

LIE IDEALS IN ASSOCIATIVE ALGEBRAS

BY

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ABSTRACT. It is shown that in a certain extensive class of algebras one can associate with each Lie ideal a corresponding associative ideal which facilitates the study of Lie ideals, especially for simple algebras. We apply this construction to obtain new, simpler proofs of some known results of Herstein [10] and others on the Lie structure of associative rings.

Introduction. Let B be the algebra of all bounded operators on a separable Hilbert space of infinite dimension, and for J a subset of B let $[B, J]$ denote the set of all finite sums of elements $[T, X] = TX - XT$ where $T \in B$ and $X \in J$. It is shown in Fong–Meiers–Sorrour [8] that a linear manifold L in B is a Lie ideal in B if and only if there is an associative two-sided ideal J in B such that $[B, J] \subseteq L \subseteq J + \mathbb{C}1$. Their proof uses some deep results in Operator Theory. In this paper we show that analogous results hold in a much more general context, and our proofs are simpler and more algebraic. We also give a partial generalization of a result of de la Harpe [4] (see also Murphy–Radjavi [11]). In certain simple algebras we are able to completely characterize the Lie ideals (see [10], where these results were originally obtained by different methods).

Terminology. The terms *algebra* and *ideal* when not qualified will always mean associative algebra and associative two-sided ideal. Every algebra B over a field F is a Lie algebra with respect to the commutator product $[x, y] = xy - yx$.

Let B be an algebra over a field F and suppose B has a set of 2×2 matrix units $e_{11}, e_{12}, e_{21}, e_{22}$. It turns out that we can say a lot about the Lie ideals of such algebras. If A is the centralizer of the matrix units, i.e. $A = \{x \in B : xe_{ij} = e_{ij}x, 1 \leq i, j \leq 2\}$, then A is a subalgebra of B , and it's well known that B is isomorphic to the algebra $M_2(A)$ of all 2×2 matrices with entries in A (see [5] p. 134).

The class of algebras over \mathbb{C} having a set of 2×2 matrix units is extensive: it includes the properly infinite von Neumann algebras, and the hyperfinite type II_1 -factors [13] pp. 48–49. Of course if H is a Hilbert space of infinite

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dimension and $B(H)$, $K(H)$ denote the algebra of bounded operations, and the ideal of compact operators respectively, then $B(H)$ and $B(H)/K(H)$ admit sets of 2×2 matrix units. More generally, any 2-homogeneous von-Neumann algebra admits a set of 2×2 matrix units [13]. In fact, if B is a Banach $*$ -algebra and there exists $P, V \in B$ with P a projection and $V^*V = P$ and $VV^* = 1 - P$, then the set $e_{11} = P$, $e_{12} = V^*$, $e_{21} = V$, $e_{22} = 1 - P$, forms a set of 2×2 matrix units for B .

Let B be a unital algebra over a field F not of characteristic 2. We shall use the following notation. If S, T are subsets of B we let $[S, T]$ denote the set of all sums $[x, y]$ where $x \in S$ and $y \in T$. For I an ideal in B , we let $I^- = \{x \in B : [b, x] \in I (b \in B)\}$. Clearly $I + F1 \subseteq I^-$. In some important examples (see below) we have equality, $I + F1 = I^-$.

Before proving the following theorem a short observation will be useful: if L is a Lie ideal in B , and $u \in B$ such that $u^2 = 1$, then $uLu \subseteq L$. This follows from the elementary calculation $uxu = x - 1/2[u, [u, x]]$. (This calculation appears in [8].)

THEOREM 1. *Let B be an algebra, over a field F not of characteristic 2, which contains a set of 2×2 matrix units. If L is a Lie ideal in B , then there is an ideal I in B such that $[B, I] \subseteq L \subseteq I^-$.*

Proof. We assume w.l.o.g. that $B = M_2(A)$ for some algebra A over F . Define

$$J = \left\{ x \in A : \begin{pmatrix} 0 & x \\ 0 & 0 \end{pmatrix} \in L \right\}.$$

Now if $x \in J$ and $a \in A$, then

$$\left[\begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & x \\ 0 & 0 \end{pmatrix} \right] = \begin{pmatrix} 0 & ax \\ 0 & 0 \end{pmatrix} \in L \quad \text{and} \quad \left[\begin{pmatrix} 0 & x \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & a \end{pmatrix} \right] = \begin{pmatrix} 0 & xa \\ 0 & 0 \end{pmatrix} \in L.$$

Thus $ax, xa \in J$. Since it's obvious J is a linear manifold, we conclude that J is an ideal in A . Now define $I = \left\{ \begin{pmatrix} x & y \\ z & t \end{pmatrix} : x, y, z, t \in J \right\}$. Then I is an ideal in B .

