

Monotone Hurwitz Numbers in Genus Zero

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Abstract. Hurwitz numbers count branched covers of the Riemann sphere with specified ramification data, or equivalently, transitive permutation factorizations in the symmetric group with specified cycle types. Monotone Hurwitz numbers count a restricted subset of these branched covers related to the expansion of complete symmetric functions in the Jucys–Murphy elements, and have arisen in recent work on the the asymptotic expansion of the Harish-Chandra–Itzykson–Zuber integral. In this paper we begin a detailed study of monotone Hurwitz numbers. We prove two results that are reminiscent of those for classical Hurwitz numbers. The first is the monotone join-cut equation, a partial differential equation with initial conditions that characterizes the generating function for monotone Hurwitz numbers in arbitrary genus. The second is our main result, in which we give an explicit formula for monotone Hurwitz numbers in genus zero.

1 Introduction

Hurwitz numbers count branched covers of the Riemann sphere with specified ramification data. They have been the subject of much mathematical interest in recent years, especially through the ELSV formula, given in [3], which expresses a Hurwitz number as a Hodge integral over the moduli space of stable curves of a given genus with a given number of marked points. This has led to a number of new proofs (see, *e.g.*, Okounkov and Pandharipande [22] and Kazarian and Lando [17]) of Witten's conjecture [27] (first proved by Kontsevich [18]), which states that a particular generating function for intersection numbers satisfies the KdV hierarchy of partial differential equations. The interest in Hurwitz numbers has much to do with these rich connections that their study has revealed between mathematical physics and algebraic geometry. There is also a connection with algebraic combinatorics because of the bijection, due to Hurwitz [14], between branched covers of the sphere and transitive factorizations in the symmetric group (see, *e.g.*, Goulden, Jackson, and Vainshtein [11]).

Monotone Hurwitz numbers, introduced in [9], count a restricted subset of the branched covers counted by the Hurwitz numbers. The topic of [9] is the Harish-Chandra–Itzykson–Zuber (HCIZ) integral (see, *e.g.*, [13, 15, 29])

$$I_N(z,A_N,B_N) = \int_{\mathbf{U}(N)} e^{zN\operatorname{tr}(A_NUB_NU^*)} \mathrm{d}U.$$

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Here the integral is over the group of $N \times N$ complex unitary matrices against the normalized Haar measure, z is a complex parameter, and A_N , B_N are $N \times N$ complex matrices. Since U(N) is compact, I_N is an entire function of $z \in \mathbb{C}$. Consequently, the function

$$F_N(z, A_N, B_N) = N^{-2} \oint_0^z \frac{I'_N(\zeta, A_N, B_N)}{I_N(\zeta, A_N, B_N)} d\zeta$$

is well defined and holomorphic in a neigbourhood of z = 0, and satisfies

$$I_N(z, A_N, B_N) = e^{N^2 F_N(z, A_N, B_N)}$$

on its domain of definition. In [9], we proved that, for two specified sequences of normal matrices $A=(A_N)_{N=1}^\infty$, $B=(B_N)_{N=1}^\infty$ that grow in a sufficiently regular fashion, the derivatives $F_N^{(d)}(0,A_N,B_N)$ of F_N at z=0 admit an $N\to\infty$ asymptotic expansion on the scale N^{-2} whose g-th coefficient is a generating function for the monotone double Hurwitz numbers of degree d and genus g. This is analogous to the well-known genus expansion of Hermitian matrix models, whose coefficients are generating functions enumerating graphs on surfaces (see, e.g., [30]). In this paper, we begin a detailed study of monotone Hurwitz numbers.

1.1 Hurwitz Numbers

The *single Hurwitz numbers* count d-sheeted branched covers of the Riemann sphere by a Riemann surface where we allow arbitrary, but fixed, branching at one ramification point and only simple branching at other ramification points. Using the Hurwitz [14] encoding of a branched cover as a factorization in the symmetric group, we obtain the following identification with an enumeration question in the symmetric group: given a partition $\alpha \vdash d$ and an integer $r \geq 0$, the single Hurwitz number $H^r(\alpha)$ is the number of factorizations

$$(1.1) (a_1 b_1)(a_2 b_2) \cdots (a_r b_r) = \sigma$$

in the symmetric group S_d , where

- $(a_1 b_1), (a_2 b_2), \dots, (a_r b_r)$ are transpositions;
- σ is in the conjugacy class C_{α} of permutations with cycle type α ;
- the subgroup $\langle (a_1 b_1), (a_2 b_2), \dots, (a_r b_r) \rangle$ acts transitively on the ground set $\{1, 2, \dots, d\}$.

Each factorization corresponds to a branched cover of the Riemann sphere, and by the Riemann–Hurwitz formula, the genus *g* of the cover is given by the relation

$$(1.2) r = d + \ell(\alpha) + 2g - 2,$$

where $\ell(\alpha)$ denotes the number of parts of α . Depending on the context, we will write $H_{\mathfrak{g}}(\alpha)$ interchangeably with $H^r(\alpha)$, using the convention that (1.2) always holds.

Remark 1.1 Equation (1.1), when rewritten as $(a_1 b_1)(a_2 b_2) \cdots (a_r b_r)\sigma^{-1} = id$, translates into a *monodromy* condition for the corresponding cover, in which σ^{-1}

specifies the branching for the point with arbitrary ramification, and $(a_i b_i)$, i = 1, ..., r specifies the (simple) branching at the remaining ramification points. The transitivity condition for the factorization translates to the requirement that the corresponding cover is *connected*.

1.2 Monotone Hurwitz Numbers

The monotone single Hurwitz number $\vec{H}^r(\alpha)$ is the number of factorizations (1.1) counted by the single Hurwitz number $H^r(\alpha)$, but with the additional restriction that

$$(1.3) b_1 < b_2 < \dots < b_r,$$

where $a_i < b_i$ by convention. As with Hurwitz numbers, depending on the context, we will write $\vec{H}_g(\alpha)$ interchangeably with $\vec{H}^r(\alpha)$, with the understanding that (1.2) holds. We will refer to a factorization (1.1) with restriction (1.3) as a *monotone* factorization of σ .

Remark 1.2 In Hurwitz's encoding, the ground set $\{1, 2, \dots, d\}$ corresponds to the set of sheets of the branched cover, once branch cuts have been chosen and the sheets have been labelled. In the case of Hurwitz numbers, the labelling of the sheets is immaterial, so Hurwitz numbers are usually defined to count branched covers with *unlabelled* sheets, which differs from our definition above by a factor of d!. However, for monotone Hurwitz numbers, the monotonicity condition depends on a total ordering of the sheets, so the labelling does matter in this case. Thus, for consistency, our convention is that both kinds of Hurwitz numbers count branched covers with labelled sheets.

1.3 Main Result

In Section 4, we obtain the following theorem. This is our main result, which gives an explicit formula for the genus zero monotone Hurwitz numbers.

Theorem 1.1 The genus zero monotone single Hurwitz number $\vec{H}_0(\alpha)$, $\alpha \vdash d$ is given by

(1.4)
$$\vec{H}_0(\alpha) = \frac{d!}{|\operatorname{Aut} \alpha|} (2d+1)^{\overline{\ell(\alpha)}-3} \prod_{i=1}^{\ell(\alpha)} {2\alpha_i \choose \alpha_j},$$

where

$$(2d+1)^{\overline{k}} = (2d+1)(2d+2)\cdots(2d+k)$$

denotes a rising product with k factors, and by convention

$$(2d+1)^{\overline{k}} = \frac{1}{(2d+k+1)^{-\overline{k}}}$$

for k < 0.

In the special case that $\alpha = (d)$, the partition with a single part equal to d, Theorem 1.1 becomes

$$\vec{H}_0((d)) = \frac{(2d-2)!}{d!} = (d-1)! C_{d-1},$$

where $C_{d-1} = \frac{1}{d} \binom{2d-2}{d-1}$ is a *Catalan* number. This case was previously obtained by Gewurz and Merola [7], who used the term *primitive* for these factorizations. In the special case that $\alpha = (1^d)$, the partition with all parts equal to 1, Theorem 1.1 becomes

$$\vec{H}_0((1^d)) = \frac{(3d-3)!}{(2d)!} 2^d.$$

Via the connection between monotone Hurwitz numbers and the HCIZ integral established in [9], this case is equivalent to a result previously obtained by Zinn-Justin [28] for the HCIZ integral.

