





RESEARCH ARTICLE

Volume and Euler classes in bounded cohomology of transformation groups

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Abstract

Let M be an oriented smooth manifold and $\text{Homeo}(M, \omega)$ the group of measure preserving homeomorphisms of M , where ω is a finite measure induced by a volume form. In this paper, we define volume and Euler classes in bounded cohomology of an infinite dimensional transformation group $\text{Homeo}_0(M, \omega)$ and $\text{Homeo}_+(M, \omega)$, respectively, and in several cases prove their non-triviality. More precisely, we define:

- Volume classes in $H_b^n(\text{Homeo}_0(M, \omega))$, where M is a hyperbolic manifold of dimension n .
- Euler classes in $H_b^2(\text{Homeo}_+(S, \omega))$, where S is an oriented closed hyperbolic surface.

We show that Euler classes have positive norms for any closed hyperbolic surface and volume classes have positive norms for all hyperbolic surfaces and certain hyperbolic 3-manifolds; hence, they are non-trivial.

1. Introduction

Let M be an oriented connected smooth manifold. Suppose ω is a finite measure induced by a volume form on M . In [5], we defined a homomorphism

$$\Gamma_b : H_b^*(\pi_1(M)) \rightarrow H_b^*(\text{Homeo}_0(M, \omega)),$$

where $H_b^*(\text{Homeo}_0(M, \omega))$ is the bounded cohomology of a discrete group. The map Γ_b is a generalization of a map defined by Gambaudo and Ghys in the quasimorphism setting [10, Section 5].

Γ_b was used in [5] to show that the 3rd bounded cohomology of $\text{Homeo}_0(M, \omega)$ is infinite dimensional for many manifolds M . In [19], more results concerning bounded cohomology, as well as standard cohomology, of $\text{Homeo}_0(M, \omega)$ were obtained. Variations of Γ_b were used in [15] to prove similar results concerning $\text{Diff}_0(S, \text{area})$, where S is a disc, sphere, or torus.

In this paper, we continue this line of research and focus on two important families of cohomology classes described below. Moreover, we construct an extension of Γ_b to a map

$$\Gamma_b^{\mathcal{M}} : H_b^*(\mathcal{M}(M, *)) \rightarrow H_b^*(\text{Homeo}(M, \omega)),$$

where $\mathcal{M}(M, *)$ is the mapping class group of once punctured M (see Section 3.3). This extension is used to define the Euler class on $\text{Homeo}_+(S, \omega)$ for an oriented closed hyperbolic surface S , and we hope that it might be useful to study the cohomology of $\text{Homeo}(M, \omega)$ for other manifolds M .

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The bounded volume class. Let M be an oriented hyperbolic manifold, and let ω_h be the volume form induced by the hyperbolic metric. In this setting, ω_h defines a class $Vol_M \in H_b^n(\pi_1(M)) \simeq H_b^n(M)$ (see Section 2.2). If M is closed, Vol_M is a natural bounded representative of $[\omega_h] \in H_{dR}^n(M)$.

Our main result positively answers the question in Section 5 of [5] for degree 2 and partially for degree 3. Moreover, it may be seen as a successful attempt to define a volume class in the bounded cohomology of an infinite dimensional transformation group.

Theorem 1.1. *Let M be an oriented manifold of dimension n such that it is either:*

- *A hyperbolic surface with a non-abelian fundamental group or*
- *A complete 3-dimensional hyperbolic manifold that fibers over the circle with a non-compact fiber.*

Suppose a measure ω is induced by a volume form on M and ω is finite. Then the class $\Gamma_b(Vol_M) \in H_b^n(\text{Homeo}_0(M, \omega))$ has positive norm and hence is non-trivial.

The class $Vol_M \in H_b^n(M)$ was considered by Gromov and Thurston in the proof of the proportionality principle [11, 21]. Moreover, it serves as a rich source for classes in 3rd bounded cohomology of free and surface groups [20].

It is worth mentioning that it is not known if the bounded cohomology in degree n of a non-abelian free group for $n > 3$ is non-trivial; hence, our proof works in dimension 2 and sometimes in dimension 3 so far. The problem of non-triviality of $\Gamma_b(Vol_M)$ for higher dimensional hyperbolic manifolds or closed hyperbolic 3-manifolds is still open.

The bounded Euler class. Let S be a closed oriented surface and ω a measure defined by an area form on S . Denote by $\text{Homeo}_+(S, \omega)$ the subgroup of $\text{Homeo}(S, \omega)$ of orientation preserving homeomorphisms.

Let $* \in S$ be a point in S and $\mathcal{M}_+(S, *)$ be the orientation preserving mapping class group of $S \setminus \{*\}$. Recall that $\pi_1(S, *) < \mathcal{M}_+(S, *)$ due to the Birman exact sequence. As we will see in Section 3.3, the map Γ_b can be extended to a map $\Gamma_b^{\mathcal{M}_+}$ such that the following diagram commutes:

$$\begin{CD}
 H_b^\bullet(\mathcal{M}_+(S, *)) @>\Gamma_b^{\mathcal{M}_+}>> H_b^\bullet(\text{Homeo}_+(S, \omega)) \\
 @VVV @VVV \\
 H_b^\bullet(\pi_1(S, *)) @>\Gamma_b>> H_b^\bullet(\text{Homeo}_0(S, \omega))
 \end{CD}$$

The vertical arrows are induced by inclusions. Thus, at the cost of passing to a bigger group $\mathcal{M}_+(S, *)$, we can generate classes in the group of ω -preserving homeomorphisms of S not necessarily isotopic to the identity.

Let $\text{Homeo}_+(S^1)$ be the group of orientation preserving homeomorphisms of the circle, and let $e_b \in H_b^2(\text{Homeo}_+(S^1))$ be the bounded Euler class. There is a natural map $\alpha : \mathcal{M}_+(S, *) \rightarrow \text{Homeo}_+(S^1)$ defined by the action of $\mathcal{M}_+(S, *) \simeq \text{Aut}_+(\pi_1(S))$ on the Gromov boundary of $\pi_1(S)$. Let $e_b^{\mathcal{M}_+}$ and e_b^S be the pullbacks of e_b to $\mathcal{M}_+(S, *)$ and $\pi_1(S)$.

Theorem 1.2. *Let S be a closed oriented surface of genus ≥ 2 , and ω a measure induced by an area form on S . Then the classes $\Gamma_b(e_b^S) \in H_b^2(\text{Homeo}_0(S, \omega))$ and $\Gamma_b^{\mathcal{M}_+}(e_b^{\mathcal{M}_+}) \in H_b^2(\text{Homeo}_+(S, \omega))$ have positive norms and hence are non-trivial.*

We emphasize that in Theorems 1.1 and 1.2 one can take instead of $\text{Homeo}_0(M, \omega)$ smaller groups like $\text{Diff}_0(M, \omega)$, or $\text{Symp}_0(S, \omega)$ or $\text{Ham}(S)$ whenever S is a hyperbolic surface, and the same results hold.

On the proof and organization of the paper. The method of the proof is a refinement (and at the same time a simplification) of the one from [5]. In the case of bounded volume classes, it is based on mapping a non-abelian free group F to $\pi_1(M)$ and to $\text{Homeo}_0(M, \omega)$, restricting Vol_M and $\Gamma_b(\text{Vol}_M)$ to F and then comparing these two classes. An identical method is used for Euler classes. This technique is quite special since we do not know many subgroups of $\text{Homeo}_0(M, \omega)$. See [18, Chapter 4] for a survey on realizations of groups by diffeomorphisms and homeomorphisms.

The outline of the paper is as follows. In Section 2.1, we give basic definitions of bounded cohomology. In Section 2.2, we define two versions of the volume class: the topological $\text{Vol}_M \in H_b^n(M)$ and its group version $\text{Vol}_M^{\text{gp}} \in H_b^n(\pi_1(M))$. The topological version is well known, and we use it in the proofs. We need the group version because Γ_b takes classes from the group cohomology. As expected, Vol_M and Vol_M^{gp} define the same class under the canonical identification $H_b^n(M) \simeq H_b^n(\pi_1(M))$. We could not find a proof of this fact in the literature; thus, for completeness, we provide a detailed argument in Lemma 2.2. In Section 2.3, we define the Euler class in the mapping class group of a punctured surface. In Section 3, we define the maps Γ_b and Γ_b^M . In Section 4, we show that for hyperbolic surfaces and certain 3-dimensional hyperbolic manifolds, the class Vol_M restricts non-trivially to a free subgroup of $\pi_1(M)$. The same result holds for Euler classes and closed surfaces of genus ≥ 2 . In Section 5, we give a simpler and at the same time more general version of a technical Lemma 3.1 from [5] and prove the main theorems. In Section 6, we discuss the case when ω is the Dirac measure.

