \beta^2)^{-1} \{ (\alpha^2 - \beta^2)p' - \alpha\beta(V_2' - V_1') \\ &\quad + \alpha^2((V_2 - c_2)^2 + p^2 - d^2) + 2\alpha\beta p(V_1 + V_2 + c_1 - c_2) + \beta^2((V_1 + c_1)^2 + p^2 - d^2) \}. \end{aligned}$$

For $V_1 = V_2 = V$, we note the following cases of (2.5) by taking (α, β) equal to $(1, 0)$, $(0, 1)$, $(1, \pm 1)$ respectively and also of (2.3) with $g(B) = \text{trace } B$.

$$-z'' + \{ p' + (V - c_2)^2 + p^2 - d^2 \} z = 0 \tag{2.6}$$

$$-z'' + \{ -p' + (V + c_1)^2 + p^2 - d^2 \} z = 0 \tag{2.7}$$

$$-z'' + (1/2)\{ (V - c_2)^2 + (V + c_1)^2 + 2p^2 - 2d^2 \pm 2p(2V + c_1 - c_2) \} z = 0 \tag{2.8}$$

$$-z'' + (1/2)\{ (V - c_2)^2 + (V + c_1)^2 + 2p^2 - 2d^2 \} z = 0. \tag{2.9}$$

Example 1. Let $V_1(x) = V_2(x) = a/x$, $a \neq 0$, $c_1 = c_2 = d = c$, and $p(x) = k/x + r/x^2$. Then (2.6) is

$$-z'' + \{ p'(x) + a^2/x^2 - 2ac/x + p(x)^2 \} z = 0$$

which is oscillatory at ∞ if $a > 0$. Similarly (2.7) is oscillatory at ∞ if $a < 0$. Thus $\sigma(L_1) \cap (-c, c)$ is infinite.

For $c_1=c_2=d$, p' and p^2 being $0(x^{-2})$ as $x \rightarrow \infty$, and V of constant sign, it follows that (2.6) or (2.7) will be oscillatory at ∞ if $|V(x)| \leq \varepsilon < 2c$ on some $[x_0, \infty)$ and $|V(x)|x^2 \rightarrow \infty$ as $x \rightarrow \infty$. This gives Theorem 3 of [15].

It is possible to relax the differentiability requirements on p , V_1 , and V_2 . For the functional $g(B)=(B(\frac{1}{0}), (\frac{1}{0})) (g(B)=(B(\frac{0}{1}), (\frac{0}{1}))$, equation (2.6) ((2.7)) is obtained without assuming V_1 and V_2 differentiable. This is because the middle terms of (2.2) involving V_1 and V_2 are replaced by zero. For these same two choices of g , the differentiability requirement on p can also be dropped by avoiding an integration by parts. In this case we get in place of (2.6) and (2.7) that if either of

$$-z'' - 2pz' + \{(V_2 - c_2)^2 + p^2 - d^2\}z = 0, \tag{2.10}$$

$$-z'' + 2pz' + \{(V_1 + c_1)^2 + p^2 - d^2\}z = 0, \tag{2.11}$$

is oscillatory at ∞ or 0, then $\sigma(L_1) \cap (-d, d)$ is infinite. For smooth p , these equations are less effective than (2.6) and (2.7) as is shown by the oscillation preserving substitution $w = z \exp \{ \int \pm p \}$ for (2.10), (2.11) respectively.

3. Finite gap spectra

The middle two terms of (2.2) may be written

$$\begin{aligned} MID &= \int_0^\infty [(y')^*JP_y - y^*PJy'] dx \\ &= \int_0^\infty \{ p[-\bar{y}'_1y_1 + \bar{y}'_2y_2 - y'_1\bar{y}_1 + y'_2\bar{y}_2] - (V_1 + c_1)(\bar{y}'_1y_2 + y'_1\bar{y}_2) \\ &\quad + (V_2 - c_2)(\bar{y}'_2y_1 + y'_2\bar{y}_1) \} dx. \end{aligned} \tag{3.1}$$

