

ERRATUM

Task-priority motion planning of underactuated systems: an endogenous configuration space approach – ERRATUM

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Figures 2 and 5 were incorrectly reproduced in the above publication (Ratajczak *et al.* 2009). The figures are reproduced below in their correct form.

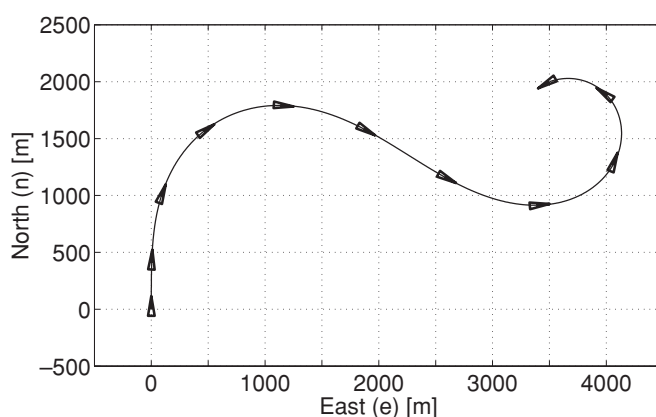


Fig. 2. Task-priority algorithm (both S_1 and S_2).

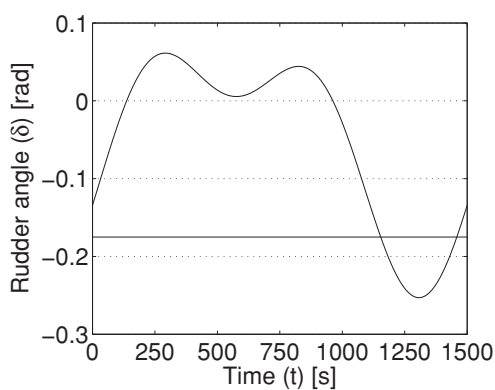


Fig. 5. Single-task algorithm (only S_1).

Reference

1. A. Ratajczak, J. Karpińska and K. Tchoń, “Task-priority motion planning of underactuated systems: An endogenous configuration space approach,” *Robotica*, doi:10.1017/S0263574709990737