2. Preliminaries

2.1. Bounded cohomology

Let us give the definitions of bounded cohomology of a group and a space.

Let G be a group. The space of bounded n -cochains is defined by

$$C_b^n(G) = \{c : G^{n+1} \rightarrow \mathbb{R} \mid c \text{ is bounded}\}.$$

Let d_n be the ordinary coboundary operator $d_n : C_b^n(G) \rightarrow C_b^{n+1}(G)$. The group G acts on $C_b^n(G)$ by

$$h(c)(g_0, \dots, g_n) = c(h^{-1}g_0, \dots, h^{-1}g_n) \quad \forall c \in C_b^n(G), \quad \forall h, g_0, \dots, g_n \in G.$$

Let $C_b^n(G)^G$ be the space of G -invariant cochains. The bounded cohomology of G , denoted by $H_b^n(G)$, is the homology of the cochain complex $\{C_b^n(G)^G, d_n\}$. Note that $C_b^n(G)^G$ is a subcomplex of the space of all G -invariant cochains; hence, we have a map $H_b^n(G) \rightarrow H^n(G, \mathbb{R})$ called the comparison map.

On $C_b^n(G)$, we have the supremum norm denoted by $\| \cdot \|$. This norm induces a semi-norm on $H_b^n(G)$; that is, if $C \in H_b^n(G)$, then

$$\|C\| = \min\{\|c\| \mid [c] = C\}.$$

Let M be a topological space. A singular simplex is a continuous map from the standard simplex to M . By $C_n(M)$, we denote the space of singular chains and by $S_n(M) \subset C_n(M)$ the set of all singular simplices in M . Let $C_b^n(M)$ be the set of linear functions from $C_n(M)$ to the reals that are bounded on $S_n(M)$. Since $S_n(M)$ generates $C_n(M)$, one can think of an element in $C_b^n(M)$ as a bounded function $c : S_n(M) \rightarrow \mathbb{R}$.

The bounded cohomology of M , denoted by $H_b^n(M)$, is the homology of the cochain complex $\{C_b^n(M), d_n\}$, where $d_n : C_b^n(M) \rightarrow C_b^{n+1}(M)$ is the standard coboundary operator. Like in the group case, we have the semi-norm and the comparison map. Sometimes it is convenient to work in the universal cover of M . Let us recall that on $C_b^n(\tilde{M})$, we have an action of $G = \pi_1(M)$ and $C_b^n(M)$ is naturally isomorphic to $C_b^n(\tilde{M})^G$.

We point out that bounded cohomology cannot be defined in terms of simplicial cochains (given some triangulation of M). For example, if the triangulation is finite, then every simplicial cochain is bounded, and we get the standard cohomology.

In this paper, the manifold M is aspherical. In this case, $H_b^n(\pi_1(M))$ is canonically isometric to $H_b^n(M)$. See [9, Chapter 5] for a relatively elementary proof of this fact. It is based on an appropriate notion of resolution for bounded cohomology. Note that by the remarkable Mapping Theorem of Gromov, the assumption on asphericity of M can be dropped, but the proof of this fact is much harder [11].

2.2. The bounded volume class

In this paper, a hyperbolic manifold is a manifold (with or without boundary) whose all sectional curvatures equal -1 . In particular, we do not assume a hyperbolic manifold to be complete. Let M be a connected, oriented, and aspherical hyperbolic n -manifold. Below, we recall the definition of Vol_M and give a detailed description of its counterpart in the group cohomology $H_b^n(\pi_1(M))$, which seems to be less known. In Lemma 2.2, we show that both versions give the same class under the canonical identification of $H_b^n(M)$ and $H_b^n(\pi_1(M))$.

We start with defining the volume class in the cohomology of a group. Let $Iso_+(\mathbb{H}^n)$ denote the group of orientation preserving isometries of the hyperbolic n -space, and let vol_h be the hyperbolic volume form on \mathbb{H}^n . Fix $* \in \mathbb{H}^n$ and for a tuple of elements $\bar{g} = (g_0, \dots, g_n)$ in $Iso_+(\mathbb{H}^n)$ consider the geodesic simplex $\Delta_{\bar{g}} \subset \mathbb{H}^n$ spanned by the points $g_0(*), \dots, g_n(*)$. This simplex can be parametrized using the barycentric coordinates [21, Chapter 6]. Therefore, we regard $\Delta_{\bar{g}}$ as a map from the standard simplex to \mathbb{H}^n . We define

$$v(\bar{g}) = \int_{\Delta_{\bar{g}}} vol_h.$$

Note that $v(\bar{g})$ is the signed volume of $\Delta_{\bar{g}}$. Moreover, v is an $Iso_+(\mathbb{H}^n)$ -invariant cocycle. Since volumes of geodesic simplices are bounded, v is bounded and we can define:

$$Vol = [v] \in H_b^n(Iso_+(\mathbb{H}^n)).$$

For $G < Iso_+(\mathbb{H}^n)$, we define v_G to be the restriction of v to G and $Vol_G = [v_G] \in H_b^n(G)$.

Recall that M is a connected, oriented, and aspherical hyperbolic n -manifold. We allow M to have cusps or a boundary that is not totally geodesic. Represent M as a quotient $M = X/\pi_1(M)$ where $X \subset \mathbb{H}^n$ is contractible and $\pi_1(M)$ acts on X by deck transformations. Note that the action of $\pi_1(M)$ on X extends uniquely to an action on \mathbb{H}^n . Denote this action by $\rho : \pi_1(M) \rightarrow Iso_+(\mathbb{H}^n)$. In what follows, we usually do not mention the representation ρ and regard $\pi_1(M)$ as a discrete subgroup of $Iso_+(\mathbb{H}^n)$. To M , we associate the class

$$Vol_{\rho(\pi_1(M))} \in H_b^n(\pi_1(M)),$$

and write $Vol_M^{SP} = Vol_{\rho(\pi_1(M))}$. The action ρ is well defined up to conjugacy; thus Vol_M^{SP} does not depend on ρ .

Let us now describe a singular cocycle that defines the class Vol_M in $H_b^n(M)$. Let σ be a singular simplex in $X \subset \mathbb{H}^n$. The straightening $str(\sigma)$ is the geodesic simplex with the same vertices as σ and parametrized using the barycentric coordinates (it is possible that $str(\sigma)$ is not contained in X). We define

$$v'_M(\sigma) = \int_{str(\sigma)} vol_h.$$

We have that v'_M is a $\pi_1(M)$ -invariant cocycle on X . It defines the bounded class $[v'_M] \in H_b^n(M)$, which we denote by Vol_M .

Hence we associate two classes to M : Vol_M in the cohomology of the space M and a class Vol_M^{SP} in the group cohomology of $\pi_1(M)$.

Remark 2.1. The definition of Vol_M can be generalized by integrating, instead of vol_h , the pullback $\tilde{\omega}$ of a closed k -form ω on M^n for $k \leq n$ (see 2, 3). For a surface and 2-forms such that $\tilde{\omega} = f vol_h$ for $f > 0$,

Theorem 1.1 holds with the same proof. As well, instead of a hyperbolic metric, one can take a pinched negatively curved metric on M , where one can straighten simplices. This should generate even more Vol_M -like classes.

Lemma 2.2. *Let M be a connected, oriented, and aspherical hyperbolic n -dimensional manifold, and let $r : H_b^n(\pi_1(M)) \rightarrow H_b^n(M)$ be the canonical isometric isomorphism. Then we have $r(Vol_M^{sp}) = Vol_M$.*

Proof. Let $M = X/\pi_1(M)$, where $X \subset \mathbb{H}^n$. First, we shall show that without loss of generality, we can assume that $X = \mathbb{H}^n$. Consider $M^{ex} = \mathbb{H}^n/\pi_1(M)$. Since $X \subset \mathbb{H}^n$, we have that M is a submanifold of M^{ex} . Moreover, M is aspherical, and by the Whitehead theorem, the inclusion $i : M \rightarrow M^{ex}$ is a homotopy equivalence. Hence

$$i^* : H_b^n(M^{ex}) \rightarrow H_b^n(M)$$

is an isometric isomorphism. Moreover, $i^*(Vol_{M^{ex}}) = Vol_M$. Thus instead of M , we can consider M^{ex} . In other words, we can assume that $X = \mathbb{H}^n$.