We need to distinguish two cases: $c_1 = \min(c_1, c_2)$ and $c_2 = \min(c_1, c_2)$. First suppose $c_1 = \min(c_1, c_2)$. Let $c = (c_1 + c_2)/2$ and $\varepsilon = c - c_1$ so that $c_2 = c + \varepsilon$. Using these values in (3.1) together with

$$\int_0^\infty \{ -c[\bar{y}'_1y_2 + y'_1\bar{y}_2] - c[\bar{y}'_2y_1 + y'_2\bar{y}_1] \} dx = \int_0^\infty -c[\bar{y}_1y_2 + y_1\bar{y}_2]' dx = 0$$

yields after integration by parts that

$$MID = \int_0^\infty \{ p'[|y_1|^2 - |y_2|^2] - V_1[\bar{y}'_1y_2 + y'_1\bar{y}_2] + (V_2 - 2\varepsilon)[\bar{y}'_2y_1 + y'_2\bar{y}_1] \} dx.$$

Thus if $0 < \beta_i \leq 1$ for $i = 1, 2$, we have that

$$Q_d(y) = \int_0^\infty \{ (y')^* \Delta_1 y' + |\beta_1 y'_1 - \beta_1^{-1} V_1 y_2|^2 + |\beta_2 y'_2 - \beta_2^{-1} (V_2 - 2\varepsilon) y_1|^2 + y^* \Delta_2 y \} dx \tag{3.2}$$

where

$$\Delta_1 = \begin{pmatrix} 1 - \beta_1^2 & 0 \\ 0 & 1 - \beta_2^2 \end{pmatrix},$$

$$\Delta_2 = P^2 - d^2I + \begin{pmatrix} p' - \beta_2^{-2}(V_2 - 2\varepsilon)^2 & 0 \\ 0 & -p' - \beta_1^{-2}V_1^2 \end{pmatrix}. \tag{3.3}$$

Thus we have

$$Q_d(y) \geq \int_0^\infty [(y')^* \Delta_1 y'_1 + y^* \Delta_2 y] dx, \tag{3.4}$$

and we have proved the following by Theorem 2.2.

Theorem 3.1. *Let $d > 0$, $0 < \beta_i \leq 1$ for $i = 1, 2$. Then $\sigma(L_1) \cap (-d, d)$ is finite if one of the following holds.*

- (i) *The matrix Δ_2 for $\beta_1 = \beta_2 = 1$ is positive definite in a neighbourhood of 0 and in a neighbourhood of ∞ .*
- (ii) *$0 < \beta_i < 1$ for $i = 1, 2$ and the matrix equation*

$$-\Delta_1 y'' + \Delta_2 y = 0 \tag{3.5}$$

is nonoscillatory at both 0 and ∞ .

In a similar manner, we may prove the following when $c_2 = \min(c_1, c_2)$. Set $c = (c_1 + c_2)/2$, $\varepsilon = c - c_2$ (so that $c_1 = c + \varepsilon$) and

$$\Delta_3 = P^2 - d^2I + \begin{pmatrix} p' - \beta_2^{-2}V_2^2 & 0 \\ 0 & -p' - \beta_1^{-2}(V_1 + 2\varepsilon)^2 \end{pmatrix}. \tag{3.6}$$

Theorem 3.2. *Let $d > 0$, $0 < \beta_i \leq 1$ for $i = 1, 2$. Then $\sigma(L_1) \cap (-d, d)$ is finite if one of the following holds.*

- (i) *The matrix Δ_3 for $\beta_1 = \beta_2 = 1$ is positive definite in a neighbourhood of 0 and in a neighbourhood of ∞ .*
- (ii) *$0 < \beta_i < 1$ for $i = 1, 2$ and the matrix equation*

$$-\Delta_1 y'' + \Delta_3 y = 0 \tag{3.7}$$

is nonoscillatory at both 0 and ∞ .

Because of the relation (3.4), the nonoscillation of (3.5) at either 0 or ∞ implies the nonoscillation of M_d at the same endpoint. Similar remarks apply to (3.7).