Theorem 1.1 is strikingly similar to the well-known explicit formula for the genus zero Hurwitz numbers

(1.5)
$$H_0(\alpha) = \frac{d!}{|\operatorname{Aut} \alpha|} (d + \ell(\alpha) - 2)! d^{\ell(\alpha) - 3} \prod_{i=1}^{\ell(\alpha)} \frac{\alpha_j^{\alpha_j}}{\alpha_j!},$$

published without proof by Hurwitz [14] in 1891 (see also Strehl [26]) and independently rediscovered and proved a century later by Goulden and Jackson [10].

There is another case in which an explicit formula similar to Theorem 1.1 is known. This is the case where we allow arbitrary, but fixed, branching at a specified ramification point and arbitrary branching at all other ramification points, which has been studied by Bousquet-Mélou and Schaeffer [2]. Given a partition $\alpha \vdash d$ and integers $r, g \geq 0$, let $G_g^r(\alpha)$ be the number of factorizations $\rho_1 \rho_2 \cdots \rho_r = \sigma$ in the symmetric group S_d that satisfy the conditions

- $\rho_1, \rho_2, \ldots, \rho_r \in S_d$,
- $\sigma \in C_{\alpha}$
- $\langle \rho_1, \rho_2, \dots, \rho_r \rangle$ acts transitively on $\{1, 2, \dots, d\}$,

and

(1.6)
$$\sum_{j=1}^{r} \operatorname{rank}(\rho_{j}) = d + \ell(\alpha) + 2g - 2,$$

where rank(ρ_j) is d minus the number of cycles of ρ_j . Each such factorization corresponds to a branched cover of the Riemann sphere, and (1.6), by the Riemann-Hurwitz formula, specifies the genus g of the cover.

Remark 1.3 Note that in this case there is more freedom for the parameters α , r, g than for the Hurwitz and monotone Hurwitz cases above. In particular, given α and r, the choice for g is not unique in (1.6) above. This explains why we have used both parameters r and g in the notation $G_q^r(\alpha)$.

Bousquet-Mélou and Schaeffer [2] solved this problem in full generality for genus zero, using a bijective correspondence to constellations and thence to a family of bicoloured trees. (For more on constellations, see Lando and Zvonkin [19].) They proved that

$$(1.7) G_0^r(\alpha) = \frac{d!}{|\operatorname{Aut} \alpha|} r \left((r-1)d - \ell(\alpha) + 2 \right)^{\overline{\ell(\alpha)} - 2} \prod_{j=1}^{\ell(\alpha)} \binom{r\alpha_j - 1}{\alpha_j},$$

an explicit form that is again strikingly similar to both (1.4) and (1.5).

The explicit formulas (1.4), (1.5) and (1.7) feature remarkably simple combinatorial functions, but we know of no uniform bijective method to explain these formulas.

1.4 Join-cut Equations

The proof that we give for Theorem 1.1, our main result, involves the generating function for monotone single Hurwitz numbers

(1.8)
$$\vec{\mathbf{H}}(z,t,\mathbf{p}) = \sum_{d\geq 1} \frac{z^d}{d!} \sum_{r\geq 0} t^r \sum_{\alpha \vdash d} \vec{H}^r(\alpha) p_\alpha,$$

which is a formal power series in the indeterminates z,t and the countable set of indeterminates $\mathbf{p}=(p_1,p_2,\dots)$, and where p_α denotes the product $\prod_{j=1}^{\ell(\alpha)}p_{\alpha_j}$. From a combinatorial point of view,

- z is an exponential marker for the size d of the ground set;
- *t* is an ordinary marker for the number *r* of transpositions;
- p_1, p_2, \ldots are ordinary markers for the cycle lengths of σ .

In Section 2, we obtain the following theorem, which gives a partial differential equation with initial condition that uniquely specifies the generating function $\vec{\mathbf{H}}$. The proof that we give is a combinatorial join-cut analysis, and we refer to the partial differential equation in Theorem 1.2 as the *monotone join-cut equation*.

Theorem 1.2 The generating function $\vec{\mathbf{H}}$ is the unique formal power series solution of the partial differential equation

$$\frac{1}{2t} \left(z \frac{\partial \vec{\mathbf{H}}}{\partial z} - z p_1 \right) = \frac{1}{2} \sum_{i,j \ge 1} \left((i+j) p_i p_j \frac{\partial \vec{\mathbf{H}}}{\partial p_{i+j}} + i j p_{i+j} \frac{\partial^2 \vec{\mathbf{H}}}{\partial p_i \partial p_j} + i j p_{i+j} \frac{\partial \vec{\mathbf{H}}}{\partial p_i} \frac{\partial \vec{\mathbf{H}}}{\partial p_j} \right)$$

with the initial condition $[z^0]\vec{\mathbf{H}} = 0$.

Theorem 1.2 is again strikingly similar to the situation for the classical single Hurwitz numbers. To make this precise, consider the generating function for the classical

single Hurwitz numbers

$$\mathbf{H}(z,t,\mathbf{p}) = \sum_{d\geq 1} \frac{z^d}{d!} \sum_{r\geq 0} \frac{t^r}{r!} \sum_{\alpha \vdash d} H^r(\alpha) p_{\alpha}.$$

It is well known (see [10, 11]) that **H** is the unique formal power series solution of the partial differential equation

$$(1.9) \qquad \frac{\partial \mathbf{H}}{\partial t} = \frac{1}{2} \sum_{i,j>1} \left((i+j) p_i p_j \frac{\partial \mathbf{H}}{\partial p_{i+j}} + ij p_{i+j} \frac{\partial^2 \mathbf{H}}{\partial p_i \partial p_j} + ij p_{i+j} \frac{\partial \mathbf{H}}{\partial p_i} \frac{\partial \mathbf{H}}{\partial p_j} \right)$$

with the initial condition $[t^0]\mathbf{H} = zp_1$. Equation (1.9) is called the (classical) *join-cut equation*, and has exactly the same differential forms on the right-hand side as the monotone join-cut equation given in Theorem 1.2. There are, however, significant differences on the left-hand side between these two versions of the join-cut equation. In the classical case (1.9), the left-hand side is a first derivative in t; in the monotone case (Theorem 1.2), the left-hand side is a first *divided difference* in t and also involves differentiation in z.

Remark 1.4 The difference in the left-hand sides between the two join-cut equations is related to the fact that the generating functions \mathbf{H} and $\vec{\mathbf{H}}$ differ in the combinatorial role played by the indeterminate t. In the case of \mathbf{H} , t is an *exponential* marker for the number t of transpositions, while in the case of $\vec{\mathbf{H}}$, t is an *ordinary* marker. This difference is due to technical combinatorial reasons, explained in Section 1.5.

Our proof of the explicit formula in Theorem 1.1 for genus zero monotone Hurwiz numbers proceeds by verification using a variant of the monotone join-cut equation given in Theorem 1.2. In general terms, this is how we obtained the explicit formula (1.4) for genus zero classical Hurwitz numbers in [10], using the classical join-cut equation (1.9). However, the technical details of this verification are quite different in this paper, because of the change in the left-hand side between these two different versions of the join-cut equation.

1.5 The Group Algebra of the Symmetric Group

In this section we express the generating functions \mathbf{H} and $\vec{\mathbf{H}}$ in terms of elements of the centre of the group algebra $\mathbb{Q}[S_d]$. This is not an essential part of our proof of the main result, but it will help explain why the indeterminate t for transposition factors is an exponential marker in \mathbf{H} , whereas it is an ordinary marker in $\vec{\mathbf{H}}$. In addition, it gives a convenient proof of the fact that the number of monotone factorizations of a permutation σ depends only on its conjugacy class, which we will need in Section 2 to prove the monotone join-cut equation.