First we show $L \subseteq I^-$. Let $\begin{pmatrix} x & y \\ z & t \end{pmatrix} \in L$ and $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in B$. We have to show

$$\left[\begin{pmatrix} a & b \\ c & d \end{pmatrix}, \begin{pmatrix} x & y \\ z & t \end{pmatrix} \right] \in I.$$

Now $\left[\begin{pmatrix} x & y \\ z & t \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right] = \begin{pmatrix} 0 & -y \\ z & 0 \end{pmatrix}$, and $\left[\begin{pmatrix} 0 & -y \\ z & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right] = \begin{pmatrix} 0 & y \\ z & 0 \end{pmatrix}$ both lie in L . Hence $\begin{pmatrix} 0 & y \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ z & 0 \end{pmatrix} \in L$. But if $u = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ then $u^2 = 1$ in B , so $uLu \subseteq L$ by the remark preceding this theorem. Hence $\begin{pmatrix} 0 & z \\ 0 & 0 \end{pmatrix} = u \begin{pmatrix} 0 & 0 \\ z & 0 \end{pmatrix} u \in L$.

Thus $y, z \in J$, and so $\begin{pmatrix} 0 & y \\ z & 0 \end{pmatrix} \in I$. Also $\begin{pmatrix} x & 0 \\ 0 & t \end{pmatrix} \in L$. Now $\left[\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} x & 0 \\ 0 & t \end{pmatrix} \right] = \begin{pmatrix} 0 & t-x \\ 0 & 0 \end{pmatrix} \in L$, so $t-x \in J$. Thus $\begin{pmatrix} x & y \\ z & t \end{pmatrix} = \begin{pmatrix} x & 0 \\ 0 & x \end{pmatrix} + \begin{pmatrix} 0 & y \\ z & t-x \end{pmatrix}$, and the second term is in I . Thus to show $\left[\begin{pmatrix} a & b \\ c & d \end{pmatrix}, \begin{pmatrix} x & y \\ z & t \end{pmatrix} \right] \in I$ we need now only show $\left[\begin{pmatrix} a & b \\ c & d \end{pmatrix}, \begin{pmatrix} x & 0 \\ 0 & x \end{pmatrix} \right] = \begin{pmatrix} [a, x] & [b, x] \\ [c, x] & [d, x] \end{pmatrix} \in I$, i.e. we need only show $[a, x] \in J$ for all a in A . But $\left[\begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} x & 0 \\ 0 & t \end{pmatrix} \right] = \begin{pmatrix} [a, x] & 0 \\ 0 & 0 \end{pmatrix} \in L$. Hence $\left[\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} [a, x] & 0 \\ 0 & 0 \end{pmatrix} \right] = \begin{pmatrix} 0 & -[a, x] \\ 0 & 0 \end{pmatrix} \in L$, implying $[a, x] \in J$. Thus $L \subseteq I^-$.

Now we show $[B, I] \subseteq L$. Let $x \in J$ and $a \in A$. Then $\begin{pmatrix} 0 & x \\ 0 & 0 \end{pmatrix} \in L$, and so $\begin{pmatrix} [a, x] & 0 \\ 0 & 0 \end{pmatrix} = \left[\begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & x \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right] \in L$. Also if $x, y \in J$ then $\begin{pmatrix} 0 & x \\ 0 & 0 \end{pmatrix}$ and $\begin{pmatrix} 0 & 0 \\ y & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & y \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ are in L , hence $\begin{pmatrix} 0 & x \\ y & 0 \end{pmatrix} \in L$. Thus if $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in B$ and $\begin{pmatrix} x & y \\ z & t \end{pmatrix} \in I$, then

$$\begin{aligned} \left[\begin{pmatrix} a & b \\ c & d \end{pmatrix}, \begin{pmatrix} x & y \\ z & t \end{pmatrix} \right] &= \left[\begin{pmatrix} a & b \\ c & d \end{pmatrix}, \begin{pmatrix} x & 0 \\ 0 & t \end{pmatrix} \right] + \left[\begin{pmatrix} a & b \\ c & d \end{pmatrix}, \begin{pmatrix} 0 & y \\ z & 0 \end{pmatrix} \right] \\ &= \begin{pmatrix} [a, x] & 0 \\ 0 & [d, t] \end{pmatrix} + \begin{pmatrix} 0 & bt-xb \\ cx-tc & 0 \end{pmatrix} + \left[\begin{pmatrix} a & b \\ c & d \end{pmatrix}, \begin{pmatrix} 0 & y \\ z & 0 \end{pmatrix} \right] \in L \end{aligned}$$

since $bt-xb$ and $cx-tc \in J$, $\begin{pmatrix} 0 & y \\ z & 0 \end{pmatrix} \in L$, and $\begin{pmatrix} 0 & 0 \\ 0 & [d, t] \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} [d, t] & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \in L$.