For the next example recall that the vector equation $-y'' + \Gamma(x)y = 0$ is nonoscillatory at ∞ if $\int_x^\infty \Gamma(s)ds$ exists and $\|\int_x^\infty \Gamma(s)ds\|_0 \leq 1/4x$ for all x sufficiently large (cf. [16]). By

$\| \cdot \|_0$ we mean the operator norm on matrices where the Euclidean norm is used for vectors. We also use that if $-y'' + \Gamma(x)y = 0$ is nonoscillatory and $\Gamma_1(x) \geq \Gamma(x)$, then $-y'' + \Gamma_1(x)y = 0$ is nonoscillatory.

Example 2. Let $p, V = V_1 = V_2$ be bounded on some $(0, \varepsilon)$ (hence (3.5) is nonoscillatory at 0) and for $x \geq \varepsilon$, let $V(x) = a \sin x/x^\delta$ with $\delta > 1$ and p satisfy $\pm p'(x) + p(x)^2 \geq a/x^2$ for some $a < 1/4$ and $|\int_x^\infty pV| = o(x^{-1})$ as $x \rightarrow \infty$. For $c_1 = c_2 = c = d$ and $\beta_1 = \beta_2 = \beta$, Δ_2 of (3.5) satisfies

$$\begin{aligned} \Delta_2 &= \begin{pmatrix} (p' + (1 - \beta^{-2})V^2 - 2cV + p^2) & 2pV \\ 2pV & -p' + (1 - \beta^{-2})V^2 + 2cV + p^2 \end{pmatrix} \\ &\geq \tilde{\Delta}_2 := \begin{pmatrix} (1 - \beta^{-2})V^2 - 2cV + a/x^2 & 2pv \\ 2pV & (1 - \beta^{-2})V^2 + 2cV + a/x^2 \end{pmatrix}. \end{aligned}$$

Now each of $\int_x^\infty V^2, \int_x^\infty V, \int_x^\infty pV$ is $o(x^{-1})$ as $x \rightarrow \infty$; hence for x sufficiently large, $\|\int_x^\infty \tilde{\Delta}_2(s)ds\|_0 \leq a_1/x$ for some $a_1 < 1/4$. Thus β can be chosen so that (3.5) is nonoscillatory; hence $\sigma(L_1) \cap (-c, c)$ is finite.

For $p(x) = k/x$, similar considerations will yield Theorem 1 of [15] except for the case $k = 1/2$.

We now consider some discrete spectrum results that do not use the operator L^2 directly.

Theorem 3.3. Let J be a subinterval of $(0, \infty)$, U be an orthogonal matrix, and d a positive number such that:

- (i) either $UP + P^*U^* \geq 2dI$ on J or $UP + P^*U^* \leq -2dI$ on J .
- (ii) $\text{Re} \int_0^\infty [y^*UJy'] dx = 0$ for all $y \in C_0(J)$.

Then for all $y \in C_0(J)$, $\|Ly\| \geq d\|y\|$.

Proof. For $y \in C_0(J)$, we have

$$\begin{aligned} \|Ly\|^2 \|y\|^2 &= \|Ly\|^2 \|Uy\|^2 \geq |(Ly, U^*y)|^2 \\ &= \left| \int_0^\infty [y^*U(Jy' - Py)] dx \right|^2 \\ &\geq \left| \text{Re} \int_0^\infty [y^*U(Jy' - Py)] dx \right|^2 \\ &= \left| (1/2) \int_0^\infty y^*(UP + P^*U^*)y dx \right|^2 \\ &\geq \left| d \int_0^\infty y^*y dx \right|^2 = d^2 \|y\|^4. \end{aligned}$$

Corollary 3.1. *Suppose the conditions of Theorem 3.3 hold for $J=[b_2, \infty)$ ($J=(0, b_1]$). Then $L^2 - d^2I$ is nonoscillatory at $\infty(0)$. If the conditions hold for $J=(0, \infty)$, then $\sigma(L_1) \cap (-d, d) = \emptyset$ if $L_0 = L$ and is either \emptyset or degenerate otherwise.*