The explicit formula for r can be found in [9, Lemma 5.2] (note that on the standard cohomology, r is just the map induced by the classifying map). We shall give a formula for the inverse of r .

Let $G = \pi_1(M)$ and $* \in \mathbb{H}^n$ be a basepoint. Let Δ be the map which to each tuple $\bar{g} = (g_0, \dots, g_n) \in G^{n+1}$ associates $\Delta_{\bar{g}}$, the geodesic simplex spanned by the $g_i(*)$ and parametrized by barycentric coordinates.

Consider the augmented cochain complexes $\{C_b^\bullet(G), d\}$ and $\{C_b^\bullet(\mathbb{H}^n), d\}$. It means that $C_b^{-1}(G) = C_b^{-1}(\mathbb{H}) = \mathbb{R}$ and in both cases d_{-1} maps a real number to a constant function. The map Δ commutes with taking facets. That is, if $\bar{f} \subset \bar{g}$ is an n -tuple in an $(n + 1)$ -tuple \bar{g} , then $\Delta_{\bar{f}}$ is just $\Delta_{\bar{g}}$ restricted to the corresponding facet. Thus Δ induces a map of augmented cochain complexes

$$\Delta^* : \{C_b^\bullet(\mathbb{H}^n), d\} \rightarrow \{C_b^\bullet(G), d\}$$

given by $\Delta^*(c)(\bar{g}) = c(\Delta_{\bar{g}})$ and the identity on the augmentations. The map Δ^* is G -invariant, and since these resolutions are relatively injective strong resolutions [9, Lemmas 4.12 and Lemma 5.4], Δ^* induces a map

$$H_b^n(\Delta) : H_b^n(M) \rightarrow H_b^n(\pi_1(M))$$

which is the inverse of r [9, Theorem 4.15]. Since r is an isometric isomorphism, the same holds for $H_b^n(\Delta)$. Moreover, it follows directly from the definitions that $\Delta^*(v'_M) = v_G$. Thus $r(Vol_M^{sp}) = Vol_M$. \square

Let ω_h be the hyperbolic volume form on a closed hyperbolic manifold M . Let us point out that $[v'_M] \in H_b^n(M)$ goes to $[\omega_h] \in H_{dR}(M) \simeq H^n(M)$ after applying the comparison map. This can be seen by the straightening of simplices homotopy; see [21] or [9, Lemma 8.12].

2.3. Euler class in the mapping class group

Let $\text{Homeo}_+^{\mathbb{Z}}(\mathbb{R})$ be the set of orientation preserving homeomorphisms f of \mathbb{R} that are lifts of maps from $\text{Homeo}_+(S^1)$. That is, $f(x + 1) = f(x) + 1$. It fits the central extension

$$\mathbb{Z} \rightarrow \text{Homeo}_+^{\mathbb{Z}}(\mathbb{R}) \xrightarrow{p} \text{Homeo}_+(S^1).$$

The Euler class $e_b \in H_b^2(\text{Homeo}_+(S^1))$ is a particular bounded class representing the Euler class of this extension [9, Chapter 10]. Let S be a closed oriented surface of genus ≥ 2 . On S , we fix a hyperbolic metric. Let $\mathcal{M}_+(S, *)$ be the subgroup of $\mathcal{M}(S, *)$ of mapping classes represented by orientation preserving homeomorphisms. By the Dehn–Nielsen theorem $\mathcal{M}_+(S, *) \simeq \text{Aut}_+(\pi_1(S, *))$; thus $\mathcal{M}_+(S, *)$ acts on the Gromov boundary $\partial\pi_1(S, *) \simeq S^1$. Hence we have a map

$$\alpha : \mathcal{M}_+(S, *) \rightarrow \text{Homeo}_+(S^1).$$

In geometric terms, α is described as follows. Let $f \in \text{Homeo}_+(S, *)$ represent an element $\psi \in \mathcal{M}_+(S, *)$. Let $\tilde{*} \in \mathbb{H}^2$ be a fixed preimage of $*$, and let \tilde{f} be the lift of f such that $\tilde{f}(\tilde{*}) = \tilde{*}$. Now $\alpha(\psi)$ is the action of \tilde{f} on $\partial\mathbb{H}^2$ and it does not depend on the choice of f representing ψ . Note that α restricted to $\pi_1(S, *) < \mathcal{M}_+(S, *)$ is just the standard action on $\partial\mathbb{H}^2$ by deck transformations.

Let $e_b^{\mathcal{M}^+} = \alpha^*(e_b)$ and e_b^S be the restriction of $e_b^{\mathcal{M}^+}$ to $\pi_1(S, *) < \mathcal{M}_+(S, *)$. The class $e_b^{\mathcal{M}^+}$ was studied in [7, 13].

3. Definitions of Γ_b and $\Gamma_b^{\mathcal{M}}$

Suppose M is a connected smooth manifold and ω is a finite measure induced by a volume form. In this section, we define the maps Γ_b and $\Gamma_b^{\mathcal{M}}$ (the latter for compact M). We start with a geometrically motivated definition of Γ_b by a system of paths. This definition naturally leads to the definition of $\Gamma_b^{\mathcal{M}}$ by a system of homeomorphisms. To show that the definitions of Γ_b and $\Gamma_b^{\mathcal{M}}$ do not depend on the chosen systems, we use a result from [19]. To this end, we rephrase our definitions in the language of couplings. In the case of Γ_b , the obvious coupling is given by the universal cover. For the convenience of the reader, we give the details in Section 3.2. It turns out that $\Gamma_b^{\mathcal{M}}$ can be described in the language of couplings as well. However, one needs to use a bigger (and therefore disconnected) cover of M (see Section 3.4).

Fix a basepoint $* \in M$. In this section, we assume that $\pi_1(M, *)$ is center free. It holds for all manifolds we are interested in and with this assumption the construction of Γ_b and $\Gamma_b^{\mathcal{M}}$ is slightly simpler.

Let $p : \tilde{M} \rightarrow M$ be the universal cover of M . We view an element $l \in p^{-1}(x)$ as a homotopy class relative to $\{*, x\}$ of a path connecting $*$ to x . The action of $\pi_1(M, *)$ on \tilde{M} is given by concatenating a loop representing $\gamma \in \pi_1(M, *)$ and a path representing $l \in \tilde{M}$.

Recall that $\text{Homeo}(M)$ is the group of all homeomorphisms of M and $\text{Homeo}_0(M)$ are those elements of $\text{Homeo}(M)$ that are isotopic to the identity of M . Similarly, $\text{Homeo}(M, \omega)$ is the group of all homeomorphisms of M preserving ω and $\text{Homeo}_0(M, \omega)$ are those elements of $\text{Homeo}(M, \omega)$ that are isotopic to the identity of M via ω -preserving maps.

In all these transformation groups, we consider their right group action on M so that fg acts by $(fg)(x) = g(f(x))$ for all $x \in M$. We are forced to use this convention since later in Section 3.3, we relate elements of $\pi_1(M, *)$ to homeomorphisms in $\text{Homeo}(M)$ using a push map, and we want the multiplication in $\pi_1(M, *)$ to be compatible with how we compose homeomorphisms.

Recall that a left action of a group G on a set X is a homomorphism $G \rightarrow \text{Aut}(X)$ and a right action is an antihomomorphism $G \rightarrow \text{Aut}(X)$. On $\text{Aut}(X)$, we compose maps starting from the right-most. In this way, we have a left action of $\pi_1(M, *)$ on \tilde{M} and a right action of $\text{Homeo}(M)$ on M .

3.1. Description of Γ_b

In this paragraph, we give the simplest, in our opinion, description of Γ_b . A more refined and general definition can be found in [5]. Another approach based on coupling of groups is given in [19]. Note that the definition in [19] is much more general and works for measurable spaces and groups of measurable transformations.

Let s_x be a path connecting $*$ to $x \in M$. By $[s_x]$, we denote the homotopy class of s_x relative to the endpoints $\{*, x\}$, and by \bar{s}_x , we denote the reverse of s_x . A system of paths for M is a function on M of the form $S(x) = [s_x]$, where s_x is any path connecting $*$ to x .