COROLLARY 2. *If the Lie ideal L in the above theorem is of finite codimension in B one can choose the ideal I to be of finite codimension also.*

Proof. Let I and J be as in the proof of the above theorem. Now if y_1, \dots, y_n are linearly independent elements of A such that $J \cap [y_1, \dots, y_n] = 0$ where $[y_1, \dots, y_n]$ denotes the linear span, then $\begin{pmatrix} 0 & y_1 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 & y_n \\ 0 & 0 \end{pmatrix}$ are linearly independent in B and $L \cap \left[\begin{pmatrix} 0 & y_1 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 & y_n \\ 0 & 0 \end{pmatrix} \right] = 0$. Thus $n \leq \dim(B/L)$, and so $\dim(A/J) < \infty$.

Now suppose $J \oplus [y_1, \dots, y_n] = A$. Then if M denotes the linear span in B of

the elements $\begin{pmatrix} y_i & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & y_i \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ y_i & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & y_i \end{pmatrix}$ ($1 \leq i \leq n$), it is easily seen that $I \oplus M = B$. Thus $\dim(B/I) < \infty$.

REMARK. If \mathcal{H} is a separable Hilbert space of infinite dimensions and \mathcal{I} is an ideal in $\mathcal{B}(\mathcal{H})$, then it was shown by Calkin [3] that $\mathcal{I}^- = I + \mathbb{C}1$. We use this interesting fact to deduce the following theorem from Theorem 1.

THEOREM 3 (Fong–Miers–Sourour [8]). *If \mathcal{H} is a separable infinite dimensional Hilbert space and \mathcal{L} is a linear manifold in $\mathcal{B}(\mathcal{H})$ then \mathcal{L} is a Lie ideal in $\mathcal{B}(\mathcal{H})$ if and only if there is an ideal \mathcal{I} of $\mathcal{B}(\mathcal{H})$ such that $[\mathcal{B}(\mathcal{H}), \mathcal{I}] \subseteq \mathcal{L} \subseteq \mathcal{I} + \mathbb{C}1$.*

REMARK. It was shown by de la Harpe [4] that if \mathcal{H} is a Hilbert space, $\dim \mathcal{H} = \infty$, and \mathcal{L} a Lie ideal in $K(\mathcal{H})$ of finite codimension, then necessarily $\mathcal{L} = K(\mathcal{H})$ (see also Murphy–Radjavi [11] for related results). Using our results above we can give a quick proof in the case where \mathcal{H} is separable of a weaker version of de la Harpe's theorem, viz if \mathcal{L} is a Lie ideal of $\mathcal{B}(\mathcal{H})$ which is of finite codimension in $K(\mathcal{H})$, then $\mathcal{L} = K(\mathcal{H})$. For, by Theorem 3, there is an ideal \mathcal{I} of $\mathcal{B}(\mathcal{H})$ such that $[\mathcal{B}(\mathcal{H}), \mathcal{I}] \subseteq \mathcal{L} \subseteq I + \mathbb{C}1$. Hence $\mathcal{I} \neq \mathcal{B}(\mathcal{H})$, since $[\mathcal{B}(\mathcal{H}), \mathcal{B}(\mathcal{H})] = \mathcal{B}(\mathcal{H})$ [2]. Thus $\mathcal{I} \subseteq K(\mathcal{H})$. Hence \mathcal{I} is of finite codimension in $K(\mathcal{H})$, since $\mathcal{L} \subseteq \mathcal{I} + \mathbb{C}1$. But this implies \mathcal{I} is closed [11]. Hence $\mathcal{I} = \mathcal{K}(\mathcal{H})$. Now $\mathcal{K}(\mathcal{H}) = [\mathcal{B}(\mathcal{H}), \mathcal{K}(\mathcal{H})]$ [1]. Hence $\mathcal{L} = \mathcal{K}(\mathcal{H})$ since $\mathcal{L} \supseteq [\mathcal{B}(\mathcal{H}), \mathcal{I}]$.

Recall that the centre $Z(B)$ of an algebra B is the set $\{x \in B : xy = yx (y \in B)\}$. It is clear that if L is a linear manifold in B such that $L \subseteq Z(B)$ or $[B, B] \subseteq L$, then L is a Lie ideal in B . The following theorem gives a class of algebras for which every Lie ideal is got in this manner, and is a weaker version of a theorem of Herstein.