Proof. For $y \in C_0([b_2, \infty))$ with $y \in D(L^2)$,

$$\|L^2y\| \|y\| \geq |(L^2y, y)| = \|Ly\|^2 \geq d^2 \|y\|^2$$

or $\|L^2y\| \geq d^2 \|y\|$. Thus the minimal operator associated with L^2 on $[b_2, \infty)$ is bounded below by d^2 . Thus a self-adjoint operator associated with L^2 on $[b_2, \infty)$ has a finite spectrum on $(-\infty, d^2)$ since it is a finite dimensional extension of the minimal operator. Thus $L^2 - d^2I$ is nonoscillatory at ∞ . Similar remarks apply to 0. Note that L_1 is a 0-dimensional (1-dimensional) extension of L_0 if $L_0 = L$ ($L_0 \neq L$) so that $\sigma(L_1) \cap (-d, d) = \emptyset$ (contains at most one element).

Two special cases of Theorem 3.3 are of interest.

(A) Suppose $U = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$. Then a calculation shows (ii) of Theorem 3.3 holds. Also

$$UP + P^*U = 2 \begin{pmatrix} c_2 - V_2 & 0 \\ 0 & c_1 + V_1 \end{pmatrix}. \tag{3.8}$$

This yields the following corollaries.

Corollary 3.2. *If V_1 and V_2 in (1.1) have compact support, then $\sigma(L_1) \cap (-c_1, c_2)$ is finite for all p .*

Corollary 3.3. *If $|V_i(x)| \rightarrow \infty$ as $x \rightarrow 0$ and as $x \rightarrow \infty$ for $i=1, 2$ and $V_1(x)V_2(x) < 0$ in both a neighbourhood of 0 and of infinity, then $\sigma(L_1) \cap (-d, d)$ is finite for all $d > 0$, i.e., L_1 has a purely discrete spectrum.*

(B) Suppose $U = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$. Again (ii) of Theorem 3.3 holds and

$$(1/2)(UP + P^*U^*) = \begin{pmatrix} p & v \\ v & p \end{pmatrix}, \quad v = (1/2)(V_1 + V_2 + c_1 - c_2). \tag{3.9}$$

The eigenvalues of (3.9) are $p \pm v$. This gives

Corollary 3.4. *Suppose $d > 0$ and in a neighbourhood of $0(\infty)$, $p \pm v \geq d$ or $p \pm v \leq -d$. Then $L^2 - d^2I$ is nonoscillatory at $0(\infty)$.*

4. The shifting method

Consider (1.1) with $c_1 = c_2 = c$ say,

$$S(y) = Jy' - \begin{pmatrix} V_2 - c & p \\ p & V_1 + c \end{pmatrix} y, \quad 0 < x < \infty, \tag{4.1}$$

and let S_1 be a self-adjoint operator determined by S . We assume the essential spectrum of S_1 is $(-\infty, -c] \cup [c, \infty)$ and that S_1 has infinitely many eigenvalues in the gap $[-c, c]$. We wish to determine which of the points $\pm c$ is a cluster point of the eigenvalues. For $0 < \varepsilon < c$, set $T_1 = S_1 + \varepsilon I$, $T_2 = S_1 - \varepsilon I$. Then spectrum of T_1 (T_2) is the spectrum of S_1 moved to the right (left) ε units. Note that T_1 becomes L_1 of Section 2 with $c_1 = c - \varepsilon$, $c_2 = c + \varepsilon$ and T_2 becomes L_1 with $c_1 = c + \varepsilon$, $c_2 = c - \varepsilon$.

Consider now T_1 . By Section 2, $-c$ is not a cluster point of the eigenvalues of S_1 if, and only if, $L^2 - (c - \varepsilon)^2 I$ with $c_1 = c - \varepsilon$, $c_2 = c + \varepsilon$ is nonoscillatory at both 0 and ∞ . Thus to show $-c$ is a cluster point of eigenvalues, it suffices to show $L^2 - (c - \varepsilon)^2 I$ is oscillatory at one of 0, ∞ . Similar considerations apply to T_2 and c .

The following theorem utilizes these ideas.