First we consider the single Hurwitz numbers. For any $\alpha \vdash d$, let C_{α} be the formal sum of all elements of the conjugacy class C_{α} , which consists of all permutations of cycle type α , considered as an element of $\mathbb{Q}[S_d]$. It is well known that the centre of $\mathbb{Q}[S_d]$ consists precisely of linear combinations of the C_{α} . If we drop the transitivity

condition for single Hurwitz numbers, the generating function for the resulting notnecessarily-transitive factorizations becomes

$$\tau(z, t, \mathbf{p}) = \sum_{d \ge 0} \frac{z^d}{d!} \sum_{r \ge 0} \frac{t^r}{r!} \sum_{\alpha \vdash d} p_{\alpha} \sum_{\sigma \in C_{\alpha}} [\sigma] C_{2, 1^{d-2}}^r$$
$$= \sum_{d \ge 0} \frac{z^d}{d!} \sum_{r \ge 0} \frac{t^r}{r!} \sum_{\alpha \vdash d} p_{\alpha} |C_{\alpha}| [C_{\alpha}] C_{2, 1^{d-2}}^r,$$

where we have used the notation [A]B for the *coefficient* of A in the expansion of B. The constant term 1 corresponding to d=0 has been added to the generating function τ for combinatorial reasons, described as follows. When we drop the transitivity condition for single Hurwitz numbers, each resulting not-necessarily-transitive factorization can be split into disjoint transitive factorizations by restricting it to the orbits of the group $\langle (a_1\,b_1),\ldots,(a_r\,b_r)\rangle$ on the ground set. Each of these orbits is a subset of the ground set $\{1,\ldots,d\}$, and the set of transpositions that act on pairs of elements in a given orbit is a subset of the positions $\{1,\ldots,r\}$ in the factorization. Conversely, transitive factorizations on disjoint ground sets can be combined by shuffling their transpositions in any way that preserves the order of transpositions acting on the same component of the ground set. Thus, each factorization counted by τ is an unordered collection of the transitive factorizations counted by H, in which the variables z (marking d) and t (marking r) are both *exponential*. From the Exponential Formula for exponential generating functions (see, *e.g.*, [12]), this situation is captured by the equation

$$\mathbf{H}(z, t, \mathbf{p}) = \log \tau(z, t, \mathbf{p}).$$

Remark 1.5 The coefficient of $z^d t^r / r!$ in $\tau(z,t,\mathbf{p})$ is in fact the image of $C_{2,1^{d-2}}^r$ under the characteristic map, ch, of Macdonald [21, p. 113], if one interprets the indeterminates p_1, p_2, \ldots as power sum symmetric functions. This can be expressed in the basis of Schur symmetric functions using irreducible characters of S_d , and then the tools of representation theory become available. While this is an interesting approach, we will not be using it here.

Now we turn to monotone single Hurwitz numbers. While the monotonicity condition may seem artificial, it arises naturally in the group algebra $\mathbb{Q}[S_d]$ via the Jucys–Murphy elements J_i , defined by

$$J_i = (1 i) + (2 i) + \cdots + (i - 1 i), \qquad i = 1, \dots, d.$$

If we drop the transitivity condition for monotone single Hurwitz numbers, the generating function for the resulting not-necessarily-transitive factorizations becomes

$$ec{ au}(z,t,\mathbf{p}) = \sum_{d\geq 0} rac{z^d}{d!} \sum_{r\geq 0} t^r \sum_{lpha \vdash d} p_lpha \sum_{\sigma \in C_lpha} [\sigma] \sum_{1\leq b_1 \leq \cdots \leq b_r \leq d} \mathsf{J}_{b_1} \cdots \mathsf{J}_{b_r}
onumber \ = \sum_{d\geq 0} rac{z^d}{d!} \sum_{r\geq 0} t^r \sum_{lpha \vdash d} p_lpha \sum_{\sigma \in C_lpha} [\sigma] h_r(\mathsf{J}_1,\ldots,\mathsf{J}_d),$$

where h_r is the r-th complete symmetric polynomial. Jucys [16] showed that the set of symmetric polynomials in the Jucys–Murphy elements is exactly the centre of $\mathbb{Q}[S_d]$, so we obtain immediately that

$$\vec{\tau}(z,t,\mathbf{p}) = \sum_{d\geq 0} \frac{z^d}{d!} \sum_{r\geq 0} t^r \sum_{\alpha \vdash d} p_{\alpha} |C_{\alpha}| [C_{\alpha}] h_r(J_1,\ldots,J_d).$$

This time, when we drop the transitivity condition for single monotone Hurwitz numbers, each resulting not-necessarily-transitive factorization can again be split into disjoint transitive factorizations by restricting it to the orbits of the group $\langle (a_1\,b_1),\ldots,(a_r\,b_r)\rangle$ on the ground set. Each of these orbits is a subset of the ground set $\{1,\ldots,d\}$, and the set of transpositions that act on pairs of elements in a given orbit is a subset of the positions $\{1,\ldots,r\}$ in the factorization. However, this time, to preserve monotonicity, transitive factorizations on disjoint ground sets can be combined by shuffling their transpositions in only one way. Thus, each factorization counted by $\vec{\tau}$ is an unordered collection of the transitive factorizations counted by \vec{H} , in which only the variable z (marking d) is *exponential*. The Exponential Formula for exponential generating functions then gives

$$\vec{\mathbf{H}}(z, t, \mathbf{p}) = \log \vec{\tau}(z, t, \mathbf{p}).$$

Remark 1.6 As with $\tau(z,t,\mathbf{p})$, the coefficients of $\vec{\tau}(z,t,\mathbf{p})$ can be expressed in terms of MacDonald's characteristic map, ch, to provide a link with representation theory. This is particularly interesting in view of Okounkov and Vershik's approach to the representation theory of the symmetric group [23], which features the Jucys–Murphy elements prominently. However, we will not be exploring this connection further in this paper.

Remark 1.7 Related results on complete symmetric functions of the Jucys–Murphy elements have been obtained by Lassalle [20] and Féray [6]. The recurrences they obtain seem to be of a completely different nature than those we obtain in this paper.

1.6 Outline

In Section 2, we prove the monotone join-cut equation of Theorem 1.2. This is based on a combinatorial join-cut analysis for monotone Hurwitz numbers that appears in Section 2.1. The monotone join-cut equation itself is then deduced in Section 2.2. The join-cut analysis also yields another system of equations that appears in Section 2.3, and is referred to there as a topological recursion.

In Section 3, we recast the monotone join-cut equation, breaking it up into a separate join-cut equation for each genus, and expressing these equations in an algebraic form that is more convenient to solve. This is based on some algebraic operators that are introduced in Section 3.1, and the transformed system of equations appears in Section 3.2.

In Section 4, we prove the main result of this paper, Theorem 1.1, which gives an explicit formula for monotone Hurwitz numbers in genus zero. Our method is

to repackage the formula as a generating function F and to show that it satisfies the genus zero monotone join-cut equation that characterizes the generating function \vec{H}_0 for genus zero monotone Hurwitz numbers. In Section 4.1, we introduce transformed variables and use Lagrange's Implicit Function Theorem to give a closed form for a differential form applied to the series F. In Section 4.2, we invert this differential form. In Section 4.3, we describe the action of the algebraic operators of Section 3 on the transformed variables and deduce the main result.

2 Join-cut Analysis

In this section, we analyze the effect of removing the last factor in a transitive monotone factorization, which leads to a recurrence relation for monotone single Hurwitz numbers. From this we obtain the monotone join-cut equation of Theorem 1.2, which uniquely characterizes the generating function $\vec{\mathbf{H}}(z,t,\mathbf{p})$, and a system of equations for a different generating function that we refer to as a *topological recursion*.

