

Volume 38 Part 1

ROBOTICA



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CAMBRIDGE
UNIVERSITY PRESS

ISSN 0263-5747

ROBOTICA

An IFAC-Affiliated Journal, and an
Official Journal of the IFR.

International Journal of Information, Education and Research
in Robotics and Artificial Intelligence

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Robotica (ISSN 0263-5747) is published as twelve Issues per Volume in January, February, March, April, May, June, July, August, September, October, November and December. The electronic-only price for Volume 38, 2020 available to institutional subscribers is £1384 (US \$2444 in USA, Canada and Mexico). EU subscribers (outside the UK) who are not registered for VAT should add VAT at their country's rate. VAT registered subscribers should provide their VAT registration number. Orders, which

must be accompanied by payment, may be sent to a bookseller, subscription agent or direct to the publishers: Cambridge University Press, University Printing House, Shaftesbury Road, Cambridge CB2 8RU, UK. Orders from the USA, Canada and Mexico should be sent to Cambridge University Press, Journals Fulfillment Department, 1 Liberty Plaza, Floor 20, New York, NY 10006, USA. Japanese prices for institutions are available from Kinokuniya Company Ltd, P.O. Box 55, Chitose, Tokyo 156, Japan. Prices include delivery by air.

Periodicals postage paid at New York, NY and additional mailing offices. POSTMASTER: send address changes in USA, Canada and Mexico to *Robotica*, Cambridge University Press, 1 Liberty Plaza, Floor 20, New York, NY 10006, USA.

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Cover Image: Design and Manufacturing of Tendon-Driven Soft Foam Robots by Nikolas Kastor, Ritwika Mukherjee, Eliad Cohen, Vishesh Vikas, Barry A. Trimmer and Robert D. White. Figure 12 'Left: The robot demonstrating a crawling gait. This gait produces a forward locomotion speed of ~13 mm/s. Center: The robot demonstrating a turning gait. Each motion of this configuration produces ~18° of rotation. Right: The robot demonstrating a flipping behavior.'