Theorem 4.1. *Suppose in (4.1) that $V_1 = V_2 = V$, p is locally absolutely continuous, and*

- (i) $p(x) = 0(1/x)$, $p'(x) = 0(1/x^2)$ as $x \rightarrow \infty$,
- (ii) $V(x) \rightarrow 0$ and $x^2 V(x) \rightarrow -\infty$ as $x \rightarrow \infty$.
- (iii) *In a neighbourhood of 0, $p(x) \geq |V(x)| + c$ or $p(x) \leq -c - |V(x)|$. Then $-c$ is a cluster point of eigenvalues and c is not.*

Proof. It follows from the above remarks that $-c$ is a cluster point of eigenvalues if (2.7), with $c_1 = c - \varepsilon = d$, $c_2 = c + \varepsilon$ ($0 < \varepsilon < c$) is oscillatory at infinity, i.e., if

$$-z'' + \{p' + V^2 + 2(c - \varepsilon)V + p^2\}z = 0 \tag{4.2}$$

is oscillatory. Now $V^2 + p' + p^2 = V^2 + 0(x^{-2})$ is small compared to $|V|$ by (i), (ii). Thus (4.2) is oscillatory at infinity by comparison with an oscillatory Euler equation, e.g., $-z'' - (1/x^2)z = 0$.

To see that c is not a cluster point of eigenvalues, we need to show $L^2 - d^2 I$ is nonoscillatory at both 0 and infinity with $d = c_2 = c - \varepsilon$, $c_1 = c + \varepsilon$. To see that $L^2 - d^2 I$ is nonoscillatory at 0 we apply Corollary 3.4. Then $p \pm v = p \pm (V + \varepsilon)$. Hence by (iii) either $p \pm v \geq d$ or $p \pm v \leq -d$; thus $L^2 - d^2 I$ is nonoscillatory at 0. To show $L^2 - d^2 I$ is nonoscillatory at infinity we use Corollary 3.1 with U as in (3.8); hence $L^2 - d^2 I$ is nonoscillatory at infinity if

$$\begin{pmatrix} c_2 - V & 0 \\ 0 & c_1 + V \end{pmatrix} = \begin{pmatrix} c - \varepsilon - V & 0 \\ 0 & c + \varepsilon + V \end{pmatrix} \geq (c - \varepsilon)I \tag{4.3}$$

near infinity. By (ii), $-2\varepsilon \leq V(x) < 0$ for x sufficiently large thus implying (4.3).

If conditions (i)–(iii) of Theorem 4.1 hold with $x^2 V(x) \rightarrow -\infty$ as $x \rightarrow \infty$ replaced by $x^2 V(x) \rightarrow \infty$ as $x \rightarrow \infty$, then c is a cluster point of eigenvalues and $-c$ is not.

Theorem 4.1 applies to Example 1 if either $r \neq 0$ or $|k| > |a|$.

In our final example we show both $\pm c$ may be cluster points.

Example 3. Suppose on $[1, \infty)$, $V_1(x) = V_2(x) = (a \sin x)/x^\delta$, $0 < \delta < 1$, $a \neq 0$ with $p', p = 0(x^{-2})$ as $x \rightarrow \infty$. Suppose also $c > 1/2$. Then c will be a cluster point of eigenvalues

if for some $\varepsilon, 0 < \varepsilon < c$, (2.6) is oscillatory at ∞ with $c_1 = c + \varepsilon, c_2 = d = c - \varepsilon$, i.e., if

$$-z'' + (p'(x) + a^2x^{-2\delta} \sin^2 x - 2a(c - \varepsilon)x^{-\delta} \sin x + p(x)^2)z = 0 \tag{4.4}$$

is oscillatory at ∞ . We analyse (4.4) by means of a result of Read [19] for partial differential equations which in the one-dimensional case applied to $-z'' + q(x)z = 0, b \leq x < \infty$, is:

Theorem [19]. *Let h be a positive, locally absolutely continuous function on $[b, \infty)$ and let ε_0 satisfy $0 < \varepsilon_0 < 1$. For $\lambda \geq 0$ define*

$$E(\lambda) = \{x \geq b : \int_b^x [-qh - (h')^2/4\varepsilon_0h] dt \geq \lambda\}. \tag{4.5}$$

If there exists an $\alpha > 0$ and a sequence $\lambda_k \rightarrow \infty$ such that

$$(1 - \varepsilon_0)(\lambda_k + \alpha) \int_{E(\lambda_k)} h^{-1} \geq 1 \tag{4.6}$$

for each k , then $-z'' + q(x)z = 0$ is oscillatory at ∞ .