2.1 Recurrence Relation

For a partition $\alpha \vdash d$, let $M^r(\alpha)$ be the number of transitive monotone factorizations of a fixed but arbitrary permutation $\sigma \in S_d$ of cycle type α into r transpositions. By the discussion in Section 1.5, this number only depends on the cycle type of σ , so it is well defined, and we immediately have

(2.1)
$$\vec{H}^r(\alpha) = |C_{\alpha}| M^r(\alpha).$$

Theorem 2.1 The numbers $M^{r}(\alpha)$ are uniquely determined by the initial condition

$$M^0(\alpha) = \begin{cases} 1 & \text{if } \alpha = (1), \\ 0 & \text{otherwise}, \end{cases}$$

and the recurrence

$$(2.2)$$

$$M^{r+1}(\alpha \cup \{k\}) = \sum_{k' \ge 1} k' m_{k'}(\alpha) M^r(\alpha \setminus \{k'\} \cup \{k+k'\})$$

$$+ \sum_{k'=1}^{k-1} M^r(\alpha \cup \{k', k-k'\})$$

$$+ \sum_{k'=1}^{k-1} \sum_{r'=0}^{r} \sum_{\alpha' \in \alpha} M^{r'}(\alpha' \cup \{k'\}) M^{r-r'}(\alpha \setminus \alpha' \cup \{k-k'\})$$

for $\alpha \vdash d$, d, $r \geq 0$, $k \geq 1$. In this recurrence, $m_{k'}(\alpha)$ is the number of parts of α of size k', and the last sum is over the $2^{\ell(\alpha)}$ subpartitions α' of α .

Proof As long as the initial condition and the recurrence relation hold, uniqueness follows by induction on r. The initial condition follows from the fact that for r = 0 we must have $\sigma = \text{id}$, and the identity permutation is only transitive in S_1 .

To show the recurrence, fix a permutation $\sigma \in S_d$ of cycle type $\alpha \cup \{k\}$, where the element d is in a cycle of length k, and consider a transitive monotone factorization

$$(a_1 b_1)(a_2 b_2) \cdots (a_r b_r)(a_{r+1} b_{r+1}) = \sigma.$$

The transitivity condition forces the element d to appear in some transposition, and the monotonicity condition forces it to appear in the last transposition, so it must be that $b_{r+1} = d$. If we move this transposition to the other side of the equation and set $\sigma' = \sigma(a_{r+1} b_{r+1})$, we get the shorter monotone factorization

$$(2.4) (a_1 b_1)(a_2 b_2) \cdots (a_r b_r) = \sigma'.$$

Depending on whether a_{r+1} is in the same cycle of σ' as b_{r+1} and whether (2.4) is still transitive, the shorter factorization falls into exactly one of the following three cases, corresponding to the three terms on the right-hand side of the recurrence.

Cut Suppose a_{r+1} and b_{r+1} are in the same cycle of σ' . Then σ is obtained from σ' by cutting the cycle containing a_{r+1} and b_{r+1} in two parts, one containing a_{r+1} and the other containing b_{r+1} , so $(a_{r+1} b_{r+1})$ is called a *cut* for σ' and also for the factorization (2.3). Conversely, a_{r+1} and b_{r+1} are in different cycles of σ , and σ' is obtained from σ by joining these two cycles, so the transposition $(a_{r+1} b_{r+1})$ is called a *join* for σ . Note that in the case of a cut, (2.4) is transitive if and only if (2.3) is transitive.

For $k' \geq 1$, there are $k'm_{k'}(\alpha)$ possible choices for a_{r+1} in a cycle of σ of length k' other than the one containing b_{r+1} . For each of these choices, $(a_{r+1} b_{r+1})$ is a cut and σ' has cycle type $\alpha \setminus \{k'\} \cup \{k+k'\}$. Thus, the number of transitive monotone factorizations of σ where the last factor is a cut is

$$\sum_{k'>1} k' m_{k'}(\alpha) M^r (\alpha \setminus \{k'\} \cup \{k+k'\}),$$

which is the first term in the recurrence.

Redundant join Now suppose that $(a_{r+1} b_{r+1})$ is a join for σ' and that (2.4) is transitive. Then we say that $(a_{r+1} b_{r+1})$ is a *redundant join* for (2.3).

The transposition $(a_{r+1} b_{r+1})$ is a join for σ' if and only if it is a cut for σ , and there are k-1 ways of cutting the k-cycle of σ containing b_{r+1} . Thus, the number of transitive monotone factorizations of σ where the last factor is a redundant join is

$$\sum_{k'=1}^{k-1} M^r(\alpha \cup \{k', k-k'\}),$$

which is the second term in the recurrence.

Essential join Finally, suppose that $(a_{r+1} b_{r+1})$ is a join for σ' and that (2.4) is not transitive. Then we say that $(a_{r+1} b_{r+1})$ is an *essential join* for (2.3). In this case, the action of the subgroup $\langle (a_1 b_1), \ldots, (a_r b_r) \rangle$ must have exactly two orbits on the ground set, one containing a_{r+1} and the other containing b_{r+1} . Since transpositions acting on different orbits commute, (2.4) can be rearranged into a product of two transitive monotone factorizations on these orbits. Conversely, given a transitive monotone factorization for each orbit, this process can be reversed, and the monotonicity condition guarantees uniqueness of the result.

As with redundant joins, there are k-1 choices for a_{r+1} to split the k-cycle of σ containing b_{r+1} . Each of the other cycles of σ must be in one of the two orbits, so there are $2^{\ell(\alpha)}$ choices for the orbit containing a_{r+1} . Thus, the number of transitive monotone factorizations of σ where the last factor is an essential join is

$$\sum_{k'=1}^{k-1} \sum_{r'=0}^{r} \sum_{\alpha' \subset \alpha} M^{r'} (\alpha' \cup \{k'\}) M^{r-r'} (\alpha \setminus \alpha' \cup \{k-k'\}),$$

which is the third term in the recurrence.

2.2 Monotone Join-cut Equation

Since the numbers $M^r(\alpha)$ are rescaled versions of the monotone single Hurwitz numbers $H^r(\alpha)$, we can rewrite the recurrence relation for $M^r(\alpha)$ from Theorem 2.1 as a partial differential equation for the generating function $\vec{\mathbf{H}}$. The result is the monotone join-cut equation of Theorem 1.2, which we restate here for convenience.

Theorem 1.2 The generating function $\vec{\mathbf{H}}$ is the unique formal power series solution of the partial differential equation

$$\frac{1}{2t} \left(z \frac{\partial \vec{\mathbf{H}}}{\partial z} - z p_1 \right) = \frac{1}{2} \sum_{i,i \ge 1} \left((i+j) p_i p_j \frac{\partial \vec{\mathbf{H}}}{\partial p_{i+j}} + i j p_{i+j} \frac{\partial^2 \vec{\mathbf{H}}}{\partial p_i \partial p_j} + i j p_{i+j} \frac{\partial \vec{\mathbf{H}}}{\partial p_i} \frac{\partial \vec{\mathbf{H}}}{\partial p_j} \right)$$

with the initial condition $[z^0]\vec{\mathbf{H}} = 0$.

Proof This equation can be obtained by multiplying the recurrence relation (2.2) by the weight

$$\frac{|C_{\alpha}| z^{d+k} t^r p_{\alpha} p_k}{2 d!}$$

and summing over all choices of d, α , k, r with $d \ge 0$, $\alpha \vdash d$, $k \ge 1$, and $r \ge 0$. The resulting sum can then be rewritten in terms of the generating function $\vec{\mathbf{H}}$ via the defining equations (2.1) and (1.8), together with the fact that

$$|C_{\alpha}| = \frac{d!}{\prod_{j>1} j^{m_j(\alpha)} m_j(\alpha)!}.$$

This shows that $\vec{\mathbf{H}}$ is indeed a solution of the partial differential equation. To see that the solution is unique, note that apart from d = 0, comparing the coefficient of

 z^dt^{-1} of each side of the partial differential equation uniquely determines $[z^dt^0]\vec{\mathbf{H}}$, and comparing the coefficient of z^dt^r of each side for $r \geq 0$ uniquely determines $[z^dt^{r+1}]\vec{\mathbf{H}}$ in terms of $[z^dt^r]\vec{\mathbf{H}}$.