Assume S is a system of paths. We shall define a map

$$\gamma : \text{Homeo}_0(M, \omega) \times M \rightarrow \pi_1(M, *)$$

Let $S(x)$ be represented by a path s_x . Fix $f \in \text{Homeo}_0(M, \omega)$ and f_t an isotopy connecting Id_M to f . We define $\gamma(f, x) \in \pi_1(M, *)$ to be the homotopy class of the loop based at $*$ which is the concatenation of s_x , the trajectory $f_t(x)$ and $\bar{s}_{f(x)}$. The element $\gamma(f, x)$ does not depend on the choice of paths representing $S(x)$ and $S(f(x))$. Moreover, $\gamma(f, x)$ does not depend on the isotopy f_t . Indeed, it follows from

[5, Proposition 3.1] that changing the isotopy f_i to another isotopy connecting Id_M and f would change $\gamma(f, x)$ by an element of the center of $\pi_1(M, *)$. Since we assumed that the center of $\pi_1(M, *)$ is trivial, $\gamma(f, x)$ is well defined. Note that γ depends on the choice of the system of paths S .

It is a simple calculation that γ satisfies a cocycle condition in the following form:

$$\gamma(fg, x) = \gamma(f, x)\gamma(g, f(x)).$$

Define $\tilde{\omega}$ to be the measure on \tilde{M} induced by the pullback of the volume form on M that defines ω . Since elements of \tilde{M} are homotopy classes relative to the endpoints of paths in M starting at $*$, the image $im(S)$ is a subset of \tilde{M} . We say that S is measurable if $im(S)$ is $\tilde{\omega}$ -measurable. In Section 3.2, we show that measurable systems of paths exist.

Now assume S is a measurable system of paths. For each n , we define

$$\Gamma_b : H_b^n(\pi_1(M, *)) \rightarrow H_b^n(\text{Homeo}_0(M, \omega))$$

to be the map induced by the following function defined on cochains (called again Γ_b):

$$\Gamma_b(c)(f_0, \dots, f_n) = \int_M c(\gamma(f_0, x), \dots, \gamma(f_n, x))d\omega(x).$$

In Section 3.2, we show that the function under the integral is measurable and that Γ_b does not depend on the choice of a measurable system of paths.

Remark 3.1. In [5], the group $\text{Homeo}_0(M, \omega)$ is defined like in this paper with an additional assumption that homeomorphisms have compact support. This additional assumption was needed to define an analog of Γ_b for the ordinary cohomology in [5, Section 3.4]. In this paper, we deal only with the bounded cohomology; therefore, we do not assume that elements of $\text{Homeo}_0(M, \omega)$ are compactly supported. Moreover, contrary to [5], here we do not assume that M carries a complete Riemannian metric.

Example 3.2. Now we explicitly describe a cocycle representing the element $\Gamma_b(\text{Vol}_M^{sp})$. Let $M = X/\pi_1(M)$, where $X \subset \mathbb{H}^n$, and let ω be any finite measure induced by a volume form on M . Assume that $\pi_1(M)$ has trivial center (equivalently, $\pi_1(M)$ is not abelian, e.g., M is not a quotient of \mathbb{H}^n by a \mathbb{Z} -action). Let $\tilde{*} \in X$ be a lift of the basepoint $*$ and $f_0, \dots, f_n \in \text{Homeo}_0(M, \omega)$. For every $x \in M$, we get a tuple of elements $\gamma(f_0, x), \dots, \gamma(f_n, x)$ in $\pi_1(M)$ that act on X . Consider the points $v_i(x) = \gamma(f_i, x)\tilde{*}$ and span a geodesic simplex $\Delta(x)$ in X with vertices $v_i(x)$. Now $\Gamma_b(\text{Vol}_M^{sp})$ is represented by a cocycle that assigns to (f_0, \dots, f_n) the average signed volume of $\Delta(x)$ over M with respect to ω .

3.2. Γ_b via coupling

Let us describe the construction of Γ_b via couplings given in [19]. A coupling is a measured space (X, μ) together with a μ -preserving left action of a group Γ and a commuting μ -preserving right action of a group Λ . Suppose that Γ is countable, the action of Γ is free, and $F \subset X$ is a strict measurable fundamental domain for an action of Γ . A map $\chi : X \rightarrow \Gamma$ is defined by the equation $\chi(\gamma \cdot x) = \gamma$ for $x \in F$ and $\gamma \in \Gamma$. Note that χ is measurable; that is, the preimage of every element in Γ is a measurable set. A function $\bar{\chi} : \Lambda \times F \rightarrow \Gamma$ given by $\bar{\chi}(\lambda, x) = \chi(x \cdot \lambda)$ induces a homomorphism $tr_\Gamma^\Lambda X : H_b^\bullet(\Gamma) \rightarrow H_b^\bullet(\Lambda)$ by the formula [19, Section 3]

$$tr_\Gamma^\Lambda(c)(\lambda_0, \dots, \lambda_n) = \int_F c(\bar{\chi}(\lambda_0, x), \dots, \bar{\chi}(\lambda_n, x))d\mu(x).$$

The map $\bar{\chi}$ is a composition of measurable functions; hence, the function under the integral is measurable. Moreover, $tr_\Gamma^\Lambda X$ does not depend on the choice of F [19, Lemma 3.3].

Let $f \in \text{Homeo}_0(M, \omega)$ and suppose f_i is an isotopy connecting the identity of M to f . Denote by \tilde{f} the endpoint of a lift of f_i to \tilde{M} . Note that, again by [5, Proposition 3.1], and by the assumption that $\pi_1(M, *)$ has a trivial center, \tilde{f} does not depend on the chosen isotopy f_i . Therefore, we have a right

$\tilde{\omega}$ -preserving action of $\text{Homeo}_0(M, \omega)$ on \tilde{M} , given by $x.f = \tilde{f}(x)$, $x \in \tilde{M}$. Note that $x.f$ is represented by a path connecting $*$ to x and then following the trajectory from x to $f(x)$ given by $f_i(x)$.

Now we consider the following coupling: $X = (\tilde{M}, \tilde{\omega})$ together with the left action of $\Gamma = \pi_1(M, *)$ and the right action of $\Lambda = \text{Homeo}_0(M, \omega)$. For this coupling, we have $\Gamma_b = \text{tr}_\Gamma^\Delta X$. Indeed, if S is a measurable system of paths, $\text{im}(S)$ is a strict measurable fundamental domain of the $\pi_1(M, *)$ -action, and vice versa, every measurable fundamental domain defines a measurable system of paths. Moreover, let S be a measurable system of paths and $F = \text{im}(S)$. Recall that $p : \tilde{M} \rightarrow M$ is the universal covering map. If γ and $\tilde{\chi}$ are defined by S and F , respectively, then $\gamma(f, p(x)) = \tilde{\chi}(f, x)$ for every $x \in F$ and $f \in \text{Homeo}_0(M, \omega)$. Thus Γ_b and $\text{tr}_\Gamma^\Delta X$ coincide. In particular, Γ_b does not depend on the choice of a measurable system of paths.

To finish the construction of Γ_b , we shall show that measurable fundamental domains exist. Suppose $\{U_i\}_{i \in \mathbb{N}}$ is a cover of M by simply connected open sets. Let \tilde{U}_i be a homeomorphic lift of U_i to \tilde{M} . Set $F_i = \tilde{U}_i \setminus p^{-1}(\cup_{j=1}^{i-1} U_j)$. Then $F = \cup_{j=1}^\infty F_j$ is a strict measurable fundamental domain.

3.3. Description of $\Gamma_b^{\mathcal{M}}$

We describe an extension of Γ_b to a map that ranges in the bounded cohomology of $\text{Homeo}(M, \omega)$. It is done by modifying the notion of a system of paths. In this and the next subsection, we assume that M is compact.

Fix a point $* \in M$. Let $\text{Homeo}(M, *)$ be the group of homeomorphisms of M fixing $*$ and $\text{Homeo}_0(M, *)$ the subgroup of homeomorphisms that are isotopic to the identity by $*$ -fixing homeomorphisms. It follows from [8, Corollary 1.1], which for compact M , $\text{Homeo}_0(M, *)$ is the connected component of the identity in $\text{Homeo}(M, *)$ equipped with the compact-open topology. Recall that in these groups, we compose homeomorphisms from left to right. Consider the mapping class group

$$\mathcal{M}(M, *) = \text{Homeo}(M, *) / \text{Homeo}_0(M, *).$$

Let $\text{Homeo}(M, * \rightarrow x) < \text{Homeo}(M)$ be the subset of homeomorphisms of M that send $*$ to x . Suppose $h_x \in \text{Homeo}(M, * \rightarrow x)$. Denote by $[h_x]$ the connected component of h_x in $\text{Homeo}(M, * \rightarrow x)$ with the compact-open topology. Note that two elements h_x and g_x in $\text{Homeo}(M, * \rightarrow x)$ are in the same connected component if and only if there exists an isotopy f_t connecting h_x to g_x such that $f_t(*) = x$ for all t . A system of homeomorphisms for M is a function on M of the form $P(x) = [h_x]$, where $h_x \in \text{Homeo}(M, * \rightarrow x)$. For example, it can be a point-pushing map along s_x , where $S(x) = [s_x]$ is a system of paths.

