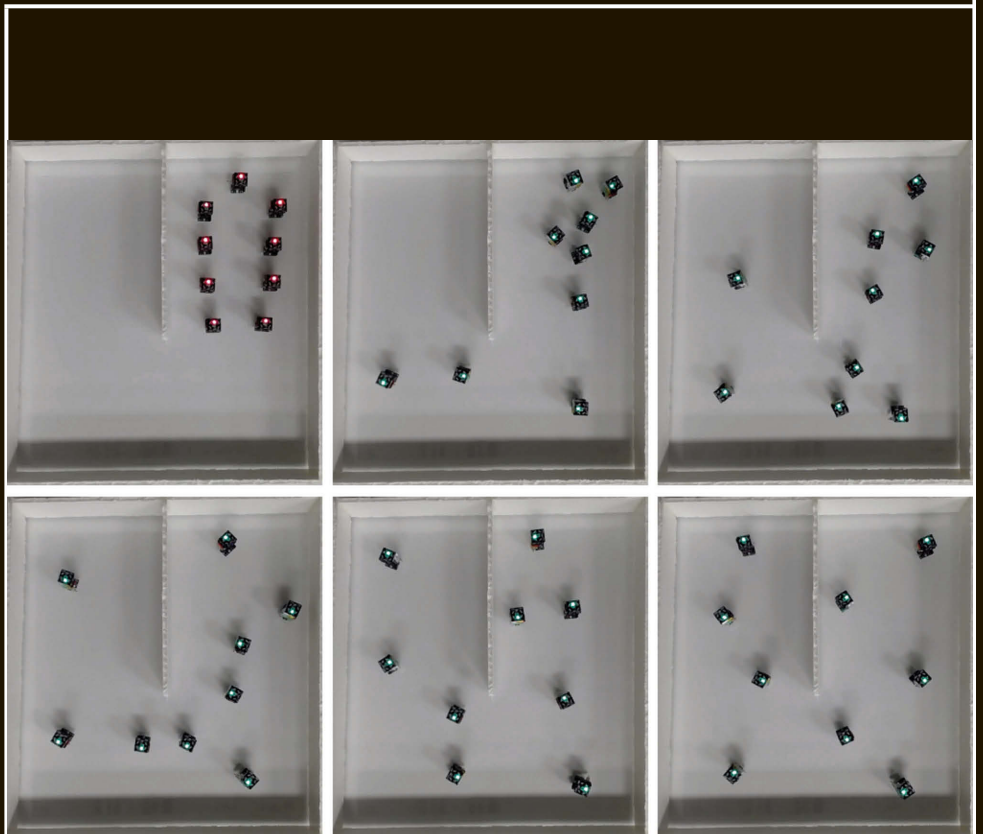


Volume 36 Part 11

# ROBOTICA



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**CAMBRIDGE**  
UNIVERSITY PRESS

ISSN 0263-5747

# ROBOTICA

An IFAC-Affiliated Journal, and an  
Official Journal of the IFR.

International Journal of Information, Education and Research  
in Robotics and Artificial Intelligence

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*Robotica* (ISSN 0263-5747) is published as twelve Issues per Volume in January, February, March, April, May, June, July, August, September, October, November and December. The electronic-only price for Volume 36, 2018 available to institutional subscribers is £1255 (US \$2216 in USA, Canada and Mexico). EU subscribers (outside the UK) who are not registered for VAT should add VAT at their country's rate. VAT registered subscribers should provide their VAT registration number. Orders, which

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Periodicals postage paid at New York, NY and additional mailing offices. POSTMASTER: send address changes in USA, Canada and Mexico to *Robotica*, Cambridge University Press, 1 Liberty Plaza, Floor 20, New York, NY 10006, USA.

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Cover Image: Design and implementation of a millirobot for swarm studies – *mROBerTO* by Justin Y. Kim, Zendai Kashino, Tyler Colaco, Goldie Nejat and Beno Benhabib. Fig. 8 ‘Collective exploration demonstrated by *mROBerTO*s using artificial potential physics’