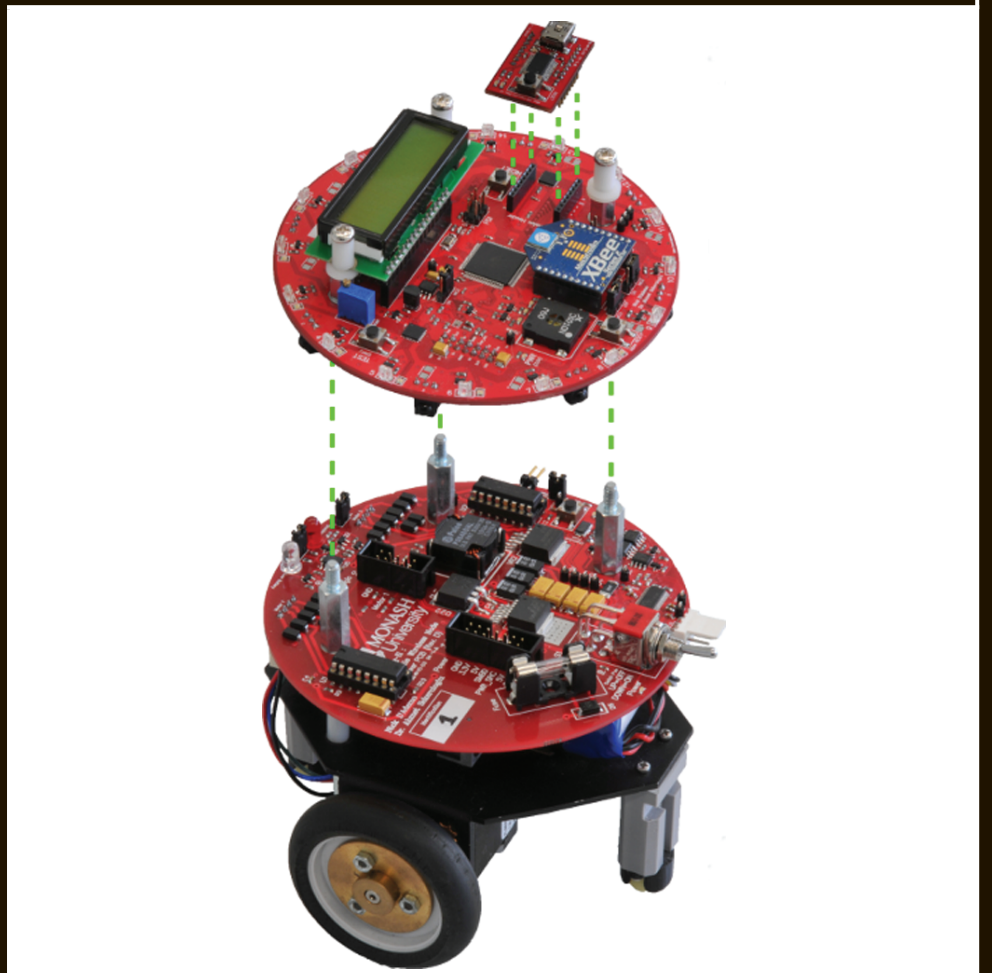


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Cover Image: Figure 6 from **Distributed formation control of networked mobile robots in environments with obstacles** by Whye Leon Seng, Jan Carlo Barca and Y. Ahmet Şekercioğlu