Let $P(x) = [h_x]$ be a system of homeomorphisms. For every $f \in \text{Homeo}(M, \omega)$, we have $h_x \circ f \circ h_{f(x)}^{-1} \in \text{Homeo}(M, *)$. We define a cocycle

$$\gamma^{\mathcal{M}} : \text{Homeo}(M, \omega) \times M \rightarrow \mathcal{M}(M, *)$$

by $\gamma^{\mathcal{M}}(f, x) = [h_x \circ f \circ h_{f(x)}^{-1}]$. Note that $\gamma^{\mathcal{M}}$ does not depend on the homeomorphisms h_x representing $P(x)$ but depends on the choice of P . There is a notion of a measurable system of homeomorphisms, we discuss it in Section 3.4.

Likewise in Section 3.1, any measurable system of homeomorphisms P induces a map

$$\Gamma_b^{\mathcal{M}} : H_b^n(\mathcal{M}(M, *)) \rightarrow H_b^n(\text{Homeo}(M, \omega)).$$

In Section 3.4, we show that $\Gamma_b^{\mathcal{M}}$ does not depend on the choice of P . Note that $\Gamma_b^{\mathcal{M}}$ generalizes the homomorphism $\mathcal{G}_{S,1}$ from [4] defined only for surfaces S and ranging in quasimorphisms on $\text{Homeo}(S, \omega)$.

Remark 3.3. If M is oriented, we can consider the oriented version of $\Gamma_b^{\mathcal{M}}$. Namely, let $\mathcal{M}_+(M, *)$ be the subgroup of $\mathcal{M}(M, *)$ of mapping classes represented by orientation preserving homeomorphisms, and let $\text{Homeo}_+(M, \omega)$ be homeomorphisms preserving ω and the orientation. Assuming that for every $x \in M$, $P(x)$ is represented by an orientation preserving homeomorphism, we have $\gamma^{\mathcal{M}}(f, x) \in \mathcal{M}_+(M, *)$

for $f \in \text{Homeo}_+(M, \omega)$. Thus we can define

$$\Gamma_b^{\mathcal{M}^+} : H_b^n(\mathcal{M}_+(M, *)) \rightarrow H_b^n(\text{Homeo}_+(M, \omega)).$$

This map is used in Theorem 1.2.

Let us now explain in what sense $\Gamma_b^{\mathcal{M}}$ extends Γ_b . Note that $\mathcal{M}(M, *) = \pi_0(\text{Homeo}(M, *))$ and $\mathcal{M}(M) = \pi_0(\text{Homeo}(M))$. Consider the fiber bundle

$$\text{Homeo}(M, *) \rightarrow \text{Homeo}(M) \xrightarrow{ev} M,$$

where $ev(f) = f(*)$. The long exact sequence of the homotopy groups gives

$$\pi_1(\text{Homeo}(M)) \xrightarrow{ev_1} \pi_1(M, *) \xrightarrow{Pu} \mathcal{M}(M, *) \xrightarrow{F} \mathcal{M}(M).$$

For $g \in \pi_1(M, *)$, $Pu(g)$ is the mapping class represented by the time-one map f_1 of a point-pushing isotopy $\{f_t\}_{t \in [0,1]}$ along a loop representing g . By [5, Proposition 3.1], $im(ev_1)$ lies in the center of $\pi_1(M, *)$; therefore, ev_1 is trivial and Pu is an embedding.

Let $[f] \in im(Pu) = ker(F) < \mathcal{M}(M, *)$, and let f_t be an isotopy connecting the identity to f in $\text{Homeo}_0(M)$. Let $Tr([f])$ be the element of $\pi_1(M, *)$ represented by $f_t(*)$. By the triviality of ev_1 , this map is well defined, and it is the inverse of Pu on $im(Pu)$.

Let S be any measurable system of paths and P a system of homeomorphisms such that $P(x) = [h_x]$ with h_x the point-pushing map along a path s_x such that $S(x) = [s_x]$. The cocycles γ and $\gamma^{\mathcal{M}}$ are defined with respect to these systems. For every $f \in \text{Homeo}_0(M, \omega)$, we have $\gamma(f, x) = Tr(\gamma^{\mathcal{M}}(f, x))$. Thus $Pu(\gamma(f, x)) = \gamma^{\mathcal{M}}(f, x)$, and we have a commutative diagram:

$$\begin{array}{ccc} \text{Homeo}(M, \omega) \times M & \xrightarrow{\gamma^{\mathcal{M}}} & \mathcal{M}(M, *) \\ \uparrow & & \uparrow Pu \\ \text{Homeo}_0(M, \omega) \times M & \xrightarrow{\gamma} & \pi_1(M, *) \end{array}$$

Thus the following diagram commute:

$$\begin{array}{ccc} H_b^\bullet(\mathcal{M}(M, *)) & \xrightarrow{\Gamma_b^{\mathcal{M}}} & H_b^\bullet(\text{Homeo}(M, \omega)) \\ \downarrow Pu^* & & \downarrow \\ H_b^\bullet(\pi_1(M, *)) & \xrightarrow{\Gamma_b} & H_b^\bullet(\text{Homeo}_0(M, \omega)). \end{array}$$

3.4. $\Gamma_b^{\mathcal{M}}$ via couplings

We shall construct a cover of M on which $\mathcal{M}(M, *)$ acts on the left and $\text{Homeo}(M, \omega)$ acts on the right.

Recall that $ev : \text{Homeo}(M) \rightarrow M$ is a fiber bundle defined by $ev(f) = f(*)$. Note that $\text{Homeo}(M, * \rightarrow x) = ev^{-1}(x)$. Denote by $\tilde{M}^{\mathcal{M}}$ the set of connected components of the fibers of ev and by $q : \text{Homeo}(M) \rightarrow \tilde{M}^{\mathcal{M}}$ the quotient map. On $\tilde{M}^{\mathcal{M}}$, we consider the quotient topology. Note that we have $q(f) = q(g)$ if and only if f can be connected to g via an isotopy preserving $f(*) = g(*)$ at all times.

The map ev factors via q :

$$\begin{array}{ccc} \text{Homeo}(M) & \xrightarrow{ev} & M \\ \downarrow q & \nearrow p^{\mathcal{M}} & \\ \tilde{M}^{\mathcal{M}} & & \end{array}$$

where $p^{\mathcal{M}}$ is the unique map making the above diagram commutative.

The evaluation map is a fiber bundle; thus, every $x \in M$ has an open neighborhood U such that $ev^{-1}(U)$ is homeomorphic to $U \times \text{Homeo}(M, *)$ by a fiber preserving homeomorphism. Moreover, by the definition of q , we have that $q(ev^{-1}(U))$ is the disjoint union of copies of U . On each such a copy, p^M is a homeomorphism. Thus, p^M is a covering map.

Denote by $\tilde{\omega}^M$ the measure on \tilde{M}^M defined by the pullback of the volume form on M that defines ω . We shall define the mentioned left and right actions.

Let $[c] \in \tilde{M}^M$ be a connected component of $ev^{-1}(c(*))$ represented by $c \in \text{Homeo}(M)$ and $[h] \in \mathcal{M}(M, *)$ be a mapping class represented by $h \in \text{Homeo}(M, *)$. The left action of $\mathcal{M}(M, *)$ on \tilde{M}^M is given by $[h].[c] = [hc] \in \tilde{M}^M$ (note that we compose homeomorphisms starting from the left), where $[hc]$ denotes the connected component of $ev^{-1}(c(*))$ containing hc . This action is transitive on the fibers of p^M and permutes the components of $q(ev^{-1}(U))$, where U is as above. Therefore, it is a deck-transformation group of \tilde{M}^M and preserves $\tilde{\omega}^M$.

Let $[c] \in \tilde{M}^M$ and $f \in \text{Homeo}(M, \omega)$. The right action of $\text{Homeo}(M, \omega)$ on \tilde{M}^M is given by $[c].f = [cf]$, where $[cf]$ is the connected component of $ev^{-1}(f(c(*)))$ containing cf . This action covers the $\text{Homeo}(M, \omega)$ -action on M and thus is $\tilde{\omega}^M$ -preserving.