2.3 Topological Recursion

In this section, we define a different type of generating function for monotone Hurwitz numbers that is similar to the type of generating function for classical Hurwitz numbers that has previously arisen in the physics literature. Specifically, by analogy with the generating function $H_g(x_1, x_2, \ldots, x_\ell)$ for Hurwitz numbers considered by Bouchard and Mariño [1, (2.11) and (2.12)], consider the generating function

(2.5)
$$\mathbf{M}_{g}(x_{1}, x_{2}, \dots, x_{\ell}) = \sum_{\alpha_{1}, \alpha_{2}, \dots, \alpha_{\ell} \geq 1} \frac{\vec{H}_{g}(\alpha)}{|C_{\alpha}|} x_{1}^{\alpha_{1} - 1} x_{2}^{\alpha_{2} - 1} \cdots x_{\ell}^{\alpha_{\ell} - 1},$$

 $\delta_{\sigma,0}\delta_{\ell,1} + x_1\mathbf{M}_{\sigma-1}(x_1, x_1, x_2, \dots, x_{\ell})$

where we take $\alpha = (\alpha_1, \alpha_2, \dots, \alpha_\ell)$ to be a *composition*, that is, an ℓ -tuple of positive integers. One form of recurrence for Hurwitz numbers, expressed in terms of the series $H_g(x_1, x_2, \dots, x_\ell)$, is referred to as *topological recursion* (see, *e.g.*, [1, Conjecture 2.1], [4, Remark 4.9], and [5, Definition 4.2]).

The following result gives the corresponding recurrence for monotone Hurwitz numbers, expressed in terms of the series $\mathbf{M}_g(x_1, x_2, \dots, x_\ell)$.

Theorem 2.2 For $g \ge 0$ and $\ell \ge 1$, we have

(2.6)
$$\mathbf{M}_{g}(x_{1}, x_{2}, \dots, x_{\ell}) =$$

$$+ \sum_{j=2}^{\ell} \frac{\partial}{\partial x_{j}} \left(\frac{x_{1} \mathbf{M}_{g}(x_{1}, \dots, \widehat{x_{j}}, \dots x_{\ell}) - x_{j} \mathbf{M}_{g}(x_{2}, \dots, x_{\ell})}{x_{1} - x_{j}} \right)$$

$$+ \sum_{g'=0}^{g} \sum_{S \subset \{2, \dots, k\}} x_{1} \mathbf{M}_{g'}(x_{1}, x_{S}) \mathbf{M}_{g-g'}(x_{1}, x_{\overline{S}}),$$

where $x_1, \ldots, \widehat{x_j}, \ldots x_\ell$ is the list of all variables x_1, \ldots, x_ℓ except $x_j; x_S$ is the product of all variables x_i with $j \in S$; and $\overline{S} = \{2, \ldots, k\} \setminus S$.

Proof Like the monotone join-cut equation of Theorem 1.2, this equation can be obtained by multiplying the recurrence (2.2) by a suitable weight and summing over an appropriate set of choices. In this case, the appropriate weight is

$$x_1^{k-1}x_2^{\alpha_1-1}x_3^{\alpha_2-1}\cdots x_\ell^{\alpha_{\ell-1}-1},$$

and the sum is over all positive integer choices of k, α_1 , α_2 , . . . , $\alpha_{\ell-1}$. In view of the Riemann–Hurwitz formula (1.2), the appropriate choice of r is

$$r = k + \ell + 2g - 3 + \sum_{j=1}^{\ell-1} \alpha_j.$$

The resulting summations can then be rewritten in terms of the appropriate generating functions by using the defining equations (2.1) and (2.5).

Remark 2.1 Note that there is an asymmetry between the variable x_1 and the variables x_2, \ldots, x_ℓ in (2.6), even though $\mathbf{M}_g(x_1, x_2, \ldots, x_\ell)$ itself is symmetric in all variables.

For small values of g and ℓ , the recurrence (2.6) can be solved directly. In particular, we obtain

$$\mathbf{M}_0(x_1) = \frac{1 - \sqrt{1 - 4x_1}}{2x_1},$$

$$\mathbf{M}_0(x_1, x_2) = \frac{4}{\sqrt{1 - 4x_1}\sqrt{1 - 4x_2}(\sqrt{1 - 4x_1} + \sqrt{1 - 4x_2})^2}.$$

If we define y_i by $y_i = 1 + x_i y_i^2$ for $i \ge 1$, then these can be rewritten as

$$\mathbf{M}_0(x_1) = y_1,$$

$$\mathbf{M}_0(x_1, x_2) = \frac{x_1 \frac{\partial y_1}{\partial x_1} x_2 \frac{\partial y_2}{\partial x_2} (x_2 y_2 - x_1 y_1)^2}{(y_1 - 1)(y_2 - 1)(x_2 - x_1)^2}.$$

In the terminology of Eynard and Orantin [5], this seems to mean that we have the spectral curve $y = 1+xy^2$, but it is unclear to us what the correct notion of Bergmann kernel should be in our case.

3 Intermediate Forms

In this section, we introduce some algebraic methodology that will allow us to solve the monotone join-cut equation. This methodology consists of a set of generating functions for monotone Hurwitz numbers of fixed genus together with families of operators. These allow us to transform the monotone join-cut equation into an algebraic operator equation for these genus-specific generating functions.

3.1 Algebraic Methodology

As the first part of our algebraic methodology, we define three families of operators that use a new countable set of indeterminates $\mathbf{x} = (x_1, x_2, \dots)$, algebraically independent of $\mathbf{p} = (p_1, p_2, \dots)$. We begin with lifting operators.

Definition 3.1 Let $\mathbf{x} = (x_1, x_2, \dots)$ and $\mathbf{p} = (p_1, p_2, \dots)$ be countable sets of indeterminates. The *i*-th *lifting operator* Δ_i is the $\mathbb{Q}[[\mathbf{x}]]$ -linear differential operator on the ring $\mathbb{Q}[[\mathbf{x}, \mathbf{p}]]$ defined by

$$\Delta_i = \sum_{k>1} k x_i^k \frac{\partial}{\partial p_k}, \qquad i \ge 1.$$

The combinatorial effect of Δ_i , when applied to a generating function, is to pick a cycle marked by p_k in all possible ways and mark it by kx_i^k instead, that is, by x_i^k once for each element of the cycle. Note that $\Delta_i x_j = 0$ for all j, so that

$$\Delta_i^2 = \sum_{j,k \ge 1} jk \, x_i^{j+k} \frac{\partial^2}{\partial p_j \partial p_k}.$$

Accompanying these lifting operators, we also have projection operators.

Definition 3.2 Let $\mathbf{x} = (x_1, x_2, \dots)$ and $\mathbf{p} = (p_1, p_2, \dots)$ be countable sets of indeterminates. The *i*-th *projection operator* Π_i is the $\mathbb{Q}[[\mathbf{p}]]$ -linear idempotent operator on the ring $\mathbb{Q}[[\mathbf{x}, \mathbf{p}]]$ defined by

$$\Pi_i = [x_i^0] + \sum_{k>1} p_k[x_i^k], \qquad i \ge 1.$$

The combinatorial effect of Π_i , when applied to a generating function, is to take any cycle marked by x_i^k and mark it by p_k instead. The combined effect of a lift and a projection when applied to a generating function in $\mathbb{Q}[[\mathbf{p}]]$ is given by

$$\Pi_i \Delta_i = \sum_{k \geq 1} k p_k \frac{\partial}{\partial p_k}.$$

Finally, we introduce splitting operators.