To apply this theorem to (4.4), we take $h(x) = x^\delta + k \sin x$ where $k = 4(c - \varepsilon)a\varepsilon_0^2, \varepsilon_0 = 1 - \varepsilon$, and $\varepsilon < 1$ is chosen so that $c > \varepsilon + 1/2(1 - \varepsilon)$. Take $b \geq 1$ so that $h(x) \geq x^\delta \varepsilon_0$ for $x \geq b$. Then the terms of the integral in (4.5) which are not 0(1) as $x \rightarrow \infty$ are:

$$\begin{aligned} \int_b^x -a^2t^{-\delta} \sin^2 t dt &= -a^2x^{1-\delta}/2(1-\delta) + 0(1), \\ \int_b^x 2a(c - \varepsilon)kt^{-\delta} \sin^2 t dt &= a(c - \varepsilon)kx^{1-\delta}/(1-\delta) + 0(1), \\ \int_b^x -h'(t)^2/4\varepsilon_0h(t) dt &\geq -\int_b^x (4\varepsilon_0^2t^\delta)^{-1}h'(t)^2 dt = -k^2x^{1-\delta}/8\varepsilon_0^2(1-\delta) + 0(1). \end{aligned}$$

Since by choice of ε ,

$$a(c - \varepsilon)k - a^2/2 - k^2/8\varepsilon_0^2 = a^2[2(c - \varepsilon)^2\varepsilon_0^2 - 1/2] > 0,$$

we see that for each $\lambda, E(\lambda)$ contains an interval $[a_\lambda, \infty)$. Thus (4.6) holds for any $\alpha > 0$ and sequence $\lambda_k \rightarrow \infty$. Therefore c is a cluster point. Similar arguments apply to give $-c$ a cluster point. It is unclear if $\pm c$ remain cluster points of eigenvalues if $c < 1/2$.

In the above examples we have that infinitely many eigenvalues are in the gap as a result of a sufficiently large long range potential $V(x)$. For the physically important case $p(x) = k/x$, an examination of (2.5) shows the difficulty of constructing a potential whose singular behavior at zero produces infinitely many eigenvalues in the gap.

Finally, we make a comment on the more general operator

$$Ty := \begin{pmatrix} \alpha_1^{-1} & 0 \\ 0 & \alpha_2^{-1} \end{pmatrix} Ly$$

where L is as in (1.1) and α_1, α_2 are positive functions. T acts in the Hilbert space of functions f satisfying $\int_0^\infty [\alpha_1 |f_1|^2 + \alpha_2 |f_2|^2] < \infty$. If we make the transformation

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}(x) = \begin{pmatrix} \eta(x) & 0 \\ 0 & \eta(x)^{-1} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}(t)$$

where $\eta(x) = [\alpha_2(x)/\alpha_1(x)]^{1/4}$ and $t = \int \sqrt{\alpha_1 \alpha_2} dx$, then a calculation shows ($\cdot = d/dt$) $Ty = \lambda y$ reduces to

$$J \left\{ z - \frac{1}{\sqrt{\alpha_1 \alpha_2}} \begin{pmatrix} p + \eta'/\eta & (V_1 + c)\eta \\ (c_2 - V_2)\eta^{-1} & -p - \eta'/\eta \end{pmatrix} z \right\} = \lambda z.$$

Since $\int (\alpha_1 |y_1|^2 + \alpha_2 |y_2|^2) dx = \int (|z_1|^2 + |z_2|^2) dt$, an eigenvalue problem $Ty = \lambda y$ can be reduced to the type studied here.

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