The above actions define a coupling on \tilde{M}^M . Moreover, by construction, if P is a system of homeomorphisms, $im(P)$ is a subset of \tilde{M}^M . We say that a system of homeomorphisms P is measurable if $im(P)$ is $\tilde{\omega}^M$ -measurable.

Every measurable system of homeomorphisms defines a strict fundamental domain for the $\mathcal{M}(M, *)$ -action and vice versa. It follows directly from definitions (see Section 3.2) that the constructions described in Section 3.3 and [19] coincide. In particular, Γ_b^M does not depend on the choice of a measurable system of paths [19, Lemma 3.3].

Note that \tilde{M}^M is disconnected and contains the universal cover of M . Indeed, let \tilde{M}_0 be the subset of \tilde{M}^M containing classes that are represented by homeomorphisms isotopic to the identity in $\text{Homeo}(M)$. The subgroup $\pi_1(M, *) < \mathcal{M}(M, *)$ acts on \tilde{M}_0 , and the quotient is M ; thus, \tilde{M}_0 is the universal cover of M . An explicit isomorphism between \tilde{M}_0 and \tilde{M} is given by the map $T : \tilde{M}_0 \rightarrow \tilde{M}$, where $T([c])$ is the homotopy class of the path $c_t(*)$ traced by any isotopy c_t connecting Id_M to c . By the triviality of $ev_1 : \pi_1(\text{Homeo}(M)) \rightarrow \pi_1(M, *)$, this map is well defined. Therefore, \tilde{M}^M consists of infinitely many copies of \tilde{M} indexed by the right cosets of $\pi_1(M, *)$ in $\mathcal{M}(M, *)$.

Finally, we show that measurable systems of homeomorphisms exist. It follows from the existence of measurable systems of paths. Let $S(x) = [s_x]$ be a measurable system of paths, and let $P(x) = [h_x]$, where h_x is a point-pushing map along s_x . Using the isomorphism $T : \tilde{M}_0 \rightarrow \tilde{M}$, we can regard $im(S)$ as a $\tilde{\omega}^M$ -measurable subset of \tilde{M}_0 , and under this identification $im(S) = im(P)$. Thus P is a measurable system of homeomorphisms.

Remark 3.4. Set $\pi = \pi_1(M, *)$. The cover \tilde{M}^M is isomorphic to $(\mathcal{M}(M, *) \times \tilde{M})/\pi$, where π acts on $\mathcal{M}(M, *) \times \tilde{M}$ by $\gamma.(h, x) = (h\gamma^{-1}, \gamma.x)$.

4. Restriction to a free subgroup

In this section, we find a free subgroup F of $\pi_1(M, *)$ such that volume and Euler classes restricted to F have positive norms.

4.1. Volume class in dimension 2

Let X be a topological space. The l^1 -homology of X is denoted by $H_n^{l^1}(X)$ [9, Chapter 6]. In l^1 -homology, we allow chains to be infinite sums $c = \sum_i^\infty a_i \sigma_i$, where $\|c\| = \sum_i^\infty |a_i| < \infty$. As usual, the norm on chains induces the norm on $H_n^{l^1}(X)$. We have a Kronecker product between l^1 -homology and bounded cohomology:

$$\langle \cdot, \cdot \rangle : H_b^n(X) \times H_n^{l^1}(X) \rightarrow \mathbf{R}.$$

The Kronecker product is defined on the level of chains by $\langle b, a \rangle = \sum_i^\infty a_i b(\sigma_i)$, where $a = \sum_i^\infty a_i \sigma_i$ and b is a bounded cochain. Moreover, we have $|\langle B, A \rangle| \leq \|B\| \|A\|$, where $B \in H_b^n(X)$ and $A \in H_n^l(X)$. The following lemma is a variation of a result obtained in [16]. We do not assume that S is closed.

Lemma 4.1. *Let S be an oriented hyperbolic surface with non-abelian fundamental group. Then Vol_S has a positive norm.*

Proof. We shall find $C \in H_2^l(S)$ such that $\langle Vol_S, C \rangle \neq 0$. We can assume that S is a quotient of \mathbb{H}^2 , as in the beginning of the proof of Lemma 2.2. Let $p : \mathbb{H}^2 \rightarrow S$ be the covering map, and let $G = \pi_1(S)$. Since G is a surface group or is free, the commutator subgroup $[G, G]$ is non-abelian and hence contains a hyperbolic element $\gamma \in [G, G]$ [14, Theorem 2.4.4]. Let $A_\gamma \subset \mathbb{H}^2$ be the axis of γ . The conjugacy class of γ is represented by the closed geodesic $L_\gamma = p(A_\gamma) \subset S$. We regard L_γ as a map from $[0, 1]$ to S . Since $\gamma \in [G, G]$, γ is homologically trivial. Hence there exists a triangulated subsurface $S_0 \subset S$ such that $\partial S_0 = L_\gamma$.

The loop L_γ is the boundary of an l^1 -chain c_0 whose simplices are contained in the image of L_γ [16, Section 3]. Thus $c = S_0 - c_0$ is an l^1 -cycle. Recall that $Vol_S = [v'_S]$. The straightening of every simplex in c_0 is degenerate (L_γ is a geodesic); thus, we have $\langle v'_S, c_0 \rangle = 0$. We can assume that the triangulation of S_0 consists of geodesic simplices; hence $\langle v'_S, S_0 \rangle$ equals the hyperbolic volume of S_0 . Hence if we set $C = [c]$, we obtain $\langle Vol_S, C \rangle > 0$. The inequality $\langle Vol_S, C \rangle \leq \|Vol_S\| \|C\|$ implies that the norm of Vol_S is positive. □

The following corollary is stated in the group version terms of the volume class.

Corollary 4.2. *Let S be an oriented hyperbolic surface with non-abelian fundamental group. There exists an embedding $i : F \rightarrow \pi_1(S)$ of a free non-abelian group F such that $i^*(Vol_S^{gp})$ has a positive norm.*

Proof. Let F be any free non-abelian subgroup of S (which can be equal to $\pi_1(S)$ if S is not closed). We have $i^*(Vol_S^{gp}) = Vol_{i(F)}$. By Lemma 2.2, we know that the norm of $Vol_{i(F)}$ is equal to the norm of $Vol_{S'}$, where $S' = \mathbb{H}^2/i(F)$, and by Lemma 4.1, the norm of $Vol_{S'}$ is positive. □

4.2. Volume class in dimension 3

For some Kleinian groups, that is, the discrete subgroups of $Iso_+(\mathbb{H}^3)$, the volume class was studied in [20]. Note that if G is a torsion-free Kleinian group, then it acts freely and properly discontinuously on \mathbb{H}^3 . Thus \mathbb{H}^3/G is a manifold.

Theorem 4.3. [20, Theorem 1] *Let $G < Iso_+(\mathbb{H}^3)$ be a torsion-free topologically tame Kleinian group such that the volume of $M = \mathbb{H}^3/G$ is infinite. Then Vol_M has a positive norm if and only if G is not elementary and geometrically infinite.*

A Kleinian group G is geometrically finite if $N_\epsilon(H(L_G)/G)$ has finite volume for some $\epsilon > 0$, where N_ϵ is an ϵ neighborhood and $H(L_G)$ is the convex closure of the limit set of G [21, Chapter 8, Definition 8.4.1]. A torsion-free Kleinian group G is topologically tame if \mathbb{H}^3/G is homeomorphic to the interior of a compact manifold.

Note that every discrete finitely generated non-abelian free subgroup F of $Iso_+(\mathbb{H}^3)$ is topologically tame [1, 6], not elementary and \mathbb{H}^3/F has infinite volume (otherwise, by the thick-thin decomposition, \mathbb{H}^3/F would have a cusp and \mathbb{Z}^2 would embed in F). Let M be an oriented 3-dimensional hyperbolic manifold. Then for every free group F in $\pi_1(M) < Iso_+(\mathbb{H}^3)$ which is geometrically infinite, Vol_F has positive norm. Below we describe our main example of such a situation, that is, manifolds that fiber over the circle with non-compact fiber.