Definition 3.3 Let $F(x_i)$ be an element of $\mathbb{Q}[[\mathbf{x}, \mathbf{p}]]$, considered as a power series in x_i , and let $j \ge 1$ be an index other than $i \ge 1$. Then the i-to-j splitting operator is defined by

Split
$$F(x_i) = \frac{x_j F(x_i) - x_i F(x_j)}{x_i - x_j} + F(0),$$

so that

Split
$$x_i^k = x_i^{k-1} x_j + x_i^{k-2} x_j^2 + \dots + x_i x_j^{k-1}, \qquad k \ge 2.$$

Combinatorially, the effect of $\operatorname{Split}_{i \to j}$ on a generating function is to take the cycle marked by x_i and split it in two cycles, marked by x_i and x_j respectively, in all possible ways. The combined effect of a lift, a split and a projection on a generating function in $\mathbb{Q}[[\mathbf{p}]]$ is

$$\Pi_1\Pi_2 \operatorname{Split}_{1\to 2} \Delta_1 = \sum_{i,j\geq 1} (i+j) p_i p_j \frac{\partial}{\partial p_{i+j}}.$$

As the second part of our algebraic methodology, we define the generating functions

(3.1)
$$\vec{\mathbf{H}}_{g} = \sum_{d \geq 1} \sum_{\alpha \vdash d} \frac{\vec{H}_{g}(\alpha) p_{\alpha}}{d!}, \qquad g \geq 0.$$

Thus, $\vec{\mathbf{H}}_g$ is the generating function for genus g monotone single Hurwitz numbers where, combinatorially, p_1, p_2, \ldots are ordinary markers for the parts of α and there is an implicit exponential marker for the size d of the ground set.

3.2 Recasting the Monotone Join-cut Equation

We are now able to recast the monotone join-cut equation as an algebraic operator equation involving our genus-specific generating series $\vec{\mathbf{H}}_g$ and the three operators that we have introduced above.

Theorem 3.4

(i) The generating function $\Delta_1 \vec{\mathbf{H}}_0$ is the unique formal power series solution of the partial differential equation

(3.2)
$$\Delta_{1}\vec{\mathbf{H}}_{0} = \prod_{\substack{1 \to 2 \\ 1 \to 2}} \text{Split } \Delta_{1}\vec{\mathbf{H}}_{0} + (\Delta_{1}\vec{\mathbf{H}}_{0})^{2} + x_{1}$$

with the initial condition $[p_0x_1^0]\Delta_1\vec{\mathbf{H}}_0=0$.

(ii) For $g \geq 1$, the generating function $\Delta_1 \vec{\mathbf{H}}_g$ is uniquely determined in terms of $\Delta_1 \vec{\mathbf{H}}_0, \Delta_1 \vec{\mathbf{H}}_1, \ldots, \Delta_1 \vec{\mathbf{H}}_{g-1}$ by the equation

$$\left(1 - 2\Delta_1 \vec{\mathbf{H}}_0 - \Pi_2 \operatorname{Split}_{1 \to 2}\right) \Delta_1 \vec{\mathbf{H}}_g = \Delta_1^2 \vec{\mathbf{H}}_{g-1} + \sum_{g'=1}^{g-1} \Delta_1 \vec{\mathbf{H}}_{g'} \Delta_1 \vec{\mathbf{H}}_{g-g'}.$$

(iii) For $g \geq 0$, the generating function $\vec{\mathbf{H}}_g$ is uniquely determined by the generating function $\Delta_1 \vec{\mathbf{H}}_g$ and the fact that $[p_0] \vec{\mathbf{H}}_g = 0$.

Proof As with Theorems 1.2 and 2.2, this result is obtained by multiplying the recurrence from Theorem 2.1 by a suitable weight and summing over a set of possible choices. Consider the generating function

$$F = \sum_{g \ge 0} u^g \vec{\mathbf{H}}_g = \sum_{g \ge 0} u^g \sum_{d \ge 1} \sum_{\alpha \vdash d} \frac{\vec{H}_g(\alpha) p_\alpha}{d!},$$

where u is an ordinary for the genus g. In view of (1.2) and (2.1), we have

$$F = \sum_{g \ge 0} u^g \sum_{d \ge 1} \sum_{\alpha \vdash d} \frac{M^{d + \ell(\alpha) + 2g - 2}(\alpha) p_{\alpha}}{\prod_{j \ge 1} j^{m_j(\alpha)} m_j(\alpha)!},$$

$$\Delta_1 F = \sum_{g \ge 0} u^g \sum_{d \ge 0} \sum_{\alpha \vdash d} \sum_{k \ge 1} \frac{M^{d + k + \ell(\alpha) + 2g - 1}(\alpha \cup \{k\}) p_{\alpha} x_1^k}{\prod_{j \ge 1} j^{m_j(\alpha)} m_j(\alpha)!}.$$

Thus, by multiplying the recurrence (2.2) by the weight

$$\frac{u^g p_{\alpha} x_1^k}{\prod_{j \ge 1} j^{m_j(\alpha)} m_j(\alpha)!}$$

and summing over all choices of g, d, α, k with $g \ge 0$, $d \ge 0$, $\alpha \vdash d$, $k \ge 1$, and $r = d + k + \ell(\alpha) + 2g - 2$, we obtain the partial differential equation

(3.3)
$$\Delta_1 F - x_1 = \prod_{1 \to 2} \text{Split } \Delta_1 F + u \Delta_1^2 F + (\Delta_1 F)^2.$$

To show that $\Delta_1 F$ is the unique solution of this partial differential equation with $[u^0 p_0 x_1^0] \Delta_1 F = 0$, note that (3.3) exactly captures the recurrence of Theorem 2.1, so each non-constant coefficient of $\Delta_1 F$ is uniquely determined.

Extracting the coefficient of u^g from (3.3) and rearranging terms gives the monotone join-cut equations of the theorem statement for g = 0 and $g \ge 1$.

Finally, note that given $\Delta_1 \vec{\mathbf{H}}_g$, we can compute

$$\Pi_1 \Delta_1 \vec{\mathbf{H}}_g = \sum_{d > 1} \sum_{\alpha \vdash d} \frac{\vec{H}_g(\alpha) p_\alpha}{(d-1)!},$$

which uniquely determines every coefficient of $\vec{\mathbf{H}}_g$ except for the constant term.

Remark 3.1 This form of the monotone join-cut equation is technically slightly stronger than the one given in Theorem 1.2, since it is obtained from the recurrence relation in Theorem 2.1 by using a less symmetric weight.

Remark 3.2 The monotone join-cut equation for higher genera will be the subject of a further paper [8], and we will not discuss it any more here.

4 Transformed Variables and Proof of the Main Result

In this section, we prove the main result, Theorem 1.1. Our strategy is to define the series F by

(4.1)
$$\mathbf{F} = \sum_{d \geq 1} \sum_{\alpha \vdash d} \frac{p_{\alpha}}{|\operatorname{Aut} \alpha|} (2d+1)^{\overline{\ell(\alpha)}-3} \prod_{j=1}^{\ell(\alpha)} \binom{2\alpha_j}{\alpha_j},$$

and then to show that the series $\Delta_1 \mathbf{F}$ satisfies the genus zero monotone join-cut equation (3.2).

Remark 4.1 We initially conjectured this formula for genus zero monotone Hurwitz numbers after generating extensive numerical data, using the group algebra approach described in Section 1.5, together with the character theory and generating series capabilities of Sage [25]. In particular, the case where α has $\ell(\alpha)=3$ parts was very suggestive, since the formula then breaks down into a product of three terms. This was also our first indication of the striking similarities between monotone Hurwitz numbers and classical Hurwitz numbers.