THEOREM 4 (Herstein [10]). *Let B be a simple algebra, over a field F not of characteristic 2, which has a set of 2×2 matrix units. Then the Lie ideals of B are precisely the linear manifolds L of B such that $L \subseteq Z(B)$ or $[B, B] \subseteq L$.*

Proof. Let L be a Lie ideal of B . By Theorem 1, there is an ideal I in B such that $[B, I] \subseteq L \subseteq I^-$. Now by the simplicity of B , $I = 0$ or B . If $I = 0$, then $L \subseteq I^- = Z(B)$. If $I = B$, the $[B, B] \subseteq L$.

REMARK. Let \mathcal{H} be an infinite dimensional separable Hilbert space and $B = \mathcal{B}(\mathcal{H})/\mathcal{K}(\mathcal{H})$. Then B is simple and has a set of 2×2 matrix units. Also $[B, B] = B$ [2], and $Z(B) = \mathbb{C}1$. Hence by Theorem 4 the only Lie ideals of B are 0, $\mathbb{C}1$, and B itself. This observation is apparently originally due to Topping.

If an algebra B satisfies $B = [B, B]$ and has a set of 2×2 matrix units, then we are able to characterize its Lie ideals in terms of its ideals. Some examples

of such algebras are: $\mathcal{B}(\mathcal{H})$ where \mathcal{H} is an infinite dimensional Hilbert space; $\mathcal{B}(\mathcal{H})/\mathcal{K}(\mathcal{H})$ if \mathcal{H} is also separable; also every properly infinite von Neumann algebra [12].

THEOREM 5. *Let B be an algebra, over a field F not of characteristic 2, with a set of 2×2 matrix units, and suppose $B = [B, B]$. Then a linear manifold L in B is a Lie ideal if and only if there is an ideal I in B such that $[B, I] \subseteq L \subseteq I^\sim$.*

Proof. The forward implication has been shown in Theorem 1. So let's suppose L is a linear manifold and I is an ideal such that $[B, I] \subseteq L \subseteq I^\sim$. Let $x \in L$ and $a, b \in B$. Then $[[a, b], x] = [a, [b, x]] - [b, [a, x]]$ by the Jacobi identity. But $x \in I^\sim$, so $[a, x], [b, x] \in I$. Now $[B, I] \subseteq L$, hence $[a, [b, x]]$ and $[b, [a, x]] \in L$. Thus $[[a, b], x] \in L$. But since $[B, B] = B$, this implies $[c, x] \in L$ for all c in B . Thus L is a Lie ideal.

THEOREM 6. *Let B be an infinite dimensional algebra over a field F not of characteristic 2 and suppose $B = [B, B]$ and B has a set of 2×2 matrix units. Then B has proper finite codimensional Lie ideals if and only if B has proper finite codimensional ideals.*

Proof. The backward implication is clearly trivial. Suppose L is a proper Lie ideal with $\dim B/L < \infty$. Then by Corollary 2 there is an ideal I in B with $[B, I] \subseteq L \subseteq I^\sim$ and $\dim B/I < \infty$. Hence $I \neq 0$ since $\dim B = \infty$. Also $I \neq B$ since $B = [B, B] \subseteq L \neq B$.

REMARK. We finish this paper with a generalization of a result in [8]. It's shown there (Theorem 1) that a linear manifold \mathcal{L} in $\mathcal{B}(\mathcal{H})$ (\mathcal{H} a separable infinite dimensional Hilbert space) is a Lie ideal in $\mathcal{B}(\mathcal{H})$ iff $U^* \mathcal{L} U \subseteq \mathcal{L}$ for every unitary U in $\mathcal{B}(\mathcal{H})$. An inspection of the proof shows that it only uses the following two facts about $\mathcal{B}(\mathcal{H})$.

(a) Every unitary in $\mathcal{B}(\mathcal{H})$ is a product of (four) symmetries.

(b) Every operator in $\mathcal{B}(\mathcal{H})$ is a finite linear combination of projections. The first result is due to Halmos–Kakutani [9], and in [7] it is shown that this result can be extended to any properly infinite von Neumann algebra B (i.e. every unitary in B is a product of symmetries in B .) The second result is due to Fillmore [6], and in [12] it is generalized to a properly infinite von Neumann algebra B (i.e. every element of B is a linear combination of projections in B .) Hence, we conclude: A linear manifold L in a properly infinite von Neumann algebra B is a Lie ideal in B if and only if $u^* L u \subseteq L$ for every unitary u in B .

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