Example 4.4. Suppose S is a connected oriented surface without boundary and free fundamental group $F = \pi_1(S)$. Let $f \in \text{Diff}^+(S)$. The mapping torus of f is a 3-dimensional manifold $M_f = S \times [0, 1] / \sim$, where $(x, 0) \sim (f(x), 1)$. That is, the boundary components of $S \times [0, 1]$ are glued together via f . Note that M_f fibers over the circle with fiber S , and conversely, every 3-manifold that fibers over a circle with fiber S can be constructed in this way. The mapping torus M_f is hyperbolic if and only if f is isotopic to a pseudo-Anosov map [22]. If M_f is hyperbolic, the hyperbolic structure is unique, and we have a unique class $\text{Vol}_{M_f}^{sp} \in H_b^3(\pi_1(M_f))$. Now the inclusion of the fiber S into M_f gives an embedding $i : F \rightarrow \pi_1(M_f)$, and $i(F)$ is a normal subgroup of $\pi_1(M)$. It follows that the limit set of $i(F)$ is equal to the limit set of $\pi_1(M)$ [21, Chapter 8, Corollary 8.1.3]; thus, it is the entire sphere at infinity. Hence $i(F)$ is geometrically infinite. By Theorem 4.3, we have that $i^*(\text{Vol}_{M_f}^{sp}) = \text{Vol}_{i(F)}$ has positive norm.

4.3. Euler class

We briefly recall basic definitions concerning quasimorphisms [9, Chapter 2]. Let G be a group. A real function $q : G \rightarrow \mathbb{R}$ is called a quasimorphism if there exists some $D \in \mathbb{R}$ such that

$$|q(ab) - q(a) - q(b)| \leq D$$

for any $a, b \in G$. The minimal such D is called the defect of q . A quasimorphism is homogeneous if $q(a^n) = nq(a)$ for any $a \in G$ and $n \in \mathbb{Z}$. The nonhomogeneous coboundary $dq(a, b) = q(a) - q(ab) + q(b)$ of q is interpreted as a second bounded cohomology class $[dq] \in H_b^2(G)$. If q is homogeneous and not a homomorphism, then $[dq]$ is non-trivial and has a positive norm [9, Corollary 6.7].

Lemma 4.5. Let S be an oriented closed surface of genus ≥ 2 . There exists an embedding $i : F \rightarrow \pi_1(S)$ of a free non-abelian group F such that $i^*(e_b^S)$ has a positive norm.

Proof. Let T^1S be the unit tangent bundle of S and denote by $q : \pi_1(T^1S) \rightarrow \pi_1(S)$ the map induced by the projection $T^1S \rightarrow S$. We will use the rotation quasimorphism $\text{Rot} : \pi_1(T^1S) \rightarrow \mathbb{R}$ defined in [12]. It is a homogeneous quasimorphism of defect 1, which trivializes the pullback $q^*(e_b^S) \in H_b^2(\pi_1(T^1S))$, that is, $q^*(e_b^S) = [d\text{Rot}]$ [12, Theorem 5.9].

Let $a, b \in \pi_1(T^1S)$ be such that $\text{Rot}(ab) \neq \text{Rot}(a) + \text{Rot}(b)$. Let $F = \langle q(a), q(b) \rangle < \pi_1(S)$. Denote this inclusion by $i : F \rightarrow \pi_1(S)$, and set $F' = q^{-1}(F)$. It follows from the definition of a and b that $\text{Rot}|_{F'}$ is a homogeneous quasimorphism that is not a homomorphism. Thus $q^*(e_b^S)|_{F'}$ has positive norm, and $i^*(e_b^S)$ must have positive norm since $q^*i^*(e_b^S) = q^*(e_b^S)|_{F'}$. Finally, F must be free of rank 2. Indeed, every subgroup of $\pi_1(S)$ is free non-abelian, abelian, or is a surface group. But surface groups are not generated by 2 elements, and abelian groups do not carry a non-trivial class in their second bounded cohomology. Thus F is free non-abelian of rank 2. □

5. Proof of the theorem

Let M be a manifold with a volume form ω . As usual, ω denotes as well the induced measure, and we assume that this measure is finite. Suppose $i : F \rightarrow \pi_1(M)$ is an embedding and consider $i^* : H_b^\bullet(\pi_1(M)) \rightarrow H_b^\bullet(F)$. Let $\rho : F \rightarrow \text{Homeo}_0(M, \omega)$ be a representation of F by homeomorphisms. Let $\rho^* : H_b^\bullet(\text{Homeo}_0(M, \omega)) \rightarrow H_b^\bullet(F)$. Thus we have a not necessarily commutative diagram:

$$\begin{array}{ccc} H_b^\bullet(\pi_1(M)) & \xrightarrow{\Gamma_b} & H_b^\bullet(\text{Homeo}_0(M, \omega)) \\ \downarrow i^* & \swarrow \rho^* & \\ H_b^\bullet(F) & & \end{array}$$

Let $\Lambda, \epsilon \in \mathbb{R}$. We say that ρ is an (F, Λ, ϵ) -inverse of Γ_b if for every $C \in H_b^*(\pi_1(M))$, we have

$$\|\rho^* \Gamma_b(C) - \Lambda i^*(C)\| \leq \epsilon \|C\|.$$

Lemma 5.1. *Let M be a manifold and ω a finite measure induced by a volume form on M . Suppose that $i : F \rightarrow \pi_1(M)$ is an embedding of a non-abelian free group F . There exists $\Lambda \in \mathbb{R}$ such that for every $\epsilon > 0$ there exists an (F, Λ, ϵ) -inverse of Γ_b .*

Proof. Let $\dim(M) = m$. Denote by $B^{m-1} \subset \mathbb{R}^{m-1}$ the $m - 1$ dimensional closed unit ball, and let $S^1 = \mathbb{R}/\mathbb{Z}$. Let us fix $\eta \in (0, 1)$ and define an isotopy $P_\eta^t \in \text{Diff}(S^1 \times B^{m-1})$ by

$$P_\eta^t(\psi, x) = (\psi + tf(\|x\|), x) \quad \forall (\psi, x) \in S^1 \times B^{m-1},$$

where $t \in [0, 1]$ and $f : [0, 1] \rightarrow \mathbb{R}$ is a smooth function such that $f(y) = 1$ for $y \leq 1 - \eta$ and $f(1) = 0$. We call P_η^t the finger-pushing isotopy and P_η^1 the finger-pushing map. Note that $P_\eta^0 = Id$ and that P_η^1 fixes point-wise the boundary of $S^1 \times B^{m-1}$ and fixes all points (ψ, x) for which $\|x\| \leq 1 - \eta$. Moreover, P_η^t fixes the boundary of $S^1 \times B^{m-1}$ for all t . Denote by g_0 be the product of the standard Euclidean Riemannian metrics on B^{m-1} and S^1 . By the theorem of Fubini, the measure induced by g_0 is preserved by the map P_η^t for every $t \in [0, 1]$. Let a_1, \dots, a_k be generators of $F := F_k$, where $k > 1$. We represent $i(a_i)$ by a loop α_i which is based at $* \in M$.

Let B be a closed ball in M containing $*$ and set $\Lambda = \omega(B)$. Suppose A_i are closed small tubular neighborhoods of α_i . Then $N_i = B \cup A_i$ is a closed neighborhood of α_i which is diffeomorphic to $S^1 \times B^{m-1}$. Let $P_\eta^t(\alpha_i) \in \text{Diff}_0(M)$ be the isotopy defined by pulling-back P_η^t via a diffeomorphism $n_{\alpha_i} : N_i \rightarrow S^1 \times B^{m-1}$ (i.e., we have $P_\eta^t(\alpha_i) = n_{\alpha_i}^{-1} \circ P_\eta^t \circ n_{\alpha_i}$ on N_i) and extending it by the identity outside N_i . Note that the Moser trick [17] allows us to choose n_{α_i} such that $P_\eta^t(\alpha_i)$ preserves ω . Let S_i be the support of $P_\eta^1(\alpha_i)$. It is a small thickening of the boundary of N_i .

The homomorphism $\rho : F \rightarrow \text{Homeo}_0(M, \omega)$ is given by:

$$\rho(a_i) = P_\eta^1(\alpha_i).$$

To simplify the notation, we identify F with its image $i(F)$. Now we consider the values of γ on elements of the form $(\rho(w), x)$, where $w \in F, x \in M$.