4.1 Transformed Variables and Lagrange Inversion

In working with the series **F**, it is convenient to make a change of variables from $\mathbf{p} = (p_1, p_2, \dots)$ to $\mathbf{q} = (q_1, q_2, \dots)$, where

(4.2)
$$q_{j} = p_{j} \left(1 - \sum_{k > 1} {2k \choose k} q_{k} \right)^{-2j}, \qquad j \geq 1.$$

This change of variables is invertible and can be carried out using the Lagrange Implicit Function Theorem in many variables (see [12]). The first result expressing \mathbf{F} in terms of the new indeterminates \mathbf{q} involves the differential operator

$$\mathcal{D} = \sum_{k>1} k p_k \frac{\partial}{\partial p_k}.$$

Theorem 4.1 Let $\gamma = \sum_{k \geq 1} {2k \choose k} q_k$ and $\eta = \sum_{k \geq 1} (2k+1) {2k \choose k} q_k$. Then

$$(2D-2)(2D-1)(2D)\mathbf{F} = \frac{(1-\gamma)^3}{1-\eta} - 1.$$

Proof From (4.1), for any $\alpha \vdash d$ with $d \ge 1$, we have

$$[p_{\alpha}](2\mathcal{D} - 2)(2\mathcal{D} - 1)(2\mathcal{D})\mathbf{F} = \frac{1}{|\operatorname{Aut}\alpha|}(2d - 2)^{\overline{\ell(\alpha)}} \prod_{j=1}^{\ell(\alpha)} {2\alpha_j \choose \alpha_j}$$
$$= \frac{(-1)^{\ell}\ell(\alpha)!}{|\operatorname{Aut}\alpha|} {2-2d \choose \ell(\alpha)} \prod_{j=1}^{\ell(\alpha)} {2\alpha_j \choose \alpha_j},$$

and we conclude that

(4.3)
$$[p_{\alpha}](2\mathcal{D} - 2)(2\mathcal{D} - 1)(2\mathcal{D})\mathbf{F} = [q_{\alpha}](1 - \gamma)^{2-2d}.$$

Now let $\phi_j = (1 - \gamma)^{-2j}$, so that (4.2) becomes $q_j = p_j \phi_j$, $j \ge 1$. Then, from the multivariate Lagrange Implicit Function Theorem [12, Theorem 1.2.9], for any formal power series $\Phi \in \mathbb{Q}[[\mathbf{q}]]$, we obtain

$$[p_{\alpha}]\Phi = [q_{\alpha}]\Phi \,\phi_{\alpha} \det \left(\delta_{ij} - q_{j}\frac{\partial}{\partial q_{j}}\log \phi_{i}\right)_{i,j\geq 1}$$
$$= [q_{\alpha}]\Phi \,\phi_{\alpha} \det \left(\delta_{ij} - \frac{2iq_{j}}{1-\gamma} \binom{2j}{j}\right)_{i,j\geq 1},$$

where $\phi_{\alpha} = \prod_{j \geq 1} \phi_{\alpha_j}$. Then we have $\phi_{\alpha} = (1 - \gamma)^{-2d}$, and using the fact that $\det(I + M) = 1 + \operatorname{tr}(M)$ for any matrix M of rank zero or one, we can evaluate the determinant as

$$\det\left(\delta_{ij} - q_j \frac{\partial}{\partial q_j} \log \phi_i\right)_{i,j \ge 1} = 1 - \sum_{k > 1} \frac{2kq_k}{1 - \gamma} \binom{2k}{k} = \frac{1 - \eta}{1 - \gamma}.$$

Substituting, we obtain

$$[p_{\alpha}]\Phi = [q_{\alpha}] \frac{(1-\eta)\Phi}{(1-\gamma)^{2d+1}}.$$

Comparing this result with (4.3), obtaining

$$[p_{\alpha}](2\mathcal{D}-2)(2\mathcal{D}-1)(2\mathcal{D})\mathbf{F} = [p_{\alpha}]\frac{(1-\gamma)^3}{1-\eta}$$

for $\alpha \vdash d$ and $d \ge 1$, and computing the constant term separately, the result follows immediately.

4.2 Inverting Differential Operators in the Transformed Variables

In order to use Theorem 4.1 to evaluate $\Delta_1 \mathbf{F}$, we need to invert the differential operators $2\mathcal{D} - 2$, $2\mathcal{D} - 1$, and $2\mathcal{D}$. We will work with the transformed variables \mathbf{q} and thus introduce the additional differential operators

$$D_k = p_k \frac{\partial}{\partial p_k}, \qquad E_k = q_k \frac{\partial}{\partial q_k}, \qquad \mathcal{E} = \sum_{k>1} k q_k \frac{\partial}{\partial q_k}.$$

As \mathbb{Q} -linear operators, the operators D_1, D_2, \ldots , and \mathcal{D} have an eigenbasis given by the set $\{p_\alpha \colon \alpha \vdash d, d \geq 0\}$, and consequently they commute with each other. Similarly, the operators E_1, E_2, \ldots , and \mathcal{E} have the set $\{q_\alpha \colon \alpha \vdash d, d \geq 0\}$ as an eigenbasis and commute with each other. However, these two families of operators do not commute with each other. By using the relation (4.2) to compute the action of E_k on p_i , we can verify the operator identity

$$E_k = D_k - \frac{2q_k}{1-\gamma} {2k \choose k} \mathcal{D}, \qquad k \ge 1.$$

It follows that $\mathcal{E} = \frac{1-\eta}{1-\gamma} \mathcal{D}$, and we can deduce the identity

(4.4)
$$D_k = E_k + \frac{2q_k}{1-\eta} {2k \choose k} \mathcal{E}, \qquad k \ge 1.$$

Thus, we can express these differential operators for \mathbf{p} and \mathbf{q} in terms of each other. In the following result, we apply these expressions to invert the differential operators that appear in Theorem 4.1.

Theorem 4.2 For $k \ge 1$, we have

$$D_k \mathbf{F} = \frac{1}{2k(2k-1)} {2k \choose k} q_k - \sum_{j \ge 1} \frac{2j+1}{2(j+k)(2k-1)} {2j \choose j} {2k \choose k} q_j q_k.$$

Proof As notation local to this proof, let

$$\mathbf{F}^{\prime\prime\prime} = (2\mathcal{D} - 2)(2\mathcal{D} - 1)(2\mathcal{D})\mathbf{F}, \quad \mathbf{F}^{\prime\prime} = (2\mathcal{D} - 1)(2\mathcal{D})\mathbf{F}, \quad \mathbf{F}^{\prime} = (2\mathcal{D})\mathbf{F}.$$

To prove the result, we use the operator identity

(4.5)
$$(1 - \gamma)^{i} (2\mathcal{E} - i) ((1 - \gamma)^{-i} G) = \frac{1 - \eta}{1 - \gamma} (2\mathcal{D} - i) (G),$$

which holds for any integer i and any formal power series G. This allows us to express the differential operators $2\mathcal{D}-2$, $2\mathcal{D}-1$, and $2\mathcal{D}$ in terms of the operators $2\mathcal{E}-2$, $2\mathcal{E}-1$, and $2\mathcal{E}$, which we can invert by recalling that they have $\{q_{\alpha}\colon \alpha\vdash d,\ d\geq 0\}$ as an eigenbasis.

We proceed in a number of stages. First we invert 2D - 2 by applying (4.5) with i = 2 to Theorem 4.1, obtaining

$$\mathbf{F}'' = (2\mathcal{D} - 2)^{-1}(\mathbf{F}''') = \frac{1}{2} + (2\mathcal{D} - 2)^{-1} \left(\frac{(1 - \gamma)^3}{1 - \eta}\right)$$
$$= \frac{1}{2} + (1 - \gamma)^2 (2\mathcal{E} - 2)^{-1}(1) = \frac{1}{2} - \frac{1}{2}(1 - \gamma)^2,$$

after checking separately that $[p_1]\mathbf{F}'' = 2$. (We need to check this since the kernel of $2\mathcal{D} - 2$ is spanned by p_1 .)

Next we apply D_k to F'' via (4.4). This is straightforward, and gives

$$D_k \mathbf{F}^{\prime\prime} = \frac{(1-\gamma)^2}{1-\eta} \binom{2k}{k} q_k.$$

Now we invert 2D - 1 by applying (4.5) with i = 1, which gives

$$D_k \mathbf{F}' = (2\mathcal{D} - 1)^{-1} (D_k \mathbf{F}'') = (1 - \gamma)(2\mathcal{E} - 1)^{-1} \left(\binom{2k}{k} q_k \right)$$
$$= (1 - \gamma) \frac{1}{2k - 1} \binom{2k}{k} q_k.$$

Finally, we invert $2\mathcal{D}$ by applying (4.5) with i = 0, giving

$$D_{k}\mathbf{F} = (2\mathcal{D})^{-1}(D_{k}\mathbf{F}') = (2\mathcal{E})^{-1}\left((1-\eta)\frac{1}{2k-1}\binom{2k}{k}q_{k}\right)$$

$$= (2\mathcal{E})^{-1}\left(\frac{1}{2k-1}\binom{2k}{k}q_{k} - \sum_{j\geq 1}\frac{2j+1}{2k-1}\binom{2j}{j}\binom{2k}{k}q_{j}q_{k}\right)$$

$$= \frac{1}{2k(2k-1)}\binom{2k}{k}q_{k} - \sum_{j\geq 1}\frac{2j+1}{2(j+k)(2k-1)}\binom{2j}{j}\binom{2k}{k}q_{j}q_{k}.$$

Again, the constant term needs to be checked separately, since the kernel of (2D) consists of the constants, but clearly D_kF has no constant term.

4.3 The Generating Function for Genus Zero

In order to work consistently in the tranformed variables \mathbf{q} , it will be useful to have descriptions of the projection and splitting operators in terms of \mathbf{q} . When considering these operators, the change of variables from \mathbf{p} to \mathbf{q} also corresponds to a change of variables from \mathbf{x} to a new countable set of indeterminates $\mathbf{y} = (y_1, y_2, \dots)$, where we impose the relations

$$(4.6) y_i = x_i (1 - \gamma)^{-2}.$$

We can express the indeterminates **p** and **q** in terms of each other using (4.2), so we can identify the rings $\mathbb{Q}[[\mathbf{p}]]$ and $\mathbb{Q}[[\mathbf{q}]]$. Since $(1 - \gamma)^{-2}$ is an invertible element in

this ring, we can further identify the rings $\mathbb{Q}[[p,x]]$ and $\mathbb{Q}[[q,y]]$ using (4.6). In this bigger ring, we have the operator identities

$$\Pi_{i} = [x_{i}^{0}] + \sum_{k \ge 1} p_{k}[x_{i}^{k}] = [y_{i}^{0}] + \sum_{k \ge 1} q_{k}[y_{i}^{k}],$$

$$\operatorname{Split}_{i \to j} G(x_{i}) = \frac{x_{j}G(x_{i}) - x_{i}G(x_{j})}{x_{i} - x_{j}} + G(0) = \frac{y_{j}G(x_{i}) - y_{i}G(x_{j})}{y_{i} - y_{j}} + G(0),$$

so the projection and splitting operators are just as easy to use with either set of indeterminates.

Remark 4.2 For completeness, note that the lifting operators can also be described in terms of \mathbf{q} and \mathbf{y} , although the expressions are somewhat more complicated. That is, using (4.4), we obtain the expression

$$\Delta_i = \sum_{k \ge 1} k x_i^k \frac{\partial}{\partial p_k} = \sum_{k \ge 1} \left(k y_i^k \frac{\partial}{\partial q_k} \right) + \frac{4 y_i (1 - 4 y_i)^{-\frac{3}{2}}}{(1 - \eta)} \sum_{k \ge 1} \left(k q_k \frac{\partial}{\partial q_k} + y_k \frac{\partial}{\partial y_k} \right).$$

We are now able to evaluate $\Delta_1 \mathbf{F}$ in the indeterminates \mathbf{q} and \mathbf{y} .

Corollary 4.3 We have

$$\Delta_1 \mathbf{F} = \Pi_2 \left(1 - \sqrt{1 - 4y_1} - \frac{y_1}{2(y_1 - y_2)} \left(1 - \sqrt{\frac{1 - 4y_1}{1 - 4y_2}} \right) \right).$$

Proof From Theorem 4.2, we have

$$\Delta_{1}\mathbf{F} = \sum_{k \geq 1} \frac{ky_{1}^{k}}{q_{k}} D_{k}\mathbf{F}$$

$$= \sum_{k \geq 1} \frac{1}{2(2k-1)} {2k \choose k} y_{1}^{k} - \sum_{j,k \geq 1} \frac{(2j+1)k}{2(j+k)(2k-1)} {2j \choose j} {2k \choose k} y_{1}^{k} q_{j}$$

$$= \Pi_{2} \Big(2G(y_{1},0) - G(y_{1},y_{2}) \Big),$$

where the power series $G(y_1, y_2)$ is defined by

$$G(y_1, y_2) = \sum_{j \ge 0} \sum_{k > 1} \frac{(2j+1)k}{2(j+k)(2k-1)} {2j \choose j} {2k \choose k} y_1^k y_2^j.$$

Then the computation

$$G(y_1, y_2) = \int_0^1 y_1 t (1 - 4y_1 t)^{-\frac{1}{2}} (1 - 4y_2 t)^{-\frac{3}{2}} \frac{dt}{t}$$

$$= \left[\frac{-y_1}{2(y_1 - y_2)} (1 - 4y_1 t)^{\frac{1}{2}} (1 - 4y_2 t)^{-\frac{1}{2}} \right]_{t=0}^1$$

$$= \frac{y_1}{2(y_1 - y_2)} \left(1 - \sqrt{\frac{1 - 4y_1}{1 - 4y_2}} \right)$$

completes the proof.

In the following result, using the above explicit expression for Δ_1 **F**, we uniquely identify **F** as the generating function for monotone single Hurwitz numbers in genus zero.

Theorem 4.4 The series **F** satisfies the genus zero monotone join-cut equation

$$\Delta_1 \mathbf{F} = \prod_{\substack{1 \to 2}} \operatorname{Split}_{1 \to 2} \Delta_1 \mathbf{F} + (\Delta_1 \mathbf{F})^2 + x_1.$$

Thus, $\mathbf{F} = \vec{\mathbf{H}}_0$ is the generating function for monotone single Hurwitz numbers in genus zero.

Proof Corollary 4.3 gives $\Delta_1 \mathbf{F} = \Pi_2 A(y_1, y_2)$, where

$$A(y_1, y_2) = 1 - \sqrt{1 - 4y_1} - \frac{y_1}{2(y_1 - y_2)} \left(1 - \sqrt{\frac{1 - 4y_1}{1 - 4y_2}}\right).$$

We need to check that the expression

$$\Delta_1 \mathbf{F} - \Pi_2 \operatorname{Split}_{1 \to 2} \Delta_1 \mathbf{F} - (\Delta_1 \mathbf{F})^2 - x_1$$

is zero. To do so, we rewrite each of the terms in this expression as

$$\Delta_{1}\mathbf{F} = \Pi_{2}\Pi_{3}(A(y_{1}, y_{2})),$$

$$\Pi_{2} \operatorname{Split}_{1 \to 2} \Delta_{1}\mathbf{F} = \Pi_{2}\Pi_{3}\left(\frac{y_{2}A(y_{1}, y_{3}) - y_{1}A(y_{2}, y_{3})}{y_{1} - y_{2}}\right),$$

$$(\Delta_{1}\mathbf{F})^{2} = \Pi_{2}\Pi_{3}\left(A(y_{1}, y_{2})A(y_{1}, y_{3})\right),$$

$$x_{1} = y_{1}(1 - \gamma)^{2} = \Pi_{2}\Pi_{3}\left(y_{1}\left(2 - \frac{1}{\sqrt{1 - 4y_{2}}}\right)\left(2 - \frac{1}{\sqrt{1 - 4y_{3}}}\right)\right)$$

to get an expression of the form $\Pi_2\Pi_3 B(y_1, y_2, y_3)$. The series $B(y_1, y_2, y_3)$ itself is not zero, but a straightforward computation shows that the series

$$\frac{1}{2}B(y_1, y_2, y_3) + \frac{1}{2}B(y_1, y_3, y_2),$$

obtained by symmetrizing with respect to y_2 and y_3 , is zero. Thus we have

$$\Pi_2\Pi_3 B(y_1, y_2, y_3) = \Pi_2\Pi_3 \left(\frac{1}{2}B(y_1, y_2, y_3) + \frac{1}{2}B(y_1, y_3, y_2)\right) = 0,$$

which completes the verification. The fact that $\mathbf{F} = \vec{\mathbf{H}}_0$ follows immediately from Theorem 3.4.

Finally, we are now able to deduce our main result.

Proof of Theorem 1.1 In view of (3.1) with g = 0, applying Theorem 4.4 gives

$$\vec{H}_0(\alpha) = d![p_\alpha]\mathbf{F}$$

for any partition α of $d \ge 1$. The result follows immediately from (4.1).

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