From the description of γ in Section 3.1, we have:

$$\gamma(\rho(w), x) = \begin{cases} e & x \in M - \bigcup_{i=1}^k N_i, \\ w & x \in B - \bigcup_{i=1}^k S_i, \\ ? & x \in (\bigcup_{i=1}^k A_i - B) \cup \bigcup_{i=1}^k S_i. \end{cases}$$

Let $C \in H_b^n(M)$, and let c be a bounded cochain representing C . Since any cochain and its anti-symmetrization define the same class, we may assume that $c(e, \dots, e) = 0$. Let

$$\bar{f} = (f_0, f_1, \dots, f_n) \in \text{Homeo}_0(M, \omega)^{n+1},$$

and denote

$$\gamma(\bar{f}, x) = (\gamma(f_0, x), \gamma(f_1, x), \dots, \gamma(f_n, x)).$$

Let $\bar{w} \in F^{n+1}$. We have

$$\rho^* \Gamma_b(c)(\bar{w}) = \Gamma_b(c)(\rho(\bar{w})) = \int_M c(\gamma(\rho(\bar{w}), x)) d\omega(x).$$

Denote $E := (\bigcup_{i=1}^k A_i - B) \cup \bigcup_{i=1}^k S_i$. We obtain

$$\begin{aligned} \rho^* \Gamma_b(c)(\bar{w}) &= \int_{B - \bigcup_{i=1}^k S_i} c(\bar{w}) d\omega(x) + \int_E c(\gamma(\rho(\bar{w}), x)) d\omega(x) \\ &= \omega \left(B - \bigcup_{i=1}^k S_i \right) i^*(c)(\bar{w}) + \int_E c(\gamma(\rho(\bar{w}), x)) d\omega(x). \end{aligned}$$

Let

$$c_{res}(\bar{\omega}) := \int_E c(\gamma(\rho(\bar{\omega}), x))d\omega(x).$$

Note that c_{res} represents a class in $H_b^n(F)$ and we can write

$$\rho^*\Gamma_b(c) = \omega(B - \bigcup_{i=1}^k S_i)i^*(c) + c_{res},$$

and

$$\|c_{res}\| \leq \omega(E)\|c\|.$$

Moreover:

$$\begin{aligned} \|\rho^*\Gamma_b(c) - \omega(B)i^*(c)\| &\leq \\ &\leq \omega\left(\bigcup_{i=1}^k S_i\right)\|i^*(c)\| + \omega(E)\|c\| \leq \\ &\leq \left[\omega\left(\bigcup_{i=1}^k S_i\right) + \omega(E)\right]\|c\|. \end{aligned}$$

Now $\omega(S_i)$ and $\omega(E)$ can be taken to be arbitrarily small by taking small η and small neighborhoods A_i . The cochain c was any cochain representing C . Thus for any chosen ϵ , we can have

$$\|\rho^*\Gamma_b(C) - \Lambda i^*(C)\| \leq \epsilon\|C\|,$$

where $\Lambda = \omega(B)$. □

Theorem 5.2. *Let M be an oriented manifold of dimension n such that it is either:*

- *A hyperbolic surface with a non-abelian fundamental group or*
- *A complete hyperbolic 3-manifold whose fundamental group contains a geometrically infinite finitely generated free group (e.g., M fibers over the circle with non-compact fiber).*

Let ω be a volume form on M such that the induced measure is finite. Then $\Gamma_b(\text{Vol}_M^{sp}) \in H_b^n(\text{Homeo}_0(M, \omega))$ has positive norm.

Proof. By Corollary 4.2 and Theorem 4.3, in both cases, we have a free group F and an embedding $i : F \rightarrow \pi_1(M)$ such that $i^*(\text{Vol}_M^{sp})$ has positive norm. Let $\rho : F \rightarrow \text{Homeo}_0(M, \omega_h)$ be an (F, Λ, ϵ) -inverse of Γ_b with ϵ satisfying

$$0 < \Lambda\|i^*(\text{Vol}_M^{sp})\| - \epsilon\|\text{Vol}_M^{sp}\|.$$

We have

$$\Lambda\|i^*(\text{Vol}_M^{sp})\| - \|\rho^*\Gamma_b(\text{Vol}_M^{sp})\| \leq \|\Lambda i^*(\text{Vol}_M^{sp}) - \rho^*\Gamma_b(\text{Vol}_M^{sp})\| \leq \epsilon\|\text{Vol}_M^{sp}\|.$$

Thus

$$0 < \Lambda\|i^*(\text{Vol}_M^{sp})\| - \epsilon\|\text{Vol}_M^{sp}\| \leq \|\rho^*\Gamma_b(\text{Vol}_M^{sp})\|.$$

Since ρ^* is a contraction, $\Gamma_b(\text{Vol}_M^{sp})$ must have positive norm. □

Theorem 5.3. *Let S be an oriented closed surface of genus ≥ 2 and ω a measure induced by an area form on S . Then the classes $\Gamma_b(e_b^S) \in H_b^2(\text{Homeo}_0(S, \omega))$ and $\Gamma_b^{\mathcal{M}^+}(e_b^{\mathcal{M}^+}) \in H_b^2(\text{Homeo}(S, \omega))$ have positive norms.*

Proof. The proof for e_b^S is the same as in Theorem 5.2 using Lemma 4.5. Note that elements of $\text{Homeo}(S, \omega)$ automatically preserve the orientation of S . Positivity of the norm of $e_b^{\mathcal{M}_+}$ follows from the commutative diagram

$$\begin{CD} H_b^2(\mathcal{M}_+(S, *)) @>\Gamma_b^{\mathcal{M}_+}>> H_b^2(\text{Homeo}(S, \omega)) \\ @V\Pu^*VV @VVV \\ H_b^2(\pi_1(S, *)) @>\Gamma_b>> H_b^2(\text{Homeo}_0(S, \omega)), \end{CD}$$

where $Pu : \pi_1(S, *) \rightarrow \mathcal{M}_+(S, *)$ is the injection from the Birman exact sequence. □

6. Dirac measure

The constructions of Γ_b and $\Gamma_b^{\mathcal{M}}$ are flexible and admit more variants. First of all, one does not need to restrict to measures coming from a volume form. What is needed is a measure with a cocycle for which the integral in the definition is well defined. Moreover, one can relax the definition of an isotopy. For example, it is not necessary to assume that isotopy preserves the measure at all times. Isotopy might be as well substituted by homotopy.

In this short section, we discuss the (somewhat degenerate) case where the measure is the Dirac measure and isotopies do not preserve the measure. In this case, Γ_b is induced by a homomorphism. Let M be a manifold and $* \in M$ a basepoint. We assume that the center of $\pi_1(M, *)$ is trivial (what we really need to assume is the triviality of ev_1 , and even in the case where it is not, one could substitute $\pi_1(M, *)$ with the quotient $\pi_1(M, *)/im(ev_1)$). By $*$ we denote as well the Dirac measure centered on $*$.

Let G be the subgroup of $\text{Homeo}_0(M)$ of all homeomorphisms f preserving $*$. Thus an element of G is isotopic to the identity by an isotopy that can move $*$. Suppose S is a system of paths. As in Section 3.1, we get a cocycle:

$$\gamma : G \times M \rightarrow \pi_1(M, *)$$

and a map

$$\Gamma_b : H_b^\bullet(\pi_1(M, *)) \rightarrow H_b^\bullet(G).$$

Note that on \tilde{M} , we can consider the counting measure on the orbit $p^{-1}(*)$. With such a measure \tilde{M} defines a coupling and every S is measurable. Moreover, Γ_b does not depend on S [19, Lemma 3.3].

Recall that we have a homomorphism

$$Tr : G \rightarrow \pi_1(M, *)$$

defined in the following way: $Tr(f)$ is the homotopy class of the loop $f_i(*)$, where f_i is any isotopy between Id_M and f .

It is straightforward to see that $\Gamma_b = Tr^*$, the map induced on bounded cohomology by Tr . Note that if we started with the group $\text{Homeo}_0(M, *)$ (isotopies preserve $*$ at all times), instead of G , then $\Gamma_b : H_b^\bullet(\pi_1(M, *)) \rightarrow H_b^\bullet(\text{Homeo}_0(M, *))$ would be trivial in positive degrees. Indeed, in this case $\Gamma_b(c)$ is a constant cocycle, and constant cocycles in positive degrees represent trivial classes.

Suppose that a non-abelian free group F embeds in $\pi_1(M, *)$. The representations ρ constructed in Lemma 5.1 are homomorphisms. Since $\gamma(\rho(w), *) = w$ for every $w \in F$, the following diagram commutes:

$$\begin{CD} H_b^\bullet(\pi_1(M, *)) @>\Gamma_b>> H_b^\bullet(G) \\ @V{i^*}VV @AA{\rho^*}A \\ H_b^\bullet(F) @<< @<< \end{CD}$$

Thus ρ is a $(F, 1, 0)$ -inverse of Γ_b . It follows that Theorems 5.2 and 5.3 hold as well for the Dirac measure. Similarly, Theorem A and Theorem B from [5] hold with $\mathcal{T}_M = G$; that is, Tr^* has the image of dimension continuum in degree 2 and 3 (if M satisfies the assumptions of Theorems A and B).

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